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## A Benders decomposition for maximum simulated likelihood estimation of advanced discrete choice models

Tom Häring, Claudia Bongiovanni, Michel Bierlaire

TRANSP-OR Laboratory

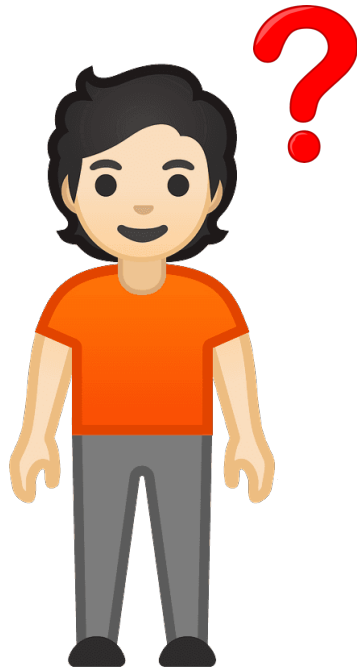
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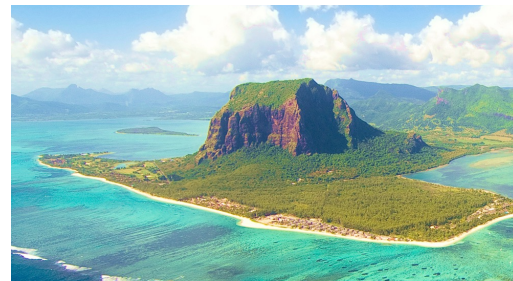
1. Why maximum likelihood estimation (MLE)?
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# Why maximum likelihood estimation (MLE)?

- **MLE** is for example used to estimate the parameters of **discrete choice models**



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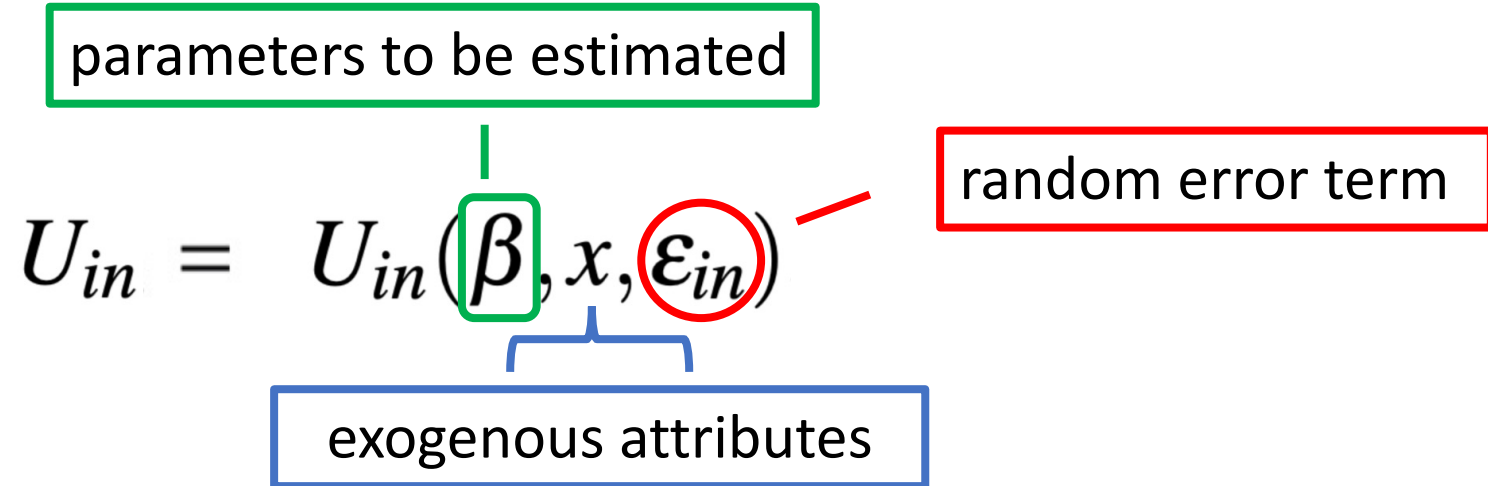
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# Why maximum likelihood estimation (MLE)?

- For each **individual**  $n$ , every **alternative**  $i$  has an associated **utility**:


$$U_{in} = U_{in}(\beta, x, \epsilon_{in})$$

parameters to be estimated

random error term

exogenous attributes

- Assumptions:
  - I.) **linear** in parameters
  - II.) we can **draw** from error terms

# Why maximum likelihood estimation (MLE)?

- For each **individual**  $n$ , every **alternative**  $i$  has an associated **utility**:

$$U_{in} = \sum_k \beta_k x_{ink} + \epsilon_{in} = V_{in} + \epsilon_{in}$$

deterministic part

stochastic part

- Behavioral assumption: the individual chooses the alternative with **the highest utility**

# Why maximum likelihood estimation (MLE)?

- Data: **observed choices**  $y_{in}$  (= 1 if ind.  $n$  chose alternative  $i$ , else = 0)
- Find parameters  $\beta_k$  such that the **likelihood** of this outcome is **maximized**
- **Log-Likelihood function:**

$$\ln \left( \prod_n \prod_i P_n(i)^{y_{in}} \right) = \sum_n \sum_i y_{in} \ln P_n(i)$$

where

$$P_n(i) = \mathbb{P}(V_{in} + \epsilon_{in} \geq V_{jn} + \epsilon_{jn} \forall j \in J)$$

# Why simulated MLE?

- DCMs model choices **realistically** [1], but in general lead to **non-convex** probabilities [2]
  - ➔ No global optimality certificates, **danger of local optima**
  - ➔ Non-convex solver  $\approx$  **Blackbox**
- **Simulation** mitigates this by giving a **linear** approximation [3] and allows DCMs to be easily **integrated** in optimization programs [2]

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[1] **Bierlaire**: *Discrete choice models* (1998)

[2] **Pacheco**: *Integrating advanced discrete choice models in mixed integer linear optimization* (2021)

[3] **Train**: *Discrete choice methods with simulation* (2009)



# Why simulated MLE?

- How:

- **Simulate**  $R$  scenarios, utilities become **deterministic**:

$$U_{inr} = V_{in} + \epsilon_{inr} \leftarrow \text{Draw from distribution}$$

- Let  $\omega_{inr}$  be the **choice variables**

- **Approximated** probabilities: 
$$\hat{P}_n(i) = \frac{1}{R} \sum_{r=0}^{R-1} \omega_{inr}$$



# Why a mixed integer linear program (MILP)?

- Allow inclusion of **integer variables** in estimation procedure
  - Model **advanced** DCMs, e. g. **latent variables / classes**
  - Additional features, e. g. **automatic / assisted specification**
- Vast literature on efficient **modeling & performance**
- Gives **control** over **optimization process**: information on **bounds, optimality gaps, user-generated cuts**, etc.

# Simulated MLE as an MILP

• **Objective:** max Log-Likelihood  $\sum_n \sum_i y_{in} \ln P_n(i)$



max sim. Log-Likelihood  $\sum_{in} y_{in} \ln \sum_{r=0}^{R-1} \omega_{inr} - y_{in} \ln R$



$$S_{in} = \sum_r \omega_{inr}$$

$$z_{in} \leq L_r - K_r S_{in}$$

$$\max \sum_n \sum_i y_{in} z_{in}$$

# Simulated MLE as an MILP

- **Constraints:**

$$\sum_i \omega_{inr} = 1 \quad \forall n, r$$

$$U_{inr} = \sum_k \beta_k x_{ink} + \epsilon_{inr} \quad \forall i, n, r$$

$$U_{nr} \geq U_{inr} \quad \forall i, n, r$$

$$U_{nr} = \sum_i U_{inr} \omega_{inr} \quad \forall n, r$$

$$S_{in} = \sum_r \omega_{inr} \quad \forall i, n$$

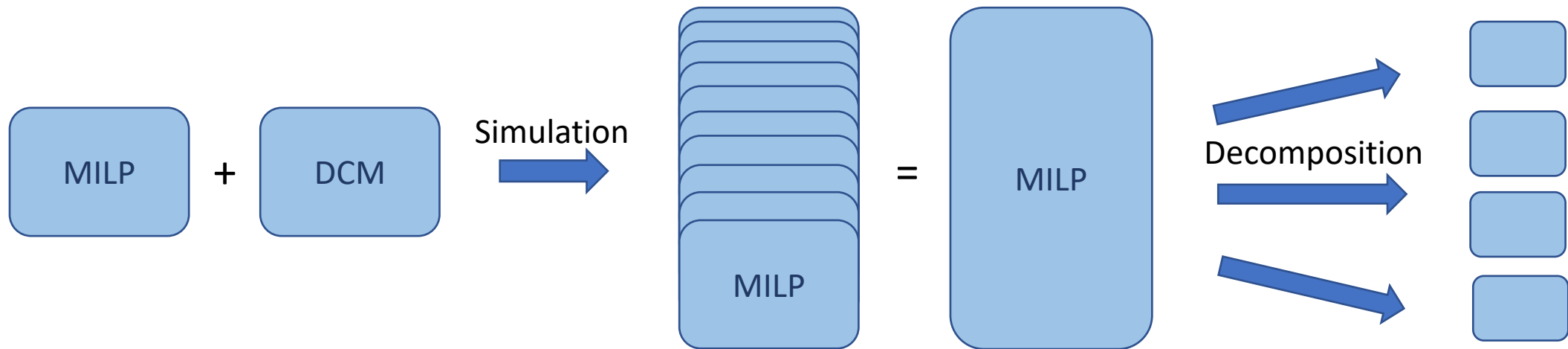
$$z_{in} \leq L_r - K_r S_{in} \quad \forall i, n$$

$$\omega_{inr} \in \{0, 1\}$$

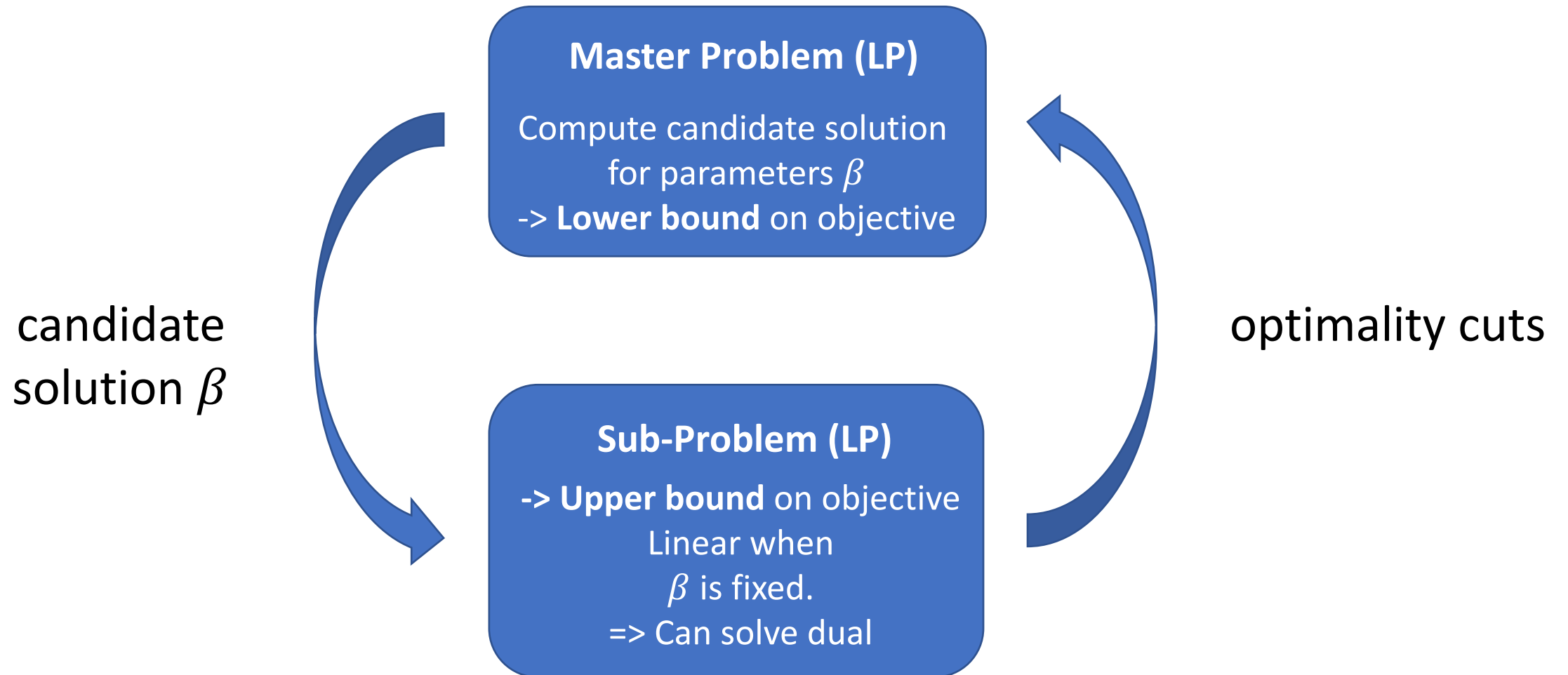
$$\beta, s, z, U, U \in \mathbb{R}$$

# Why decomposition?

- Problem: Simulation **increases problem size** by solving **many scenarios**  
    ➔ **only small instances** can be solved in reasonable time [1]
- To solve large MILPs efficiently we consider **decomposition methods**



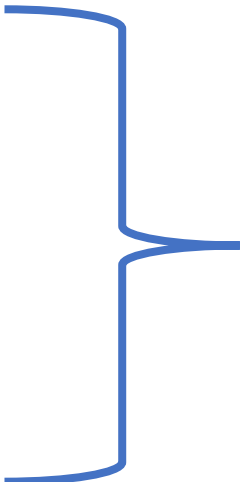
# The Benders decomposition



# The Benders decomposition

- For a **fixed**  $\beta_k$  the rest of the MILP becomes a **Knapsack-problem**  
**=> totally unimodular:**

- Utilities become fixed  $U_{inr} = \sum_k \beta_k^{\text{fixed}} x_{ink} + \epsilon_{inr}$

- Now: 
$$U_{nr} = \sum_i U_{inr} \omega_{inr}$$
$$U_{nr} \geq U_{inr}$$
$$\sum_i \omega_{inr} = 1$$
$$\omega_{inr} \in [0, 1]$$

$$\omega_{i^*nr} = 1$$

for the alternative  $i^*$   
with highest utility

# The Benders decomposition

- Start with **initial guess** for the variable to be fixed

- **Subproblems:**

- relax **integral domains**:  $\omega_{inr} \in [0, 1]$

- add **constraints**:  $\beta_k = \beta_k^{\text{fixed}} \quad (\varphi_k^\beta)$

➔ RHS of primal = objective of dual =  $\dots + \sum_k \varphi_k^\beta \beta_k^{\text{fixed}}$

- **solve dual**, get optimal values for  $\varphi_k^\beta$

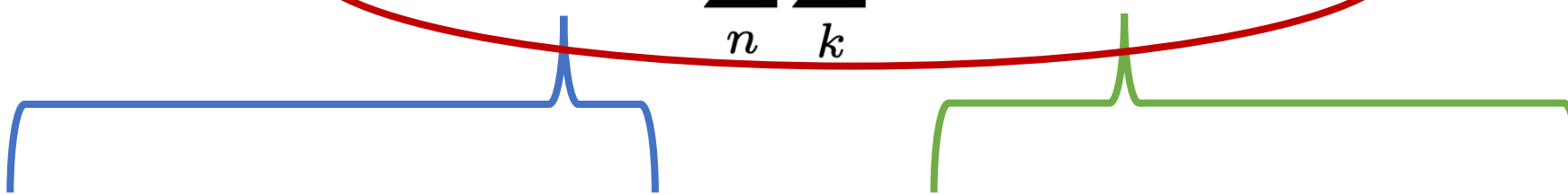


# The Benders decomposition

- Solve master problem:

$$\begin{array}{ll} \min_{\beta, \mathcal{L}} & \mathcal{L} \\ \text{s.t.} & \mathcal{L} \geq \mathcal{L}^* + \sum_n \sum_k \varphi_{nk}^\beta (\beta_k - \beta_k^{\text{fixed}}) \end{array}$$

Benders cut



objective value of primal / dualReplace fixed variable value by actual MP variable

# The Benders decomposition

- **Typically:**

- The variable to be fixed is **integer**, so that the subproblems are linear
- Thus **MP is an integer program (bottleneck!)**

- **But in our case:**

- The variable to be fixed is **continuous**, but thanks to TU-ness the subproblems are (*technically*) still linear!
- Thus **SP is a linear program!**

From solving an MILP to iteratively solving LP's!

# The Benders decomposition

- **Difficulty:**

Simply adding the constraint  $\beta_k = \beta_k^{\text{fixed}}$  **does not work in our case** because of the **non-linearity** of the problem

# The Benders decomposition

- **Constraints:**

Goal: linear in  $\beta_k$

$$\begin{aligned}
 \sum_i \omega_{inr} &= 1 && \forall n, r \\
 U_{inr} &= \sum_k \beta_k x_{ink} + \epsilon_{inr} && \forall i, n, r \\
 U_{nr} &\geq U_{inr} && \forall i, n, r \\
 U_{nr} &= \sum_i U_{inr} \omega_{inr} && \forall n, r \\
 \beta_k &= \beta_k^{\text{fixed}} && \forall k \\
 S_{in} &= \sum_r \omega_{inr} && \forall i, n \\
 z_{in} &\leq L_r - K_r S_{in} && \forall i, n \\
 \omega_{inr} &\in [0, 1]
 \end{aligned}$$

Non-linear!

$$\beta, s, z, U, U \in \mathbb{R}$$

# The Benders decomposition

- **Constraints:**

$$\begin{aligned}\sum_i \omega_{inr} &= 1 \\ \sum_i U_{inr} &= \sum_k \beta_k x_{ink} + \epsilon_{inr} \\ U_{nr} &\geq U_{inr} \\ U_{nr} &= \sum_i U_{inr} \omega_{inr} \\ \beta_k &= \beta_k^{\text{fixed}}\end{aligned}$$

# The Benders decomposition

- **Constraints:**

$$\sum_i \omega_{inr} = 1$$
$$U_{inr} = \sum_k \beta_k x_{ink} + \epsilon_{inr}$$

$$U_{nr} \geq U_{inr}$$

$$U_{nr} = \sum_i U_{inr}^{\text{fixed}} \omega_{inr}$$

$$\beta_k = \beta_k^{\text{fixed}}$$

} **Disconnected!**

# The Benders decomposition

- **Constraints:**

$$\begin{aligned}\sum_i \omega_{inr} &= 1 \\ \sum_i U_{inr} &= \sum_k \beta_k x_{ink} + \epsilon_{inr} \\ U_{nr} &\geq U_{inr} \\ U_{nr} &= \sum_i \omega_{inr} \left[ \sum_k \beta_k x_{ink} + \epsilon_{inr} \right] \\ \beta_k &= \beta_k^{\text{fixed}}\end{aligned}$$



# The Benders decomposition

- **Constraints:**

$$\begin{aligned}\sum_i \omega_{inr} &= 1 \\ \sum_i U_{inr} &= \sum_k \beta_k x_{ink} + \epsilon_{inr} \\ U_{nr} &\geq U_{inr} \\ U_{nr} &= \sum_i \left[ \sum_k (\omega_{inr} \beta_k) x_{ink} + \omega_{inr} \epsilon_{inr} \right] \\ \beta_k &= \beta_k^{\text{fixed}}\end{aligned}$$

# The Benders decomposition

- **Constraints:**

$$\begin{aligned}\sum_i \omega_{inr} &= 1 \\ U_{inr} &= \sum_k \beta_k x_{ink} + \epsilon_{inr} \\ U_{nr} &\geq U_{inr} \\ U_{nr} &= \sum_i \left[ \sum_k \eta_{inrk} x_{ink} + \omega_{inr} \epsilon_{inr} \right] \\ \eta_{inrk} &= \beta_k \omega_{inr} \\ \beta_k &= \beta_k^{\text{fixed}}\end{aligned}$$

# The Benders decomposition

- **Constraints:**

$$\sum_i \omega_{inr} = 1$$
$$U_{inr} = \sum_k \beta_k x_{ink} + \epsilon_{inr}$$

$$U_{nr} \geq U_{inr}$$

$$U_{nr} = \sum_i \left[ \sum_k \eta_{inrk} x_{ink} + \omega_{inr} \epsilon_{inr} \right]$$

$$\psi_{inrk} = \frac{1}{2}(\beta_k + \omega_{inr})$$

$$\phi_{inrk} = \frac{1}{2}(\beta_k - \omega_{inr})$$

$$\eta_{inrk} = \psi_{inrk}^2 - \phi_{inrk}^2 \rightarrow \text{piece-wise linear approximations}$$

$$\beta_k = \beta_k^{\text{fixed}} \rightarrow \text{Does not preserve total unimodularity}$$

# The Benders decomposition

- **Constraints:**

$$\begin{aligned}\sum_i \omega_{inr} &= 1 \\ U_{inr} &= \sum_k \beta_k x_{ink} + \epsilon_{inr} \\ U_{nr} &\geq U_{inr} \\ U_{nr} &= \sum_i U_{inr} \omega_{inr} \\ \beta_k &= \beta_k^{\text{fixed}}\end{aligned}$$

Convex?

# The Benders decomposition

- We design a **quasi**-linearization:

$$\begin{array}{l} \eta_{inrk} = \beta_k \omega_{inr} \\ \beta_k = \beta_k^{\text{fixed}} \end{array} \quad \longrightarrow \quad \begin{array}{l} \chi_{inr} + \omega_{inr} = 1 \\ \eta_{inrk} + \beta_k^{\text{fixed}} \chi_{inr} = \beta_k^{\text{fixed}} \\ \sum_i \eta_{inrk} = \beta_k \end{array}$$

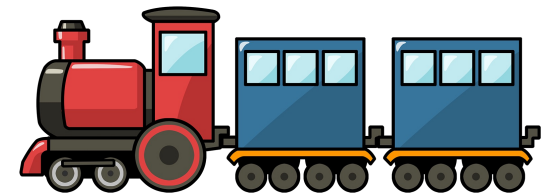
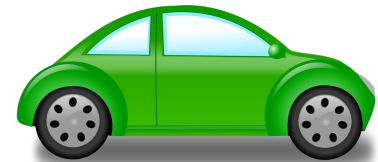
# Application to a mode choice problem

- Dataset: **RP** data on **mode choice**, Netherlands, 1987
- Simple **binary logit model**:

choice between two modes – **car** and **rail**

$$U_{\text{car},n} = \beta_{\text{time}} * \text{traveltime}_{\text{car}}$$

$$U_{\text{rail},n} = \beta_{\text{time}} * \text{traveltime}_{\text{rail}}$$



- Compare **decomposition** vs. **undecomposed MILP**

N	R	sLL-M	sLL-D	Gap [%]	T-M	T-D
20	50	-12.607	-12.658	-0.40	64.942	10.061
20	100	-12.212	-12.258	-0.38	403.694	9.902
20	200	-12.283	-12.648	-2.97	1117.064	16.939
50	50	-30.848	-31.030	-0.59	286.679	29.780
50	100	-30.461	-31.040	-1.90	1558.604	65.006
50	200	-30.566	-30.692	-0.41	5375.655	98.206
100	50	-65.204	-65.801	-0.92	2820.229	28.781
100	100	-65.784	-67.419	-2.49	4346.067	274.163
100	200	-65.699	-66.018	-0.49	10800+	295.741
200	50	-123.551	-124.027	-0.39	1476.185	120.579
200	100	-124.000	-124.243	-0.20	10800+	327.253
200	200	-124.707	-124.106	0.48	10800+	1262.755



N	R	$\beta - M$	$\beta - D$	Gap [%]	T - M	T - D
20	50	-1.048	-0.97	7.44	65	10
20	100	-1.143	-1.11	2.89	404	10
20	200	-1.182	-2.16	-82.74	1117	17
50	50	-1.223	-0.935	23.55	287	30
50	100	-1.223	-1.783	-45.79	1559	65
50	200	-1.223	-1.307	-6.87	5376	98
100	50	-0.889	-0.612	31.16	2820	29
100	100	-0.943	-0.451	52.17	4346	274
100	200	-0.899	-0.85	5.45	10800	296
200	50	-1.39	-1.322	4.89	1476	121
200	100	-1.49	-1.393	6.51	10800	327
200	200	-1.021	-1.377	-34.87	10800	1263

# Application to a mode choice problem

- First **conjecture**: gaps are caused by **log-linearization** in MSLE
- **Remedy**: apply decomposition to *continuous pricing problem (CPP)*
  - ➔ Almost **equivalent** problem structure, **no log-linearization**

# Application to a continuous pricing problem

- Continuous pricing problem:

$$\max_{p, \omega, U, H} \sum_n \sum_r \sum_i \frac{1}{R} \theta_{in} p_i \omega_{inr}$$

s.t.

$$\sum_i \omega_{inr} = 1 \quad \forall n, r$$

$$H_{nr} = \sum_i U_{inr} \omega_{inr} \quad \forall n, r$$

$$H_{nr} \geq U_{inr} \quad \forall i, n, r$$

$$U_{inr} = \sum_{k \neq l} \beta_k x_{ink} + \beta_l p_i + \epsilon_{inr} \quad \forall i, n, r$$

$$\omega \in \{0, 1\}$$

$$p, U, H \in \mathbb{R}$$

# Application to a continuous pricing problem

N	R	obj-MILP	obj-D	Gap [%]	P-MILP	P-D	Gap [%]	T-MILP	T-D
20	50	216.407	209.196	3.33	28.475	30.764	-8.04	7	11
20	100	202.642	201.712	0.46	28.302	26.576	6.1	37	21
20	200	200.901	200.185	0.36	30.03	28.721	4.36	205	49
50	50	440.686	437.243	0.78	28.579	29.989	-4.94	55	27
50	100	431.088	426.669	1.03	28.99	27.778	4.18	241	62
50	200	429.605	429.108	0.12	28.574	28.655	-0.28	1022	163
100	50	990.026	988.732	0.13	29.118	28.944	0.6	252	31
100	100	977.606	976.149	0.15	30.099	29.925	0.58	1224	69
100	200	978.589	976.932	0.17	30.106	30.185	-0.26	3039	304
200	50	1906.696	1904.189	0.13	28.977	28.678	1.03	1144	65
200	100	1882.793	1877.641	0.27	29.277	30.052	-2.65	4104	359
200	200	1873.964	1871.614	0.13	29.276	29.343	-0.23	10811	690

# Large number of draws (MSLE)

N	R	sLL-M	sLL-D	Gap [%]	T-M	T-D
50	20	-29.417	-29.908	1.67	22	6
50	50	-29.294	-31.173	6.41	279	26
50	100	-28.885	-29.42	1.85	1375	42
50	150	-29.973	-30.092	0.4	2852	70
50	200	-30.091	-30.101	0.03	10800	131
50	250	-30.741	-30.775	0.11	10800	156
50	300	-30.837	-30.843	0.02	10800	133
50	400	-30.632	-30.638	0.02	10800	130
50	600	-30.479	-30.51	0.1	10800	289
50	800		-32.035		10800	319
50	1000		-30.523		10800	349

# Ideas for future work

- Improving Benders:
  - Find a better way to linearize the product (?)
  - Find a convex-quadratic formulation (?)
- Investigate column generation
- Combined column generation + Benders approach



Thanks!

