GEOMETRIC DEEP LEARNING FOR MEDIUM-RANGE WEATHER PREDICTION

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Professor: Pierre Vandergheynst

Expert: Peter Düben







WHAT IS MEDIUM-RANGE WEATHER PREDICTION AND WHY DO IT?

What is it?

2 days - 2 weeks forecasting

Usefulness

Economic resource management

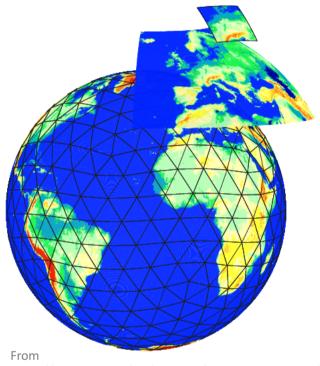
→ preparation for extreme weather events



From https://america.cgtn.com/2018/08/17/the-heat-extreme-weather

CHALLENGES

- Extended area of influence
- Dependent on quality of initial atmospheric state
- Influence of land and ocean



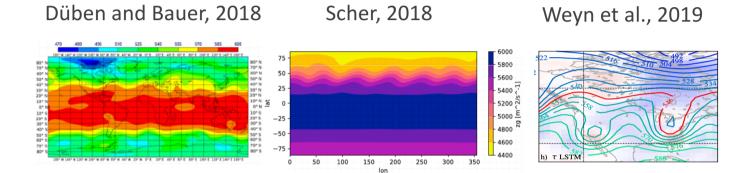
https://www.dwd.de/EN/research/weatherforecasting/ num_modelling/06_nwp_emergency_response_system /num_weather_prediction_emergency_system.html

WHY USE DATA-DRIVEN METHODS?

- Current operational NWP: successful but needs a lot of computing power
- Data-driven methods provide:
 - Flexible models that can automatically learn representations from the data
 - Empirically good performance when enough data
 - Computationally cheaper forecasts

PREVIOUS WORKS

Planar projections

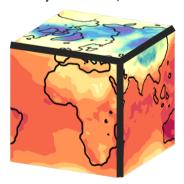


Spherical approximations



Adapted from Rasp, S., Dueben, P. D., Scher S., Weyn, J. A., Mouatadid, S., and Thuerey, N. (2020). WeatherBench: A benchmark dataset for data-driven weather forecasting. arXiv.

Weyn et al., 2020

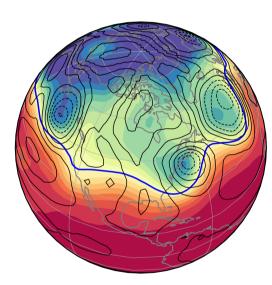


Adapted from Weyn, J . A., Durran, D. R , and Caruana, R. (2020). Improving data-driven global weather prediction using deep convolutional neural networks on a cubed sphere. JAMES.

OUR WORK

Objectives

- Use spherical domain with adapted spherical grid
- Implement computations on the sphere
- Include temporal dimension
- Informed feature selection
- Benchmark using a wide range of metrics
- Spatial evaluation using new metrics



Adapted from J. A. Weyn, D. R. Durran, and R. Caruana, 2020. Improving data-driven global weather prediction using deep convolutional neural networks on a cubed sphere. JAMES.

02_WeatherBench

WEATHERBENCH: DATASET (Rasp et al., 2020)

The	ERA5	data
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WeatherBench

• Time span: 1979 to present 1979 to 2018

Temporal resolution:
1 hour
1 hour

• Spherical resolution (lat/lon grid): 0.25° 5.625°, 2.8125° and 1.40525°

• Vertical resolution: 37 pressure levels 10 pressure levels

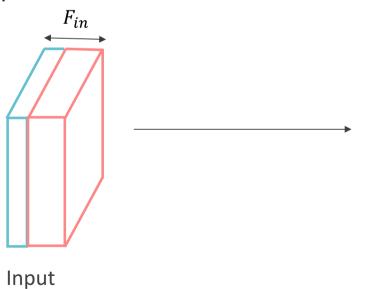
• Atmospheric fields: 344 19

02_WeatherBench

WEATHERBENCH: FEATURES

Static

- Constants
 - Soil type
 - Orography
 - Latitudes / longitudes
 - Land-sea mask
- Radiation



Dynamic

- Temperature
- Geopotential height
- Wind
- Humidity
- Vorticity



02_WeatherBench

WEATHERBENCH: BENCHMARKING

Features: **Z500** and **T850**

Metrics (p_n, o_n) are prediction and observation respectively):

$$RMSE = \sqrt{\frac{1}{N}} \sum_{n} (p_n - o_n)^2$$

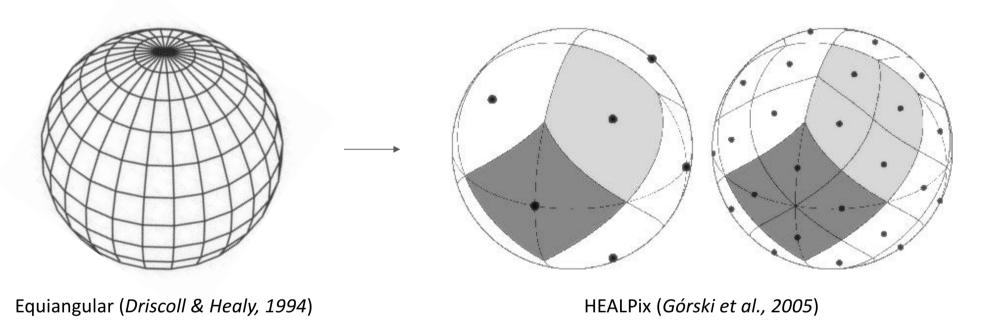
$$MAE = \frac{1}{N} \sum_{n} |p_n - o_n|$$

$$ACC = \frac{\sum_{n} p'_{n} o'_{n}}{\sum_{n} p''_{n}^{2} \sum_{n} o''_{n}^{2}}, \text{ with } x'_{n} = x_{n} - \frac{1}{N} \sum_{n} x_{n}$$

METHODOLOGY - OUTLINE

- Sphere discretization
- Spherical convolutions
- Temporal dimension
- Network architecture
- Training

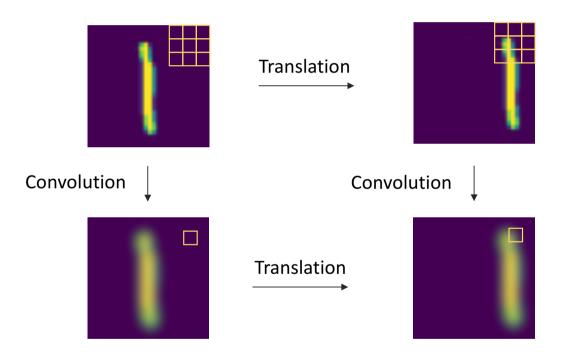
SPHERE DISCRETIZATION



- Avoids oversampling at the poles
- Not region dependent

EQUIVARIANT CONVOLUTIONS

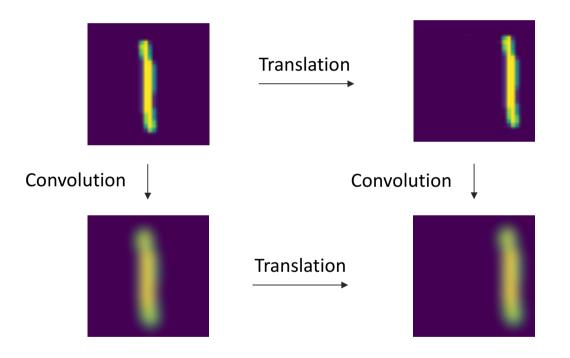
On images



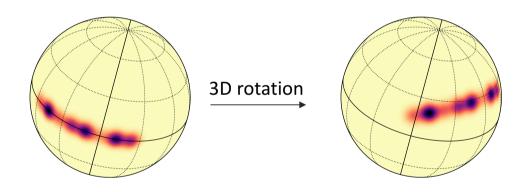
- → 2D shift makes convolutions translation equivariant:
- Fewer parameters
- Not dependent on location
 - More robustness
 - No data augmentation

EQUIVARIANT CONVOLUTIONS

On images



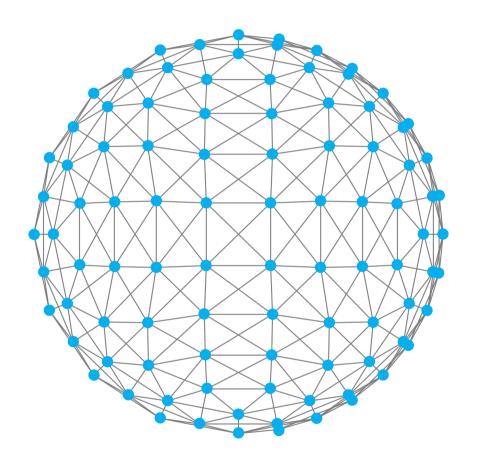
On the sphere



From Defferrard, M (2020). DeepSphere: a graph-based spherical CNN. ICLR'20 spotlight. https://zenodo.org/record/3777976#.XvtpzS2Q3ys

⇒ Goal: replace 2D translation convolutions by SO(3) rotation convolutions

GRAPH SPHERICAL CONVOLUTIONS



Discrete domain: graph $G = (V, \mathcal{E}, A)$

- \mathcal{V} : vertices
- ε: edges (weighted according to distance)
- *A*: adjacency (edge weights)
- *D*: degree matrix (neighbors)

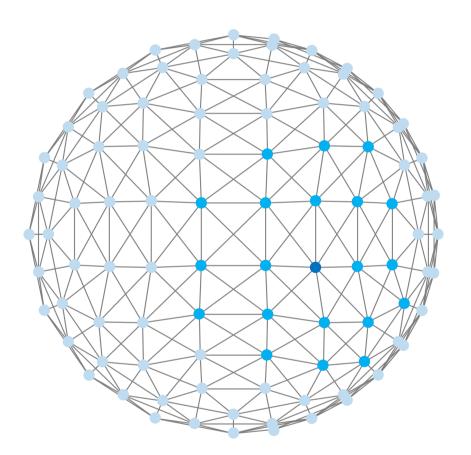
Spherical convolutions (Defferrard et al., 2016)

- Laplacian: L = D A
- L is diagonalized by the Fourier basis
- Convolutions are multiplications in Fourier space
- For a signal x and a kernel g_{α} :

$$y = g_{\alpha}(L) x$$

 $\rightarrow \mathcal{O}(n^2)$ operations in general

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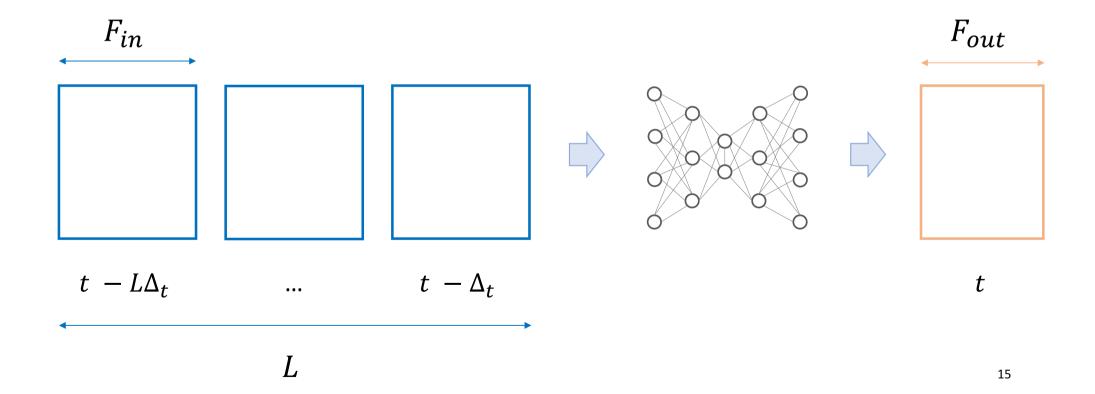
Rotation equivariance – Cost compromise: L is sparse \rightarrow less neighbors

 $\rightarrow \mathcal{O}(n)$ operations

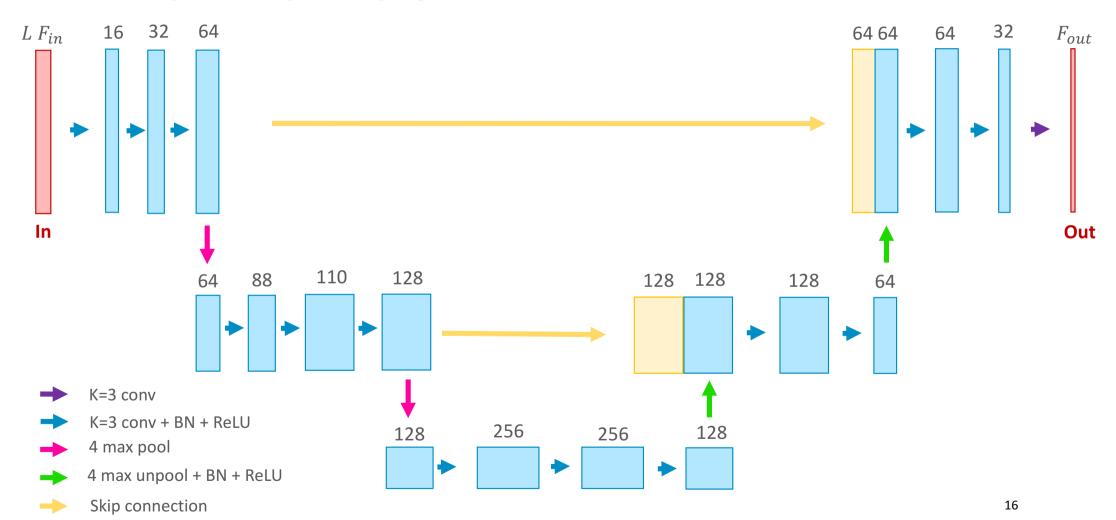
TEMPORAL DIMENSION

L: sequence length

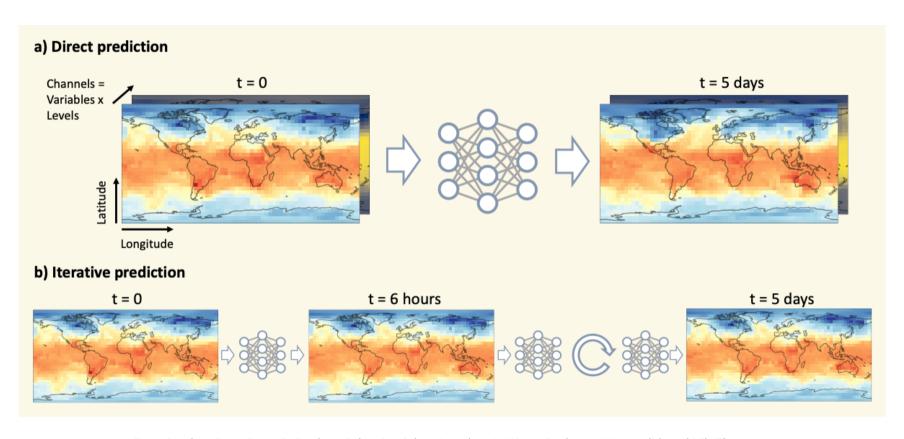
 Δ_t : temporal discretization and forecast lead time



NETWORK ARCHITECTURE



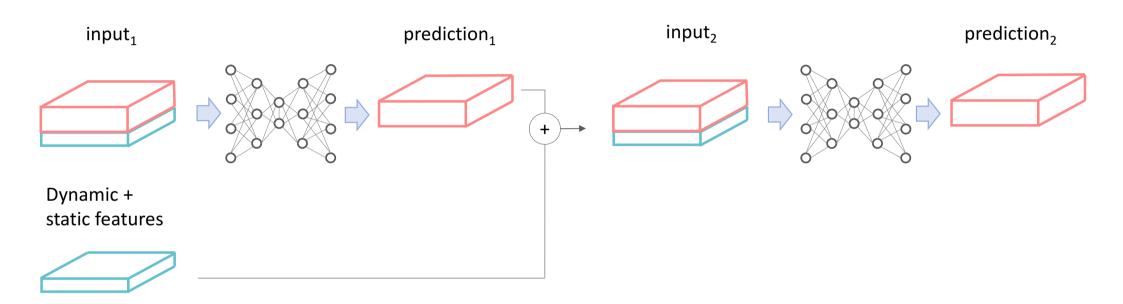
ITERATIVE PREDICTIONS



From Stephan Rasp, Peter D. Dueben, Sebastian Scher, Jonathan A. Weyn, Soukayna Mouatadid, and Nils Thuerey, 2020. WeatherBench: A benchmark dataset for data-driven weather forecasting. arXiv.

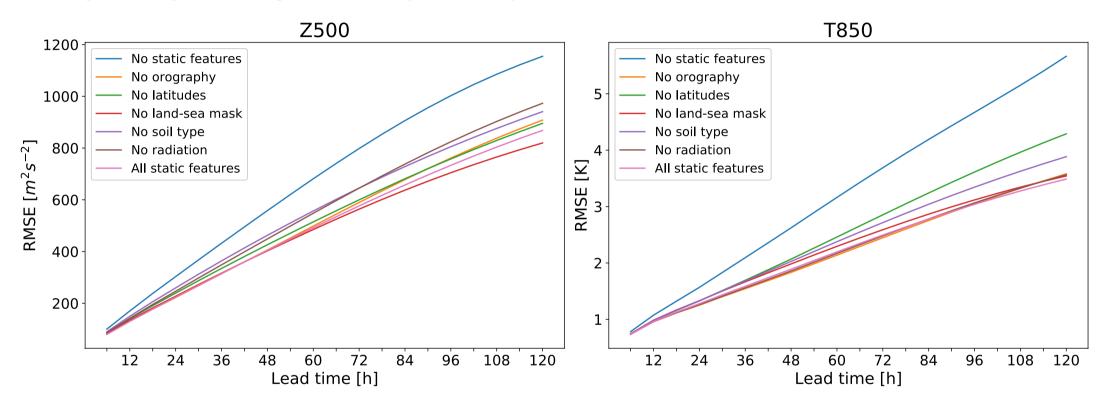
ITERATIVE TRAINING

Static features



 $Loss = \alpha_1 MSE(pred_1, obs_1) + \alpha_2 MSE(pred_2, obs_2)$

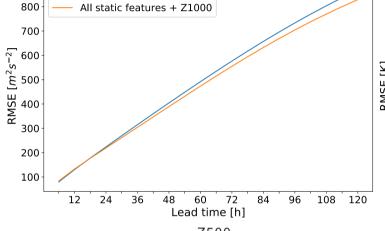
STATIC FEATURE IMPORTANCE



- → Static features help with first direct prediction and decrease the error slope for subsequent iterations
- ⇒ Z500 and T850 benefit from different static features

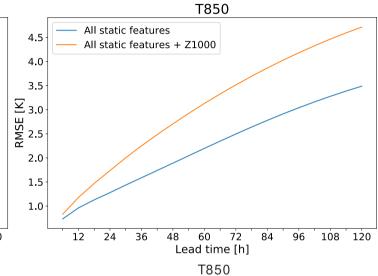
DYNAMIC FEATURES

Z1000

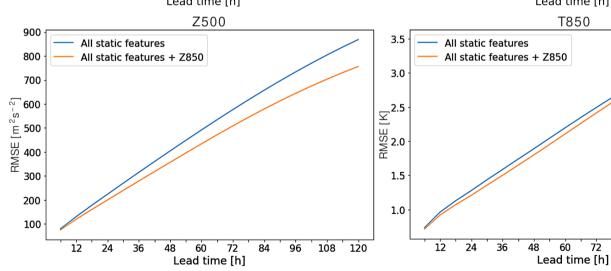


Z500

All static features



Z850



20

84

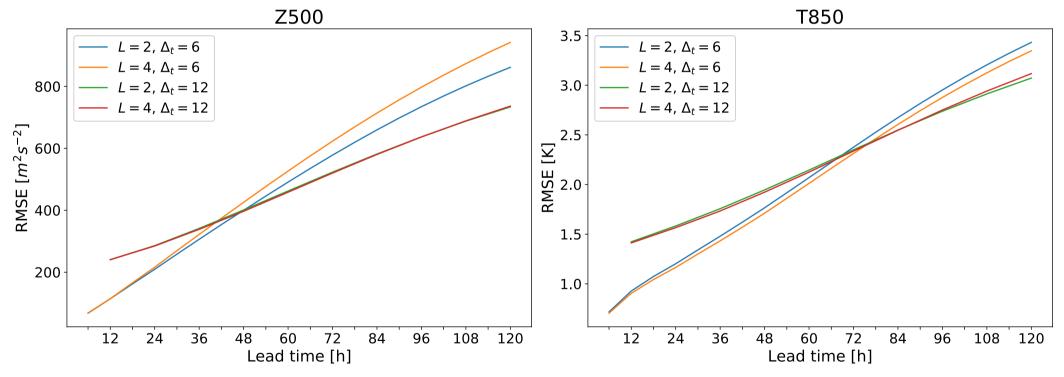
96

108 120

SEQUENCE LENGTH AND TIME RESOLUTION

L : sequence length

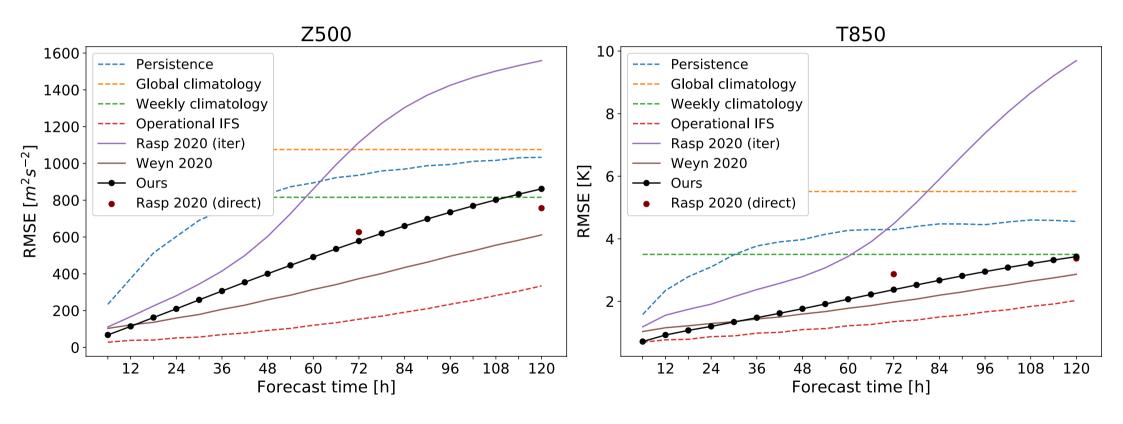
 Δ_t : temporal resolution



- ightharpoonup No clear benefit from using a large L
- \implies Short term predictions require small Δ_t , error stabilizes in the long term with larger Δ_t .

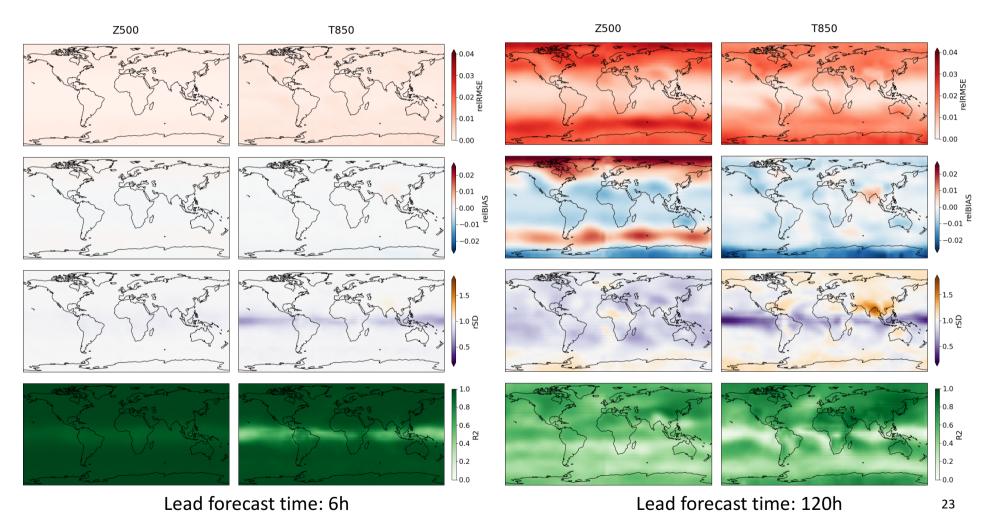
BENCHMARK - RMSE

Best model: all static features, L = 2, $\Delta_t = 6$ h



04_ Results

SKILL SPATIAL DISTRIBUTION



05_ Future research lines

FUTURE RESEARCH LINES

- → Improve predictive skill
 - Better usage of the space
 - O Atmosphere depth: systematic integration of several pressure levels
 - Multi-scale
 - Temporal dimension
 - Vertical dimension
 - More sofisticated architecture
 - ResNets
- → Add a **notion of confidence** to the predictions

THANKS FOR THE INVOLVEMENT

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Expert: Peter Düben

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07_ Supplementals

DATASET DIVISION

Training: 1979 - 2012

Validation: 2013 - 2016

O Testing: 2017 - 2018