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Effects of humid air on aerodynamic journal bearings

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Abstract

The development of aerodynamic bearings applications where ambient conditions cannot be controlled (e.g., for automotive fuel cell compressor) raises the question of the effects of condensation in the humid air on performance. A modified Reynolds equation is obtained in relation to humid air thermodynamic equations, accounting for the variation of compressibility and viscosity in the gas mixture. The load capacity and stability of plain and herringbone-grooved journal bearings is computed on a wide range of operating and ambient conditions. In general, performance metrics show an independence on humid-air effects at moderated temperature, although the stability of the grooved journal bearing exhibits strong variations in particular conditions. In consequence, a safety margin of 25% is suggested for the critical mass.

Keywords: Aerodynamic Lubrication, Gas Bearings, Humid air, Simulation

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a	Groove length (m)
b	Ridge length (m)
C	Damping (N s m^{-1})
c_s	NGT coefficient (-)
c	Viscosity coefficient (-)
\tilde{c}	Molar concentration (-)
D	Bearing diameter (m)
e	Eccentricity (m)
f	NGT coefficient (-)
g	NGT coefficient (-)
H	Groove depth ratio h_g/h_0 at $\epsilon = 0$ (-)
h	Clearance (m)
h_0	Nominal clearance (m)
h_g	Groove clearance (m)
h_r	Ridge clearance (m)
K	Stiffness (N m^{-1})
L	Bearing length (m)
M_c	Critical mass (kg)
M_r	Critical mass ratio (-)
\tilde{m}	Molar mass (kg mol^{-1})
P	Pressure (Pa)
R	Radius (m)
r	Specific gas constant ($\text{J kg}^{-1}\text{K}^{-1}$)
T	Temperature (K)
t	Time (s)
U	Bearing tangential velocity (m/s)
W	Load capacity (N)
W_r	Load capacity ratio (-)
w	Humidity ratio (-)
X	Coordinate in the direction of the displacement (m)
x	Coordinate in the inertial frame (m)
y	Coordinate in the inertial frame (m)
z	Axial coordinate (m)
Greek symbols	
α	Groove aspect ratio (-)
β	Bulk modulus (Pa)
$\hat{\beta}$	Groove angle (rad)

ϵ	Eccentricity ratio (-)
θ	Circumferential coordinate (rad)
Λ	Compressibility number (-)
μ	Dynamic viscosity (Pa s)
ρ	Density (kg m^{-3})
σ	Squeeze number (-)
Φ	Viscosity coefficient (-)
ϕ	Relative humidity (-)
Ω	Bearing angular velocity (rad s^{-1})
ω	Excitation angular velocity (rad s^{-1})
	Superscripts
—	Normalized
*	Saturated
	Subscripts
<i>a</i>	Ambient condition
<i>air</i>	Air
<i>c</i>	Critical
<i>cond</i>	Condensable
<i>g</i>	Groove
<i>non – cond</i>	Non-condensable
<i>r</i>	Ridge, ratio
<i>T</i>	Isothermal
<i>vap</i>	Water vapor (gas phase)
<i>w</i>	Water liquid phase
<i>x</i>	<i>x</i> -axis
<i>y</i>	<i>y</i> -axis
<i>z</i>	<i>z</i> -axis
0	Static, unperturbed
1	Perturbed
	Acronyms
<i>HA</i>	Humid air
<i>HGJB</i>	Herringbone grooved journal bearing
<i>PJB</i>	Plain journal bearing
<i>NGT</i>	Narrow groove theory

1. Introduction

The use of aerodynamic bearings expands progressively to domains where the ambient conditions cannot be satisfactorily conditioned, either due to economical or to technical reasons. In particular, gas bearing-supported pressurizers of Proton-Exchange Membrane (PEM) fuel cells [1, 2, 3] for automotive applications are subject to a large range of ambient temperatures and relative humidities. Thus, the knowledge of the effect of ambient humidity on the performance of an aerodynamic bearing is necessary to ensure the viability of a given design.

1.1. Nature of the issue

Water vapor contained in humid air (HA) is subject to condensation if the saturation pressure is reached within the fluid film of gas-lubricated bearings. The resulting effects might influence the bearing behavior. Several works [4, 5] theoretically and experimentally investigated the influence of HA on the static pressure field of hard disk drive heads, showing that vapor condensation can occur, which reduces the pressure in the bearing, leading to a reduction of the head's flying height. For the same application, Hua et al. [6] performed transient simulations investigating the settling time of the flying head and showed that HA effects affect the final state of the bearing. In the previously mentioned works, the simulation method to model HA effects consists in applying a correction on the pressure field obtained from the ideal-gas form of the Reynolds equation. Kirpekar et al. [7] introduced a modification of the Reynolds equation to obtain a more rigorous approach. Ma et Liu [8, 9] investigated the dynamic phase equilibrium in the mixture to conclude to the quasi-immediacy of the thermodynamic equilibrium in the gas film. Aoki et al. [10] experimentally highlighted the influence of the water film thickness on the behavior of the bearing in ultra-thin film lubrication. More recently, the same phenomenon was further studied by Choi et al. [11]. Tani et al. [12] measured the clearance loss in a slider bearing lubricated with water-nitrogen and ethanol-nitrogen mixtures and further confirmed the clearance reduction in humid conditions. Ma et al. [13] theoretically studied the influence of the adsorbed water film on the heat transfer in a slider bearing, highlighting an increase of the heat transfer coefficient. Matthes et al. [14, 15] experimentally investigated the influence of relative humidity on the touch-down power of an aerodynamic slider bearing. They reported a reduction of touch-down energy loss with increasing humidity ratios. The

37 literature on the HA-lubricated bearings is still limited to slider geometries
38 with ultra-thin film lubrication applied to data storage, with no application
39 to journal bearings, despite the growing interest for aerodynamic bearings
40 employed in humid environments.

41 1.2. Goals and objectives

42 The present work investigates the HA effects on the performance of plain
43 journal bearings (PJB) and of herringbone-grooved journal bearings (HGJB).
44 The objectives are to: (1) develop an expression of the Reynolds equation for
45 HA-lubricated journal bearings, (2) evaluate the deviation of HA-lubricated
46 journal bearing from ideal-gas lubrication in terms of load capacity and whirl
47 stability in a large range of ambient temperatures, relative humidities and
48 operating conditions and (3) devise design guidelines for robust design con-
49 sidering HA effects.

50 1.3. Scope of the Paper

51 The Reynolds equation for compressible fluids is adapted to express the
52 local density, exhibiting the bulk modulus whose expression depends on
53 whether the saturation conditions are locally met or not. The expression
54 of the bulk modulus is derived from the classical humid air theory and ac-
55 counts for the drying effect of condensing vapor. The perturbation method
56 is applied on the Reynolds equation and a finite difference scheme is used to
57 solve the equations. Static and dynamic bearing properties are obtained by
58 integration of the pressure fields. The concept of critical mass is used as a
59 stability metric regarding the whirl instability. The deviation of HA lubrica-
60 tion from the ideal-gas case is investigated for both PJB and HGJB in terms
61 of load capacity and critical mass. The selected HGJB geometry maximizes
62 the stability at moderated compressibility number ($\Lambda = 1$). The consid-
63 ered operating conditions vary in temperature from 275 to 370 K, in relative
64 humidity from 0 to 1 with different eccentricity ratios and compressibility
65 numbers up to 30. Based on the generated results, a set of design guidelines
66 is suggested for the design of HA-lubricated journal bearings based on the
67 ideal-gas Reynolds equation.

68 2. Theory

69 HA lubrication implies a condensable gas mixture of water (condensable)
70 and air, considered as incondensable. The main working hypotheses in the

71 following development are as follows: (1) the gas film is isothermal, (2) the
72 thermodynamic equilibrium is instantaneous as suggested by Ma et Liu [8],
73 (3) only the gas phase is considered. The hypothesis (1) is justified by the
74 large contact area of the gas film with the rotor and bushings. These areas
75 are heterogeneous nucleation sites justifying (2) and the very small volume of
76 condensed water regarding the gas phase justifies (3). The Reynolds equation
77 adds the hypothesis of thin film, laminar flow, Newtonian fluid and negligible
78 inertial effects. It is recalled as follows:

$$\partial_X \left(\frac{\rho h^3}{12\mu} \partial_X P \right) + \partial_z \left(\frac{\rho h^3}{12\mu} \partial_z P \right) = \frac{U}{2} \partial_X(\rho h) + \partial_t(\rho h) \quad (1)$$

79 Since the practical problem targeted in the present work involves an at-
80 mospheric pressure, both gases (air and water vapor) are considered as ideal.
81 However, for an isothermal gas, the saturation partial pressure of water can
82 be reached within the film as mixture pressure increases. At this point (dew
83 point), water vapor starts condensing and limits its contribution to the mix-
84 ture pressure build-up on which the bearing relies to serve its purpose. At
85 this point, the behavior of the mixture deviates from an ideal gas, namely:

$$P = \rho r_a T \quad (2)$$

86 where r_a is the specific gas constant of the ambient HA. **In order to account**
87 **for the condensation effects, Equation 2 is not used to substitute the density**
88 **with the pressure in Reynolds equation.** Instead, the following changes of
89 variable are applied:

$$\frac{\partial P}{\partial X} = \left(\frac{\partial P}{\partial \rho} \right)_T \cdot \frac{\partial \rho}{\partial X}, \quad \frac{\partial P}{\partial z} = \left(\frac{\partial P}{\partial \rho} \right)_T \cdot \frac{\partial \rho}{\partial z} \quad (3)$$

90 Where $(\partial_\rho P)_T$ is associated to the bulk modulus β of the lubricant gas:

$$\rho \left(\frac{\partial P}{\partial \rho} \right)_T = \beta \quad (4)$$

91 The following normalization is performed on Equation 1 to express it in
92 cylindrical coordinates (Equation 6):

$$\begin{aligned} \bar{\rho} = \rho/\rho_a \quad \bar{\mu} = \mu/\mu_a \quad \bar{\beta} = \beta/P_a \quad \theta = X/R \\ \bar{z} = z/R \quad \bar{h} = h/h_0 \quad \bar{t} = t\omega \end{aligned} \quad (5)$$

$$\partial_\theta \left(\frac{\bar{\beta} \bar{h}^3}{\bar{\mu}} \partial_\theta \bar{\rho} \right) + \partial_z \left(\frac{\bar{\beta} \bar{h}^3}{\bar{\mu}} \partial_z \bar{\rho} \right) = \Lambda \partial_\theta (\bar{\rho} \bar{h}) + \sigma \partial_{\bar{t}} (\bar{\rho} \bar{h}) \quad (6)$$

93 Where Λ and σ are the compressibility and squeeze number respectively,
94 defined as follows for journal bearings (Figure A.1):

$$\Lambda = \frac{6\mu_a \Omega R^2}{P_a h_0^2} \quad (7)$$

$$\sigma = 2\Lambda \frac{\omega}{\Omega} \quad (8)$$

In order to obtain the dynamic coefficients and to compute the critical mass, the clearance is perturbed by an infinitesimal harmonic motion ϵ_{1x} and ϵ_{1y} ($\epsilon_{x/y} = e_{x/y}/h_0$) in the x and y directions respectively [16]:

$$\bar{h} = \bar{h}_0 - \epsilon_{1x} \cos \theta e^{i\bar{t}} - \epsilon_{1y} \sin \theta e^{i\bar{t}} \quad (9)$$

$$= 1 - \epsilon_{0x} \cos \theta - \epsilon_{0y} \sin \theta - \epsilon_{1x} \cos \theta e^{i\bar{t}} - \epsilon_{1y} \sin \theta e^{i\bar{t}} \quad (10)$$

95 where ϵ_{0x} and ϵ_{0y} are the static equilibrium eccentricity ratios. The other
96 perturbed terms involved in Equation 7 are:

$$\bar{\rho} = \bar{\rho}_0 + \epsilon_{1x} \bar{\rho}_{1x} e^{i\bar{t}} + \epsilon_{1y} \bar{\rho}_{1y} e^{i\bar{t}} \quad (11)$$

$$\bar{\beta} = \bar{\beta}_0 + \epsilon_{1x} \left(\frac{\partial \bar{\beta}}{\partial \bar{\rho}} \right)_0 \bar{\rho}_{1x} e^{i\bar{t}} + \epsilon_{1y} \left(\frac{\partial \bar{\beta}}{\partial \bar{\rho}} \right)_0 \bar{\rho}_{1y} e^{i\bar{t}} \quad (12)$$

$$\frac{1}{\bar{\mu}} = \frac{1}{\bar{\mu}_0} + \epsilon_{1x} \left(\frac{-1}{\bar{\mu}^2} \frac{\partial \bar{\mu}}{\partial \bar{\rho}} \right)_0 \bar{\rho}_{1x} e^{i\bar{t}} + \epsilon_{1y} \left(\frac{-1}{\bar{\mu}^2} \frac{\partial \bar{\mu}}{\partial \bar{\rho}} \right)_0 \bar{\rho}_{1y} e^{i\bar{t}} \quad (13)$$

97 Terms of order 0 and 1 with respect to ϵ_{1x} and ϵ_{1y} are retained and
98 grouped in Equations 14 and 15 respectively. The same procedure is reiter-
99 ated in the y direction without being repeated here.

$$\partial_\theta \left[\frac{\bar{\beta}_0 \bar{h}_0^3}{\bar{\mu}_0} \partial_\theta \bar{\rho}_0 \right] + \partial_z \left[\frac{\bar{\beta}_0 \bar{h}_0^3}{\bar{\mu}_0} \partial_z \bar{\rho}_0 \right] - \Lambda \partial_\theta (\bar{\rho}_0 \bar{h}_0) = 0 \quad (14)$$

$$\begin{aligned}
& \partial_\theta \left[\left(\frac{\partial \bar{\beta}}{\partial \bar{\rho}} \right)_0 \bar{\rho}_{1x} \frac{\bar{h}_0^3}{\bar{\mu}_0} \partial_\theta \bar{\rho}_0 + \bar{\beta}_0 \left(\frac{-1}{\bar{\mu}^2} \frac{\partial \bar{\mu}}{\partial \bar{\rho}} \right)_0 \bar{\rho}_{1x} \bar{h}_0^3 \partial_\theta \bar{\rho}_0 + \right. \\
& \qquad \qquad \qquad \left. \frac{\bar{\beta} 3 \bar{h}_0^2}{\bar{\mu}_0} \cos \theta \partial_\theta \bar{\rho}_0 + \frac{\bar{\beta}_0 \bar{h}_0^3}{\bar{\mu}_0} \partial_\theta \bar{\rho}_{1x} \right] \\
& + \partial_z \left[\left(\frac{\partial \bar{\beta}}{\partial \bar{\rho}} \right)_0 \bar{\rho}_{1x} \frac{\bar{h}_0^3}{\bar{\mu}_0} \partial_\theta \bar{\rho}_0 + \bar{\beta}_0 \left(\frac{-1}{\bar{\mu}^2} \frac{\partial \bar{\mu}}{\partial \bar{\rho}} \right)_0 \bar{\rho}_{1x} \bar{h}_0^3 \partial_\theta \bar{\rho}_0 + \right. \\
& \qquad \qquad \qquad \left. \frac{\bar{\beta} 3 \bar{h}_0^2}{\bar{\mu}_0} \cos \theta \partial_\theta \bar{\rho}_0 + \frac{\bar{\beta}_0 \bar{h}_0^3}{\bar{\mu}_0} \partial_\theta \bar{\rho}_{1x} \right] \\
& - \Lambda \partial_\theta (\bar{\rho}_0 \cos \theta + \bar{\rho}_{1x} \bar{h}_0) - i \sigma (\bar{\rho}_0 \cos \theta + \bar{\rho}_{1x} \bar{h}_0) = 0
\end{aligned} \tag{15}$$

100 A central finite difference scheme is employed to discretize the equations with
101 the boundary conditions of periodicity for $\theta = 0$ and $\theta = 2\pi$ and ambient
102 density at $\bar{z} = \pm L/D$. The procedure consists in solving successively both
103 unperturbed and perturbed equations to obtain the corresponding pressure
104 fields, integrating them over the bearing domain to get the load capacity and
105 complex impedances leading to the computation of the critical mass [17].

106 The same method can be applied to the HGJB using the Narrow Groove
107 Theory (NGT) to obtain a modified Reynolds equation [18]. This procedure
108 predicts the overall pressure generated by an infinite number of groove-ridge
109 pairs over the bearing domain, smoothing the local pressure variation over a
110 ridge-groove pair. Only the resulting differential equation is displayed here:

$$\begin{aligned}
& \partial_\theta [\bar{\beta} (f_1 \partial_\theta \bar{\rho} + f_2 \partial_z \bar{\rho})] + \partial_z [\bar{\beta} (f_2 \partial_\theta \bar{\rho} + f_3 \partial_z \bar{\rho})] \\
& \qquad \qquad \qquad + c_s \left(\sin \hat{\beta} \partial_\theta (f_4 \bar{\rho}) - \cos \hat{\beta} \partial_z (f_4 \bar{\rho}) \right) \\
& \qquad \qquad \qquad - \Lambda \partial_\theta (f_5 \bar{\rho}) - \sigma \partial_t (f_5 \bar{\rho}) = 0
\end{aligned} \tag{16}$$

111 where the geometry is presented in Figure A.2 and functions f_i are sum-
112 marized in the Appendix. A first-order perturbation is applied to this equa-
113 tion following Equations 9 to 13 and zeroth- and first-order equations are
114 segregated to be solved successively.

115 The problem of HA lubrication consists in the expression of $(\partial_{\bar{\rho}} \bar{P})_T$. As
116 long as the saturation partial pressure of water vapor is not locally reached,
117 the mixture is assumed to be an ideal gas. Thus, the term $(\partial_{\bar{\rho}} \bar{P})_T$, encapsu-
118 lated in the bulk modulus, is equal to unity:

$$(\partial_{\bar{\rho}} \bar{P})_T = \frac{\rho_a}{P_a} (\partial_{\rho} P)_T = \frac{\rho_a r_a T}{P_a} = 1 \tag{17}$$

119 Only when the saturation pressure is met, condensing water will stop
 120 building up pressure, leading to $(\partial_\rho \bar{P})_T < 1$, thus, departing from the ideal-
 121 gas behavior.

122 The ideal-gas equation for the gas mixture is:

$$P = \rho r T \quad (18)$$

123 The value of $(\partial_\rho P)_T$ is simply:

$$(\partial_\rho P)_T = r T + \rho T \partial_\rho r \quad (19)$$

124 where r is the mixture specific gas constant

$$r = \frac{r_{air} + w r_{vap}}{1 + w} \quad (20)$$

125 and w is the humidity ratio defined as the ratio of mass water vapor per unit
 126 mass of dry air:

$$w = \frac{M_{vap}}{M_{air}} \quad (21)$$

127 The value of w of the gas phase is defined locally depending on whether the
 128 saturation conditions are met or not:

$$w = \min(w_a, w^*(T_a, P)) \quad (22)$$

129 w^* is the saturation humidity ratio, which is a function of the ambient tem-
 130 perature and local pressure as follows:

$$w^* = \frac{\tilde{m}_{vap} P_{vap}^*(T_a)}{\tilde{m}_{air} P - P_{vap}^*(T_a)} \quad (23)$$

131 where P_{vap}^* is the saturation pressure of water that depends on the tempera-
 132 ture only, computed using a fluid database [19]. Since Equation 6 deals with
 133 density rather than pressure, it is convenient to have an expression of w^* as
 134 a function of density. For that purpose Equation 18 is inserted in Equation
 135 23 and w^* is isolated:

$$w^* = \frac{-c_2 + \sqrt{c_2^2 - 4c_1c_3}}{2c_1} \quad (24)$$

136 with

$$c_1 = (\rho r_{vap} T - P_{vap}^*) \quad (25)$$

$$c_2 = r_{air} \rho T - P_{vap}^* (1 + \tilde{m}_{vap}/\tilde{m}_{air}) \quad (26)$$

$$c_3 = P_{vap}^* \tilde{m}_{vap}/\tilde{m}_{air} \quad (27)$$

137 If saturation is reached and the water content in the gas phase decreases,
138 the mixture viscosity evolves accordingly. It is expressed from [20] as follows:

$$\mu = \frac{(1 - \tilde{c}_{vap}) - \mu_{air}}{1 - \tilde{c}_{vap} + \tilde{c}_{vap} \Phi_{av}} + \frac{\tilde{c}_{vap} \mu_{vap}}{\tilde{c}_{vap} + (1 - \tilde{c}_{vap}) \Phi_{va}} \quad (28)$$

139 where

$$\Phi_{av} = \frac{\sqrt{2}}{4} \left(1 + \frac{\tilde{m}_{air}}{\tilde{m}_{vap}}\right)^{-0.5} \left(1 + \left(\frac{\mu_{air}}{\mu_{vap}}\right)^{0.5} \left(\frac{\tilde{m}_{vap}}{\tilde{m}_{air}}\right)^{0.25}\right)^2 \quad (29)$$

$$\Phi_{va} = \frac{\sqrt{2}}{4} \left(1 + \frac{\tilde{m}_{vap}}{\tilde{m}_{air}}\right)^{-0.5} \left(1 + \left(\frac{\mu_{vap}}{\mu_{air}}\right)^{0.5} \left(\frac{\tilde{m}_{air}}{\tilde{m}_{vap}}\right)^{0.25}\right)^2 \quad (30)$$

140 \tilde{c}_{vap} is the molar concentration of water vapor in the gas phase, related to
141 the humidity ratio as follows:

$$\tilde{c}_{vap} = \frac{1}{1 + \frac{\tilde{m}_{vap}}{w\tilde{m}_{air}}} \quad (31)$$

142 The deviation from the ideal-gas law and the change of viscosity provide the
143 necessary tools for the modeling of HA-lubricated journal bearings.

144 3. Numerical computations and results

145 Journal bearings lubricated with condensable humid air are compared to
146 equivalent non-condensable (ideal gas) cases using two performance metrics,
147 namely the load capacity ratio W_r and the critical mass ratio M_r , defined as
148 follows:

$$W_r = \frac{W_{cond}}{W_{non-cond}} \quad (32)$$

$$M_r = \frac{M_{c,cond}}{M_{c,non-cond}} \quad (33)$$

$$(34)$$

149 Both the investigated geometries have a L/D ratio of 1. Moreover, the
 150 HGJB geometry is based on the design obtained in [21] maximizing the min-
 151 imum critical mass for the range $\Lambda \in [0, 1]$ (Equation 39) when the grooved
 152 member rotates:

$$\alpha = 0.6 \quad (35)$$

$$\hat{\beta} = 145.8^\circ \quad (36)$$

$$H = 2.25 \quad (37)$$

153 Unless specified differently, the presented simulations are performed at an
 154 ambient temperature of 308 K, which is assumed to represent a pessimistic
 155 temperature for humid environments. A first simulation of the PJB running
 156 at $\Lambda = 30$, and $\epsilon_x = 0.5$ allows to understand the consequences of humid air
 157 lubrication. Figure A.3 presents the pressure relative to the ambient at the
 158 mid-span of the considered bearing and the relative deviation of the pressure
 159 compared to the non-condensable case with an ambient relative humidity of
 160 0.8. The relative humidity ϕ is defined as follows:

$$\phi = \frac{P_{vap}}{P^*} \quad (38)$$

161 The pressure is not only affected in the zone where it exceeds the dew
 162 point, exhibiting a reduction larger than 0.8% , but also outside this zone,
 163 although the deviation is even more modest. The pressure field is globally
 164 affected because of the elliptical characteristic of the Reynolds equation. The
 165 pressure value at one particular point affects the entire fluid film domain.
 166 This kind of observation is impossible with HA effects considered *a posteriori*,
 167 on top of the pressure field computed with non-condensable gas lubrication,
 168 as usually seen in the literature [4, 5, 6].

169 Figure A.4 presents the isolines of the load capacity ratio W_r for the
 170 PJB at $\epsilon_x = 0.5$ as a function of the ambient relative humidity ϕ_a and the
 171 compressibility number Λ . Load capacity drops when the saturation pressure
 172 is reached inside the bearing and the condensation onset is reached at lower
 173 values of ϕ_a as Λ increases, until it converges toward a limit value. This
 174 is due to the well-known limiting solution for PJB with $\Lambda \rightarrow \infty$, at which
 175 a limit pressure field is reached. With a maximum relative deviation of
 176 approximately 1.5% at this ambient temperature, the loss of load capacity

177 remains low at all values of compressibility number, even at high ambient
 178 relative humidity. Deviation of this order of magnitude can be considered as
 179 negligible from a practical point of view.

180 Figure A.5 depicts the evolution of M_r with ϕ_a and Λ . Once the saturation
 181 pressure is reached within the gas film, the condensation effects have a small
 182 yet negative influence on M_r . Such a modest evolution of the critical mass
 183 remains without consequences on the practical design and performance of a
 184 PJB.

185 Figures A.6 and A.7 present the same approach with the HGJB for W_r
 186 and M_r respectively, at $\epsilon_x = 0.05$. The load capacity is negatively affected by
 187 the condensation, with a maximum deviation of less than 1%. Regarding the
 188 stability in the saturated domain, M_r is above unity on the left side of the line
 189 $\Lambda \approx 9$ and below unity on its right side. The largest low- and high-deviation
 190 values are reached at the line itself, with a very abrupt change of trend.
 191 The underlying phenomenon is the point of very high stability observed for
 192 HGJB for particular values of Λ . Under the condition of saturated humid
 193 air lubrication, the position of this stability peak is shifted to slightly lower
 194 values of Λ (Figure A.8), explaining the abrupt variation of M_r in this zone.
 195 The divergence of the 25%-deviation lines along the ϕ_a axis translates a rise
 196 in the amplitude of this variation with the ambient humidity ratio. However,
 197 M_r gets close to 1 as soon as the operating conditions deviate from this
 198 particular zone.

199 From a design perspective, the minimum value of the critical mass be-
 200 tween the targeted value of compressibility number Λ^* and 0 bears a par-
 201 ticular importance, since it indicates the stability threshold of a bearing
 202 accelerating from rest to nominal speed. A new metric is defined to compare
 203 the minimum value of the critical mass in this range:

$$M_{r,min} = \frac{\min_{\Lambda \in [0, \Lambda^*]} M_{c,cond}}{\min_{\Lambda \in [0, \Lambda^*]} M_{c,non-cond}} \quad (39)$$

204 Figure A.9 depicts the evolution of M_r and $M_{r,min}$ with Λ^* for the saturated
 205 ambient condition ($\phi_a = 1$). The improvement of critical mass observed
 206 for the condensable lubrication on the left-hand side of the turn-over point
 207 at $\Lambda^* \approx 9$ is translated into a moderately improved value of the minimum
 208 critical mass ($\approx 3\%$). Past this point, $M_{r,min}$ coincides with the line of M_r ,
 209 resulting in a depreciation of the minimum critical mass reaching 25%, which
 210 is not negligible from a design perspective.

211 The knowledge of the HA-effects on the synchronous stiffness and damp-
 212 ing presents a practical interest to predict the imbalance response of a rotor.
 213 The total stiffness and damping ratio in the x direction are defined as follows:

$$K_{x,r} = \frac{(\sqrt{K_{xx}^2 + K_{yx}^2})_{cond}}{(\sqrt{K_{xx}^2 + K_{yx}^2})_{non-cond}} \quad (40)$$

214

$$C_{x,r} = \frac{(\sqrt{C_{xx}^2 + C_{yx}^2})_{cond}}{(\sqrt{C_{xx}^2 + C_{yx}^2})_{non-cond}} \quad (41)$$

215 Figure A.10 presents the synchronous value of these two parameters for
 216 the PJB and HGJB as a function of Λ . The stiffness ratio is slightly above 1
 217 for small values of Λ , however without practical significance. The PJB case
 218 exhibits a constantly decreasing trend at higher compressibility numbers,
 219 converging around a loss lower than 1.5%. The HGJB shows a modest loss
 220 of stiffness at intermediate values of Λ and an equally modest gain at low
 221 and high values of Λ . However, the deviation remains lower than $\pm 0.5\%$
 222 in all investigated cases, which can be regarded as negligible. Qualitatively,
 223 the damping ratio behaves similarly to the stiffness ratio for the PJB, with
 224 a rapid decrease and a nearly constant plateau at approximately -2.5% for
 225 high values of Λ . The damping ratio of the HGJB exhibits a different trend,
 226 as a local minimum at $\Lambda \approx 6$ is visible with a reduction of nearly 3%. At
 227 higher compressibility numbers, this parameter increases and exceeds unity
 228 with a gain lower than 0.5%. In a practical perspective, the synchronous
 229 dynamic coefficients of both bearings can be considered as independent of
 230 HA effects.

231 The effects of the eccentricity ratio on the considered bearings are pre-
 232 sented in Figure A.11, at $\Lambda = 10$ and $\phi_a = 0.9$. The evolution of W_r shows
 233 no clear trend for the HGJB and diminishes for the PJB as soon as the
 234 saturation point is reached, yet in an insignificant order of magnitude. The
 235 value of M_r for the HGJB increases slightly because of the further shift in the
 236 critical mass curve. The M_r of the PJB shows a local minimum at $\epsilon_x \approx 0.17$,
 237 however at levels without practical implications. Both metrics for HGJB are
 238 affected by humid-air effects already at a concentric position because of the
 239 inherent pressure build-up due to the grooved pattern, while saturation is
 240 reached only above $\epsilon_x \approx 0.1$ for the PJB.

241 Figure A.12 presents the evolution of the minimum value of $M_{r,min}$ for
 242 $\Lambda^* = 50$ with the eccentricity ratio, in saturated ambient conditions. This

243 metric shows a minimum at concentric position and relaxes as the eccentricity
 244 ratio increases.

245 The effects of the ambient temperature are presented in Figure A.13 for
 246 both PJB and HGJB at $\phi_a = 0.9$. The concentration of water in the gas
 247 mixture increases with temperature at equal value of relative humidity, thus
 248 enhancing the effects of humid-air lubrication at high ambient temperature.
 249 All metrics are affected in significant proportions at temperatures approach-
 250 ing 100 °C. The strong enhancement of M_r for the HGJB is due to the fact
 251 that the stability peak is shifted to lower values of Λ as the temperature
 252 increases with constant ϕ_a . For both bearings, the load capacity is reduced
 253 by 2% at a temperature of 330 K. On the same Figure, the minimum value of
 254 $M_{r,min}$ for $\Lambda^* = 50$ in saturated ambient conditions is shown in order to rep-
 255 resent the worst case scenario. The temperature has a significant influence,
 256 since this indicator approaches 0 near 100 °C. The humid air effects are still
 257 significant on this indicator at lower temperatures, since the 10%-reduction
 258 threshold is located at 290 K.

259 The influence of liquid water droplets formed in the bearing clearance
 260 due to condensation can be questioned, since the formation of a liquid phase
 261 in the lubrication film can threaten the viability of the bearing. However,
 262 because of its significant difference of density at near-normal conditions (three
 263 orders of magnitude), the liquid phase, which was neglected in the previous
 264 computations, might occupy an insignificant volume in the mixture. In order
 265 to analyze this, the void fraction, defined as the volume of gas phase over
 266 the total two-phase volume, is used:

$$\delta = \frac{v_{gas}}{v_{liquid} + v_{gas}} \quad (42)$$

267 Figure A.14 shows the "1-void fraction" of the mixture for different ambient
 268 temperature and $\phi_a = 1$ in the situation where all the water from the sat-
 269 urated solution condenses, which is an overestimation of reality. Under this
 270 assumption, the void fraction gets the following expression:

$$\delta = \frac{1}{1 + w_a \rho_{air} / \rho_w} \quad (43)$$

271 The minimum value barely reaches 99% for T just below 100 °C, which is
 272 suggested to be sufficiently large to discard any risk linked to the formation
 273 of a local liquid film in the bearing clearance.

274 4. Conclusions

275 A modified form of the Reynolds equation suited for humid-air lubrica-
276 tion was developed and applied to grooved and plain journal bearings on
277 a wide range of operating conditions (compressibility number, eccentricity
278 ratio, ambient temperature and relative humidity). Cases accounting for va-
279 por condensation in the lubrication film were compared to non-condensable
280 cases (ideal gas) in terms of load capacity and stability (critical mass). The
281 investigations lead to the following observations:

- 282 • Humid air (HA) lubrication affects the pressure distribution in a lubri-
283 cation gas film even at locations where the pressure does not exceed
284 the dew pressure
- 285 • Consequences of HA lubrication are in general more significant at high
286 compressibility numbers Λ , ambient humidity ratios and eccentricity
287 ratios. High levels of ambient temperature increase the sensitivity of
288 load capacity and stability to humid-air effects, as the mass concentra-
289 tion of water in air increases
- 290 • Herringbone-grooved journal bearings (HGJB) are more sensitive to
291 HA effects than plain journal bearings (PJB), notably because of their
292 inherent pressure build-up even at concentric position, whereas PJBs
293 require a higher eccentricity to develop HA effects.
- 294 • Vapor condensation negatively affects the load capacity of journal bear-
295 ings, however without practical significance at temperature levels met
296 in atmospheric conditions ($T_a < 310$ K). The critical mass of PJBs is
297 affected in negligible proportions, while HGJBs can experience a signifi-
298 cantly reduced critical mass at particular compressibility numbers, with
299 a reported reduction up to 25% in realistic atmospheric temperatures.
300 In consequence, an equivalent margin is suggested on the critical mass
301 to ensure a safe operation of HGJBs designed from the non-condensable
302 Reynolds equation.
- 303 • In realistic situations, the presence of liquid droplets in the bearing
304 clearance is unlikely to be a threat to the integrity of the system due
305 to the very small void fraction calculated in worst-case scenarii.

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385 **Appendix A. NGT**

386 The terms composing equation 16 are developed here.

$$\bar{h}_r = \frac{h_r}{h_0} = \frac{h_r}{h_r(\epsilon = 0)} \quad (\text{A.1})$$

$$\bar{h}_g = \frac{h_g}{h_0} \quad (\text{A.2})$$

$$H = \frac{h_g(\epsilon = 0)}{h_0} \quad (\text{A.3})$$

$$g_1 = \bar{h}_g^3 \bar{h}_r^3 \quad (\text{A.4})$$

$$g_2 = (\bar{h}_g^3 - \bar{h}_r^3)^2 \alpha (1 - \alpha) \quad (\text{A.5})$$

$$g_3 = (1 - \alpha) \bar{h}_g^3 + \alpha \bar{h}_r^3 \quad (\text{A.6})$$

$$c_s = - \frac{6\mu\Omega R^2}{p_a h_0^2} \alpha (1 - \alpha) (H - 1) \sin \hat{\beta} \quad (\text{A.7})$$

$$f_1 = \frac{g_1 + g_2 \sin^2 \hat{\beta}}{g_3} \quad (\text{A.8})$$

$$f_2 = \frac{g_2 \sin \hat{\beta} \cos \hat{\beta}}{g_3} \quad (\text{A.9})$$

$$f_3 = \frac{g_1 + g_2 \cos^2 \hat{\beta}}{g_3} \quad (\text{A.10})$$

$$f_4 = \frac{\bar{h}_g^3 - \bar{h}_r^3}{g_3} \quad (\text{A.11})$$

$$f_5 = \alpha \bar{h}_g + (1 - \alpha) \bar{h}_r \quad (\text{A.12})$$

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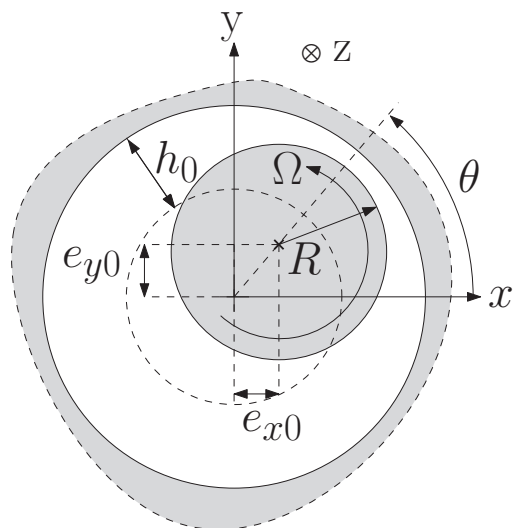


Figure A.1: Nomenclature of a journal bearing

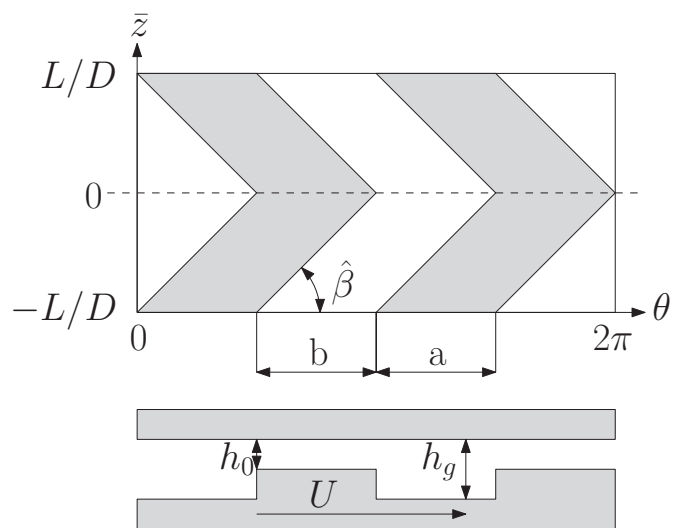


Figure A.2: Geometry and nomenclature of a HGJB

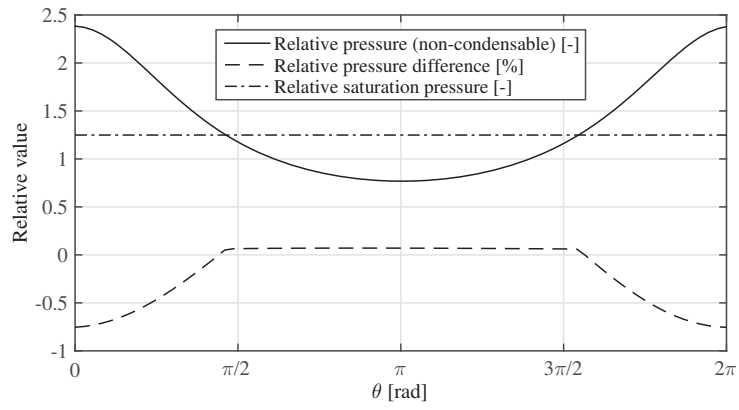


Figure A.3: Relative pressure and deviation along the circumference of a PJB at $\bar{z} = 0$, $\epsilon_x = 0.5$, $\phi_a = 0.8$ and $\Lambda = 30$)

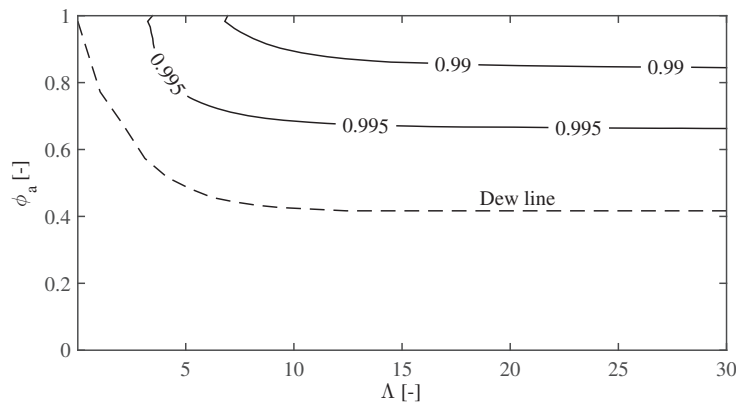


Figure A.4: Isolines of W_r for PJB at $\epsilon_x = 0.5$ ($T_a = 308$ K)

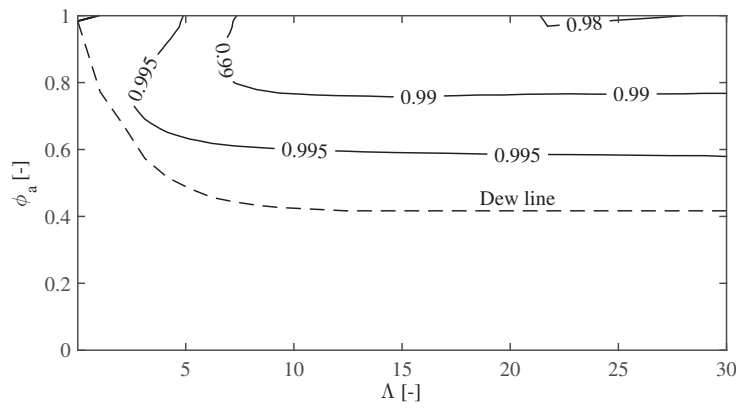


Figure A.5: Isolines of M_r for PJB at $\epsilon_x = 0.5$ ($T_a = 308$ K)

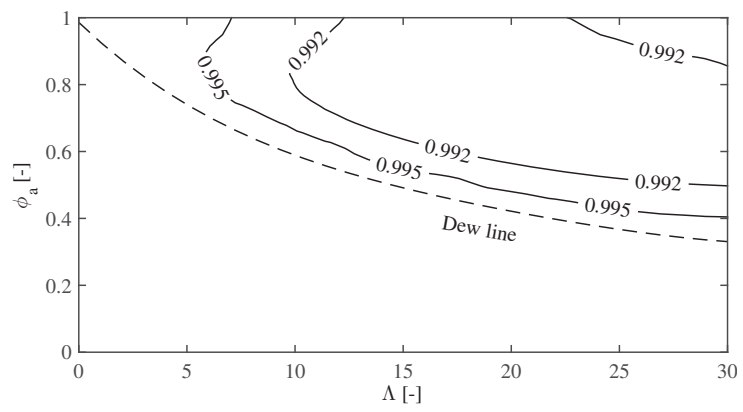


Figure A.6: Isolines of W_r for HGJB at $\epsilon_x = 0.05$ ($T_a = 308$ K)

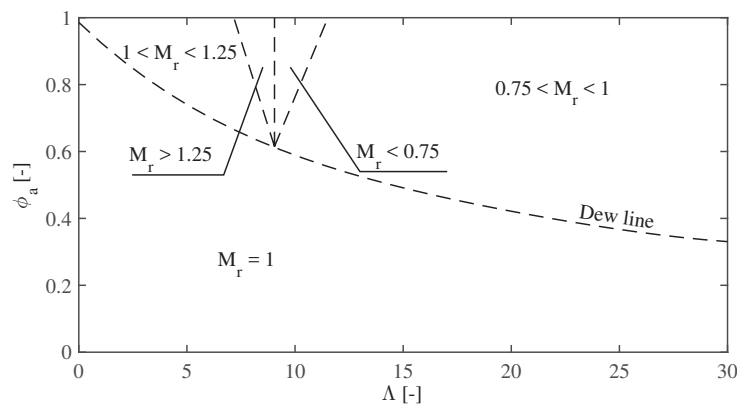


Figure A.7: Isolines of M_r for HGJB at $\epsilon_x = 0.05$ ($T_a = 308$ K)

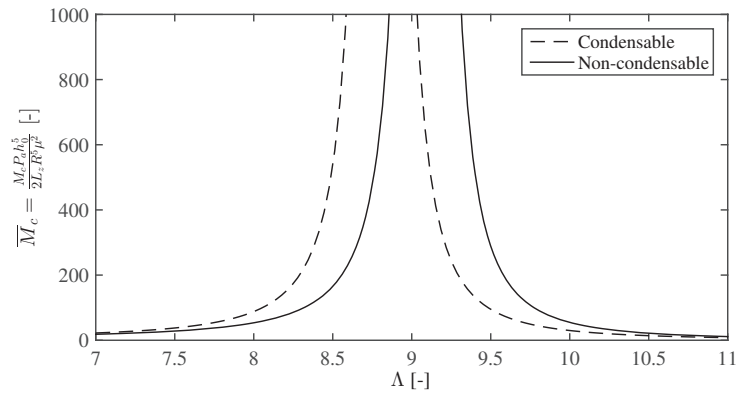


Figure A.8: Critical mass for HGJB at $\epsilon_x = 0.05$ ($T_a = 308$ K, $\phi_a = 1$) as a function of Λ with and without vapor condensation

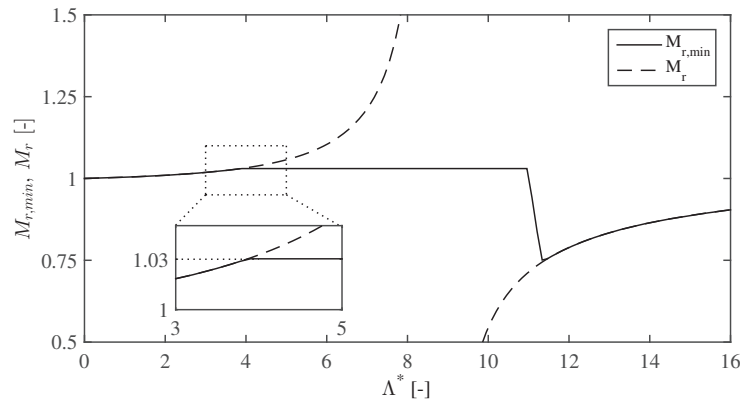


Figure A.9: M_r and $M_{r,min}$ for HGJB at $\epsilon_x = 0.05$ ($T_a = 308$ K, $\phi_a = 1$) as a function of Λ

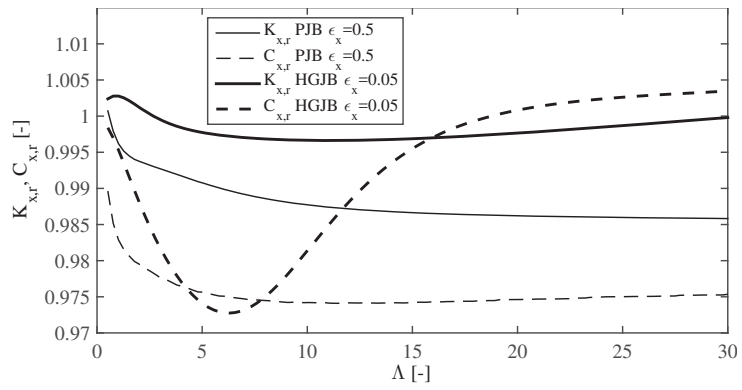


Figure A.10: Evolution of total stiffness and damping ratio for PJB and HGJB ($T_a = 308$ K, $\phi_a = 1$) as a function of Λ

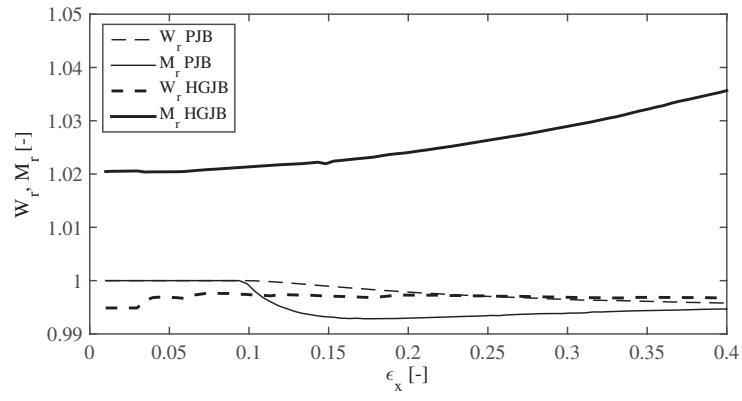


Figure A.11: Evolution of W_r and M_r for HGJB and PJB with the eccentricity ratio ($T_a=308$ K, $\Lambda=5$, $\phi_a=0.9$)

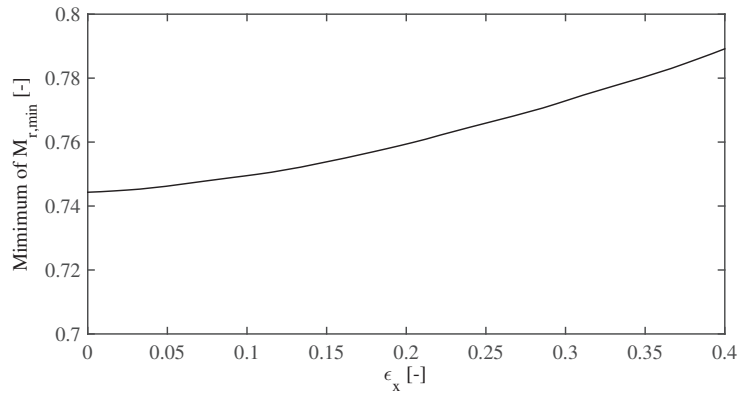


Figure A.12: Evolution of the minimum value of $M_{r,min}$ for $\Lambda^* = 50$ with the eccentricity ratio for HGJB ($T_a = 308$ K, $\phi_a = 1$)

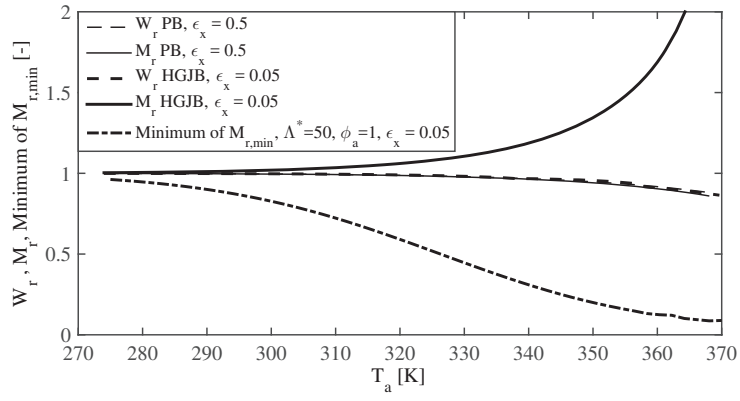


Figure A.13: Evolution of W_r and M_r for HGJB and PJB with the ambient temperature ($\Lambda = 5$, $\phi_a=0.9$), together with the evolution of the minimum value of $M_{r,\min}$ for $\phi_a=1$

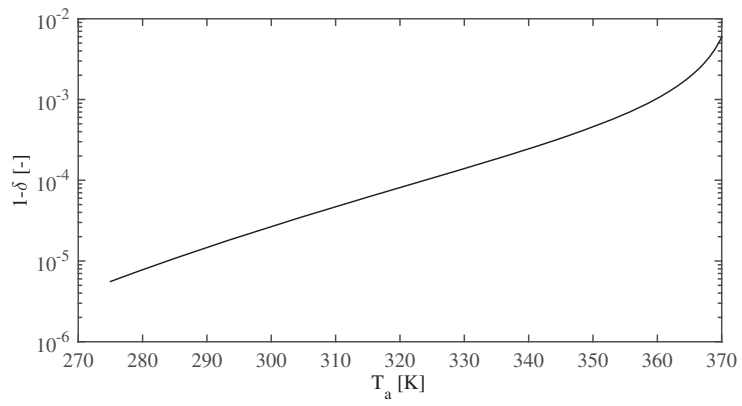


Figure A.14: Void fraction as a function of temperature in the limit case where all the water content condenses ($\phi_a=1$)