# New insights on scrape-off layer plasma turbulence

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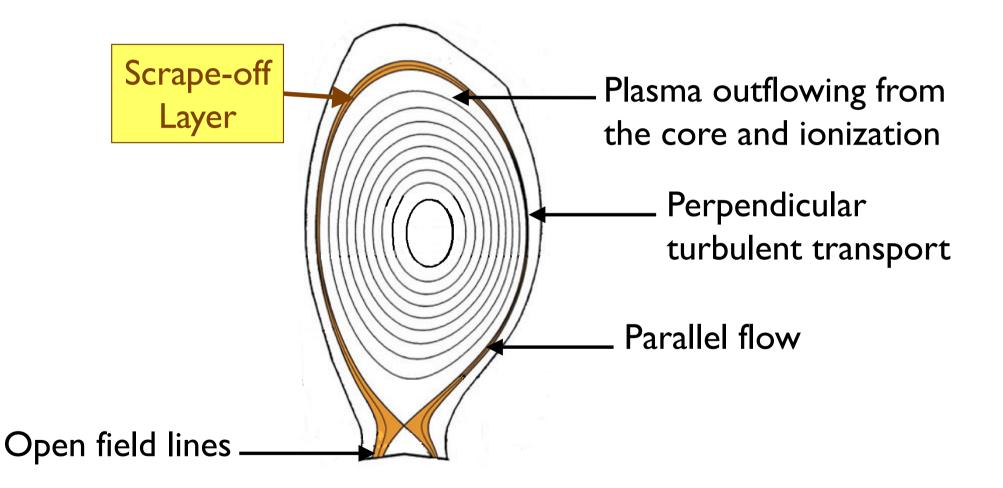
What are the properties of SOL plasma and how can we simulate it? Mechanisms setting the SOL width? ES potential? Toroidal rotation? How do our simulations compare with experiments?

SWISS PLASMA

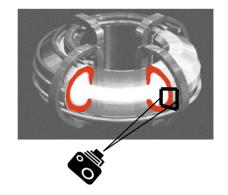
CENTER

POLYTECHNIOUE

#### SOL channels particles and heat to the wall

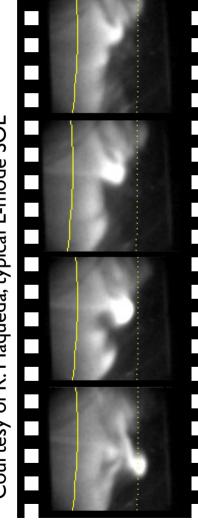


# SOL plasma properties

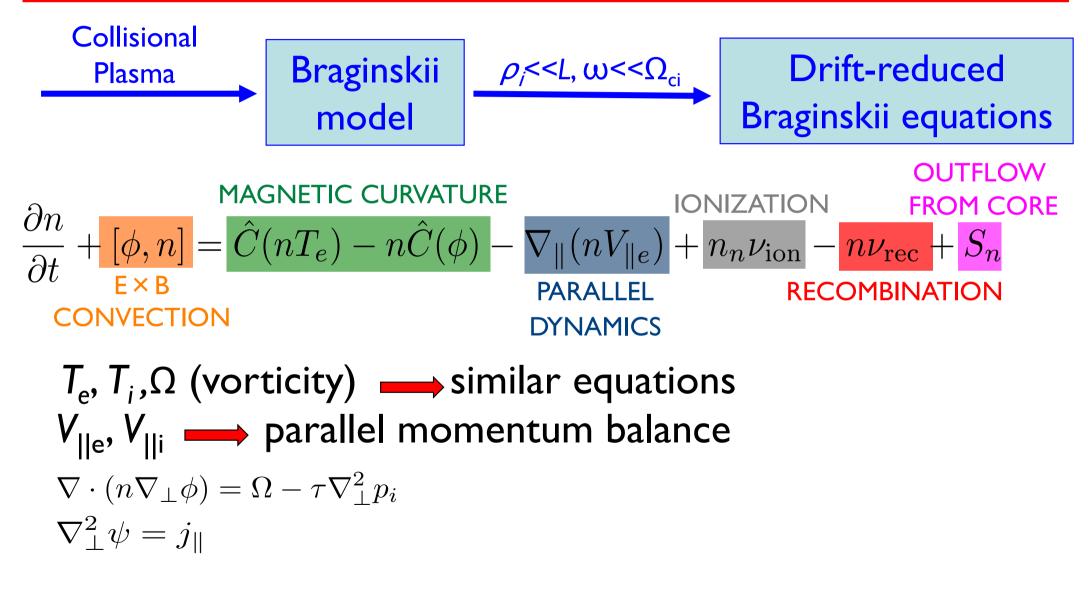


- $n_{fluc} \sim n_{eq}$
- $L_{fluc} \sim L_{eq}$
- Fairly cold (< 100 eV,  $n_e \sim 10^{19} \text{ m}^{-3}$ ) magnetized plasma
- Role of neutrals
- Sheath physics

Courtesy of R. Maqueda, typical L-mode SOL

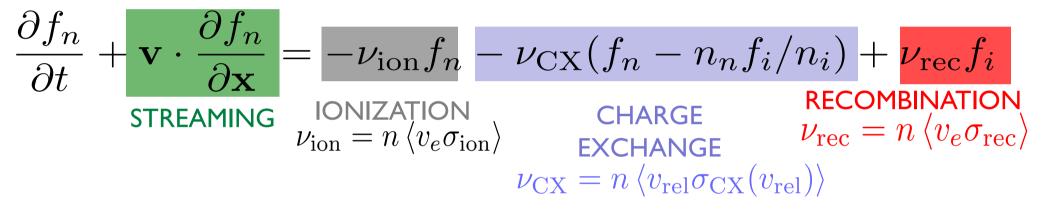


## A model to evolve plasma turbulence in the SOL



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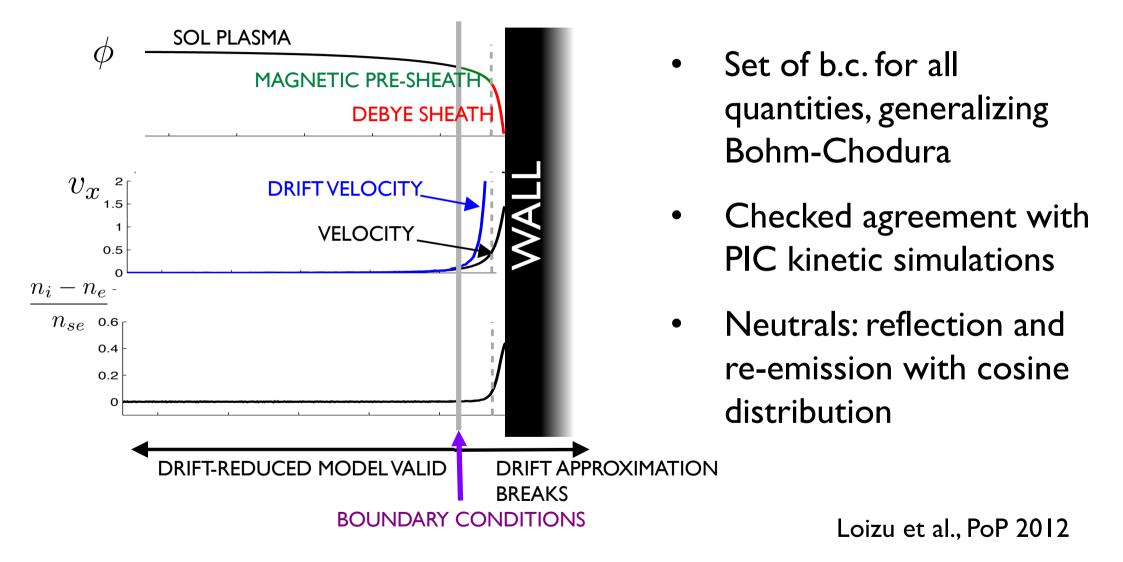
#### + coupling with neutrals



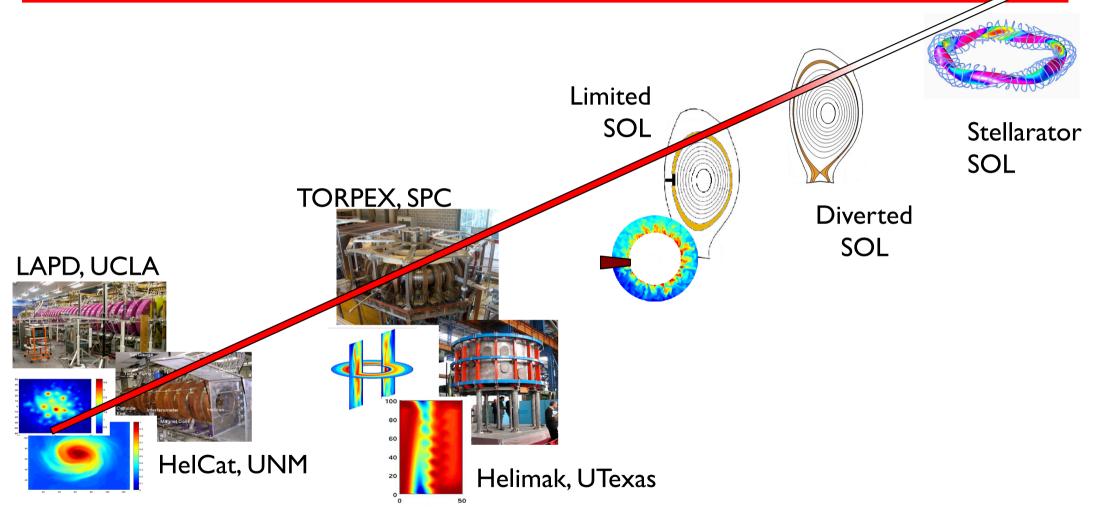
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Wersal & Ricci, NF 2015
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We solve in 3D geometry, taking into account plasma outflow from the core, turbulent transport, ionization and charge exchange processes, and losses at the vessel

## Boundary conditions at the plasma-wall interface

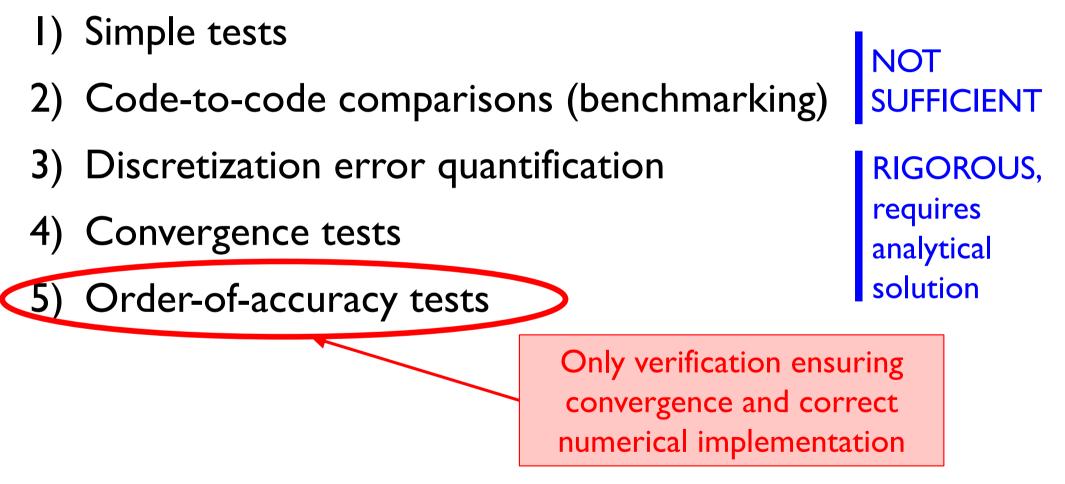


## GBS: our simulation tool



Ricci et al., PPCF 2012; Halpern et al., JCP 2016

#### How do you make sure there are no bugs in your code?

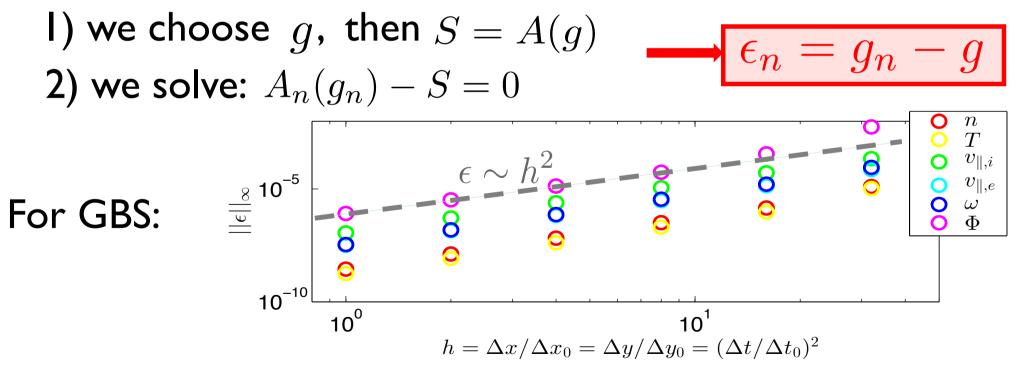


Riva et al., PoP 2014; Ricci et al., PoP 2015; Riva et al., PoP 2017

Order-of-accuracy tests, method of manufactured solution

Our model: 
$$A(f) = 0$$
,  $f$  unknown  
We solve  $A_n(f_n) = 0$ , but  $\epsilon_n = f_n - f = ?$ 

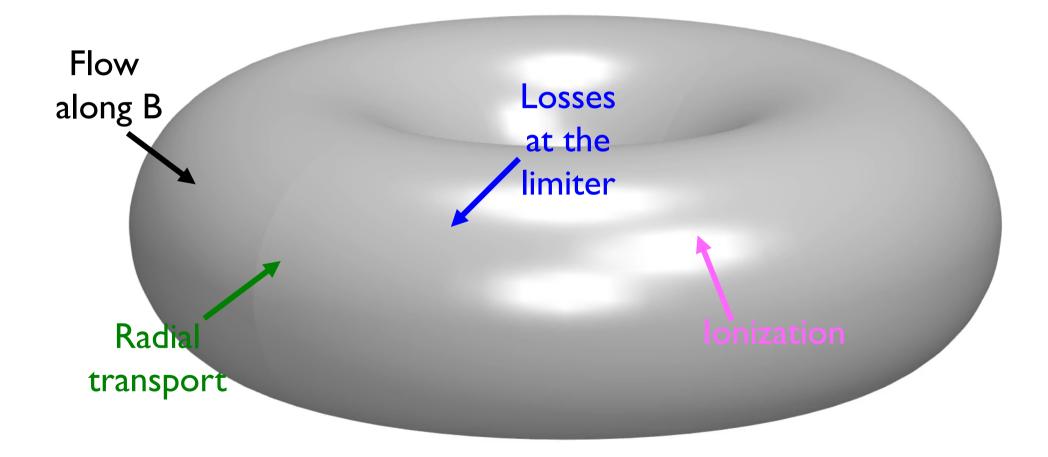
#### Method of manufactured solution:



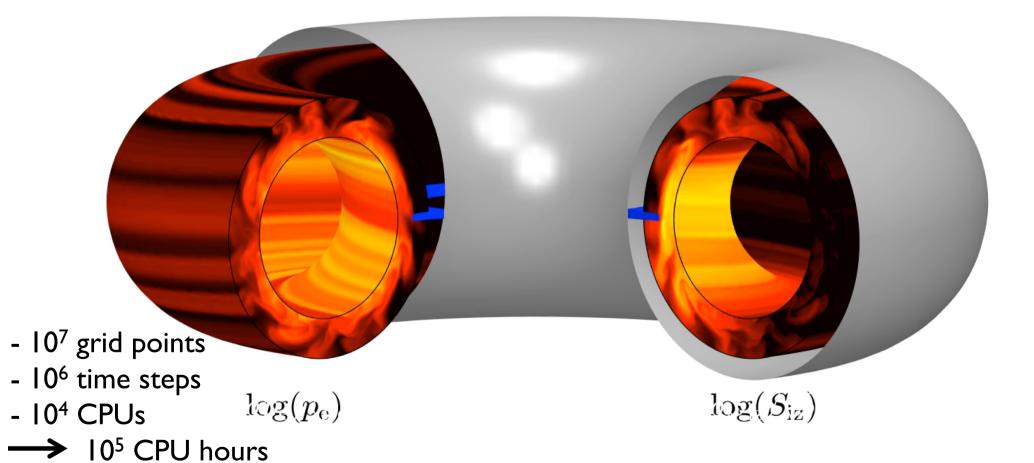
## **GBS:** our simulation tool Limited SOL Stellarator SOL TORPEX, SPC Diverted SOL LAPD, UCLA HelCat, UNM Helimak, UTexas

Ricci et al., PPCF 2012; Halpern et al., JCP 2016

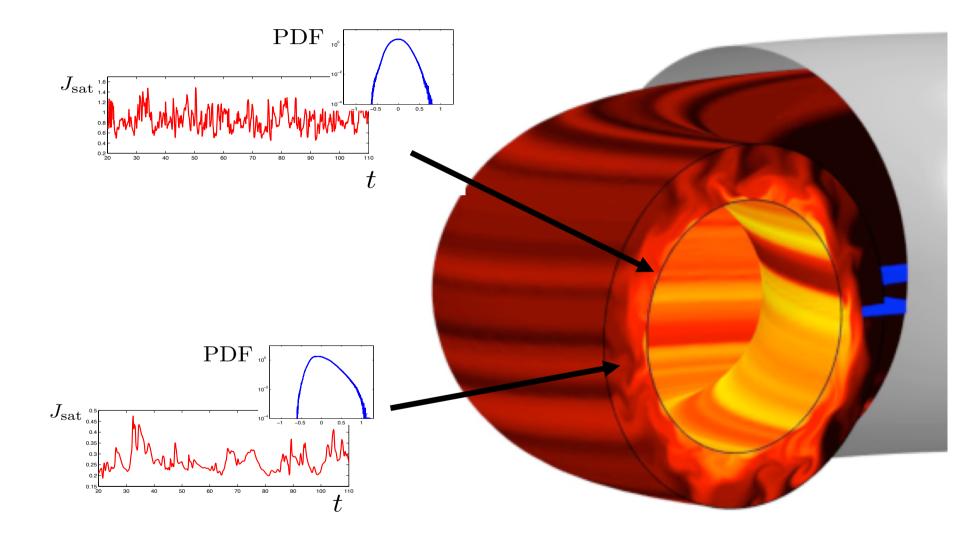
#### GBS evolves plasma and neutrals self-consistently



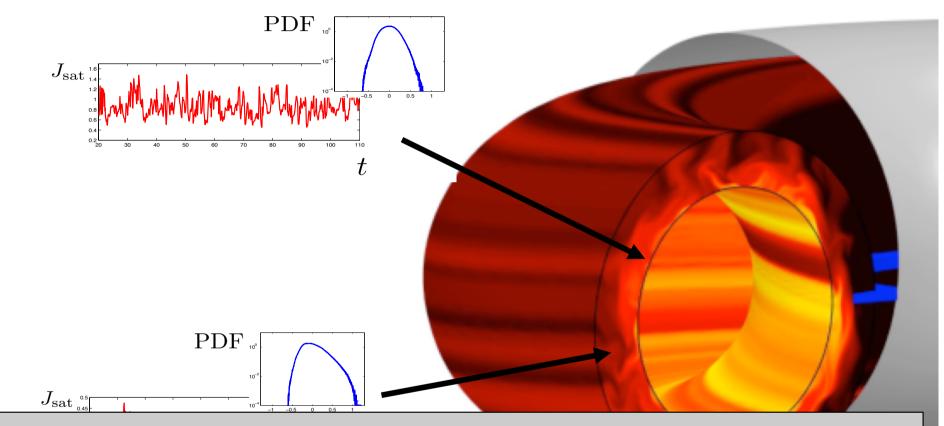
### GBS evolves plasma and neutrals self-consistently



#### Main experimental features retrieved

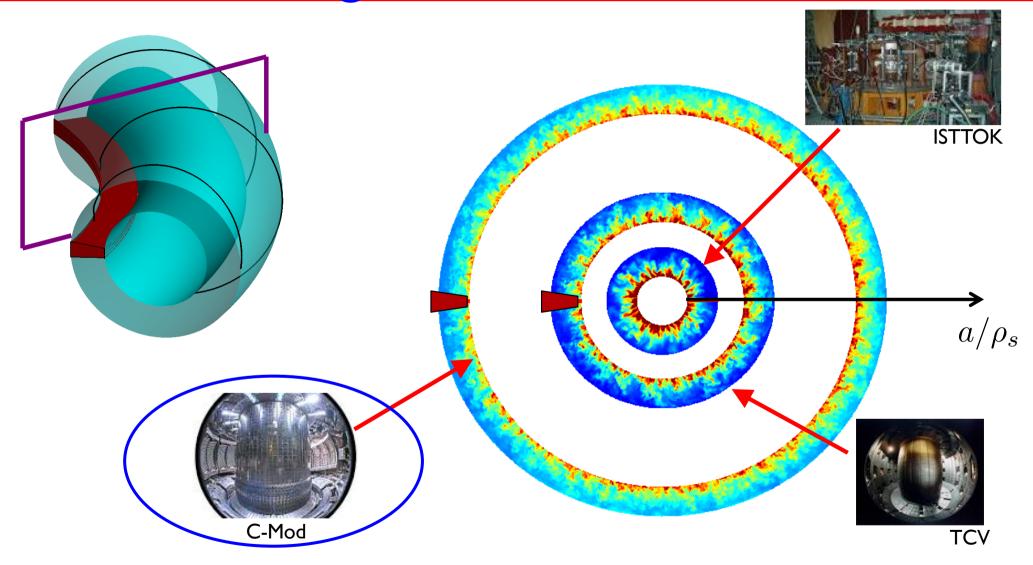


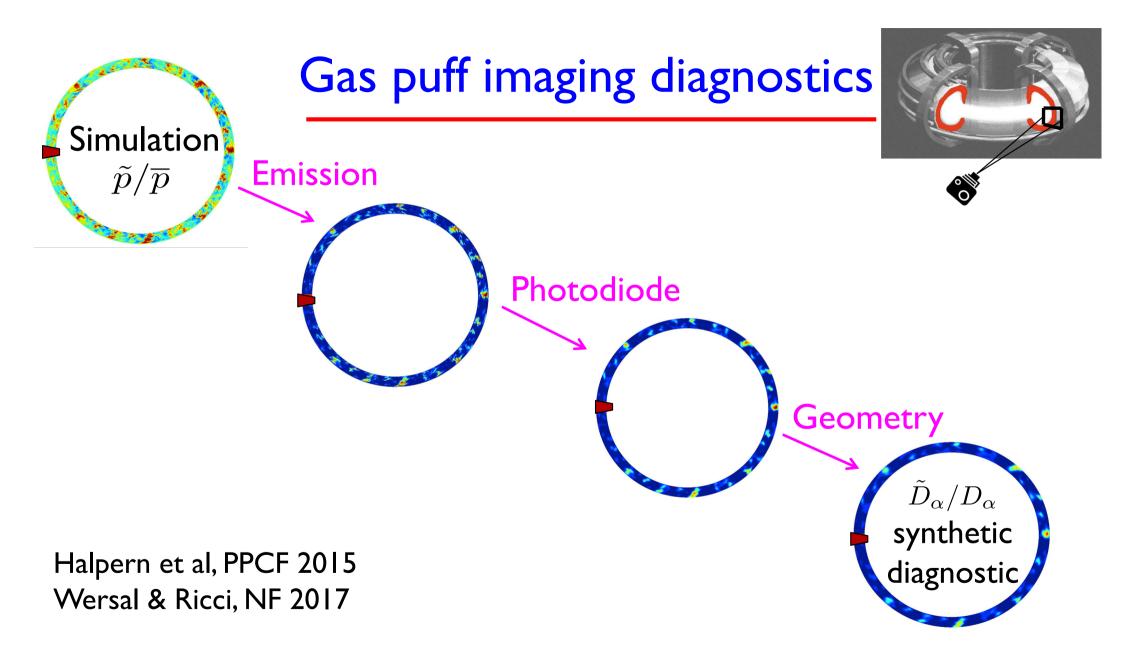
#### Main experimental features retrieved



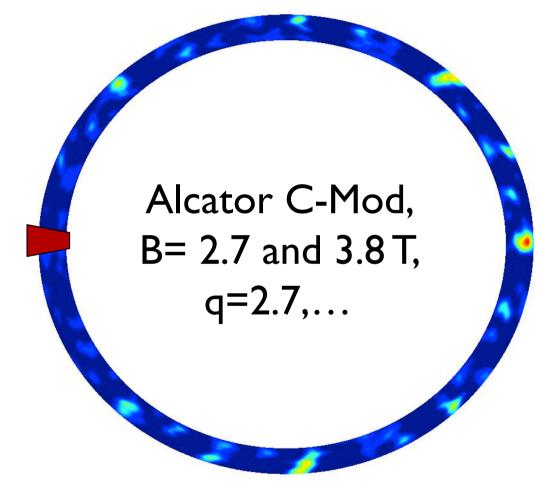
Simulations contain physics of ballooning modes, drift waves, Kelvin-Helmholtz, blobs, parallel flows, sheath losses...

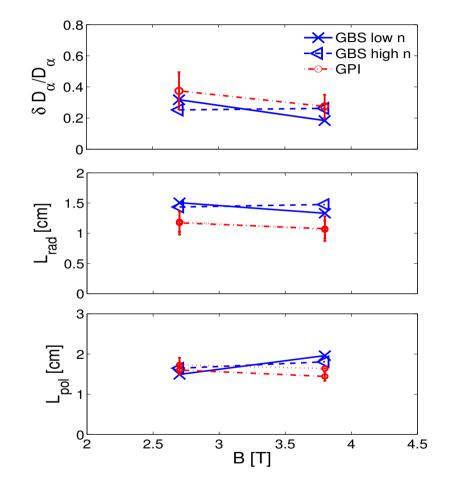
# A large validation effort





# C-Mod fluctuation properties well captured





Halpern et al., PPCF 2015

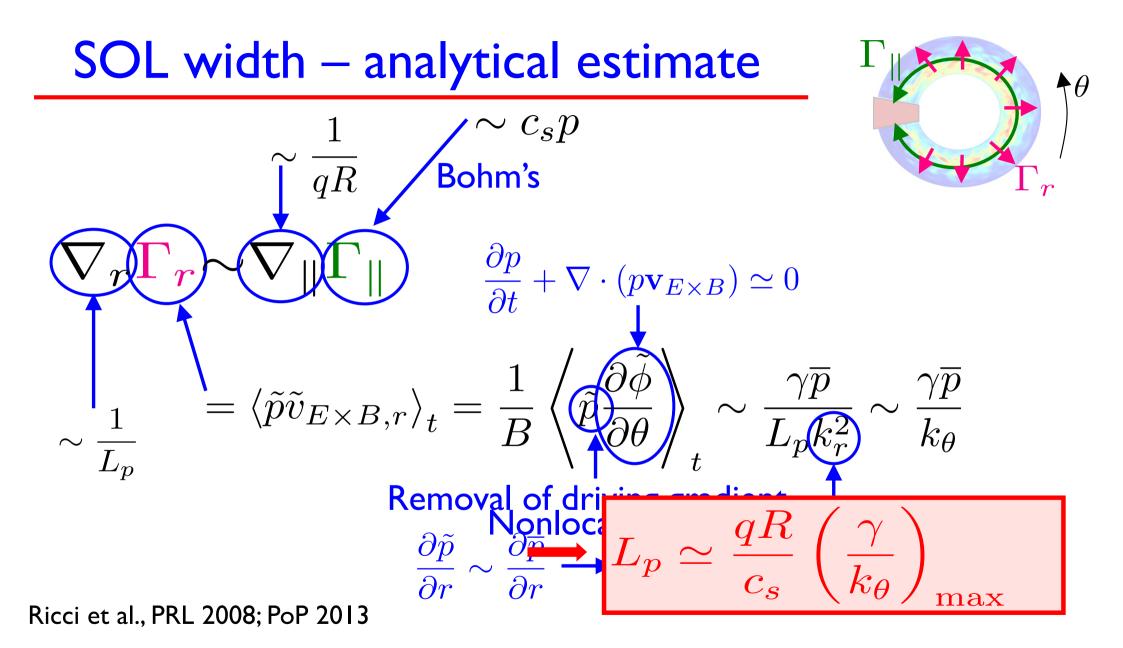
# A few of the key questions we addressed

• How is the SOL width established?

• Why is there a difference between near and far SOL?

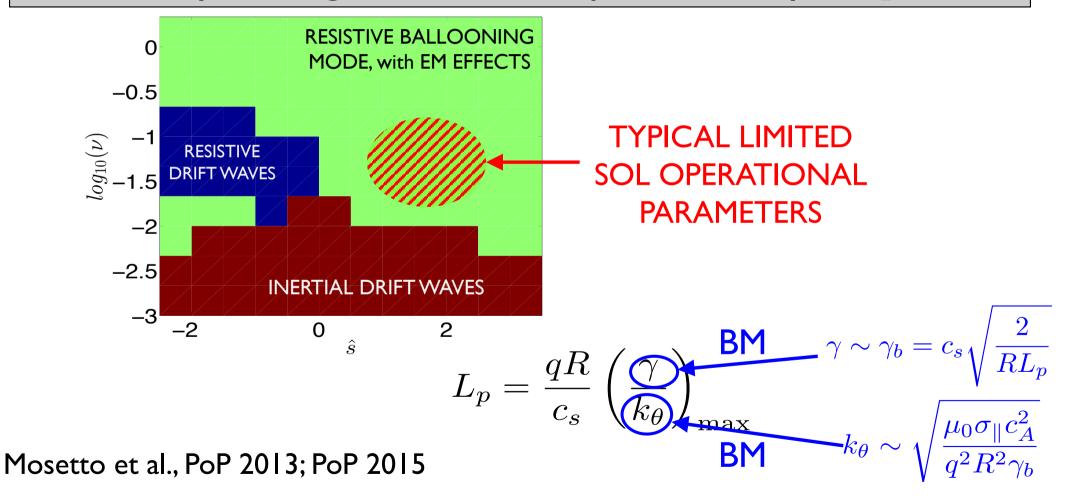
• What determines the SOL electrostatic potential?

• Are there mechanisms to generate toroidal rotation in the SOL?



# SOL turbulent regimes

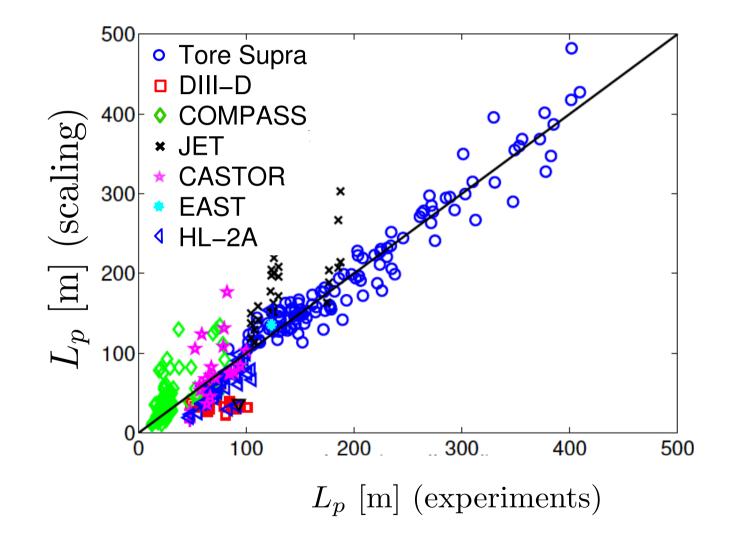
#### Instability driving turbulence depends mainly on $q, \nu, \hat{s}$ .



## Successful validation of ballooning scaling

Good agreement with simulation results and ITPA database

Halpern et al., NF 2013; NF 2014, PPCF 2016



# A few of the key questions we addressed

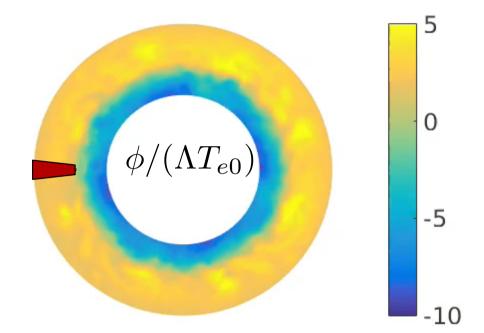
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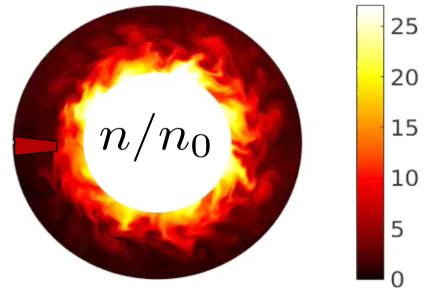
• What determines the SOL electrostatic potential?

• Are there mechanisms to generate toroidal rotation in the SOL?

## Different turbulent properties in near and far SOL



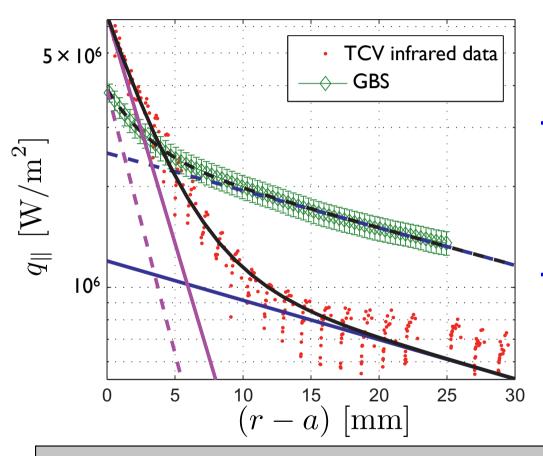
Strong shear flow at the LCFS...

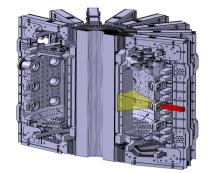


Halpern & Ricci, NF 2017

... resulting into a strong density gradient

#### Narrow feature at LCFS, long decay in far SOL





- TCV comparison: similar scale lengths, reduced heat flux in narrow feature
- Short scale: turbulence correlation length

Nespoli et al., JNM 2017 Halpern & Ricci, NF 2017

# ITER inner wall was redesigned

# A few of the key questions we addressed

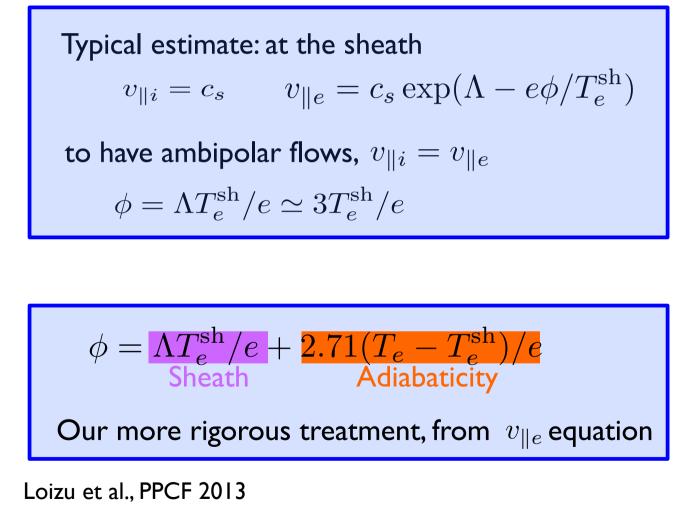
• How is the SOL width established?

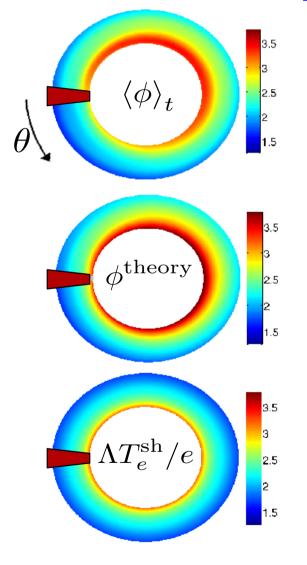
• Why is there a difference between near and far SOL?

• What determines the SOL electrostatic potential?

• Are there mechanisms to generate toroidal rotation in the SOL?

#### Potential in the SOL set by sheath and electron adiabaticity





# A few of the key questions we addressed

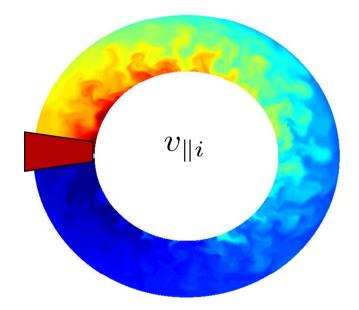
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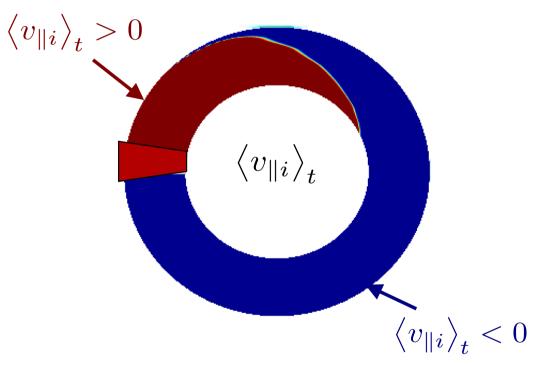
• Why is there a difference between near and far SOL?

• What determines the SOL electrostatic potential?

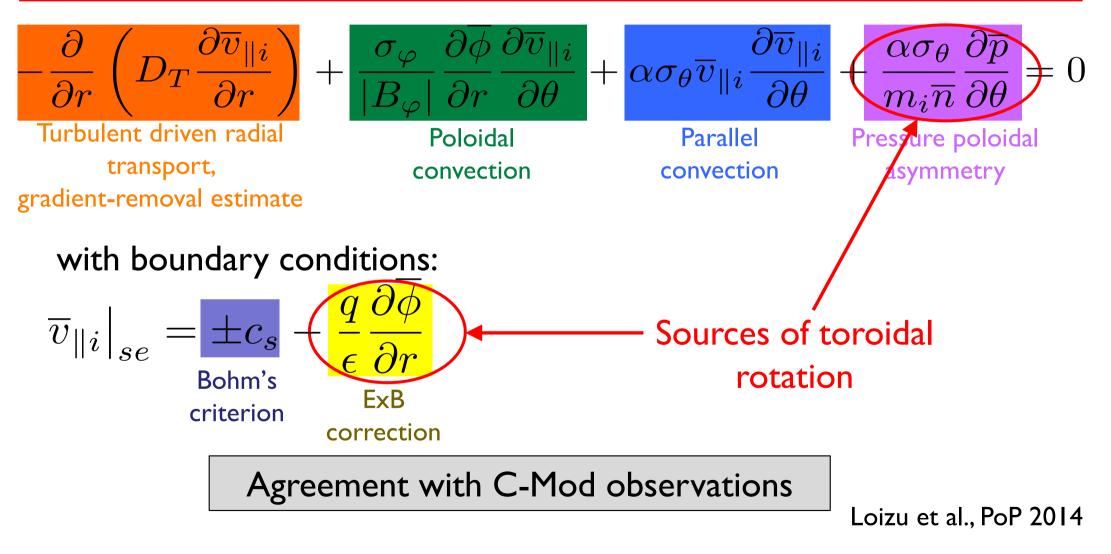
• Are there mechanisms to generate toroidal rotation in the SOL?

### GBS simulations show intrinsic toroidal rotation

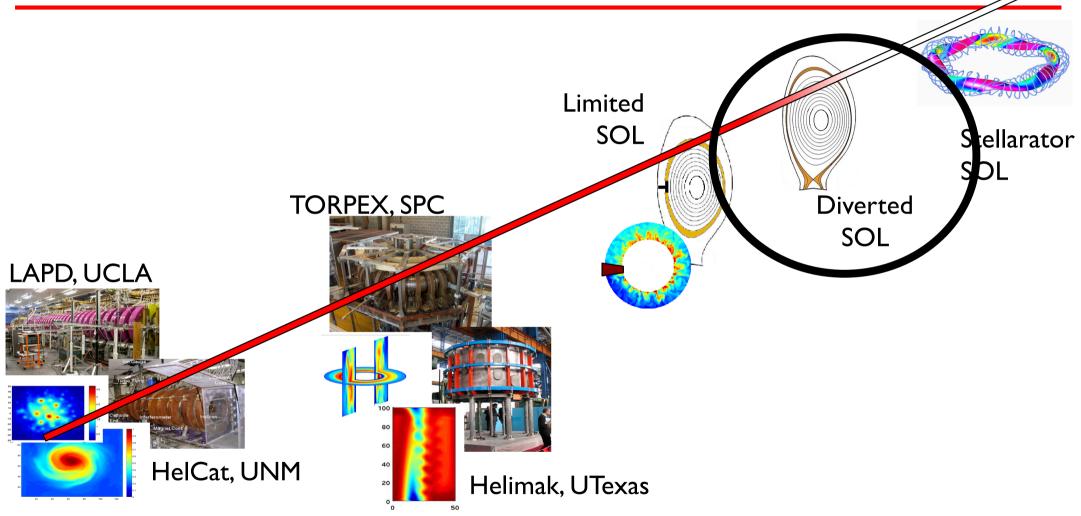




# 2D equation for the equilibrium flow

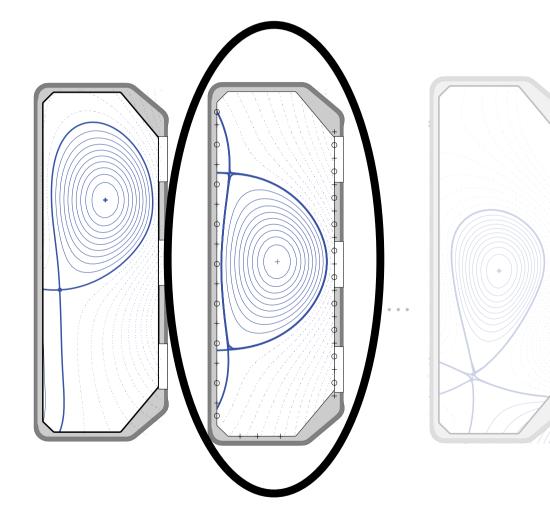


## **GBS: our simulation tool**



Ricci et al., PPCF 2012; Halpern et al., JCP 2016

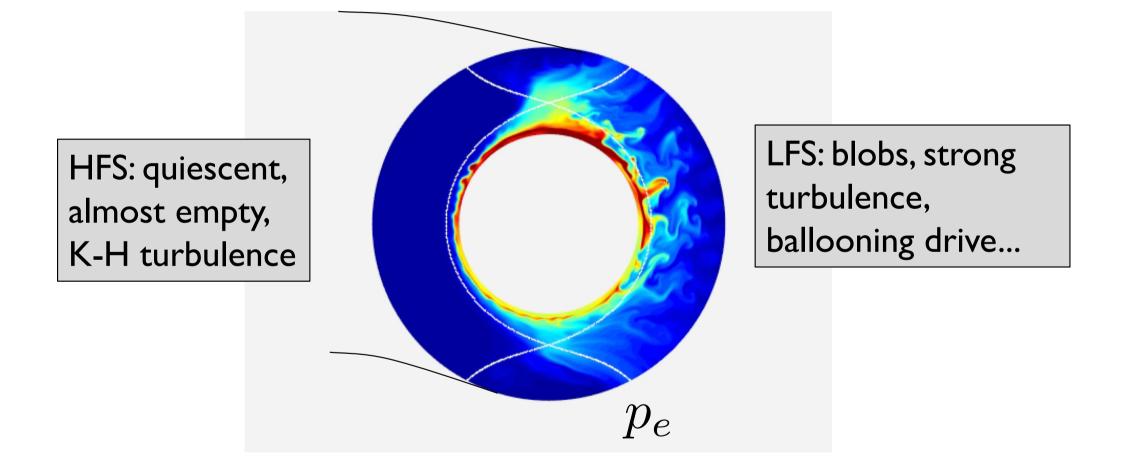
#### Flexible non-field aligned algorithm for diverted geometries



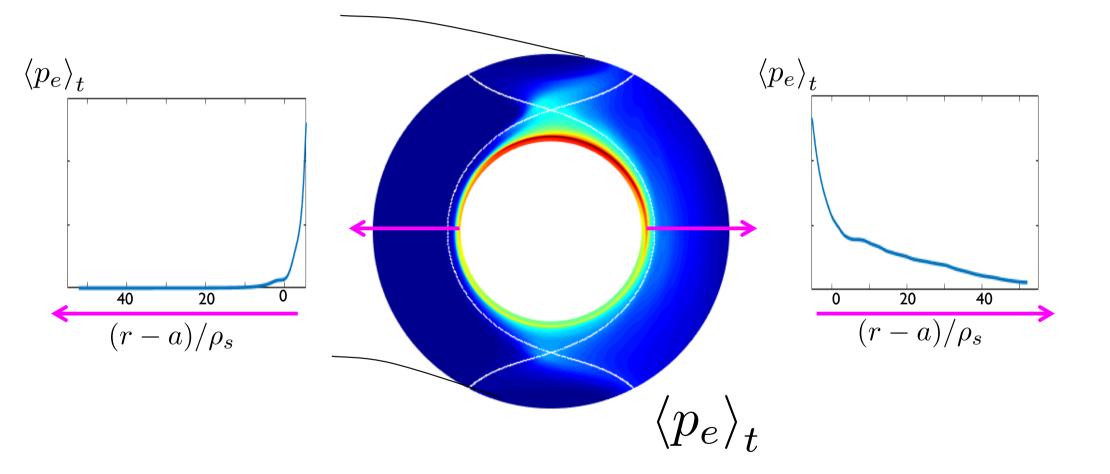
Double null:

- Possible heat exhaust solution
- High and low field sides separated

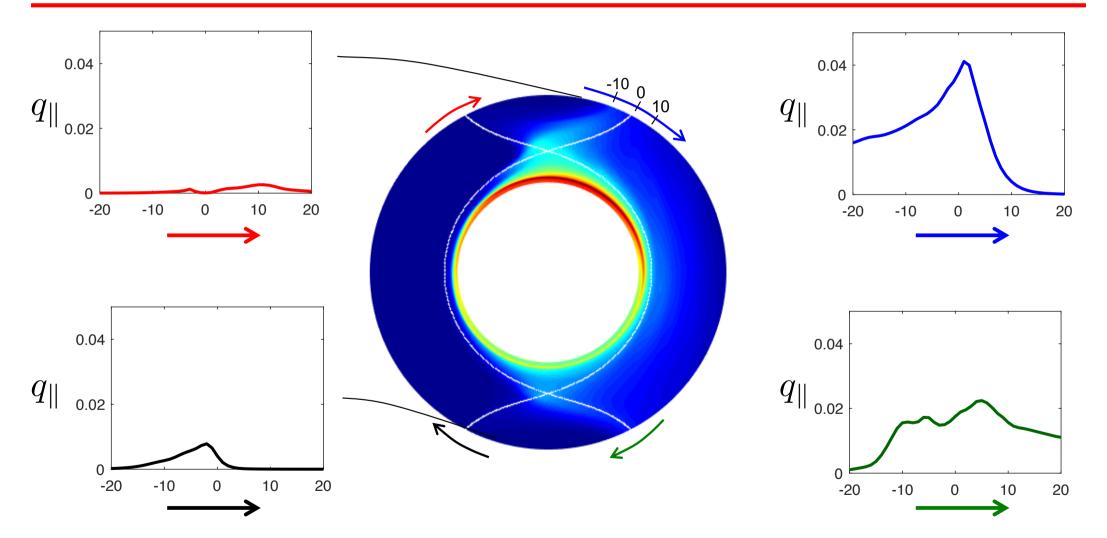
## GBS simulations of double-null configurations



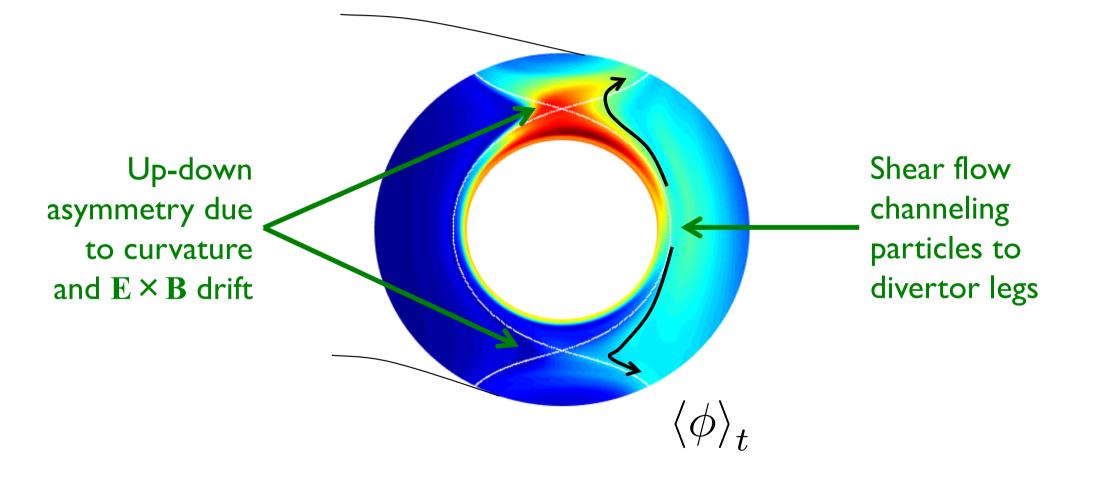
# Steep gradient at HFS, 2 scale lengths at LFS



## Very different heat fluxes along 4 legs



### **Complex circulation pattern**



# What are we learning on SOL dynamics?

- The use first-principles simulations and analysis to investigate SOL plasma dynamics
- Progressive approach to complexity
- Results in limited configuration:
  - SOL width set by resistive ballooning-driven turbulence saturated by the gradient removal mechanism in good agreement with multi-machine database
  - Presence of strong shear flow at the LCFS, resulting into 2 scale lengths
  - Mechanisms setting electrostatic potential and toroidal rotation
- Diverted configurations, complex flow patterns

http://people.epfl.ch/paolo.ricci

# Extra slides

## The complete set of equations

$$\frac{\partial n}{\partial t} = -\rho_{\star}^{-1}[\phi, n] + \frac{2}{B}\left[C(p_e) - nC(\phi)\right] - \nabla_{\parallel}(nv_{\parallel e}) + \mathcal{D}_n(n) + S_n + n_n nr_{iz} - n^2 r_{rec}$$
(1)

$$\frac{\partial \tilde{\omega}}{\partial t} = -\rho_{\star}^{-1}[\phi, \tilde{\omega}] - v_{\parallel i} \nabla_{\parallel} \tilde{\omega} + \frac{B^2}{n} \nabla_{\parallel} j_{\parallel} + \frac{2B}{n} C(\rho) + \mathscr{D}_{\tilde{\omega}}(\tilde{\omega})$$
(2)

$$\frac{\partial \mathbf{v}_{\parallel e}}{\partial t} + \frac{m_i}{m_e} \frac{\beta_e}{2} \frac{\partial \Psi}{\partial t} = -\rho_{\star}^{-1} [\phi, \mathbf{v}_{\parallel e}] - \mathbf{v}_{\parallel e} \nabla_{\parallel} \mathbf{v}_{\parallel e} + \frac{m_i}{m_e} \left( \mathbf{v} \frac{\dot{j}_{\parallel}}{n} + \nabla_{\parallel} \phi - \frac{1}{n} \nabla_{\parallel} p_e - 0.71 \nabla_{\parallel} T_e \right) + \mathscr{D}_{\mathbf{v}_{\parallel e}} (\mathbf{v}_{\parallel e})$$
(3)

$$\frac{\partial \mathbf{v}_{\parallel i}}{\partial t} = -\rho_{\star}^{-1} [\phi, \mathbf{v}_{\parallel i}] - \mathbf{v}_{\parallel i} \nabla_{\parallel} \mathbf{v}_{\parallel i} - \frac{1}{n} \nabla_{\parallel} \mathbf{p} + \mathscr{D}_{\mathbf{v}_{\parallel i}} (\mathbf{v}_{\parallel i}) + n_n (\mathbf{r}_{iz} + \mathbf{r}_{cx}) (\mathbf{v}_{\parallel n} - \mathbf{v}_{\parallel i})$$

$$\tag{4}$$

$$\frac{\partial T_e}{\partial t} = -\rho_{\star}^{-1}[\phi, T_e] - v_{\parallel e} \nabla_{\parallel} T_e + \frac{4T_e}{3B} \left[ \frac{1}{n} C(p_e) + \frac{5}{2} C(T_e) - C(\phi) \right] + \frac{2T_e}{3} \left[ \frac{0.71}{n} \nabla_{\parallel} j_{\parallel} - \nabla_{\parallel} v_{\parallel e} \right]$$
(5)

$$+\mathscr{D}_{T_{e}}(T_{e})+\mathscr{D}_{T_{e}}^{\parallel}(T_{e})+S_{T_{e}}-n_{n}r_{iz}E_{iz}$$

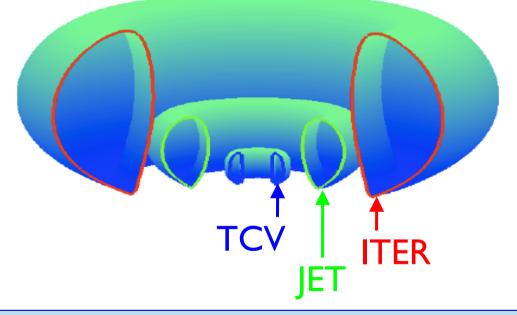
$$\frac{\partial T_{i}}{\partial t}=-\rho_{\star}^{-1}[\phi,T_{i}]-v_{\parallel i}\nabla_{\parallel}T_{i}+\frac{4T_{i}}{3B}\left[\frac{1}{n}C(\rho_{e})-\tau\frac{5}{2}C(T_{i})-C(\phi)\right]+\frac{2T_{i}}{3}\left[(v_{\parallel i}-v_{\parallel e})\frac{\nabla_{\parallel}n}{n}-\nabla_{\parallel}v_{\parallel e}\right]$$
(6)

$$+\mathscr{D}_{T_{i}}(T_{i})+\mathscr{D}_{T_{i}}^{\parallel}(T_{i})+S_{T_{i}}+n_{n}(r_{iz}+r_{cx})(T_{n}-T_{i}+(v_{\parallel n}-v_{\parallel i})^{2})$$

$$\nabla_{\perp}^{2}\phi = \omega, \ \nabla_{\perp}^{2}\Psi = j_{\parallel}, \ \rho_{\star} = \rho_{s}/R, \ \nabla_{\parallel}f = \mathbf{b}_{0}\cdot\nabla f + \frac{\beta_{e}}{2}\rho_{\star}^{-1}[\Psi, f], \ \tilde{\omega} = \omega + \tau\nabla_{\perp}^{2}T_{i}, \ p = n(T_{e} + \tau T_{i})$$

# ITER design based on scaling law

SOL basic physics understanding is still missing



## Simulations of SOL turbulence are crucial

#### The full set of GBS equations

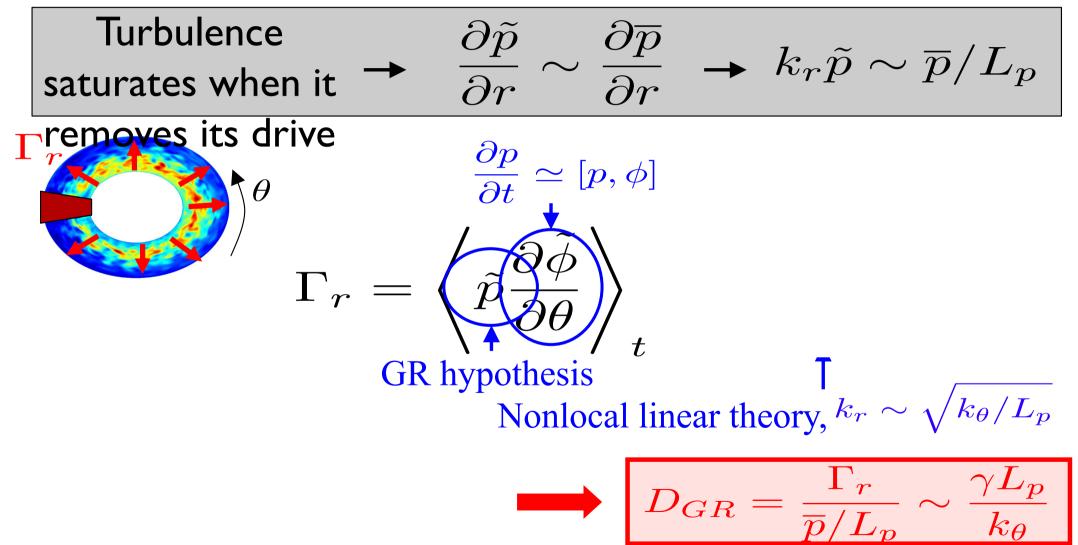
$$\begin{split} \partial_t n &= -\frac{R}{B} \left[ \phi, n \right] + \frac{2}{B} \left[ \hat{C} \left( p_e \right) - n \hat{C} \left( \phi \right) \right] - \nabla_{\parallel} \left( n v_{\parallel e} \right) + S_n \\ \partial_t \nabla_{\perp}^2 \phi &= -\frac{R}{B} \left[ \phi, \nabla_{\perp}^2 \phi \right] + \frac{2B}{n} \hat{C} \left( p_e \right) - v_{\parallel i} \nabla_{\parallel} \nabla_{\perp}^2 \phi + \frac{B^2}{n} \nabla_{\parallel} j_{\parallel} \\ \partial_t \left( v_{\parallel e} + \frac{m_i \beta_e}{m_e 2} \psi \right) &= -\frac{R}{B} \left[ \phi, v_{\parallel e} \right] - v_{\parallel e} \nabla_{\parallel} v_{\parallel e} \\ &+ \frac{m_i}{m_e} \left\{ -\nu \frac{j_{\parallel}}{n} + \nabla_{\parallel} \phi - \frac{1}{n} \nabla_{\parallel} p_e - 0.71 \nabla_{\parallel} T_e - \frac{2}{3n} \nabla_{\parallel} G_e \right\} \\ \partial_t v_{\parallel i} &= -\frac{R}{B} \left[ \phi, v_{\parallel i} \right] - v_{\parallel i} \nabla_{\parallel} v_{\parallel i} - \frac{1}{n} \nabla_{\parallel} p_e \\ \partial_t T_e &= -\frac{R}{B} \left[ \phi, T_e \right] - v_{\parallel e} \nabla_{\parallel} T_e + \frac{4}{3} \frac{T_e}{B} \left[ \frac{7}{2} \hat{C} \left( T_e \right) + \frac{T_e}{n} \hat{C} \left( n \right) - \hat{C} \left( \phi \right) \right] + S_{T_e} \\ &+ \frac{2}{3} T_e \left[ 0.71 \nabla_{\parallel} v_{\parallel i} - 1.71 \nabla_{\parallel} v_{\parallel e} + 0.71 \left( \frac{v_{\parallel i} - v_{\parallel e}}{n} \right) \nabla_{\parallel} n \right] \end{split}$$

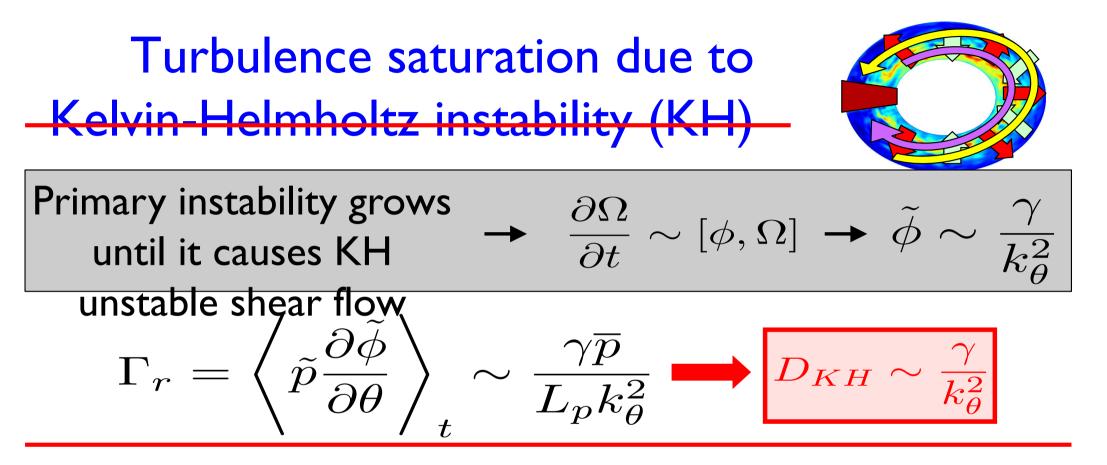
#### Need boundary conditions for: $n, v_{\parallel e}, v_{\parallel i}, T_e, \nabla^2_{\perp} \phi, \psi, \phi$

### Gradient-removal estimate of ExB velocity transport

$$\begin{split} \Gamma_{v,r} \sim \left\langle \tilde{v}_{\parallel i} \frac{\partial \tilde{\phi}}{\partial \theta} \right\rangle_{t} \underbrace{\Gamma_{\text{Parallel momentum}}_{\gamma \tilde{v}_{\parallel i} \sim \partial_{r} \overline{v}_{\parallel i} \partial_{\theta} \phi}}_{\left| \frac{\partial \overline{v}_{\parallel i}}{\partial r} \sim \partial_{r} \overline{v}_{\parallel i} \partial_{\theta} \phi} \right\rangle^{2} \left\langle \frac{\partial \overline{v}_{\parallel i}}{\partial r} \right\rangle_{t} \frac{\partial \overline{v}_{\parallel i}}{\partial r} \\ \underbrace{\Gamma_{v,r}}_{\gamma p \sim \partial_{r} \overline{p} \partial_{\theta} \phi} \left\langle \tilde{p}^{2} \right\rangle_{t} \frac{\partial \overline{v}_{\parallel i}}{\partial r} \left\langle \frac{\partial \overline{v}_{\parallel i}}{\partial r} \right\rangle_{r} - \frac{\gamma}{k_{\theta}} L_{p} \frac{\partial \overline{v}_{\parallel i}}{\partial r} \\ \underbrace{\Gamma_{v,r}}_{qR} \left\langle \frac{\partial \overline{v}_{\parallel i}}{\partial r} \right\rangle_{r} \left\langle \frac{\partial \overline{v}_{\parallel i}}{\partial r} \right\rangle_{r} \\ \underbrace{\Gamma_{v,r}}_{r} = -D_{T} \frac{\partial \overline{v}_{\parallel i}}{\partial r}, \quad D_{T} = \frac{L_{p}^{2} c_{s}}{qR} \end{split}$$

### Turbulent transport with gradient removal (GR) saturation

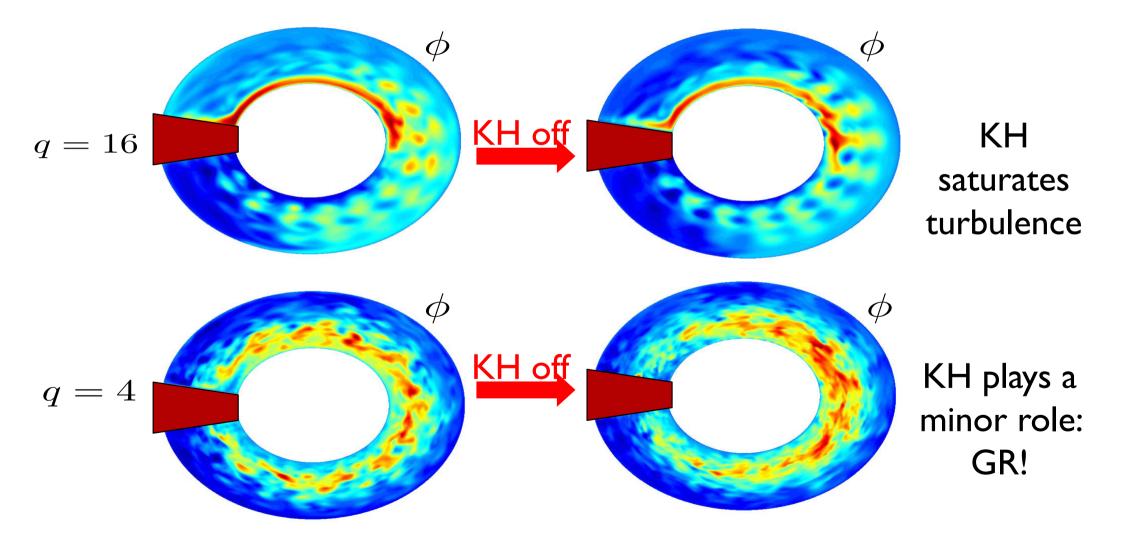




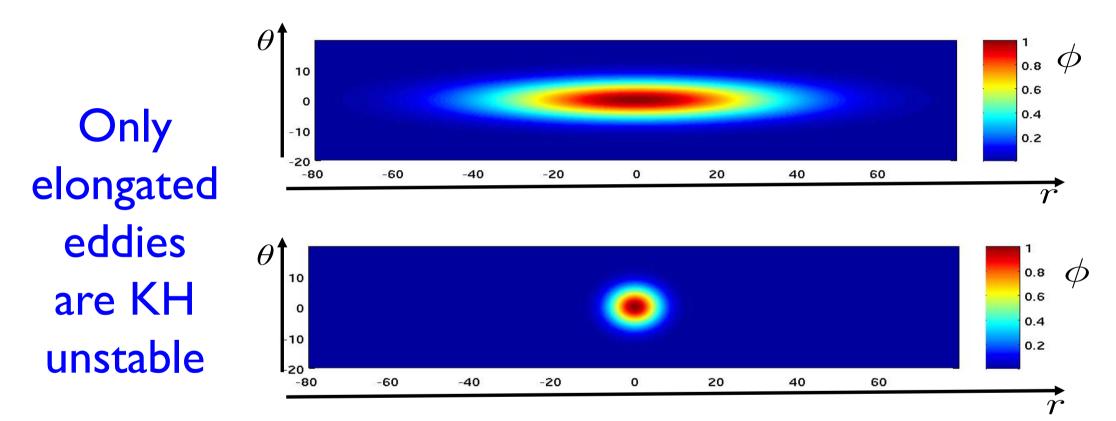
## KH vs GR mechanism:

 $\frac{D_{KH}}{D_{GR}} \sim \frac{1}{k_{\theta}L_{p}} < 1$  We expect KH to limit the transport, provided that KH is unstable!

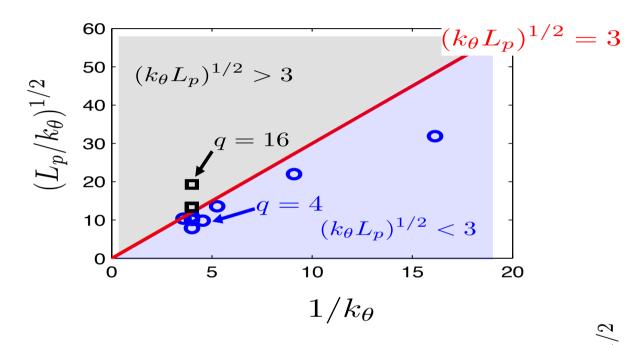
## Is KH really setting transport?



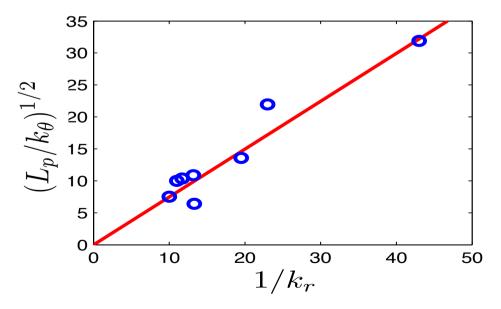
## Why is KH stable at low q but not higher q?



By comparing eddy turn over time and KH growth rate, KH unstable if:  $\sqrt{k_{\theta}L_p} > 3$  Why is KH stable at low q but not higher q?



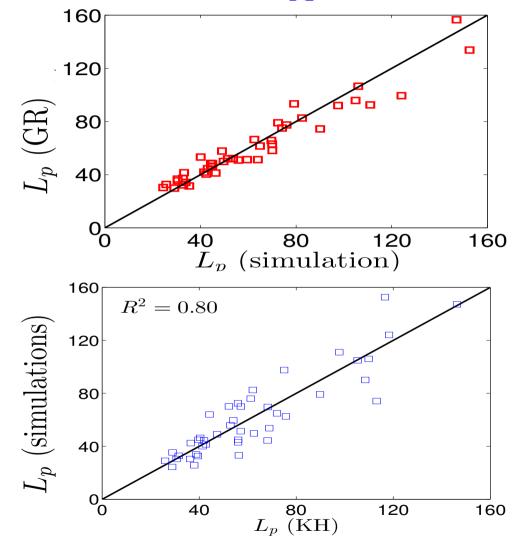
q=4 simulations are in the KH stable region



The eddies show the GR scaling properties

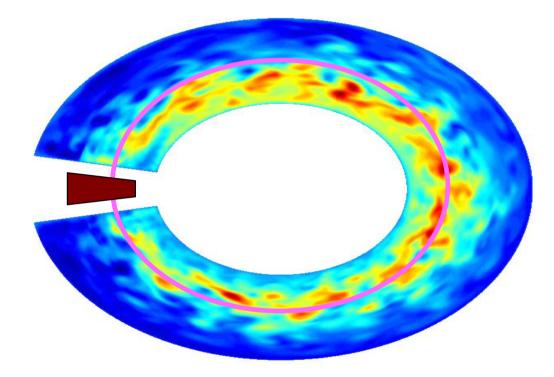
## KH vs GR scaling?

$$R^{2} = 93\%$$

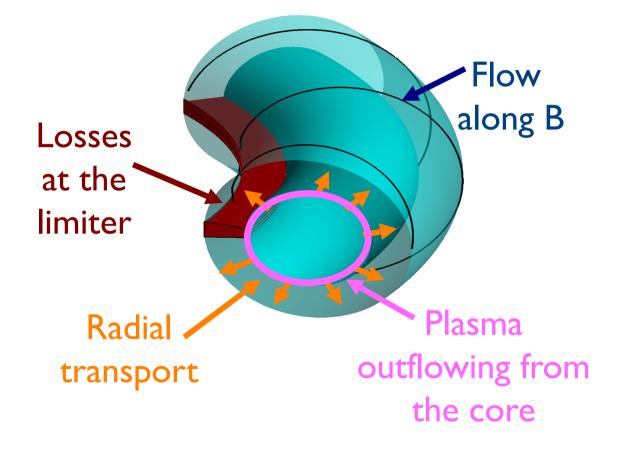


 $R^2 = 80\%$ 

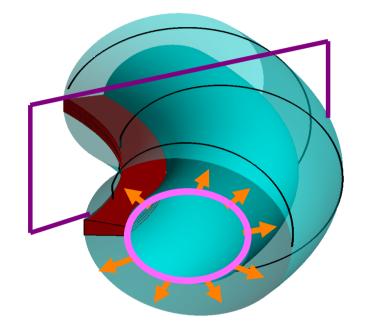
# Details of the source



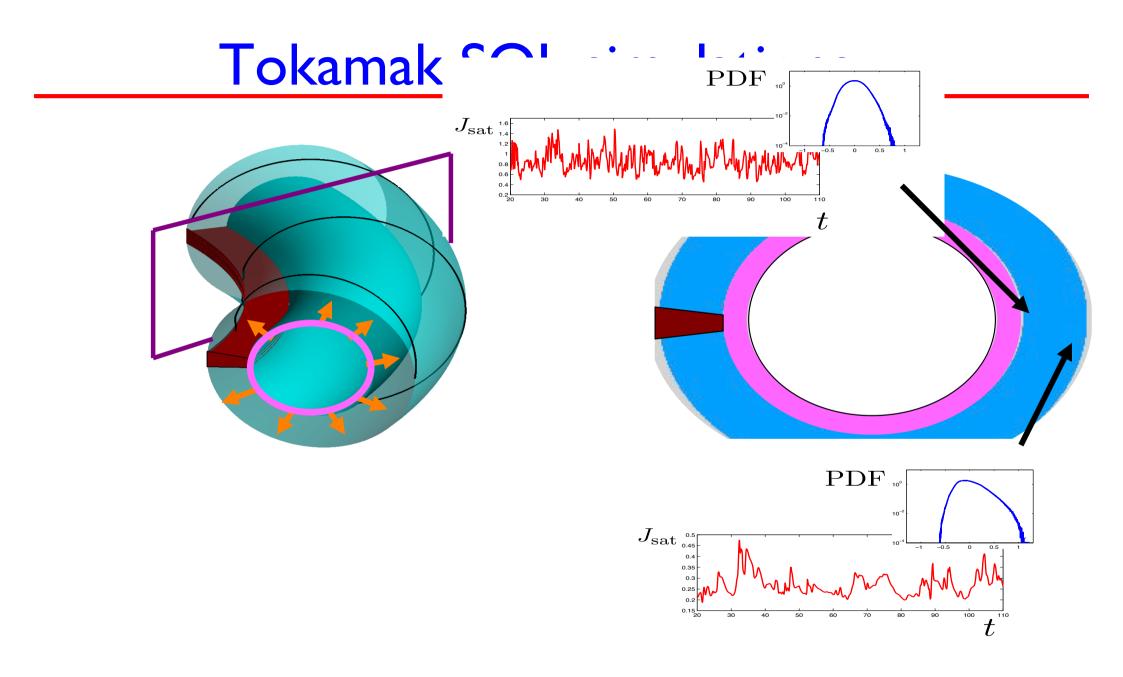
# **Tokamak SOL simulations**

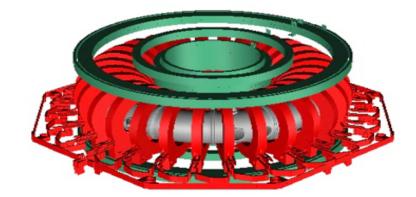


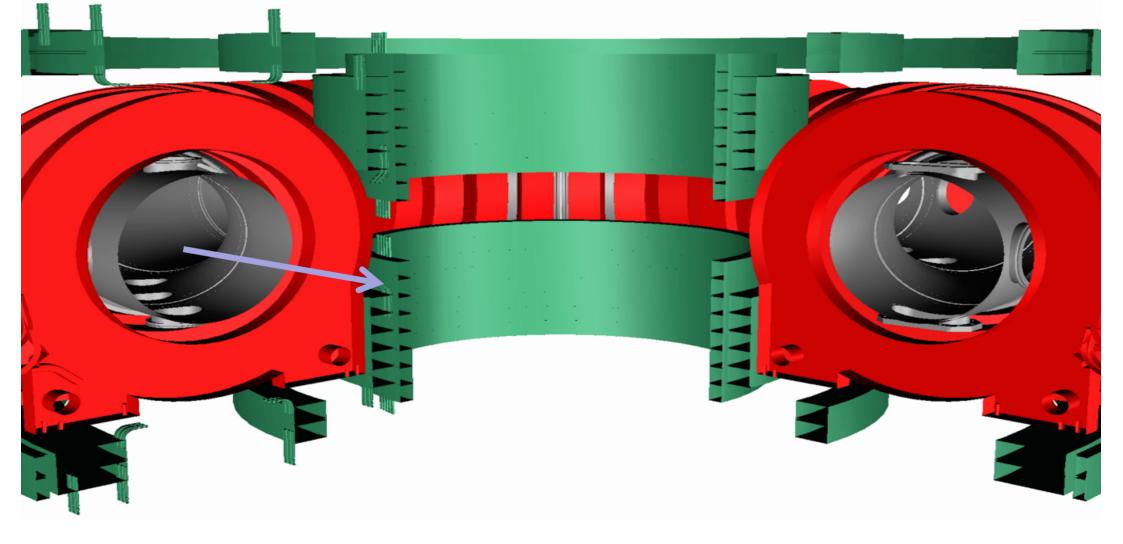
# **Tokamak SOL simulations**

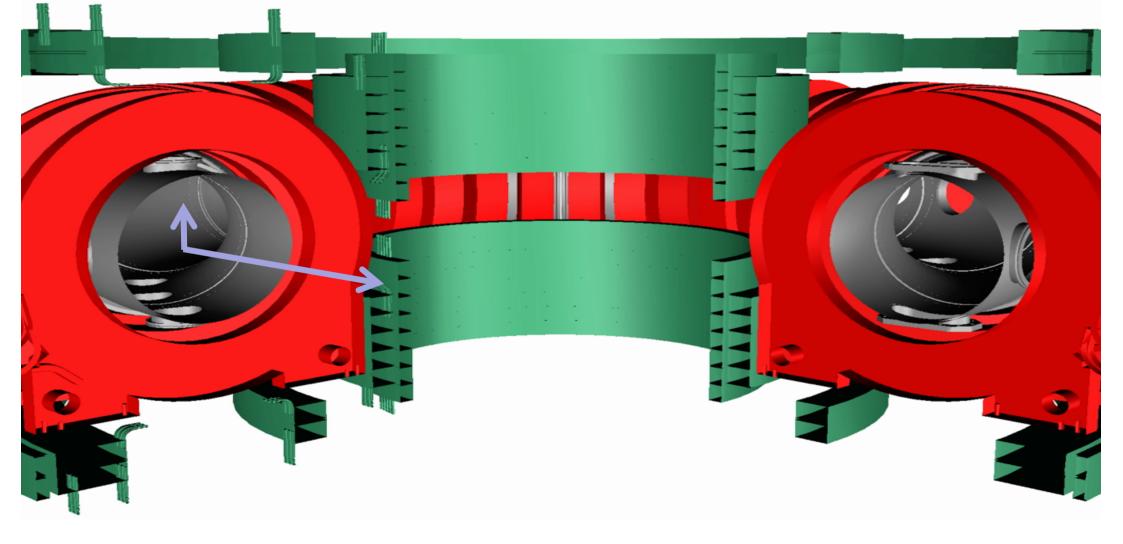


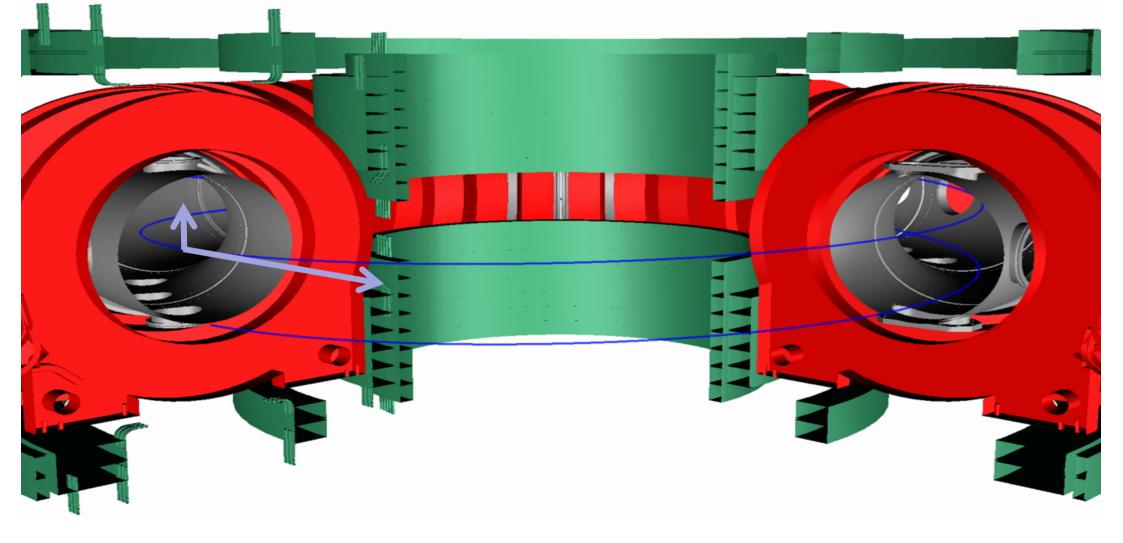
#### **Tokamak SOL simulations** 200 2.5 100 2 $\mathbf{N}$ 0 1.5 -100 1 -200 0.5 $\begin{array}{c} \mathbf{0} \\ R - R_0 \end{array}$ 200 -200 -100 100



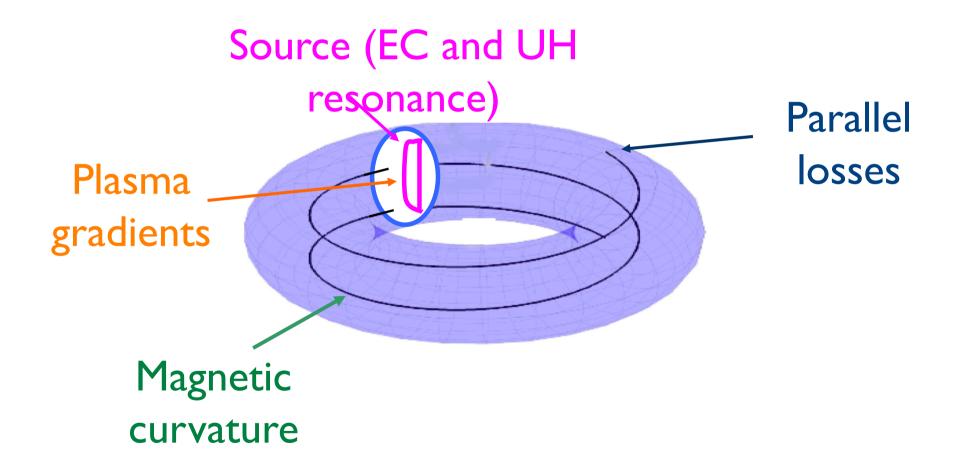




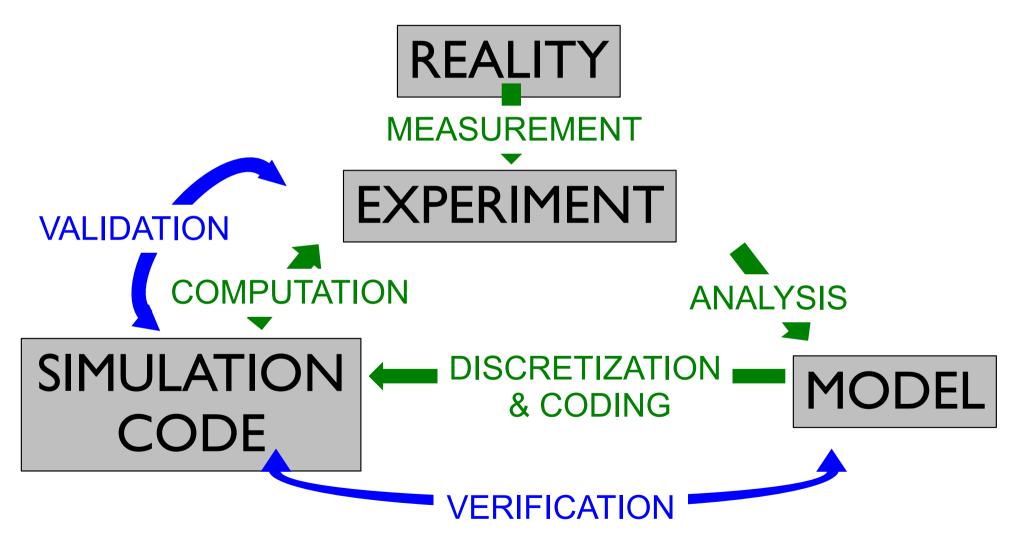




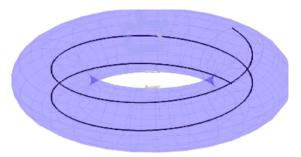
# Key elements of the TORPEX device

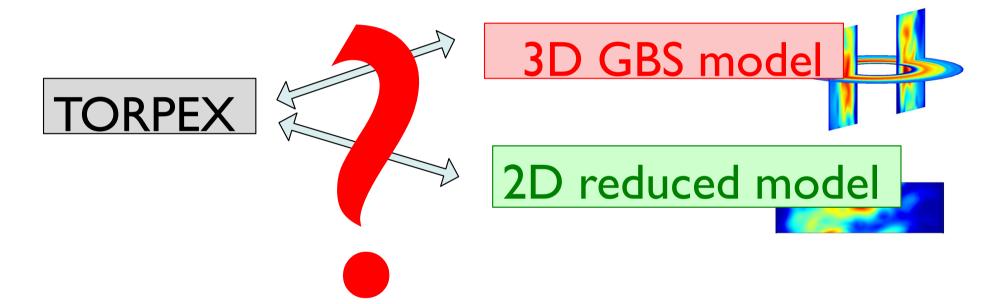


# Verification & Validation



Our project, paradigm of turbulence code validation





What is the agreement of experiment and simulations as a function of N (number of field line turns)? Is 3D necessary?

The validation methodology [Based on ideas of Terry et al., PoP 2008; Greenwald, PoP 2010]

What quantities can we use for validation? The more, the better...

- Definition & evaluation of the validation observables

What are the uncertainties affecting measured and simulation data?

- Uncertainty analysis

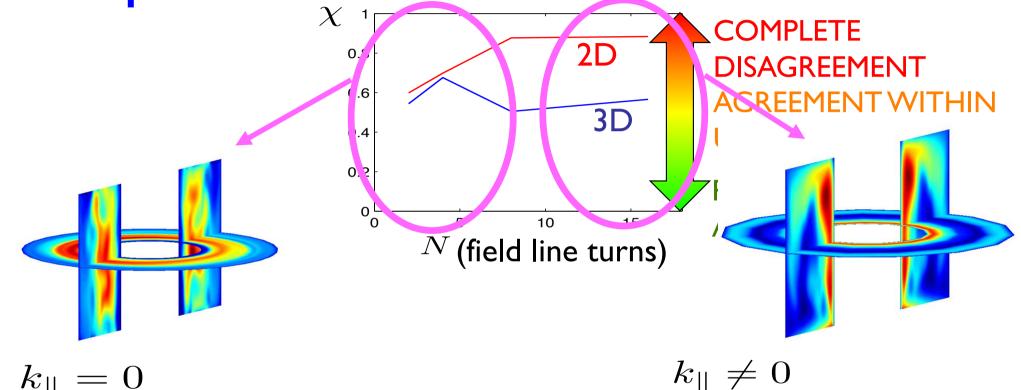
For one observable, within its uncertainties, what is the level of agreement?

- Level of agreement for an individual observable

How directly can an observable be extracted from simulation and experimental data? How worthy is it, i.e. what should be its weight in a composite metric?

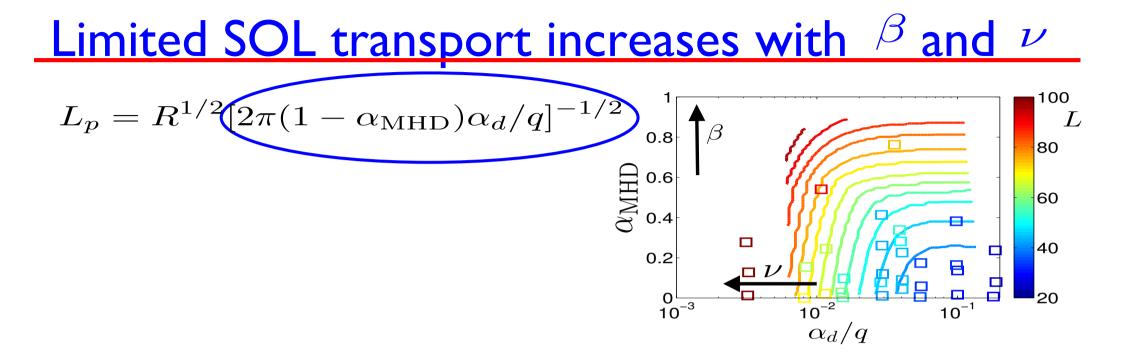
- The observable hierarchy

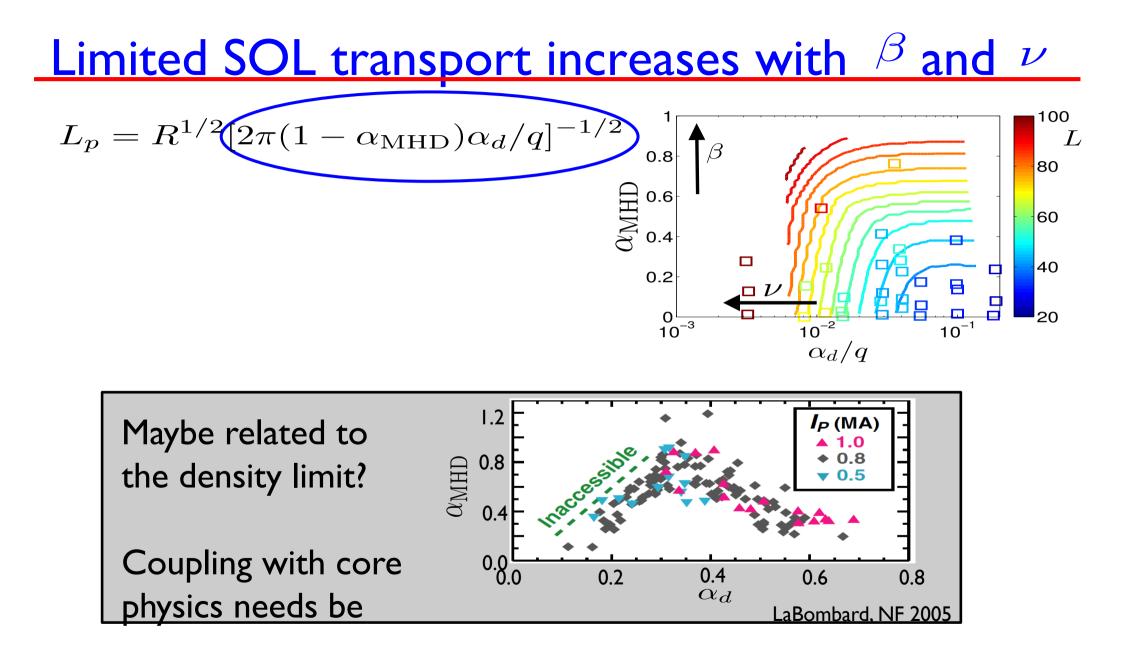
# Interpretation of the validation results



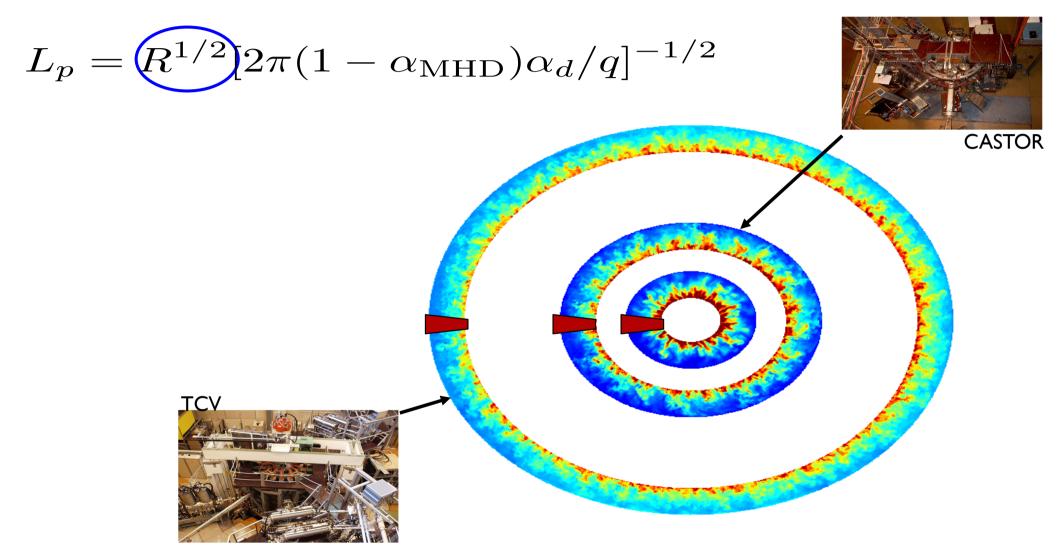
- $k_{\parallel}=0$
- Ideal interchange turbulence
- 2D model appropriate

- Resistive interchange turbulence
- 2D model not

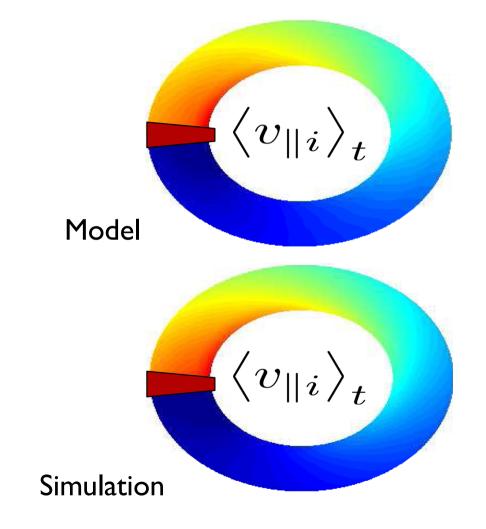




### Limited SOL width widens with R



### Our model well describes simulation results...



## ... and experimental trends

Analytical solution, far from limiter:

$$M = M_s e^{-r/l} + \left[ rac{\Lambda}{2lpha} rac{
ho_s}{L_T} e^{-r/L_T} 
ight]$$
 -

Core coupling Sheath contribution, co-current

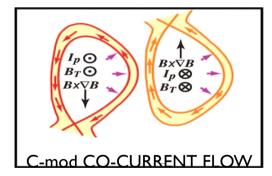
$$-\frac{\sigma_{\varphi}}{2}\left(rac{\delta n}{n}+rac{\delta T}{T}
ight)
ight]\left(1-e^{-r/l}
ight)$$

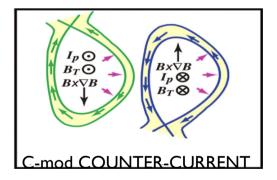
Pressure poloidal asymmetry at divertor plates, due to ballooning transport, direction: depends

Typically co-current

 $M_{\parallel} \lesssim 1$ 

• Can become counter-current by reversing **B** or divertor position





Loizu et al., PoP 2014