## Supplementary material for the paper: A coordinator-driven communication reduction scheme for distributed optimization using the projected gradient method

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**Theorem 1** Let N agents update with probabilities  $p_i$  and  $p_{\min} = \min_i p_i$ . Let  $\nu = 1 - \sqrt{(1 - 2\gamma\mu + \mu\gamma^2 L)}$ , where L is the Lipschitz constant of  $\nabla h$  and  $\mu$  the strong convexity constant of h, while  $\gamma < 2/L$ . If  $z^*$  is the unique optimizer of Problem 7 in [1], for any time instant k > K, the sequence  $\{z^k\}$  generated by Algorithm 1 satisfies

$$\mathbb{E}[\|z^{k+\mathcal{K}} - z^*\|^2] \le \left(1 - \frac{\rho(\mu-\epsilon)}{N}\right)^k \mathbb{E}[\|z^{\mathcal{K}} - z^*\|^2] + \frac{\rho}{N} \left(\frac{1}{\epsilon} + \frac{\rho(1+\delta)}{N\rho_{\min}\delta}\right) \sum_{j=1}^k \left(1 - \frac{\rho(\mu-\epsilon)}{N}\right)^{k-j} \mathbb{E}[\|e^{\mathcal{K}-1+j}\|^2] , \qquad (1)$$

for  $\rho \in (0, Np_{\min}/(2(1+\delta))), \delta > 0, \nu > \epsilon > 0$ , and  $e^k = (e_1^k, \ldots, e_N^k) \in \mathbb{R}^{Nn}$  the vector that is constituted of the components  $e_i^k = \gamma(\nabla \phi_i^{\gamma}(v^k) - g_i^k), i = 1, \ldots, N$ , while  $e^K = 0$ .

**Proof 1** The key point is to observe that the approximate iteration  $z_i^{k+1} = v_i^k - \gamma g_i^k$  can be expressed as an inexact projected gradient iteration. To this end, we introduce the error sequence  $\{e^k\}$  so as to write

$$e_i^k + \mathcal{P}_{\mathcal{Z}_i}\left(v_i^k\right) = v_i^k - \gamma g_i^k \quad , \tag{2}$$

while

$$\mathcal{P}_{\mathcal{Z}_i}\left(v_i^k\right) = v_i^k - \gamma \nabla \phi_i^{\gamma}(v_i^k) \quad . \tag{3}$$

Substituting (3) in (2) we have that

$$e_i^k = \gamma(\nabla \phi_i^{\gamma}(v_{i,k}) - g_i^k) \quad . \tag{4}$$

Using the error (4), the randomized coordinate descent iteration can be expressed as

$$\begin{cases} z_{i_k}^{k+1} &= z_{i_k}^k + \eta^k \left( e_{i_k}^k + \mathcal{P}_{\mathcal{Z}_{i_k}} \left( z_{i_k}^k - \gamma \nabla_{i_k} h(z^k) \right) - z_{i_k}^k \right) \\ z_{i \neq i_k}^{k+1} &= z_{i \neq i_k}^k \end{cases},$$

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or, more compactly, as

$$z^{k+1} = z^k + \eta^k U_{i_k} \Big( \mathcal{P}_{\mathcal{Z}} \left( z^k - \gamma \nabla h(z^k) \right) - z^k + e^k \Big) \quad .$$

$$\tag{5}$$

The matrix  $U_{i_k} : \mathbb{R}^{Nn} \mapsto \mathbb{R}^{Nn}$  is drawn from a set of orthogonal projection matrices  $\{U_i\}_{i=1}^N$  such that  $U_i : z \mapsto (0, \dots, 0, z_i, 0, \dots, 0)$ ,  $i = 1, \dots, N$  and  $\sum_{i=1}^N U_i = I$ . Consequently,  $U_{i_k}$  isolates the  $i_k^{\text{th}}$  component of its argument, thus it updates the corresponding component of z, while the other components (agents) are set to their previous values. The projection operator  $\mathcal{P}_Z$  is defined as  $\mathcal{P}_Z = \mathcal{P}_{Z_1} \times \mathcal{P}_{Z_2} \times \cdots \times \mathcal{P}_{Z_N}$ .

Equation (5) is an instance of a more general inexact fixed-point iteration. By introducing the operator

$$T: \mathbb{R}^n \mapsto \mathbb{R}^n, \quad T:=\mathcal{P}_{\mathcal{Z}}\left(I-\gamma \nabla h\right)$$

and

$$S: \mathbb{R}^n \mapsto \mathbb{R}^n, \quad S = I - T$$
.

equation (5) can be written as

$$z^{k+1} = z^k + \eta^k U_{i_k} (T z^k - z^k + e^k) = z^k - \eta^k U_{i_k} s^k \quad , \tag{6}$$

where  $s^k = Sz^k - e^k$ , and  $e^k$  is given by (4). We set the relaxation parameter to  $\eta^k = \frac{\rho}{N\rho_{i_k}}$ , where  $\rho > 0$  will be bounded from above later on.

Our purpose is to bound the distance of  $z^{k+1}$  to the fixed point  $z^*$  as a function of  $||z^k - z^*||$  and  $||e^k||$ , always in expectation. We thus introduce  $Z^k = \{z^0, z^1, \ldots, z^k\}$ , and by taking the conditional expectation and squaring (6), we get

$$\mathbb{E}[\|z^{k+1} - z^*\|^2 \mid Z^k] = \|z^k - z^*\|^2 - 2\frac{\rho}{N} \mathbb{E}[\langle z^k - z^*, \frac{1}{p_{i_k}} U_{i_k} s^k \rangle \mid Z^k] + \frac{\rho^2}{N^2} \mathbb{E}[\|\frac{1}{p_{i_k}} U_{i_k} s^k\|^2 \mid Z^k]$$

$$= \|z^k - z^*\|^2 - 2\frac{\rho}{N} \sum_{i=1}^N p_i \langle z^k - z^*, \frac{1}{p_i} U_i s^k \rangle + \frac{\rho^2}{N^2} \sum_{i=1}^N p_i \langle \frac{1}{p_i} U_i s^k, \frac{1}{p_i} U_i s^k \rangle$$

$$\leq \|z^k - z^*\|^2 - 2\frac{\rho}{N} \langle z^k - z^*, s^k \rangle + \frac{\rho^2}{N^2 p_{\min}} \|s^k\|^2 , \qquad (7)$$

where the second equality follows from the definition of the expectation and the third one from the fact that  $U_i$  is an orthogonal projection operator.

Let us now analyze the second and third term in (7).

• Bound  $-2\frac{\rho}{N}\langle z^k - z^*, s^k \rangle$ : From the definition of  $s^k = Sz^k - e^k$ , it holds that

$$\langle z^{k} - z^{*}, s^{k} \rangle = \langle z^{k} - z^{*}, Sz^{k} \rangle - \langle z^{k} - z^{*}, e^{k} \rangle \quad .$$

$$(8)$$

We will now upper-bound the resulting inner product terms. In order to do so, we must use both the Lipschitz continuity of  $\nabla h$  and the strong convexity of h.

**Lemma 1** Let  $S = I - \mathcal{P}_{\mathcal{Z}}(I - \gamma \nabla h)$  as defined above. Then

$$\langle z^k - z^*, Sz^k \rangle \geq \frac{1}{2} \|Sz^k\|^2$$
.

**Proof 2** If  $T = \mathcal{P}_{\mathcal{Z}}(I - \gamma \nabla h)$  is a nonexpansive operator, then the property holds for S = I - T from [3, Proposition 4.33]. Nonexpansivity of T can be easily shown (see, e.g., [2, Proposition 2.2]), from where the result follows.

**Lemma 2** Denoting as L be the Lipschitz continuous gradient constant of h and  $\mu$  its strong convexity modulus, it holds that

$$\langle z^k - z^*, Sz^k 
angle \geq 
u \| z^k - z^* \|^2$$
 ,

where  $\nu = 1 - \sqrt{(1 - 2\gamma\mu + \mu\gamma^2 L)}$  for  $\gamma < 2/L$ .

**Proof 3** From [3, Example 22.5] we have that if T is  $\beta$ -Lipschitz continuous for some  $\beta \in [0, 1)$  then I - T is  $(1 - \beta)$ -strongly monotone. It is proven in [2, Proposition 2.2] that  $||Tz - Tz^*|| \leq \sqrt{(1 - 2\gamma\mu + \mu\gamma^2 L)}||z - z^*||$  for  $\gamma < 2/L$ , so T is  $\beta$ -Lipschitz continuous with  $\beta = \sqrt{(1 - 2\gamma\mu + \mu\gamma^2 L)}$ , which concludes the proof.

Using Lemmata 1 and 2 we get

$$-2\frac{\rho}{N}\langle z^{k}-z^{*},Sz^{k}\rangle \leq -\frac{\rho\nu}{N}\|z^{k}-z^{*}\|^{2}-\frac{\rho}{2N}\|Sz^{k}\|^{2}$$
(9)

For the second inner product term in (8) we can easily derive the bound

$$2\frac{\rho}{N}\langle z^{k} - z^{*}, e^{k} \rangle \le 2\frac{\rho}{N} \|z^{k} - z^{*}\| \|e^{k}\| \quad .$$
(10)

Equations (9) and (10) result in the bound

$$-2\frac{\rho}{N}\langle z^{k}-z^{*},s^{k}\rangle \leq -\frac{\rho\nu}{N}\|z^{k}-z^{*}\|^{2}-\frac{\rho}{2N}\|Sz^{k}\|^{2}+2\frac{\rho}{N}\|z^{k}-z^{*}\|\|e^{k}\| \quad (11)$$

• Bound  $\frac{\rho^2}{N^2 \rho_{\min}} \|s^k\|^2$ : Using again the definition of  $s^k$ , we have that

$$|s^{k}||^{2} = ||Sz^{k}||^{2} + ||e^{k}||^{2} - 2\langle Sz^{k}, e^{k} \rangle$$
  
$$\leq ||Sz^{k}||^{2} + ||e^{k}||^{2} + \frac{\delta}{p_{\min}} ||Sz^{k}||^{2} + \frac{1}{\delta p_{\min}} ||e^{k}||^{2} , \qquad (12)$$

where the inner product term was bounded by employing Young's inequality.<sup>1</sup> We finally get the bound:

$$\frac{\rho^2}{N^2 \rho_{\min}} \|s^k\|^2 \le \frac{\rho^2}{N^2 \rho_{\min}} (1+\delta) \|Sz^k\|^2 + \frac{\rho^2}{N^2 \rho_{\min}\delta} (1+\delta) \|e^k\|^2 \quad . \tag{13}$$

<sup>1</sup>For two nonnegative real numbers x and y, it holds that  $xy \leq \frac{\delta x^2}{2} + \frac{y^2}{2\delta}$  for every  $\delta > 0$ .

Using (11) and (13), inequality (7) can be written as

$$\mathbb{E}[\|z^{k+1} - z^*\|^2 \mid Z^k] \le \|z^k - z^*\|^2 - \frac{\rho\nu}{N} \|z^k - z^*\|^2 + \frac{\rho}{N} \left(\frac{\rho(1+\delta)}{N\rho_{\min}} - \frac{1}{2}\right) \|Sz^k\|^2 + 2\frac{\rho}{N} \|z^k - z^*\| \|e^k\| + \frac{\rho^2}{N^2 \rho_{\min}\delta} (1+\delta) \|e^k\|^2 .$$
(14)

The third term in the sum can be eliminated by asumming that

$$\frac{\rho(1+\delta)}{N\rho_{\min}} - \frac{1}{2} < 0 \Rightarrow \rho < \frac{N\rho_{\min}}{2(1+\delta)} \quad , \tag{15}$$

which gives rise to the inequality

$$\mathbb{E}[\|z^{k+1} - z^*\|^2 \mid Z^k] \le \|z^k - z^*\|^2 - \frac{\rho\nu}{N} \|z^k - z^*\|^2 + 2\frac{\rho}{N} \|z^k - z^*\| \|e^k\| + \frac{\rho^2}{N^2 \rho_{\min}\delta} (1+\delta) \|e^k\|^2$$
(16)

The complicating term on the right hand side can be eliminated by using once more Young's inequality, i.e.,

$$2\frac{\rho}{N} \|z^{k} - z^{*}\| \|e^{k}\| \leq 2\frac{\rho}{N} \left(\frac{\epsilon}{2} \|z^{k} - z^{*}\|^{2} + \frac{1}{2\epsilon} \|e^{k}\|^{2}\right)$$
$$= \frac{\rho\epsilon}{N} \|z^{k} - z^{*}\|^{2} + \frac{\rho}{N\epsilon} \|e^{k}\|^{2} .$$

Using the above in (16) and taking the expectation in both sides, we recover the inequality

$$\mathbb{E}[\|z^{k+1} - z^*\|^2] \le \left(1 - \frac{\rho(\nu - \epsilon)}{N}\right) \mathbb{E}[\|z^k - z^*\|^2] + \frac{\rho}{N} \left(\frac{1}{\epsilon} + \frac{\rho(1 + \delta)}{Np_{\min}\delta}\right) \mathbb{E}[\|e^k\|^2]$$

for  $\rho \in (0, Np_{\min}/(2(1+\delta)))$  and any  $\delta > 0, \epsilon > 0$ , which concludes the proof.

## References

- [1] G. Stathopoulos and C. N. Jones *A coordinator-driven communication reduction scheme for distributed optimization using the projected gradient method*. Proceedings of the 17th IEEE European Control Conference, 2018.
- [2] Peng, Z. and Xu, Y. and Yan, M. and Yin, W. *ARock: an Algorithmic Framework for Asynchronous Parallel Coordinate Updates*. SIAM Journal on Scientific Computing, 2016.
- [3] H.H. Bauschke and P.L. Combettes *Convex Analysis and Monotone Operator Theory in Hilbert Spaces.* Springer, 2011.