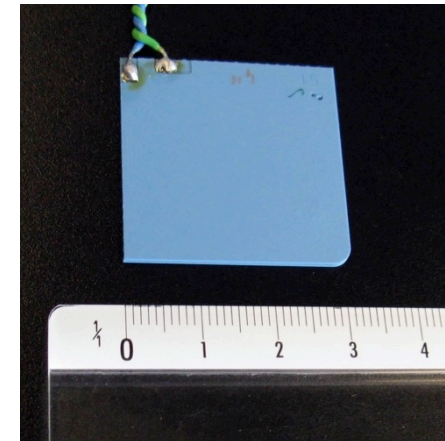
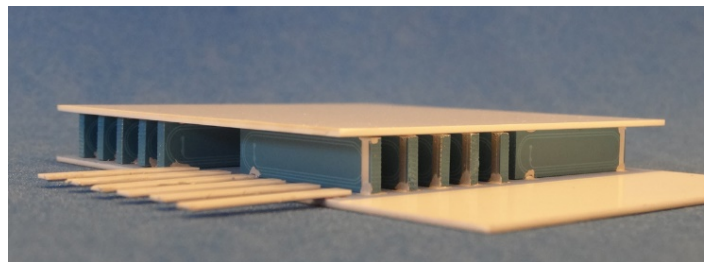
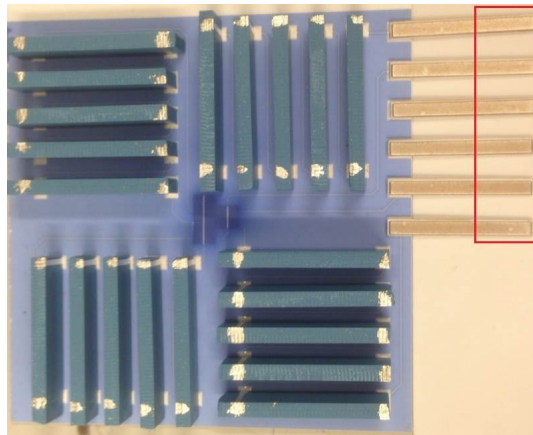


# LTCC and thick-film ceramic magnetic sensors for tokamak nuclear fusion

Thomas Maeder<sup>1</sup>, Caroline Jacq<sup>1</sup>, Duccio Testa<sup>2</sup>, Matthieu Toussaint<sup>2</sup>, Yannick Fournier<sup>1</sup>, Martin Stöck<sup>12</sup>, Gaël Farine<sup>1</sup>, Adrien Corne<sup>12</sup>, Xinyue Jiang<sup>1</sup>, Lucas Güniat<sup>12</sup>, Benoît Ellenrieder<sup>12</sup>, Philipp Windischhofer<sup>12</sup>, Christian Schlatter<sup>2</sup>, and Peter Ryser<sup>1</sup>

- 1) EPFL–LPM / *Laboratoire de production microtechnique*
- 2) EPFL – SPC / Swiss Plasma Center



# Outline

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- 1. Introduction**
- 2. Coil-type magnetic sensors**
- 3. LTCC 1D sensor**
- 4. LTCC 3D sensor**
- 5. Connection issues**
- 6. Conclusion & outlook**

## 1. Introduction

- Tokamak nuclear fusion
- LTCC & thick-film technology

## 2. Coil-type magnetic sensors

## 3. LTCC 1D sensor

## 4. LTCC + thick-film 3D sensor

## 5. Interconnection and packaging

## 6. Conclusion & outlook

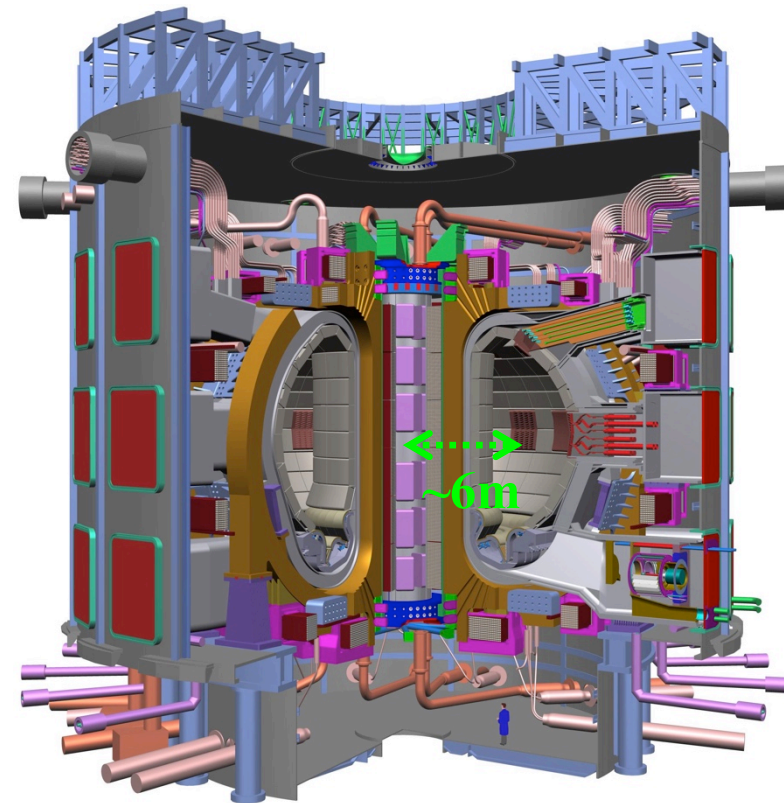
# ITER – Int'l thermonuclear exp. reactor

**Goal: demonstrate feasibility of fusion energy for peaceful purposes**

- Tokamak machine
- $Q \geq 10$  more energy from fusion than required for plasma heating
- Burning plasma physics
- Power:  $P_{\text{fusion}} \geq 500$  MW

Plasma Volume: 840 m<sup>3</sup>  
Nominal Plasma Current: 15 MA  
Typical Temperature: 20 keV  
Typical Density: 10<sup>20</sup> m<sup>-3</sup>  
Pulse Length >1'000 s

$R \sim 6.2$  m;  $B_T \sim 5.3$  T;  
 $I_p \sim 15$  MA



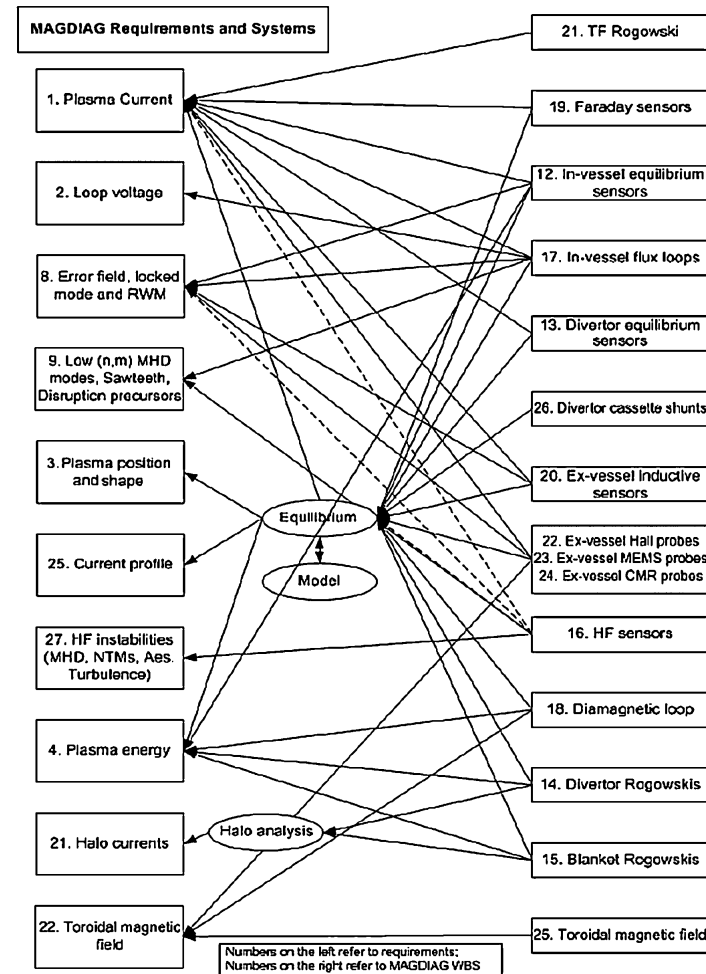


# Magnetic diagnostics

## > 1'000 sensors envisioned for ITER!

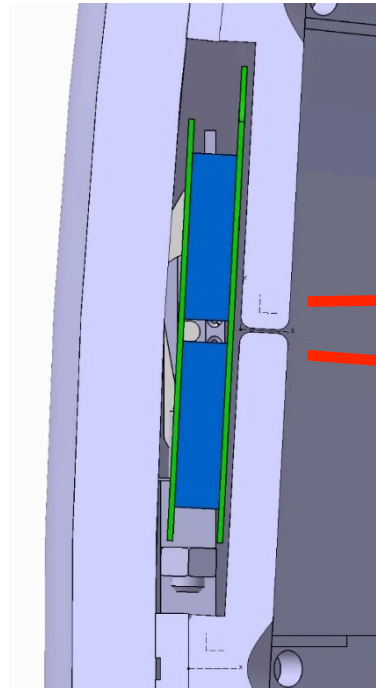
- Redundancy -> reliability
- Different technologies
  - Many sensor types
  - In-vessel & ex-vessel
  - Different environments
    - More or less harsh ( $T$ ,  $\Delta T$ )
  - High neutron flux
- Magnetic coils:
  - LF, equilibrium,  $< \sim 1$  kHz
  - HF, MHD instabilities,  $< \sim 300$  kHz

Testa-D Chavan-R Guterl-J Lister-JB et al., IEEE Transactions on Plasma Science 38 (3), 284-294, 2010.

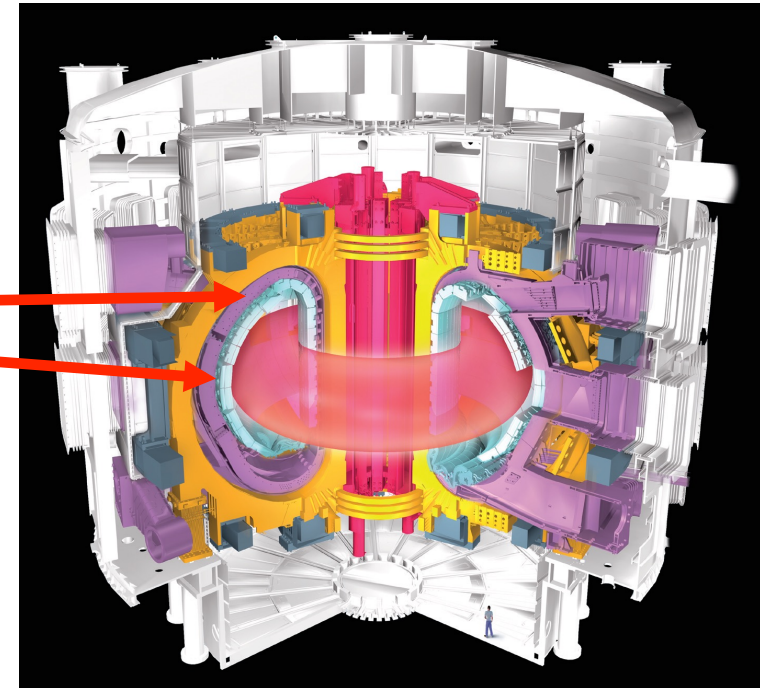


# Magnetic sensors in walls

- Magnetic sensors behind the protection tiles
- Measure magnetic field disruptions (both LF and HF)
- Different sensors for LF & HF domains



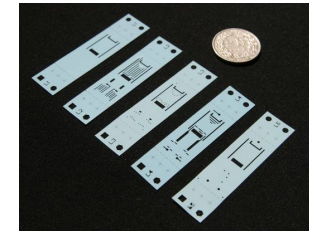
Cross-section of  
the external  
walls



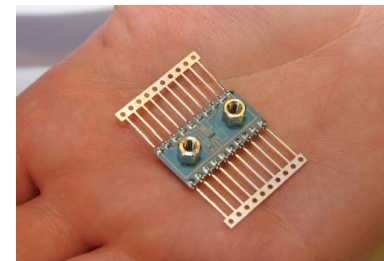
Tokamak

# Thick-film technology & LTCC

- Thick-film / LTCC circuit : series of layers
- Each layer comes as a paste:
  - Functional material (as powder)
  - Organic vehicle: binder + solvent
  - Conductors, resistors, dielectrics, catalyst
  - Screen-printing with a mask

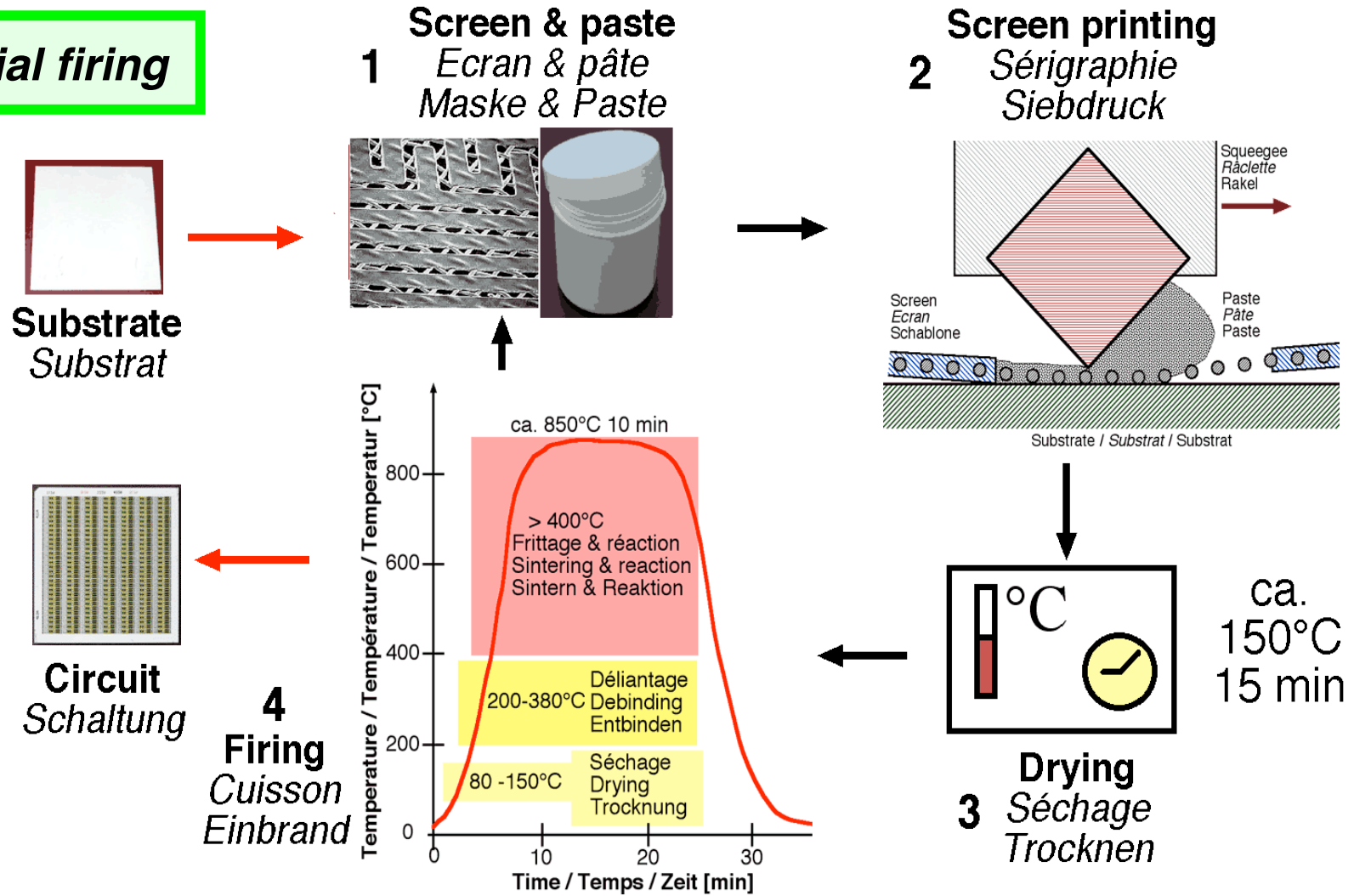


	<b>Thick-film</b>	<b>LTCC</b>
Substrate	Alumina	LTCC tape
Multilayer dielectric	Extra printed ink	LTCC tape
Firing	Sequential	Together (co-firing)



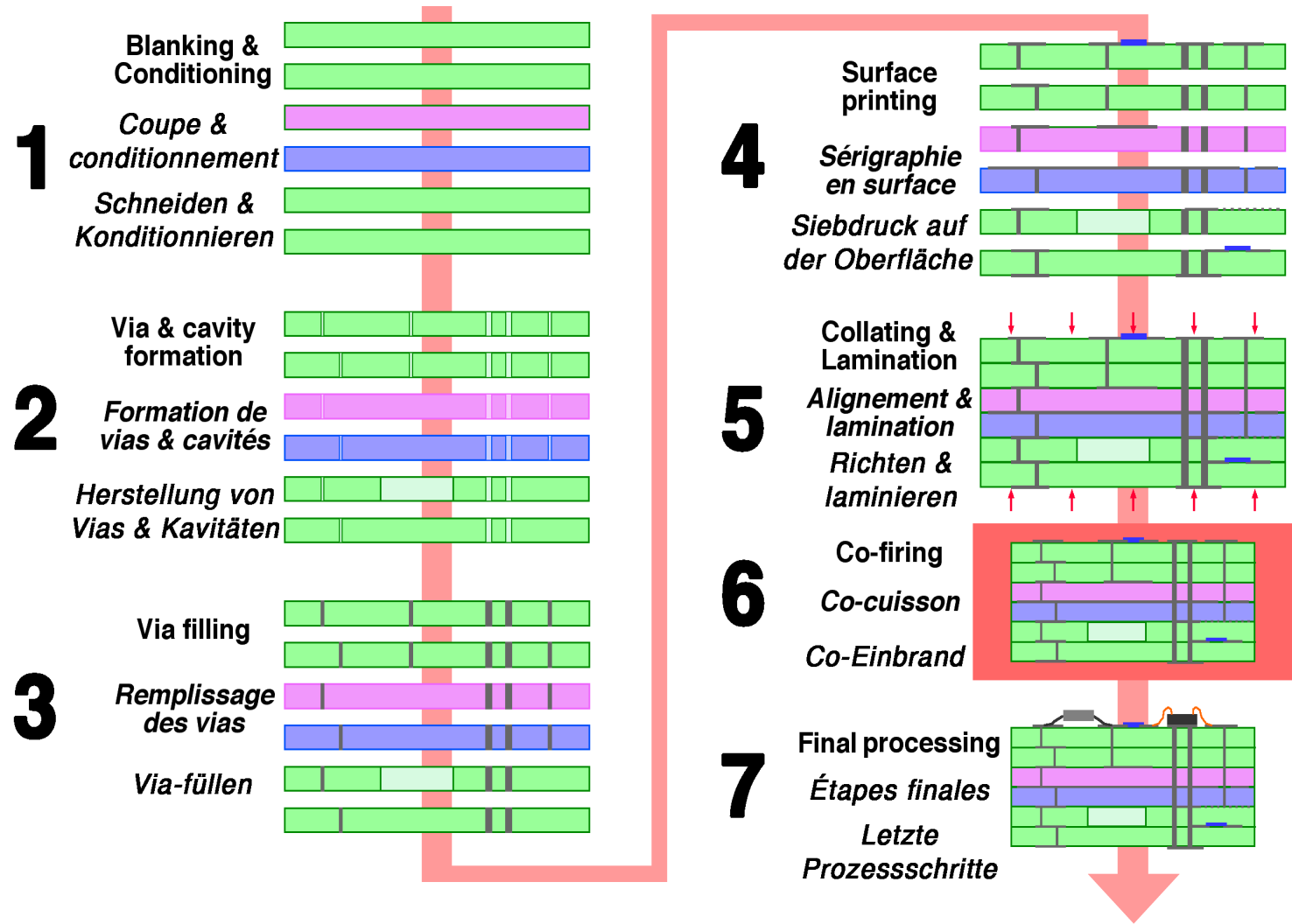
# Thick-film - process flow

## Sequential firing



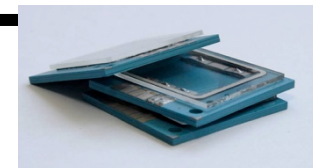
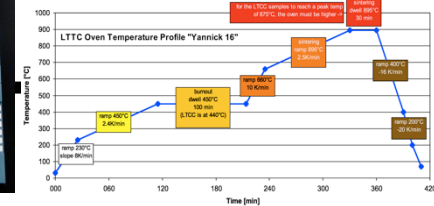
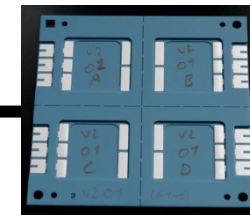
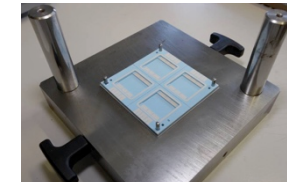
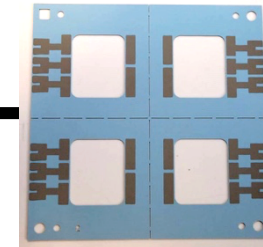
# LTCC - process flow

## Co-firing



# LTCC - principle

1. Raw sheets easily cut  
(laser, punch tool)
2. Formation of vias & cavities
3. Vias filled for interlayer contacts
4. Layers individually printed  
(multilayer circuits )
5. Stacking & lamination of layers to  
get a 3D structure
6. Firing  
-> sintering, monolithic circuit
7. Individualisation and post-firing  
(assembly by soldering)





# LTCC – the material

## a. Tapes

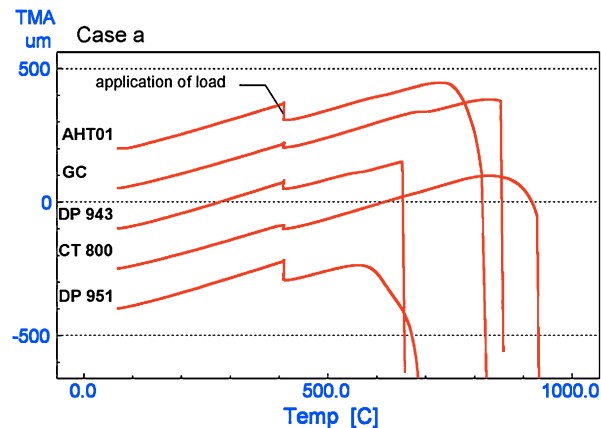
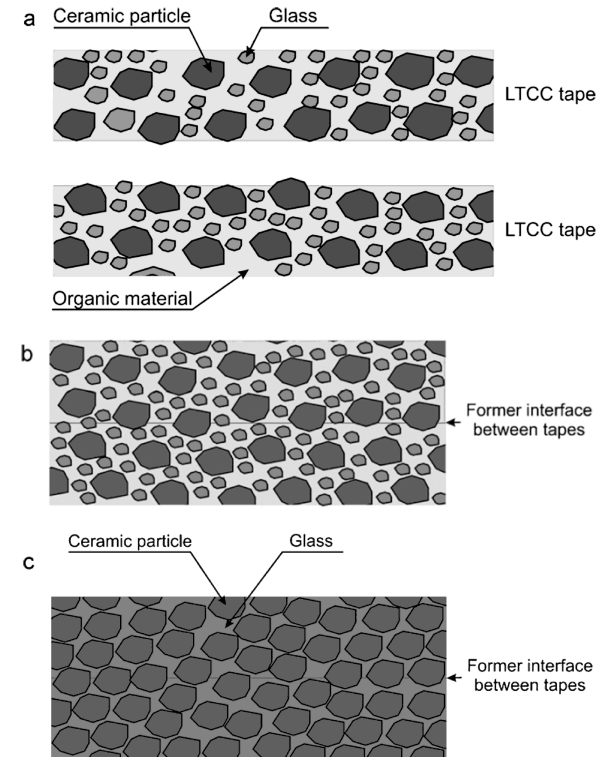
- Organic binder matrix
- Glass + ceramic powder

## b. Lamination

- Joining through organic binder

## c. Firing

- Debinding – **critical step!**
- Viscous sintering with glass
- Crystallisation by **glass-ceramic** reaction



Bienert-C Roosen-A, Journal of the European Ceramic Society 30 (2), 369-374, 2010.

Jurków-D Golonka-L, "Low-pressure, thermo-compressive lamination", J. Eur. Ceram. Soc. 32 (10), 2431–2441, 2012.

All compositions OK @500°C //  
**DuPont / DP951**

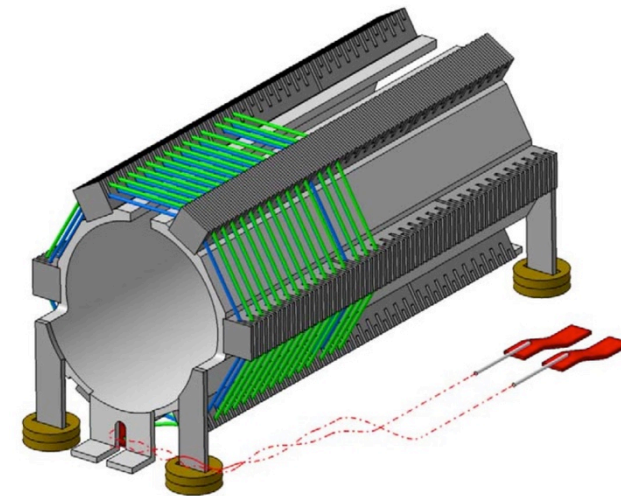


1. Introduction
- 2. Coil-type magnetic sensors**
3. LTCC 1D sensor
4. LTCC + thick-film 3D sensor
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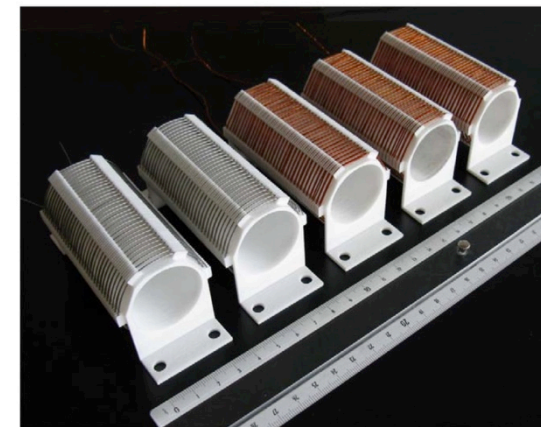
- **Classical Mirnov coils**
- **Monolithic ceramic coils**
- **Materials & design issues**

# Mirnov-type coils

- ITER reference design
  - 80×40×40 mm<sup>3</sup> – bulky!
  - $NA_{\text{eff}} \sim 670 \text{ cm}^2$  - OK
  - Slotted stainless-steel body
  - Ceramic guides
  - Two layers of W wire
  - Wire exposed
  - W stiff, brittle -> difficult
  
- ***Need compact, monolithic solution***



ITER reference design: 80×40×40 mm<sup>3</sup>

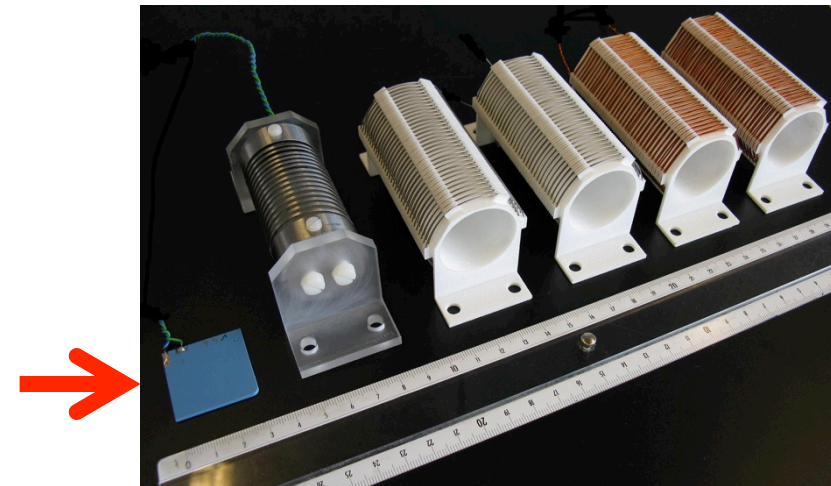


Alternative designs (W or Cu wire)

Toussaint-M Testa-D Baluc-N Chavan-R Fournier-Y Lister-  
JB Maeder-T Marmillod-P Sanchez-F Stöck-M, Fusion  
Engineering and Design 86 (6-8), 1248-1251, 2011.

# LTCC magnetic sensors for tokamaks

- Much smaller sensor than traditional Mirnov coils
  - Volume ~1:20!
- Similar effective area & properties
- Intimate contact between winding and ceramic support
- Winding shielded from external environment (plasmas, ...)



LTCC 1D sensor (left) vs traditional Mirnov coils (right)

- **Presumably more robust**
- **Low profile – mounting in wall, behind protection tiles**

# Magnetic coils for tokamaks

Signal (ideal):

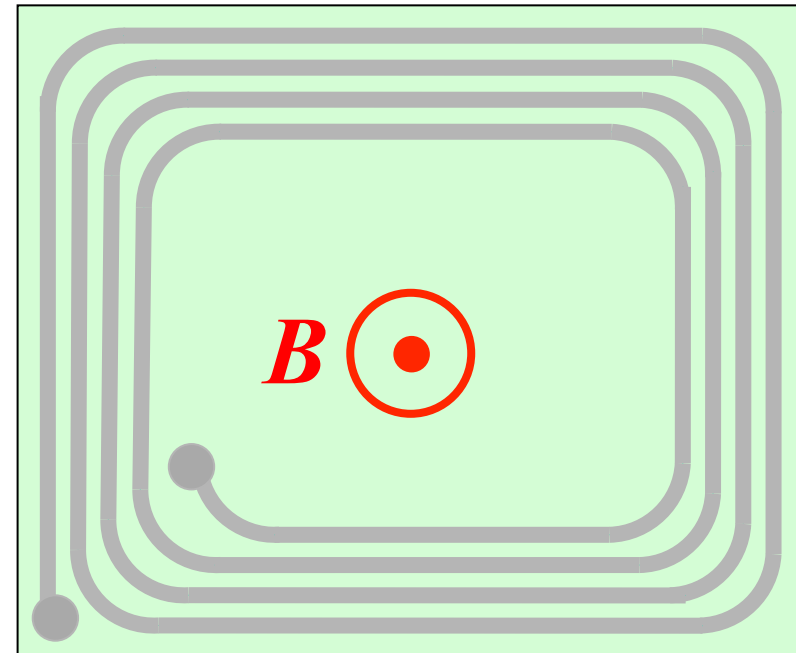
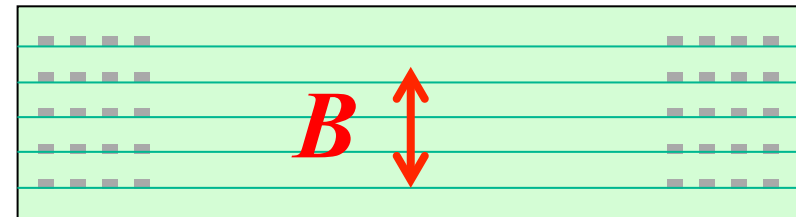
$$U_{AC} = i \cdot \omega \cdot B_{AC} \cdot NA_{eff}$$

- $U_{AC}$  : signal voltage
- $\omega$  : angular frequency
- $B_{AC}$  : magnetic field
- $NA_{eff}$  : effective integral coil area



- Signal  $U$  ?
- Capacitance  $C$  ?
- Inductance  $L$  ?
- **Resonance:**

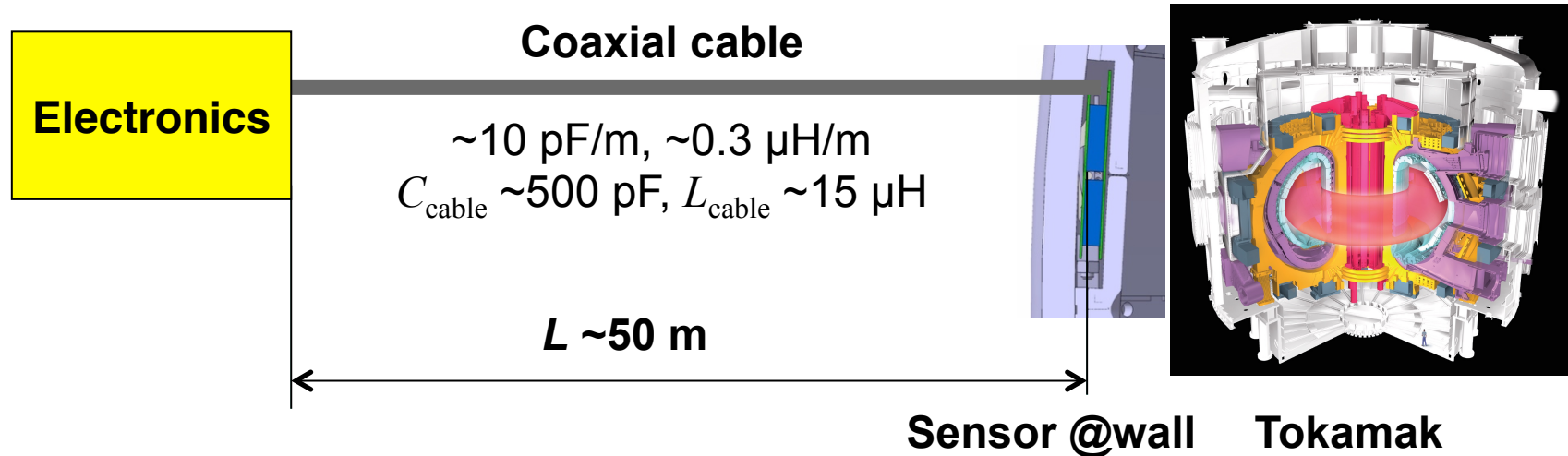
$$2\pi \cdot f_{res} = \omega_{res} = (L \cdot C)^{-0.5}$$



Multiple turns parallel and perpendicular to the magnetic field

# Magnetic coils for tokamaks

Long cables due to high-energy neutron flux!



- Capacitance  $C$  :  $C_{\text{cable}}$  dominant
- Inductance  $L$  :  $L_{\text{self}}$  dominant – **minimise!**
- **Resonance:**

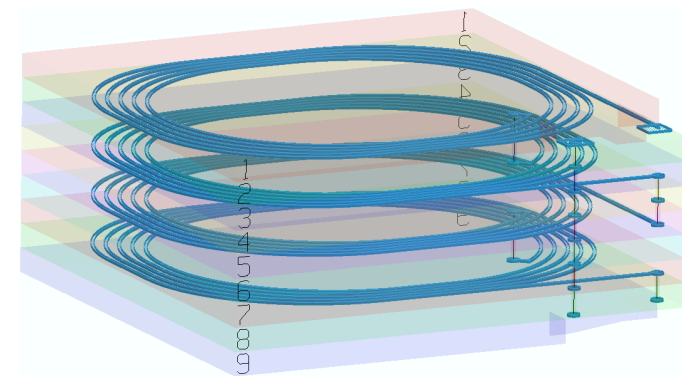
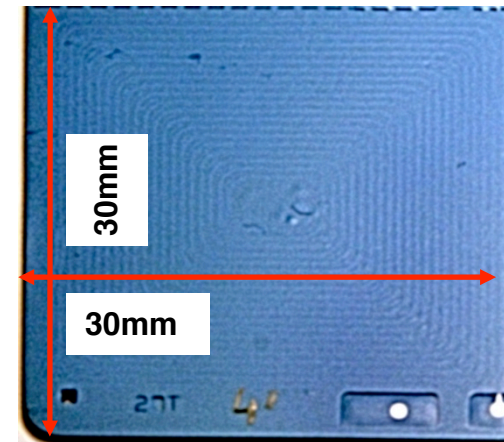
$$2\pi \cdot f_{\text{res}} = \omega_{\text{res}} = (L \cdot C)^{-0.5}$$

1. Introduction
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- **Design & variants**
- **Results**
- **Conclusion - design rules**

# 1D LTCC HF magnetic sensor design

- Size: 30 x 30 x (0.7...2.4) mm<sup>3</sup>
- Body material: LTCC glass-ceramic
  - DuPont / DP 951
- Wire material: silver / Ag
- Stack of layers electrically connected by via holes filled with metallic ink
- Metallic ink printed on each active layer



**1<sup>st</sup> generation 1D sensor & coil design**

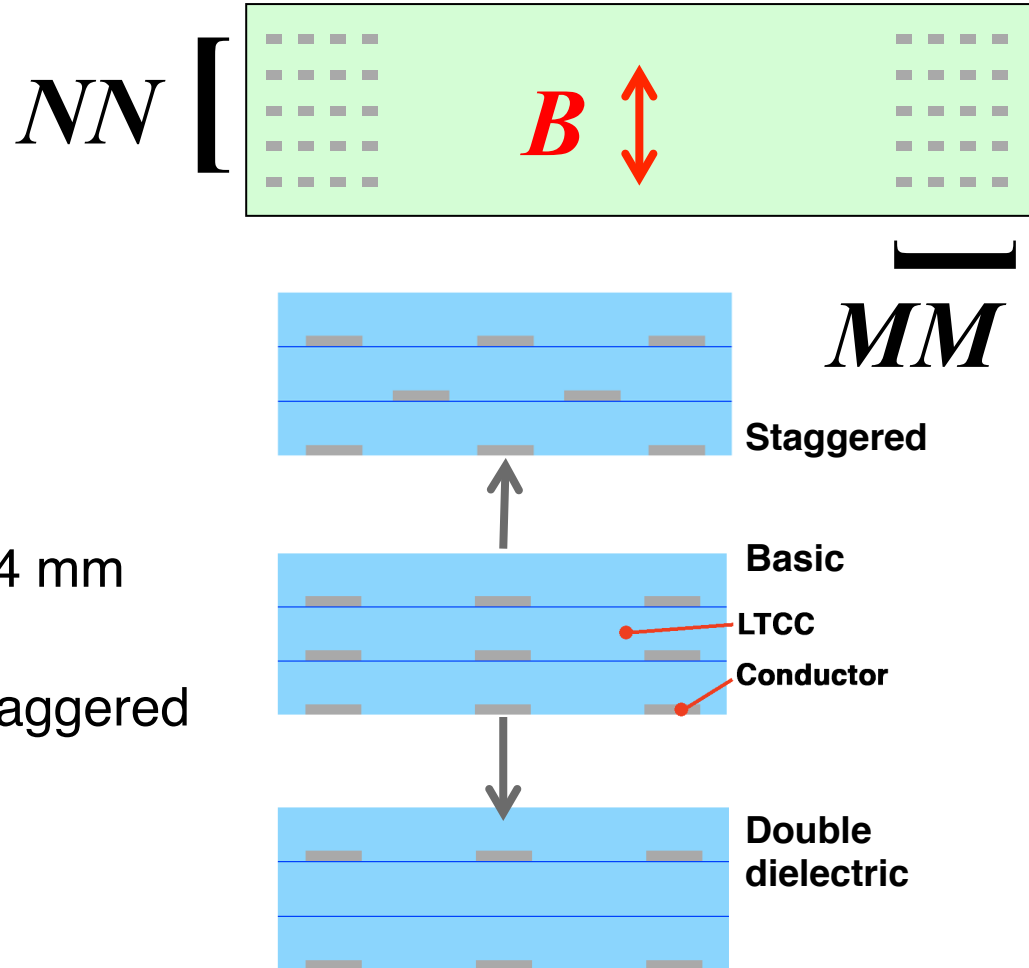
Testa-D Fournier-Y Maeder-T Toussaint-M Chavan-R Guterl-J Lister-JB Moret-JM Schaller-B Tonetti-G, Fusion Science and Technology 59 (2), 376-396, 2011, <http://infoscience.epfl.ch/record/164698>



# 1D LTCC HF magnetic sensor variants

## Parameters

- Number of turns/layer:
  - $MM = 5, 10$  and  $20$
- Number of layers:
  - $NN = 2, 4, 6, 8$  and  $10$
- Interlayer
  - Thickness:  $0.22$  mm or  $0.44$  mm (1 or 2 LTCC tapes)
  - Arrangement: straight or staggered



Testa-D Fournier-Y Maeder-T Toussaint-M Chavan-R Guterl-J Lister-JB Moret-JM Schaller-B Tonetti-G, Fusion Science and Technology 59 (2), 376-396, 2011, <http://infoscience.epfl.ch/record/164698>

# 1D LTCC HF magnetic sensor results

## ■ Self-resonance frequency

- $f_{res,self}$  from 1.1 to >15 MHz

## ■ Resistance:

- $R_{self} = 7...100 \Omega$
- Model easy, only requires total wire length

## ■ Inductance

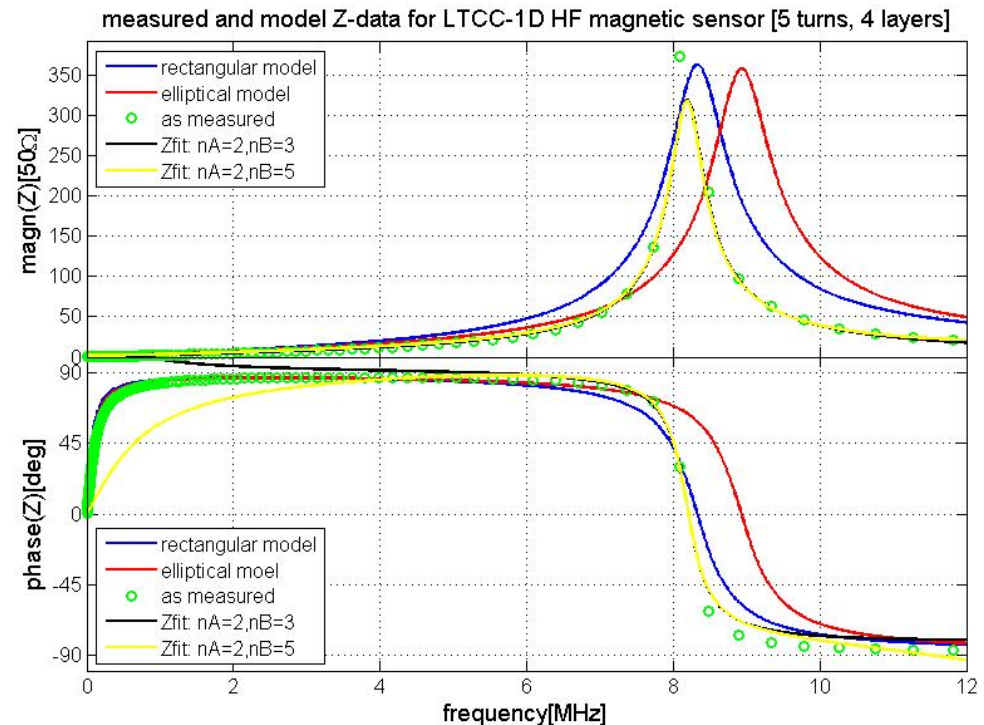
- $L_{self} = 5...595 \mu H$
- Very sensitive to design, accurate model needed

## ■ Capacitance

- $C_{self} : 22...58 \text{ pF}$
- Much smaller than that due to signal cables  $\sim 10 \text{ pF/m} \rightarrow 500 \text{ pF}$
- Accurate model not needed

## ■ Good agreement between circuit models & measurements

## ■ Meeting ITER requirements possible in principle

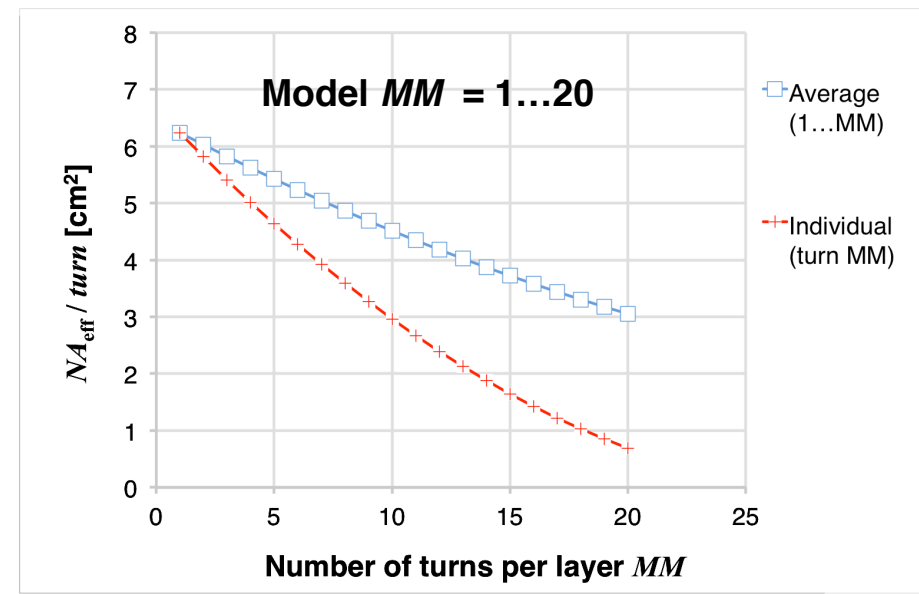
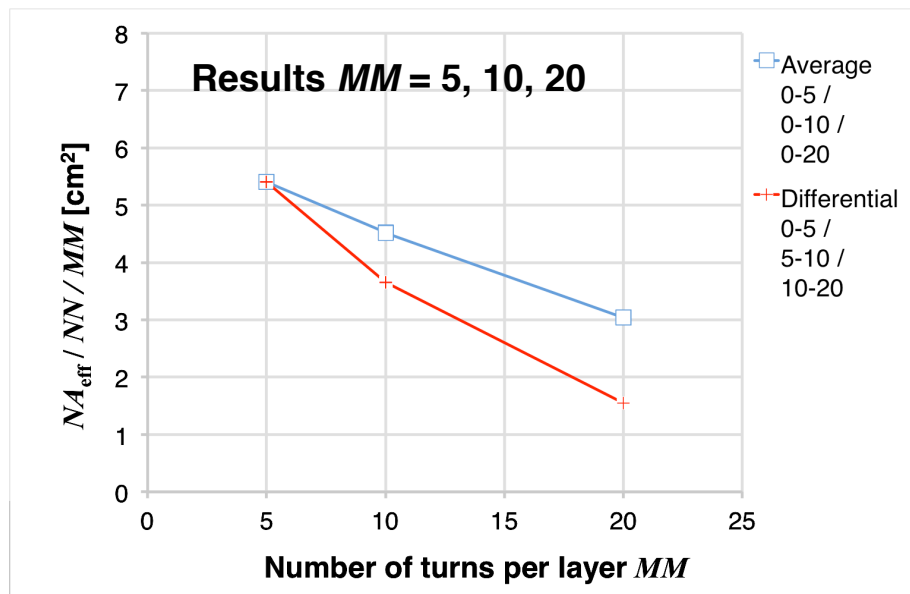


Measurement vs modelling

# 1D LTCC HF magnetic sensor results

## Some design rules:

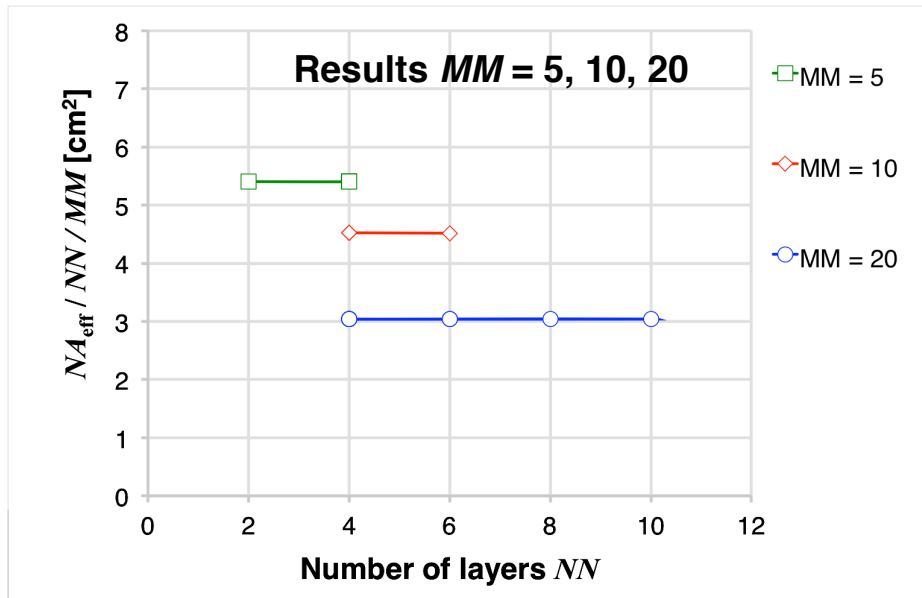
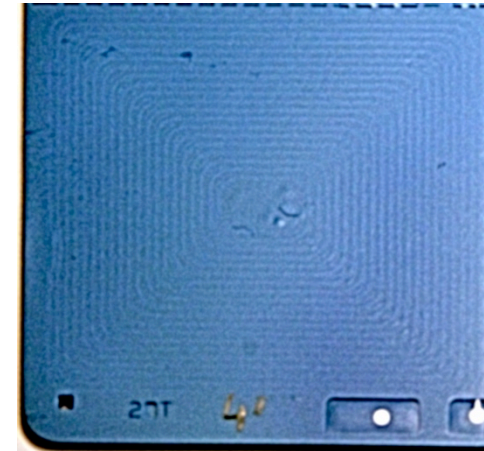
- Turns per layer  $MM$  : compromise
  - Small contribution of inner turns to  $NA_{\text{eff}}$
  - Increase of  $L_{\text{self}}$
  - Surface / resistance  $\sim$  perimeter
  - **But: low-cost, reliable** (no additional layers)



# 1D LTCC HF magnetic sensor results

## Some design rules:

- **Layers  $NN$  : increase**
  - Linear contribution to  $NA_{\text{eff}}$
  - But: strong increase of  $L_{\text{self}}$ 
    - $\sim NN^2$  for 0 diel. thickness, in practice smaller
  - More layers required (complexity, yield, cost)



## ■ Interlayer:

- Staggered winding not needed (small effect, only on  $C_{\text{self}}$ )
- **Increase spacing to especially decrease  $L_{\text{self}}$**
- More vias, more cost
- *Other alternatives for 3D*

1. Introduction
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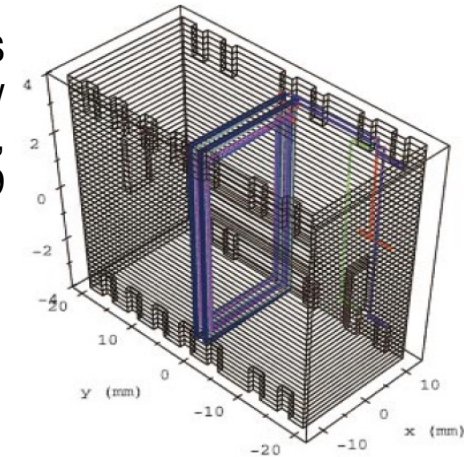
- **Introduction – previous work**
- **New concept & design**
- **Conclusion - design rules**

# 3D ceramic magnetic sensor

## ■ Sensing in X, Y, Z

- Practical, compact sensor
- Crosstalk, fabrication ???

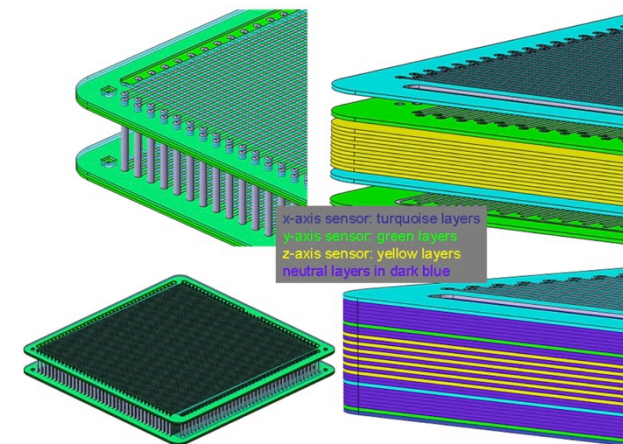
Takahashi-H Sakakibara-S  
Kubota-Y Yamada-H, Review  
of Scientific Instruments 72,  
2001, 3249-3259



## ■ Previous work

- First 3D attempts at PPPL using HTCC technology in 1999
- Idea abandoned due to high cost, poor yield (1'000s of vias)
- Also: difficult to design, high coupling, ...

## ■ New ideas needed!



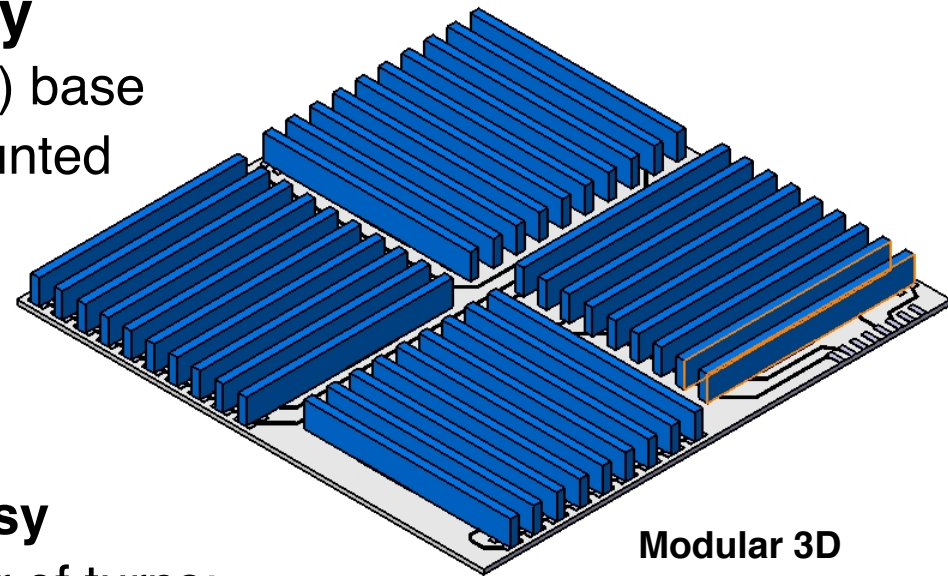
Our first 3D sensor concept



# 3D ceramic magnetic sensor concept

## ■ Mixed, modular technology

- Z: classical thick-film (alumina) base
- XY: LTCC modules, edge-mounted
- Relatively low-profile
- *Separation between XY coils*



Modular 3D  
sensor  
concept

## ■ Production

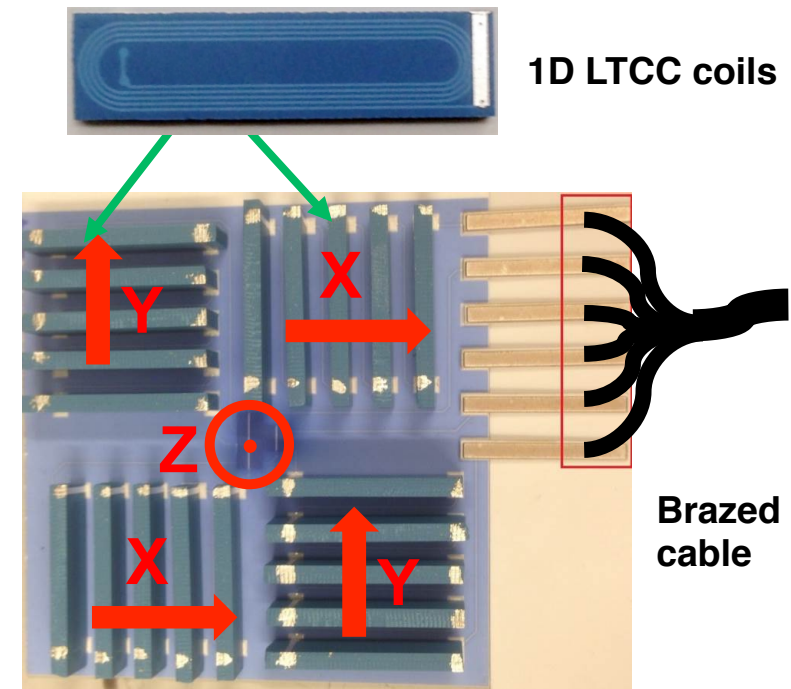
- Base with ~square Z coil – **easy**
- LTCC "sticks" with low number of turns:
  - Production easy, winding in LTCC plane
  - Simple, low via count – **good yield**
  - Can be pre-tested before mounting – **good overall yield** as well
- **Issue: assembly**



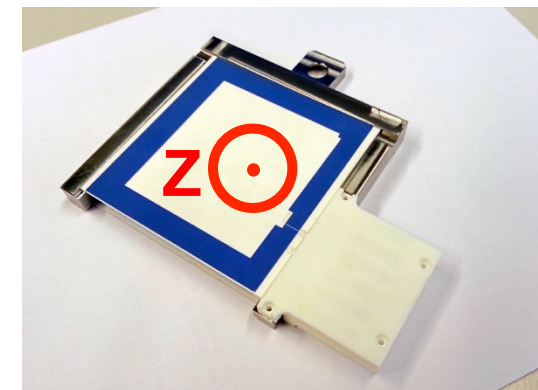
# 3D ceramic magnetic sensor design

- **Design – Z**
  - Large area in base, high  $NA_{\text{eff}}$  easy
  
- **Design – XY**
  - Small area – low height
  - **Small 1D LTCC X & Y modules**
  - Multiply to achieve higher  $NA_{\text{eff}}$
  - Fully coupled  $L_{\text{self}} \sim N^2$
  - Fully separate:  $L_{\text{self}} \sim N$
  - Compromise: 10 in series with low  $N$ , mounting at some distance to minimise inductive coupling

Testa-D Corne-A Farine-G Jacq-C Maeder-T Toussaint-M, "3D, LTCC-type, high-frequency magnetic sensors for the TCV Tokamak", Fusion Engineering and Design 96-97, 989-992, 2015, <http://infoscience.epfl.ch/record/206105>



3D magnetic sensor (V2) elements on base

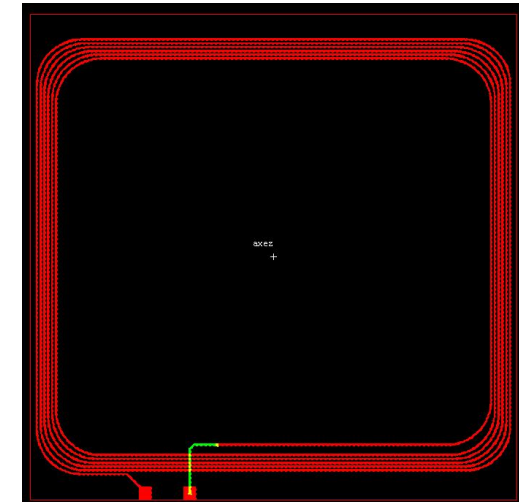


Sensor V2 - bottom of base with Z coil

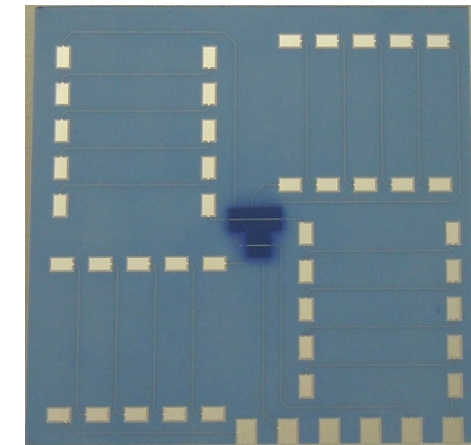
# 3D ceramic magnetic sensor – Z coil

## Single coil on back of base

- $NA_{\text{eff}} = 178 \text{ cm}^2$
- $R_{\text{self}} = 17 \Omega$
- $L_{\text{self}} = 7.4 \mu\text{H}$
- $f_{\text{res}} > 12 \text{ MHz}$ 
  - Still good with cables due to low  $L_{\text{self}}$
  - With  $C_{\text{cable}} = 500 \text{ pF}$ ,  $\sim 2.6 \text{ MHz}$
- *Favourable, high  $NA_{\text{eff}}$  with low  $R_{\text{self}}$  &  $L_{\text{self}}$*



V2 -bottom of base with  
Z coil



V2 - top of base for  
mounting XY coils (&  
last half-turn)

Testa-D Corne-A Farine-G Jacq-C Maeder-T  
Toussaint-M, "3D, LTCC-type, high-frequency  
magnetic sensors for the TCV Tokamak", Fusion  
Engineering and Design 96-97, 989-992, 2015,  
<http://infoscience.epfl.ch/record/206105>

# 3D sensor – XY coil – LTCC optimisation

Type	$MM$	$NN$	$NA_{\text{eff}}$ [cm <sup>2</sup> ]	$R_{\text{self}}$ [Ω]	$L_{\text{self}}$ [μH]
Old	4.5*	13	77	28	60
New	2.5*	9	38	9	12



Testa-D Corne-A Farine-G Jacq-C Maeder-T Toussaint-M, "3D, LTCC-type, high-frequency magnetic sensors for the TCV Tokamak", Fusion Engineering and Design 96-97, 989-992, 2015,

<http://infoscience.epfl.ch/record/206105>

- Turns =  $MM \times NN + 0.5$  (in base) = 59 / 23
- Sensor V2

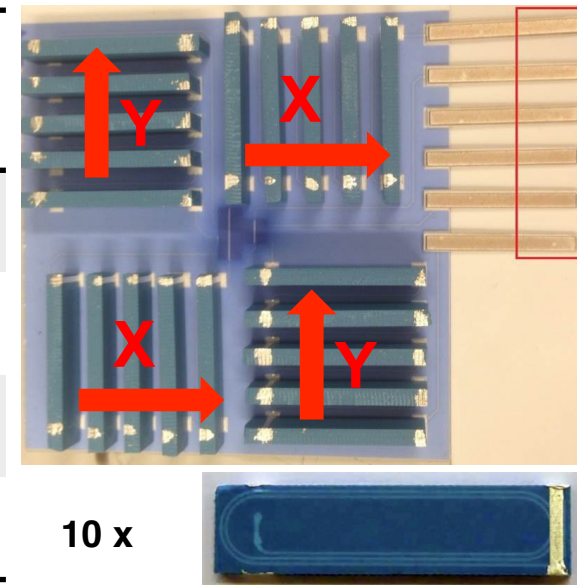
## ■ Ratios

- $NA_{\text{eff}}$  : ~2:1
- $R_{\text{self}}$  : ~3:1
- $L_{\text{self}}$  : ~5:1

- Numbering up simpler elements to minimise  $L_{\text{self}}$  &  $R_{\text{self}}$

## 3D sensor – XY coil – overall

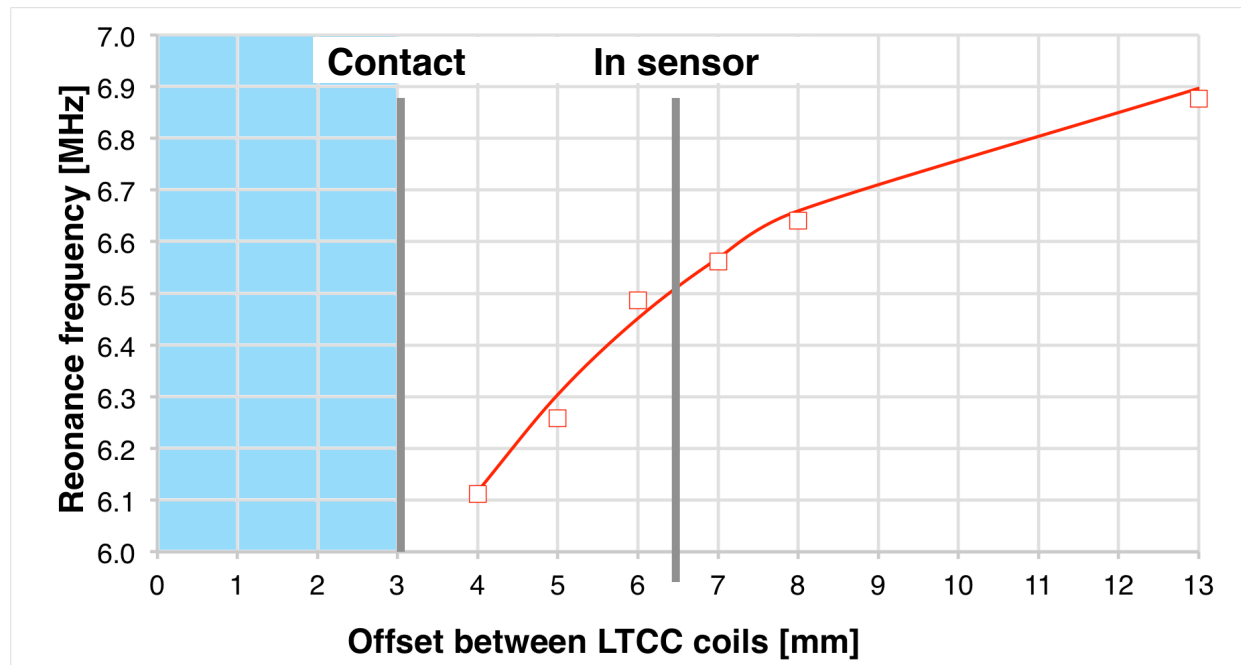
(New LTCC coils)	$NA_{\text{eff}}$ [cm <sup>2</sup> ]	$R_{\text{self}}$ [Ω]	$L_{\text{self}}$ [μH]	$f_{\text{res}}$ [MHz]
Sensor X	298	127	158	~5.5
10 x single	376	90	123	>12
$\Delta$	-78	37	35	
$\Delta_{\text{rel}}$	-21%	+41%	+28%	



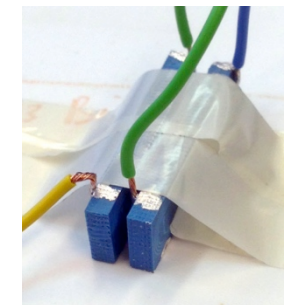
### Whole X sensor vs 10x LTCC module (additivity) ?

- $NA_{\text{eff}}$  : mounting differences (angles & distance to base)
- $R_{\text{self}}$  : extra wiring in base for routing
- $L_{\text{self}}$  : mutual coupling between adjacent LTCC modules
- $f_{\text{res}}$  : wiring capacitances
  - Not so relevant, as  $C_{\text{self}} \ll C_{\text{cable}}$  : For 500 pF, 0.57 vs 0.64 MHz

# 3D sensor – XY coil separation



Corne-A, "Capteur de champ magnétique 3D pour fusion nucléaire",  
Projet de semestre,  
Section de  
microtechnique, LPM,  
EPFL, Lausanne (CH),  
2014.



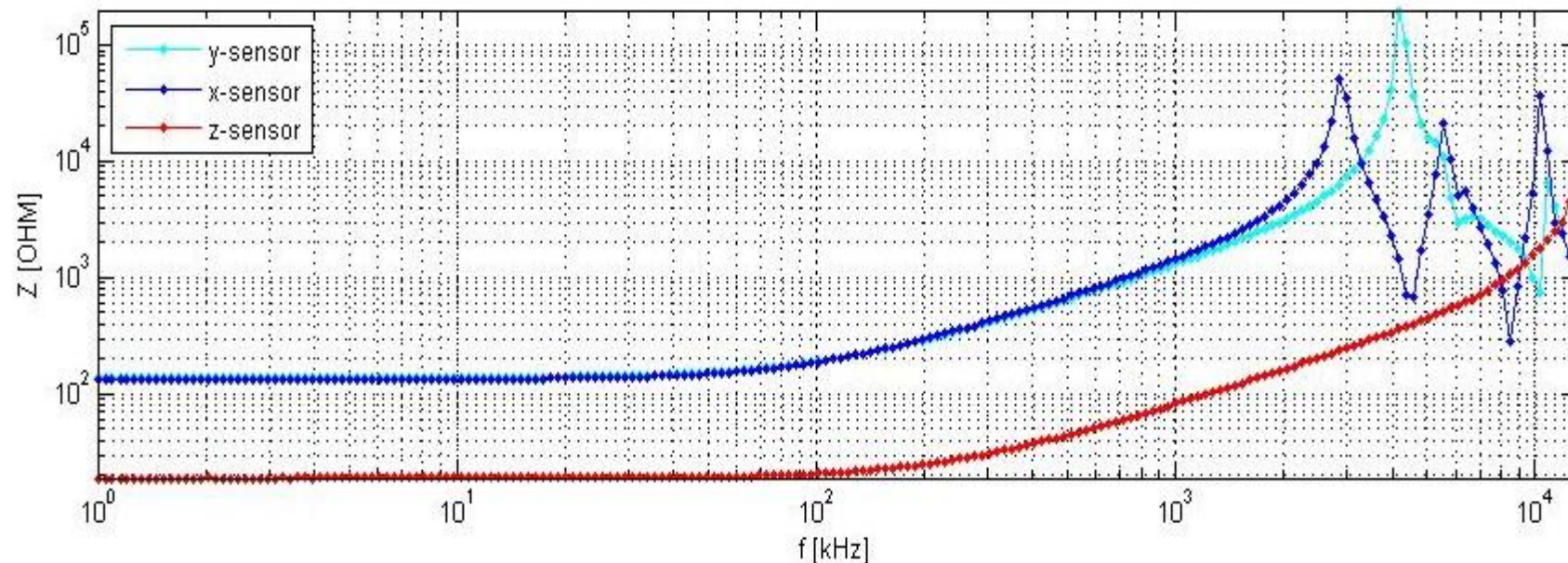
## Interaction between two adjacent coils (old type)

- Narrow coil (max. ~6 mm) – fast decrease with distance
  - Also valid for new coils – same width
- Rough agreement with sensor results
  - $\Delta L/L \sim +28\% \rightarrow \Delta f/f$  should be  $-(\Delta L/L)^{0.5} \sim -13\%$

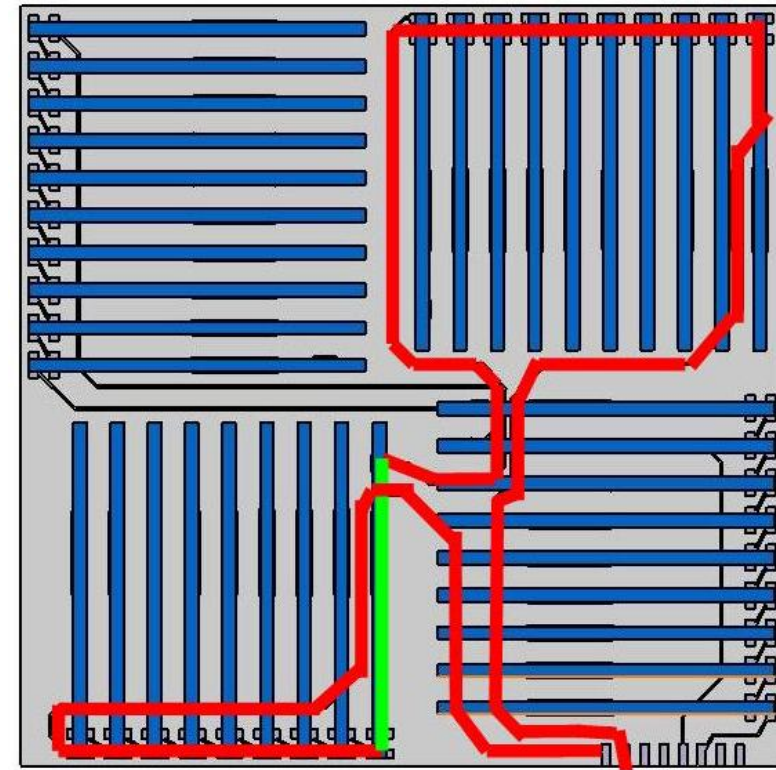
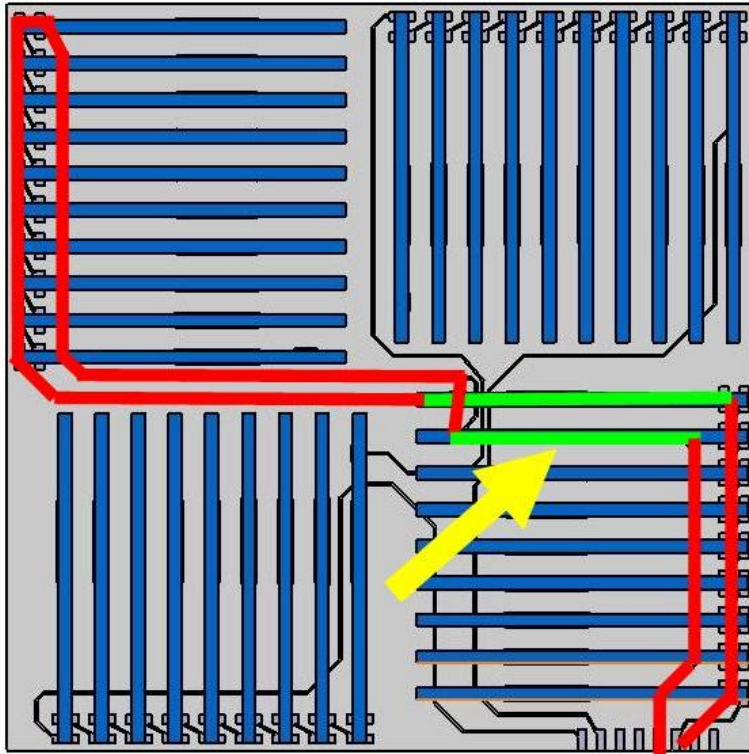


# LTCC-3D sensor-V1: electrical data

- Design OK:  $L_{\text{SELF,TOT}} \propto N_{\text{TURNS}} * L_{\text{TURN}} + L_{\text{MUT}}$  instead of  $\propto (N_{\text{TURNS}})^2 * L_{\text{TURN}}$
- However significant improvements are needed:
  - $\delta B_{\text{POL}}$  (x-axis),  $\delta B_{\text{TOR}}$  (y-axis): clearly different electrical characteristics (should be exactly the same) and very large parasitic coupling ( $NA_{\text{PAR}}/NA_{\text{EFF}} > 10\%$ )
  - Parasitic effective area  $\delta B_{\text{RAD}}$  (z-axis) also too large,  $\sim 10\%$  (should be  $< 2\%$ )



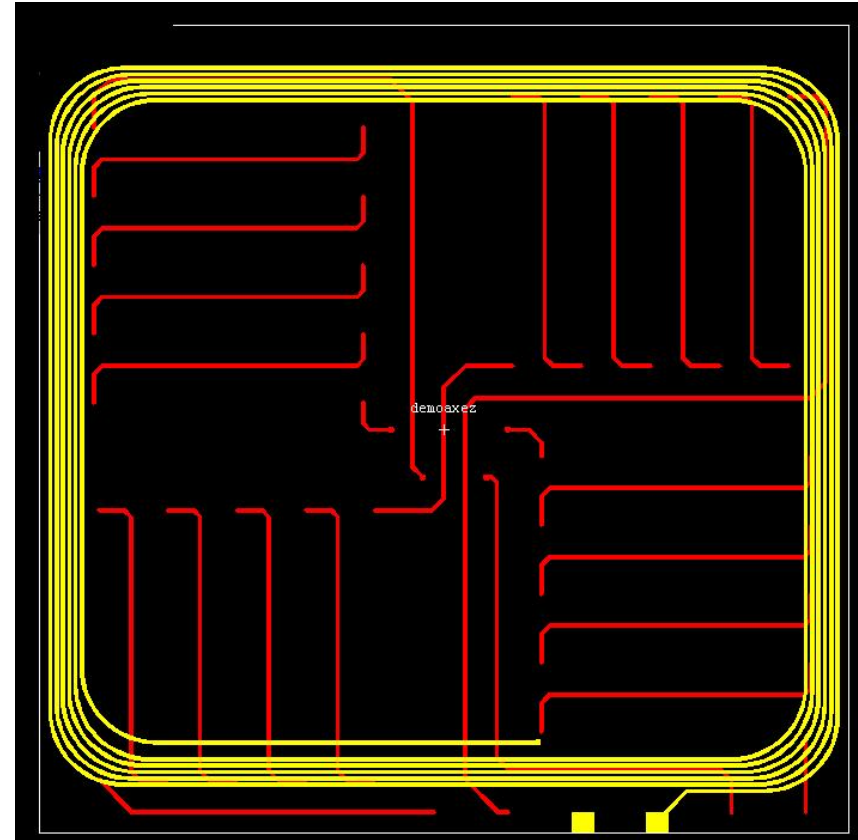
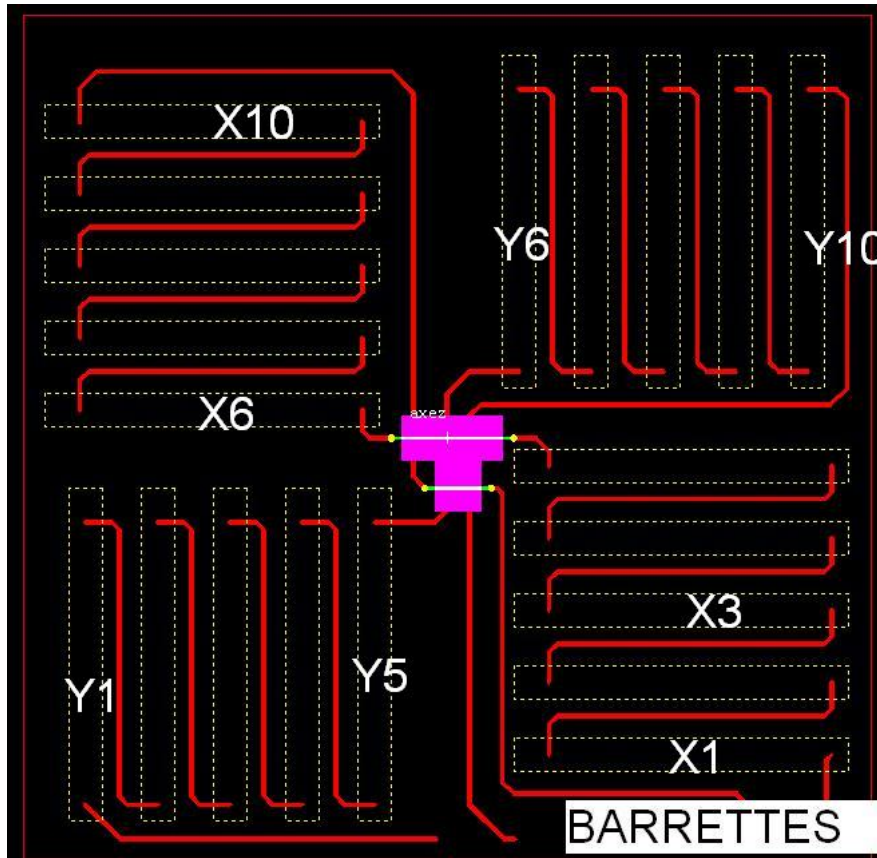
# 3D sensor V1 – on-board wiring



- On-board wiring: large parasitic loops and mutual inductances between all three measurement axes
- Improvement needed: optimise to avoid / reduce loops

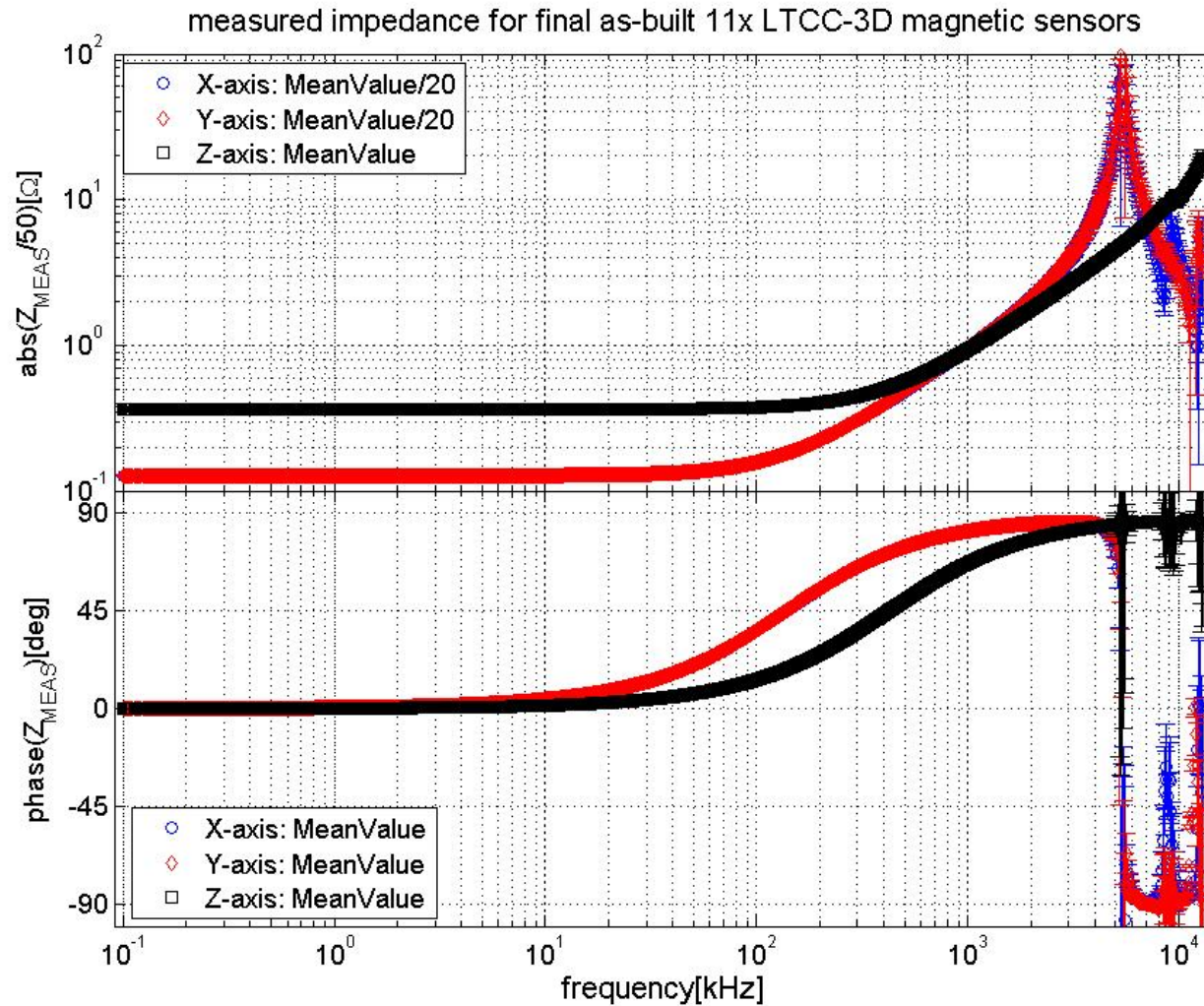


# Sensor V2 – optimised on-board wiring



- Optimized design of on-board wiring up to output connection pads
- Reduced parasitic loops and mutual coupling

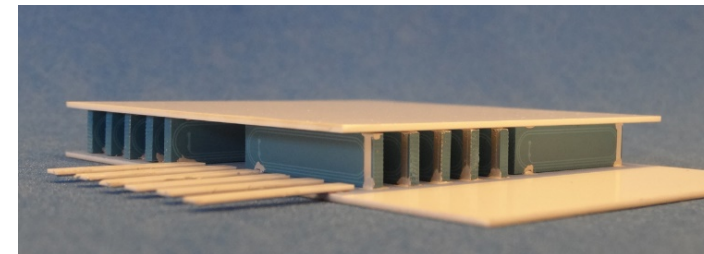
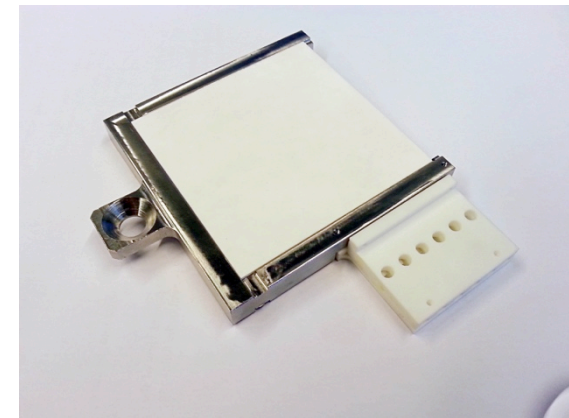
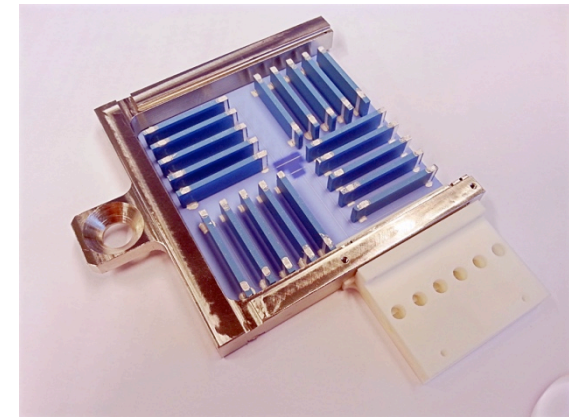
# LTCC 3D sensors: impedance data



# 3D sensor – conclusions

## Working 3D sensor developed

- Innovative modular concept for XY
  - Simple LTCC edge-mounted solenoids
  - Good yield, separation -> low  $L_{\text{self}}$
  
- Sufficient  $NA_{\text{eff}}$ 
  - X/Y/Z :  $\sim 300/260/180 \text{ cm}^2$
  
- High resonance frequencies
  - XY :  $\sim 5.5 \text{ MHz}$  ; Z :  $> 12 \text{ MHz}$
  - With  $C_{\text{cable}} = 500 \text{ pF}$ : XY/Z  $\sim 0.6/2.6 \text{ MHz}$
  
- Mounted in EPFL-SPC TCV
  - *Tokamak à Configuration Variable*



# Outline (3)

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1. Introduction
2. Coil-type magnetic sensors
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4. LTCC + thick-film 3D sensor
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6. Conclusion & outlook



# Mounting LTCC sensors onto base

## Preparation

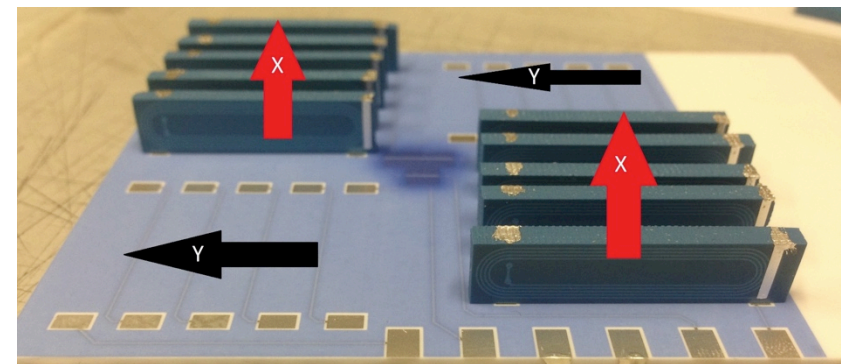
- Metallisation of LTCC modules on edges (post-firing Ag conductor)

## High-temperature connection to base

- Fritted Ag conductor + additional low-melting glass to improve bonding
- Also for lid
- Possible alternatives
  - Ag pressure sintering
  - Brazing (risk of Ag leaching)
  - Special soldering (e.g. TLP)

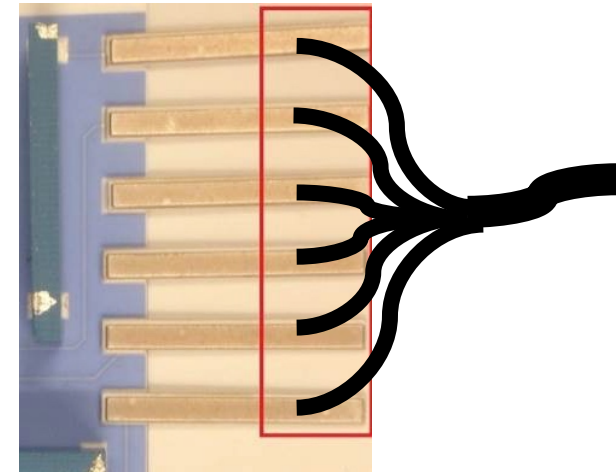
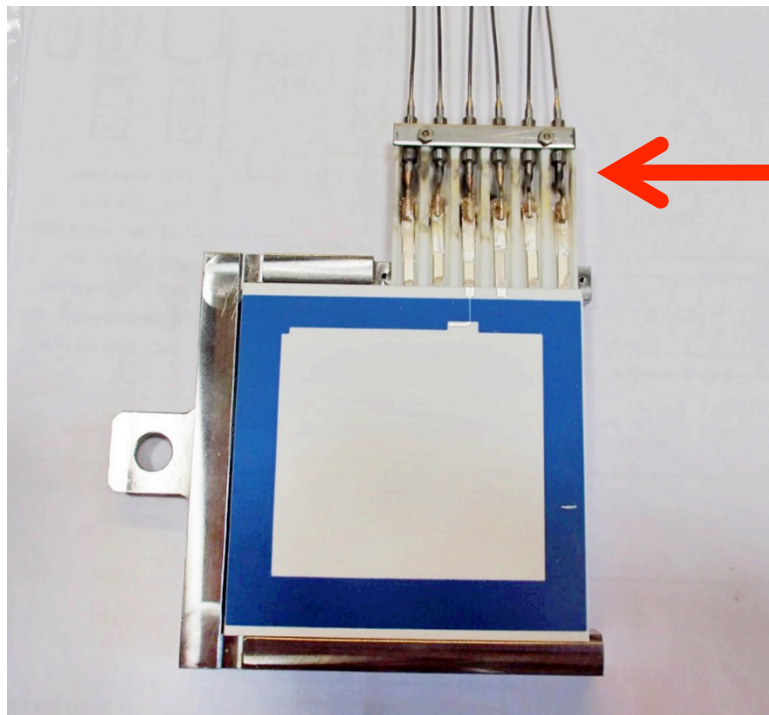


Corne-A, "Capteur de champ magnétique 3D pour fusion nucléaire",  
Projet de semestre,  
Section de  
microtechnique, LPM,  
EPFL, Lausanne (CH),  
2014.



# Cabling

- Cables brazed to Ag metallisation
- Cannot braze directly to base
  - Temperature gradients – cracking
  - Metallised alumina beams – mitigation of thermal gradients



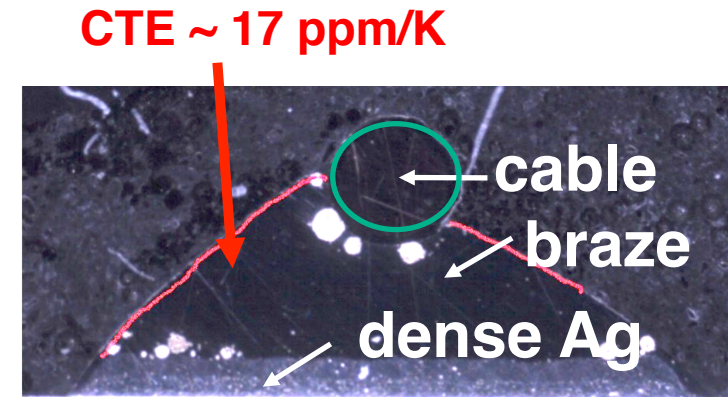
Jacq-C Maeder-T Güniat-L Corne-A Testa-D Ryser-P, Proceedings, IMAPS/ACerS 11th International CICMT Conference, Dresden (DE), 234-238, 2015.

# Cabling – brazing cable to alumina

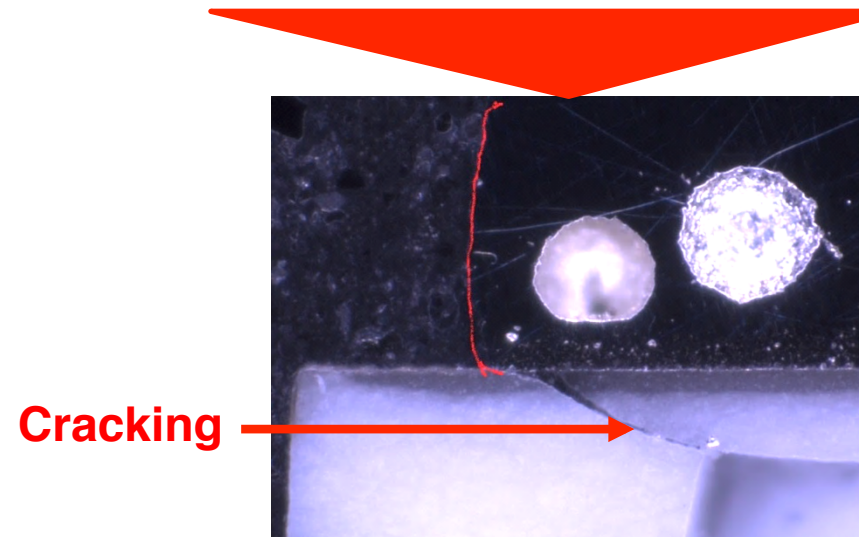
- Issue: **cracking** of alumina due to **local thermal expansion mismatch**
- Dense Ag metallisation too stiff to absorb differential strain



Jacq-C Maeder-T Güniat-L Corne-A Testa-D Ryser-P, Proceedings, IMAPS/ACerS 11th International CICMT Conference, Dresden (DE), 234-238, 2015.



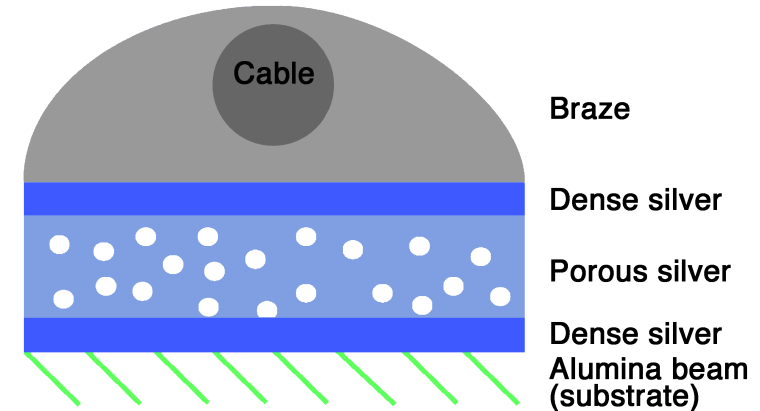
CTE ~ 7 ppm/K alumina





# Cabling – porous metallisation

- Dense Ag metallisation too stiff to absorb differential strain
- **Use porous interlayer**
  - Sandwich of dense/porous/dense silver
  - Formulation of 7 inks
  - “Rich” binder to allow successive printing of porous layers
  - Parameters: porogen size, volume percent, porous layer thickness
  - Porogen = graphite powder

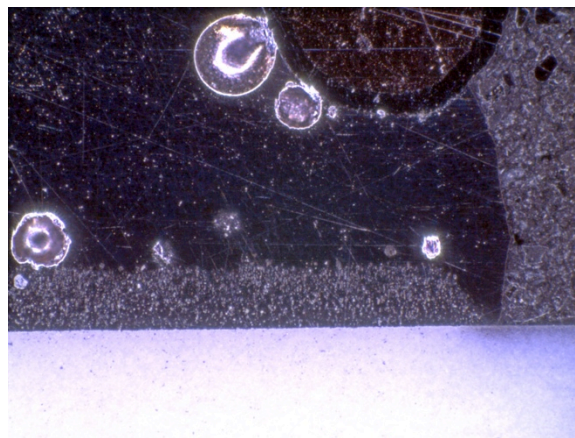
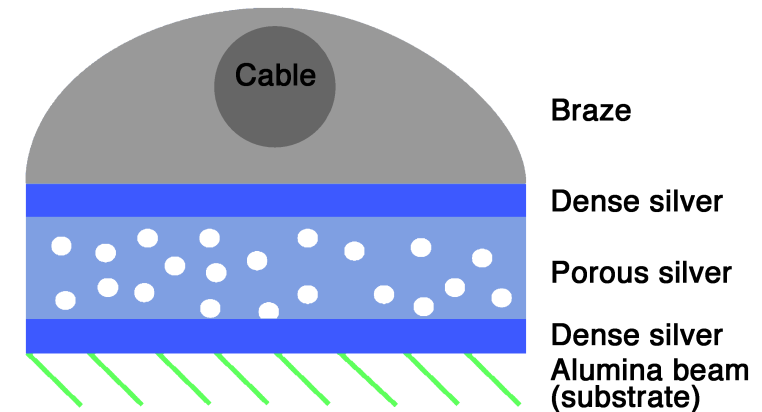


Denomination	Graphite	Particle size (µm)	Volume percent (%)
KS4_50	KS4	< 4	50
KS5-44_10	KS5-44	5-44	10
KS5-44_25	KS5-44	5-44	25
KS5-44_50	KS5-44	5-44	50
KS5-44_75	KS5-44	5-44	75
KS44_50	KS44	< 44	50
KS75_50	KS75	< 75	50

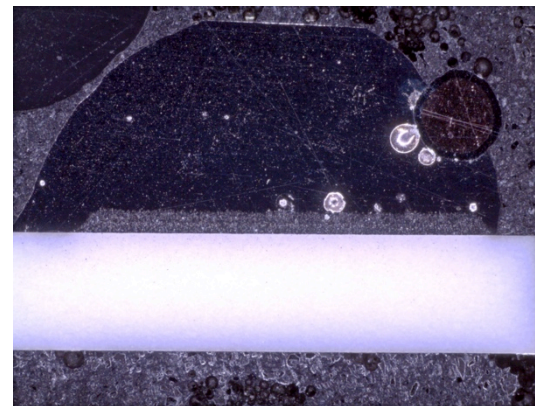
Jacq-C Maeder-T Güniat-L Corne-A Testa-D Ryser-P, Proceedings, IMAPS/ACerS 11th International CICMT Conference, Dresden (DE), 234-238, 2015.

# Cabling – porous metallisation

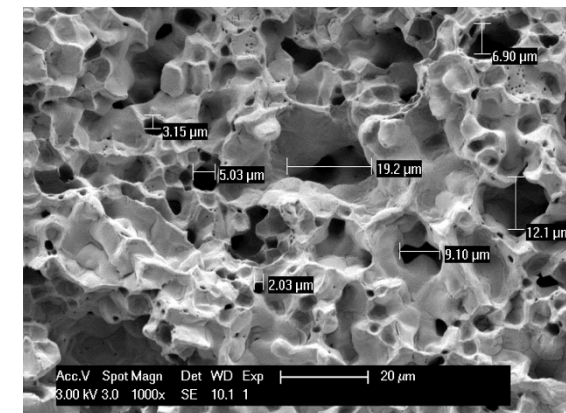
- Cables brazed to porous metallisation
- No more cracking for porosity ~50%



**Cross section (zoom)**



**Cross section w/o cracks**



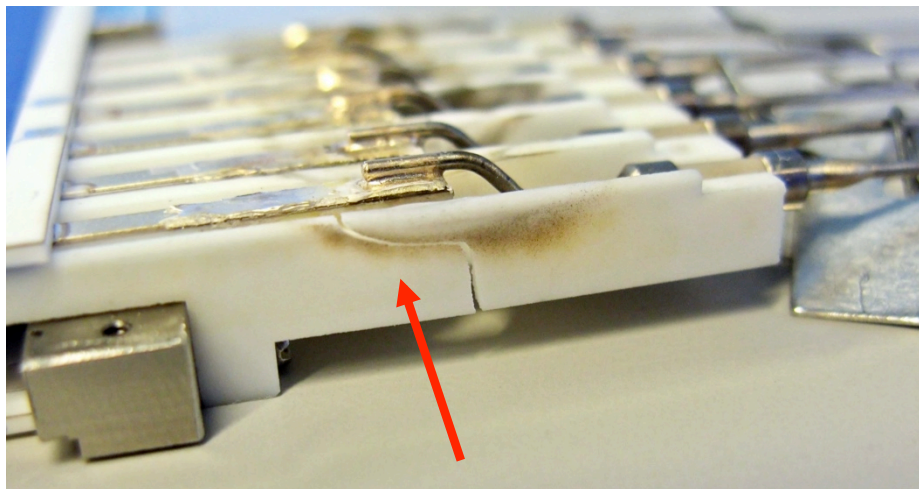
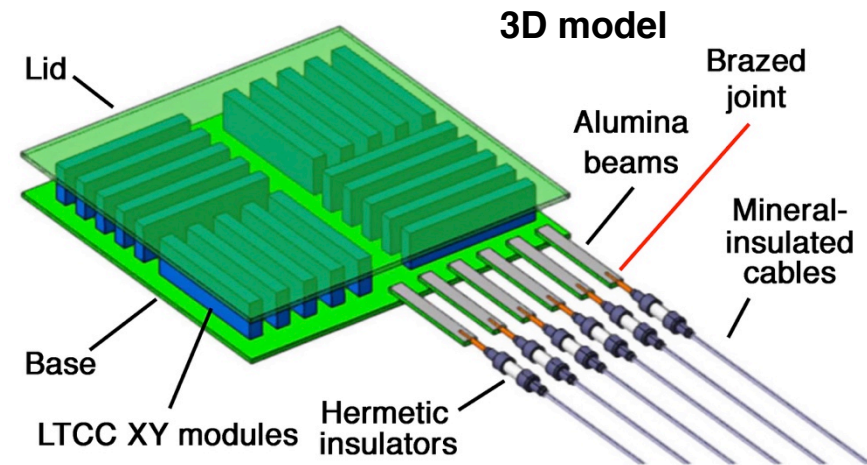
**Porous metallisation (SEM)**

Jacq-C Maeder-T Güniat-L Corne-A Testa-D Ryser-P, Proceedings, IMAPS/ACerS 11th International CICMT Conference, Dresden (DE), 234-238, 2015.

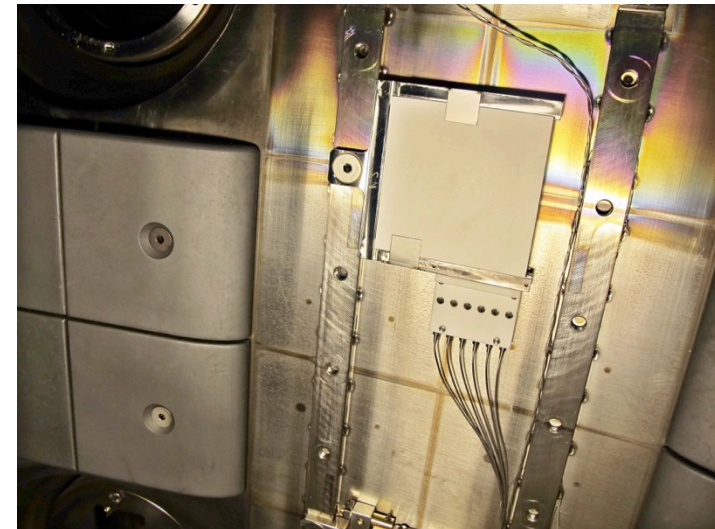
# Cabling – other solutions

## First solution cumbersome:

- Long, fragile alumina beams
- Additional space needed
- Issues with brazing operation
- Workshop cabling, must install whole assembly into tokamak



**Cracking of auxiliary ceramic part due to thermal stresses during brazing**

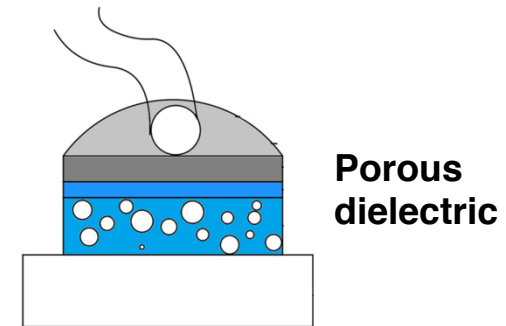
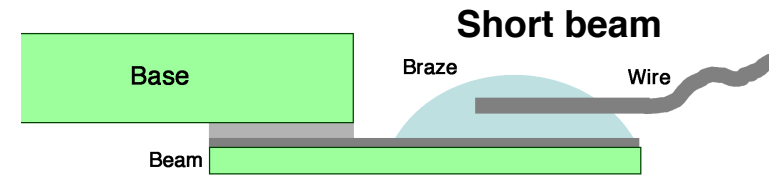


**Sensor mounted in TCV tokamak**

# Cabling – other solutions

## Three alternatives investigated:

1. Simply shortening the alumina beams
2. Brazing wires directly on base, with porous dielectric thermal insulator
3. Replacing the alumina beams by silver wire (attachment with paste to base)

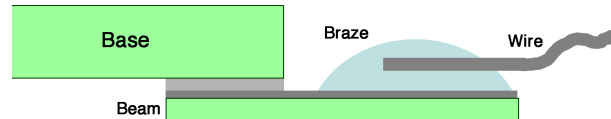


Jacq-C Maeder-T Toussaint-M Ellenrieder-BR Windischhofer-P Jiang-X Testa-D Ryser-P, Proceedings, 12th IMAPS/ACerS international Conference on Ceramic Interconnect and Ceramic Microsystems Technologies (CICMT), Denver (USA), 58-63, 2016.

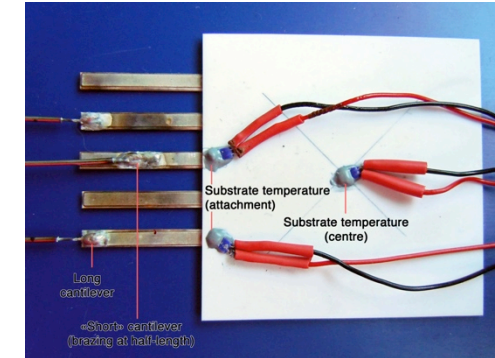


# Cabling – other solutions

## Results:



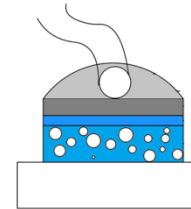
Brazing to long & "short" beams (at half-length)



### 1. Short beams: OK

- ~20 vs 45 mm free length

### 2. Porous dielectric: failure – broken dielectric

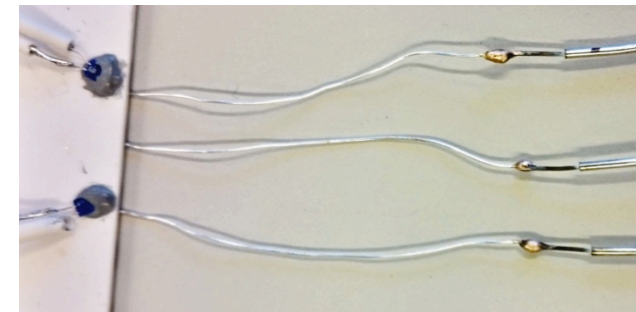


Brazing to porous dielectric – failure of dielectric due to very high thermal gradient

### 3. Silver wire: OK, best

- Mechanical decoupling
- Also: screw / crimp attach
- Bonding with Ag/glass to substrate

Brazing to Ag wire – crimping also possible



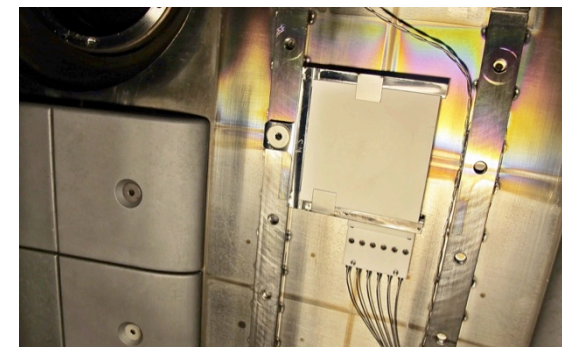
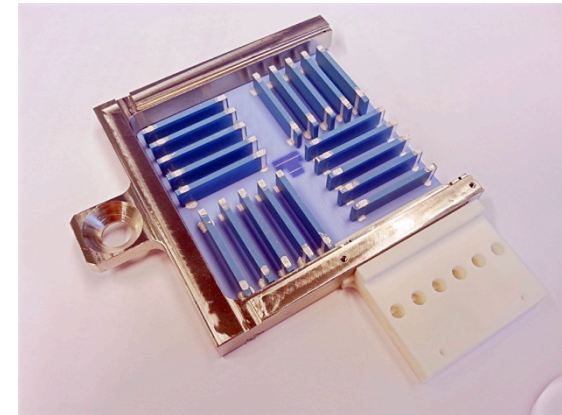
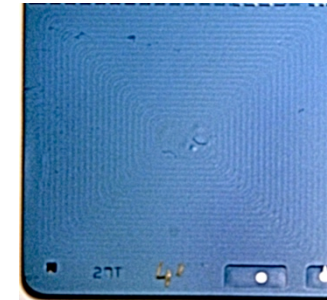
# Outline (3)

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# Conclusions

- Ceramic 1D & 3D magnetic sensors designed and produced successfully using LTCC and thick-film technology
- Small size, low profile for mounting behind tokamak wall
- Design rules for coils derived from results
- **3D sensors installed in TCV tokamak**





# Outlook

## Better packaging technology

- Ag pressure sintering for mounting parts
- Resistance welding / pressure sintering for cables

Brazing to Ag  
wire – crimping  
also possible

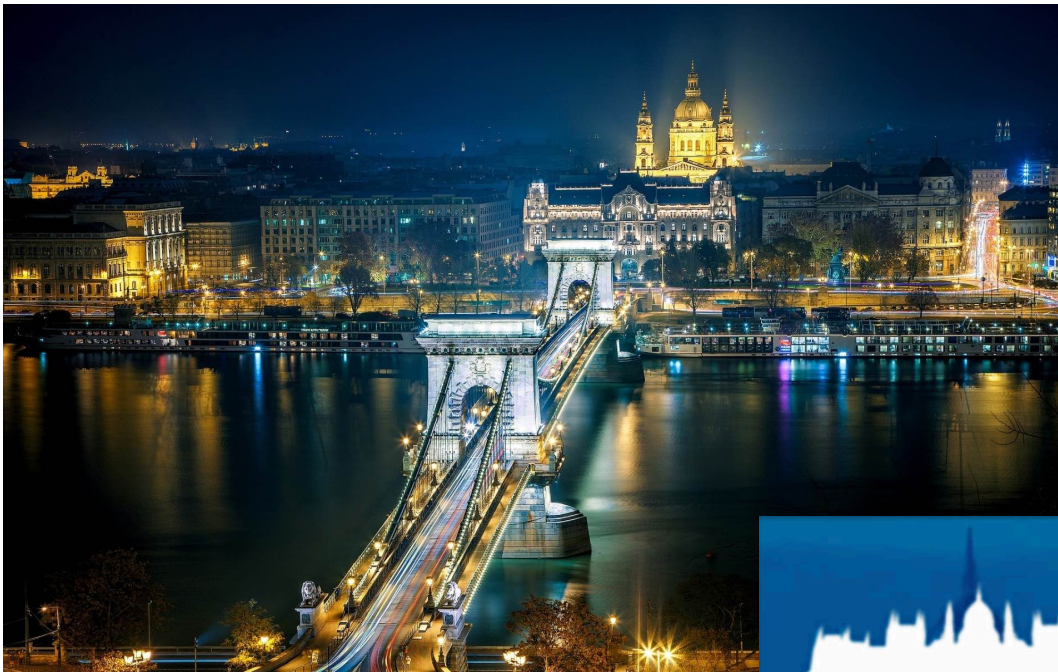
## Field-installable electrical connection

- Sensor handled in tokamak without bulky cabling
- HT / HV connectors
- Crimp / screw contact to e.g wire segments attached to base



**Merci**

# Thank you for your kind attention



## Questions ?



# Further reading / references

## Packaging & interconnection

- Jacq-C et al., "Solutions for thermally mismatched brazing operations for ceramic tokamak magnetic sensor", Proceedings, 12th IMAPS/ACerS international Conference on Ceramic Interconnect and Ceramic Microsystems Technologies (CICMT), Denver (USA), 58-63, 2016.
- Jacq-C et al., "Porous thick-film silver metallisation for thermally mismatched brazing operations in tokamak magnetic sensor", Proceedings, IMAPS/ACerS 11th International CICMT Conference, Dresden (DE), 234-238, 2015.

## 1D LTCC sensors

- D.Testa et al., Prototyping a high frequency inductive magnetic sensor using the non-conventional, low temperature co-fired ceramics technology for use in ITER, Fus. Sci. Tech. 59 (2011), 376
- G.Chitarin et al., Technology developments for ITER in-Vessel equilibrium magnetic sensors, Fus. Eng. Des. 84 (2009), 593

## 3D LTCC sensors

- D.Testa et al., 3D, LTCC-type, High-Frequency Magnetic Sensors for the TCV Tokamak, Fus. Eng. Des. 96-97 (2015) 989

## Further reading / references

### 3D HTCC sensors:

- H. Takahashi et al., Magnetic probe construction using thick-film technology, Rev. Sci. Instrum. 72 (2001), 3249

### ITER magnetic diagnostic system:

- J.Lister et al., The magnetic diagnostics Set for ITER, Fus. Eng. Des. 84 (2009), 295
- D.Testa et al., The magnetic diagnostic set for ITER, IEEE Transactions on Plasma Science 38 (2010), 284
- D.Testa et al., Functional performance analysis and optimization for the high-frequency magnetic diagnostic system in ITER, Fus. Sci. Tech. 57 (2010), 208; and Fus. Sci. Tech. 57 (2010), 238
- D.Testa et al., Assessment of the ITER High-Frequency Magnetic Diagnostic Set, Fus. Eng. Des. 86 (2011), 1149

### Mirnov-type HF magnetic sensors for ITER:

- M.Toussaint et al., Design of the ITER high-frequency magnetic diagnostic coils, Fus. Eng. Des. 86 (2011), 1248
- D.Testa et al., Prototyping conventional wound high frequency magnetic sensors for ITER, Fus. Sci. Tech. 61 (2012), 19