# A representation formula for the voltage perturbations caused by diametrically small conductivity inhomogeneities. Proof of uniform validity 

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#### Abstract

We revisit the asymptotic formulas originally derived in [D.J. Cedio-Fengya, S. Moskow, M.S. Vogelius, Identification of conductivity imperfections of small diameter by boundary measurements. Continuous dependence and computational reconstruction, Inverse Problems 14 (1998) 553-595; A. Friedman, M. Vogelius, Identification of small inhomogeneities of extreme conductivity by boundary measurements: A theorem on continuous dependence, Arch. Ration. Mech. Anal. 105 (1989) 299-326]. These formulas concern the perturbation in the voltage potential caused by the presence of diametrically small conductivity inhomogeneities. We significantly extend the validity of the previously derived formulas, by showing that they are asymptotically correct, uniformly with respect to the conductivity of the inhomogeneities. We also extend the earlier formulas by allowing the conductivities of the inhomogeneities to be completely arbitrary $L^{\infty}$, positive definite, symmetric matrix-valued functions. We briefly discuss the relevance of the uniform asymptotic validity, and the admission of arbitrary anisotropically conducting inhomogeneities, as far as applications of the perturbation formulas to "approximate cloaking" are concerned.


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Keywords: Voltage representation formulas; Small inhomogeneities; Cloaking

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## 1. Introduction

Asymptotic formulas that quantify the effect of small conductivity inhomogeneities on the voltage potential of an electrical conductor have recently received quite a bit of attention, see for instance $[1,4,5]$ and references therein. One important application of such formulas has been the approximate solution of the electrical impedance tomography problem, namely: "to determine the location and (some) geometric properties of the inhomogeneities from boundary measurements of voltages and current fluxes" [3]. Another more recent application is the precise estimation of the degree of near-invisibility associated with approximate cloaks obtained by so-called "mapping techniques", see [9]. Let $\Omega$ be a connected, bounded, smooth domain in $\mathbb{R}^{d}, d=2,3$, let $\gamma_{0}$ be a smooth background conductivity, and let $f \in H^{-1 / 2}(\partial \Omega)$ be a prescribed normal boundary flux (with $\int_{\partial \Omega} f d \sigma=0$ ). $u_{0}$ denotes the background voltage potential, i.e., the solution to

$$
\begin{equation*}
\nabla \cdot\left(\gamma_{0} \nabla u_{0}\right)=0 \quad \text { in } \Omega, \quad\left(\gamma_{0} \nabla u_{0}\right) \cdot n=f \quad \text { on } \partial \Omega, \tag{1.1}
\end{equation*}
$$

say, with $\int_{\partial \Omega} u_{0} d \sigma=0$. We could allow any finite number of (well separated) conductivity inhomogeneities inside $\Omega$ - but for simplicity let us assume there is only one (the principal effect of a finite number would simply be the sum of the individual effects). This conductivity inhomogeneity has small diameter (say, of magnitude $0<\rho \ll 1$ ). We shall denote the open set occupied by the inhomogeneity $D_{\rho}$. The conductivity inside $D_{\rho}$ is given by the symmetric, positive definite matrix-valued function $\gamma_{1, \rho}$. We define $\gamma_{\rho}$ to be the conductivity

$$
\gamma_{\rho}= \begin{cases}\gamma_{0} & \text { in } \Omega \backslash D_{\rho}  \tag{1.2}\\ \gamma_{1, \rho} & \text { in } D_{\rho}\end{cases}
$$

$u_{\rho}$ denotes the voltage potential corresponding to the conductivity distribution $\gamma_{\rho}$, i.e., the solution to

$$
\begin{equation*}
\nabla \cdot\left(\gamma_{\rho} \nabla u_{\rho}\right)=0 \quad \text { in } \Omega, \quad\left(\gamma_{\rho} \nabla u_{\rho}\right) \cdot n=f \quad \text { on } \partial \Omega, \tag{1.3}
\end{equation*}
$$

with $\int_{\partial \Omega} u_{\rho} d \sigma=0$. Initially we shall just assume that $D_{\rho}$ is contained in a small ball, i.e., in a set of the form $x_{0}+\rho B_{1}$, where $x_{0}$ is a point in $\Omega, B_{1}$ is the unit ball, centered at the origin, and $\rho$ is taken sufficiently small that $x_{0}+\rho B_{1} \Subset \Omega$. For simplicity let us assume $\Omega$ contains the origin, and that $x_{0}=0$. By $B_{\delta}$ we shall denote the ball of radius $\delta$, centered at the origin. The first result in this paper (Theorem 1 in Section 2) asserts that, given any positive $s$ and $\delta$

$$
\begin{equation*}
\left\|u_{\rho}-u_{0}\right\|_{H^{s}\left(\Omega \backslash \overline{B_{\delta}}\right)} \leqslant C \rho^{d}\|f\|_{H^{-1 / 2}(\partial \Omega)} \tag{1.4}
\end{equation*}
$$

with a constant $C$ that is independent of $\gamma_{1, \rho}, \rho$ and $f$, but depends on $\Omega, \delta, s$, and the background conductivity $\gamma_{0}$. The novelty here is that the constant $C$ is independent of $\gamma_{1, \rho}$, the ( $\rho$ dependent) conductivity of the inhomogeneity. If we only consider a conductivity $\gamma_{1}$, that is isotropic and independent of $\rho$, and we do not insist that the constant $C$ be independent of $\gamma_{1}$, then the estimate (1.4) follows immediately from the representation formula(s) proven in [4,5]. However, it is exactly the dependence of $\gamma_{1, \rho}$ on $\rho$, and the independence of the constant $C$ of $\gamma_{1 . \rho}$ that is important for applications to cloaking. More precisely: to obtain meaningful estimates of the degree of near-invisibility associated with certain approximate cloaks constructed by "mapping techniques" it is most convenient to have an estimate for $u_{\rho}-u_{0}$ that is uniform in $\gamma_{1, \rho}$. For instance, in [9] one could have used the fact that $C$ is independent of $\gamma_{1, \rho}$ to give a much more direct proof of the near-invisibility estimate - as it were (without recognizing this uniformity) the analysis in [9] relies on a somewhat indirect argument based on monotonicity and the validity of the estimate (1.4) in the two degenerate isotropic cases, $\gamma_{1}=0$ and $\gamma_{1}=\infty$.

Having proven the uniform estimate (1.4) we then return to consider the question of uniform validity of asymptotic formulas such as that derived in [5]. For that purpose we consider $D_{\rho}$ of the form $D_{\rho}=\rho D \Subset \Omega$, where $D$ is
a bounded, simply connected, smooth domain. For simplicity we take $\gamma_{0}$ to be a constant positive definite symmetric matrix, whereas we permit $\gamma_{1, \rho}$ to be an arbitrary positive definite symmetric matrix-valued $L^{\infty}$ function. The representation formula from [5] asserts that for constant, isotropic $\gamma_{0}$ and $\gamma_{1}$ ( $\rho$ independent)

$$
\begin{equation*}
u_{\rho}(x)=u_{0}(x)+\rho^{d}|D| \nabla_{y} G(x, 0) \cdot\left(\gamma_{0}-\gamma_{1}\right) M \nabla u_{0}(0)+o\left(\rho^{d}\right), \tag{1.5}
\end{equation*}
$$

where $o\left(\rho^{d}\right) / \rho^{d} \rightarrow 0$ as $\rho \rightarrow 0$. The function $G(x, y)$ is a particular Green's function (the so-called Neumann function) for the Laplacian on the domain $\Omega$, namely the solution to

$$
\begin{equation*}
\Delta_{x} G(x, y)=-\delta_{\{x=y\}}, \quad \text { with } \frac{\partial}{\partial n_{x}} G(x, y)=-\frac{1}{|\partial \Omega|}, \tag{1.6}
\end{equation*}
$$

normalized by $\int_{\partial \Omega} G(x, y) d \sigma_{x}=0$. In order to calculate the matrix $M$ let $\phi_{k}$ denote the solution to

$$
\begin{equation*}
\nabla \cdot\left(\gamma \nabla \phi_{k}\right)=0 \quad \text { in } \mathbb{R}^{d}, \quad \phi_{k}(z)-z_{k} \rightarrow 0 \quad \text { as }|z| \rightarrow \infty, \tag{1.7}
\end{equation*}
$$

with $\gamma$ denoting the rescaled conductivity function

$$
\gamma= \begin{cases}\gamma_{0} & \text { in } \mathbb{R}^{d} \backslash D \\ \gamma_{1} & \text { in } D\end{cases}
$$

The matrix $M$ is given by

$$
M_{j k}=\frac{1}{|D|} \int_{D} \frac{\partial \phi_{k}}{\partial z_{j}} d z
$$

In [5] it is shown that the matrix $M$ (corresponding to constant isotropic $\gamma_{0}$ and $\gamma_{1}$ ) is symmetric and positive definite. Furthermore, in this case $M$ is a function of the single scalar variable $c=\gamma_{1} / \gamma_{0}$, and it is shown that $\left(1-\frac{\gamma_{1}}{\gamma_{0}}\right) M=$ $(1-c) M(c)$ has finite limits as $c \rightarrow 0$ and $c \rightarrow \infty$. These limits are exactly the symmetric, positive definite matrices that appear in the asymptotic formulas for the two degenerate cases, $\gamma_{1}=0$ and $\gamma_{1}=\infty$ (see [6]). The second term in the right-hand side of (1.5) is therefore of order $\rho^{d}$ uniformly in $\gamma_{1}$ - it will also, uniformly in $\gamma_{1}$, represent the leading term of $u_{\rho}-u_{0}$ provided the remainder term $o\left(\rho^{d}\right)$ can be shown to have the property that $o\left(\rho^{d}\right) / \rho^{d} \rightarrow 0$, uniformly in $\gamma_{1}$ as $\rho \rightarrow 0$. This uniform smallness assertion (for variable, $\rho$ dependent, anisotropic $\gamma_{1, \rho}$ ) is exactly the content of Theorem 2 in Section 3.

It is well known that a formula similar to (1.5) (and a bound similar to (1.4)) holds for (subsequences of) arbitrarily shaped, volumetrically small inhomogeneities, with $\rho^{d}|D|$ replaced by $\left|D_{\rho}\right|$, provided $\gamma_{1, \rho}$ stays bounded and bounded away from zero (cf. [4]). However, for these results to be valid uniformly in $\gamma_{1, \rho}$ a condition of the type $D_{\rho}=\rho D$ (or $D_{\rho} \subset \rho D$ ) is absolutely essential. To see this consider $D_{\rho}$ in the form of a thin, "square" sheet $(-1,1)^{d-1} \times(-\rho, \rho)$ (or a smoothed-out version of this). For a fixed $\rho$ the solutions corresponding to a sequence of conductivity problems with (isotropic) conductivities $\gamma_{1}$ approaching $+\infty$ will converge to a solution to the conductivity problem in $\Omega \backslash \overline{D_{\rho}}$ that is constant on $\partial D_{\rho}$. It is therefore not very difficult to see that we may pick a sequence $\rho_{n} \rightarrow 0$ and a sequence of isotropic (constant) conductivities $\gamma_{1, n} \rightarrow \infty$ such that the corresponding sequence of solutions to the conductivity problems approaches a function that solves $\nabla \cdot\left(\gamma_{0} \nabla w_{0}\right)=0$ in $\Omega \backslash\left([-1,1]^{d-1} \times\{0\}\right)$, and is constant on $[-1,1]^{d-1} \times\{0\}$. Since this limit generically is not $\gamma_{0}$-harmonic in all of $\Omega$, and thus not equal to $u_{0}$, it follows that the estimate (1.4), or a formula like (1.5) (with $\rho^{d}|D|$ replaced by $\left|D_{\rho}\right|$ ) cannot hold uniformly in $\gamma_{1}$ for $D_{\rho}$ of the form $D_{\rho}=(-1,1)^{d-1} \times(-\rho, \rho)$.

In Section 4 we show that the condition $D_{\rho}=\rho D$ may be slightly relaxed without affecting the uniform validity of the principal two terms of the asymptotic expansion of $u_{\rho}$. To be precise, Theorem 3 asserts that the result in Theorem 2 still remains valid for domains $D_{\rho}$ that satisfy $\left(1-r_{\rho}\right) \rho D \subset D_{\rho} \subset\left(1+r_{\rho}\right) \rho D$ with $r_{\rho} \rightarrow 0$ as $\rho \rightarrow 0$.

We conclude the main part of this paper with a brief discussion of potential applications of our results to approximate cloaking. Appendix A of this paper contains a number of results concerning solvability, uniqueness and representation formulas for exterior problems, that were crucial for the analysis in Section 3.

## 2. A preliminary uniform estimate

In this section, $\gamma_{0}$ denotes a smooth (say, $C^{\infty}$ ) symmetric, positive definite matrix-valued function, defined on $\bar{\Omega}$, and $\gamma_{1, \rho}$ denotes a symmetric (uniformly) positive definite matrix-valued $L^{\infty}$ function defined on $D_{\rho}$. The conductivity $\gamma_{\rho}$ is given by (1.2). To simplify notation concerning we introduce

$$
C_{+}^{\infty}(\bar{\Omega})=\left(C^{\infty}(\bar{\Omega})\right)^{d \times d} \cap\{\gamma(x) \text { symmetric, positive definite, } \min \gamma>0\}
$$

and

$$
L_{+}^{\infty}\left(D_{\rho}\right)=\left(L^{\infty}\left(D_{\rho}\right)\right)^{d \times d} \cap\{\gamma(x) \text { symmetric, positive definite, ess inf } \gamma>0\} .
$$

Here $\min \gamma$ signifies the largest real number $m$, such that $\xi^{t} \gamma(x) \xi \geqslant m|\xi|^{2}$ for all $\xi \in \mathbb{R}^{d}$, and all $x \in \bar{\Omega}$, and ess inf $\gamma$ denotes the supremum of the set of real numbers $m$ for which $\xi^{t} \gamma(x) \xi \geqslant m|\xi|^{2}$ for all $\xi \in \mathbb{R}^{d}$, and almost all $x \in D_{\rho}$. Let $F$ be an element of $L^{2}(\Omega)$, with support inside $\Omega \backslash \overline{B_{\delta}}$, for some $\delta>0$, and let $f$ be an element of $H^{-1 / 2}(\partial \Omega)$, with $\int_{\Omega} F d x-\int_{\partial \Omega} f d \sigma=0$. Consider the standard weak solution, $v_{\rho} \in H^{1}(\Omega)$, to the boundary value problem

$$
\begin{equation*}
\nabla \cdot\left(\gamma_{\rho} \nabla v_{\rho}\right)=F \quad \text { in } \Omega, \quad\left(\gamma_{\rho} \nabla v_{\rho}\right) \cdot n=f \quad \text { on } \partial \Omega, \tag{2.1}
\end{equation*}
$$

normalized by $\int_{\partial \Omega} v_{\rho} d \sigma=0$. Let $v_{0} \in H^{1}(\Omega)$ denote the solution to the corresponding problem with $\gamma_{\rho}$ replaced by the background conductivity $\gamma_{0}$,

$$
\begin{equation*}
\nabla \cdot\left(\gamma_{0} \nabla v_{0}\right)=F \quad \text { in } \Omega, \quad\left(\gamma_{0} \nabla v_{0}\right) \cdot n=f \quad \text { on } \partial \Omega, \tag{2.2}
\end{equation*}
$$

normalized by $\int_{\partial \Omega} v_{0} d \sigma=0$. These two solutions are also the minimizers of the corresponding energies

$$
E_{\rho}(v)=\frac{1}{2} \int_{\Omega}\left\langle\gamma_{\rho} \nabla v, \nabla v\right\rangle d x+\int_{\Omega} F v d x-\int_{\partial \Omega} f v d \sigma
$$

and

$$
E_{0}(v)=\frac{1}{2} \int_{\Omega}\left\langle\gamma_{0} \nabla v, \nabla v\right\rangle d x+\int_{\Omega} F v d x-\int_{\partial \Omega} f v d \sigma
$$

in $H^{1}(\Omega) \cap\left\{\int_{\partial \Omega} v d \sigma=0\right\}$. The smoothness of $\gamma_{0}$ is needed to insure that $v_{0}$ be smooth, and that all the "error" norms are equivalent by elliptic regularity estimates. As a first result in this section we shall prove

Lemma 1. Suppose $D_{\rho} \subset B_{K \rho}$ for some positive constant $K$, independent of $\rho$. Let $\gamma_{\rho}$ be given by (1.2), with $\gamma_{0} \in$ $C_{+}^{\infty}(\bar{\Omega})$ and $\gamma_{1, \rho} \in L_{+}^{\infty}\left(D_{\rho}\right)$. For a fixed $\delta>0$, let $F$ be an element of $L^{2}(\Omega)$, with support inside $\Omega \backslash \overline{B_{\delta}}$, and let $f$ be an element of $H^{-1 / 2}(\partial \Omega)$, with $\int_{\Omega} F d x-\int_{\partial \Omega} f d \sigma=0$. Let $v_{\rho}$ and $v_{0}$ denote the solutions to (2.1) and (2.2) respectively, normalized by $\int_{\partial \Omega} v_{\rho} d \sigma=\int_{\partial \Omega} v_{0} d \sigma=0$. There exist a constant $\rho_{0}$, independent of $\gamma_{1, \rho}, F$ and $f$, and a constant $C$, independent of $\gamma_{1, \rho}, \rho, F$ and $f$, such that

$$
\begin{equation*}
\left|E_{\rho}\left(v_{\rho}\right)-E_{0}\left(v_{0}\right)\right| \leqslant C \rho^{d}\left(\|F\|_{L^{2}\left(\Omega \backslash \overline{\left.B_{\delta}\right)}\right.}^{2}+\|f\|_{H^{-1 / 2}(\partial \Omega)}^{2}\right), \quad \text { for } \rho<\rho_{0} \tag{2.3}
\end{equation*}
$$

The constants $\rho_{0}$ and $C$ depend on $\gamma_{0}, \Omega, \delta$ and $K$.
Proof. It obviously suffices to consider $\delta$ sufficiently small (say, that $\overline{B_{\delta}} \subset \Omega$ or even $\overline{B_{2 \delta}} \subset \Omega$ ). Pick $\rho_{0}<\delta / 2 K$ so that $B_{2 K \rho}$ is contained in $B_{\delta}$ for $\rho<\rho_{0}$. We divide the proof of the estimate (2.3) into two separate cases.

The case $\boldsymbol{E}_{\boldsymbol{\rho}}\left(\boldsymbol{v}_{\boldsymbol{\rho}}\right) \geqslant \boldsymbol{E}_{\mathbf{0}}\left(\boldsymbol{v}_{\mathbf{0}}\right)$. In this case

$$
\begin{equation*}
\left|E_{\rho}\left(v_{\rho}\right)-E_{0}\left(v_{0}\right)\right|=E_{\rho}\left(v_{\rho}\right)-E_{0}\left(v_{0}\right) \leqslant E_{\rho}\left(v^{*}\right)-E_{0}\left(v_{0}\right) \quad \forall v^{*} \in H^{1}(\Omega), \tag{2.4}
\end{equation*}
$$

and we proceed to construct an appropriate $v^{*}$. Let $0 \leqslant \chi_{\rho} \leqslant 1$ denote a smooth cut-off function with

$$
\chi_{\rho} \equiv 1 \quad \text { in } B_{K \rho}, \quad \chi_{\rho} \equiv 0 \quad \text { in } \Omega \backslash \overline{B_{2 K \rho}}, \quad \text { and } \quad\left|\nabla \chi_{\rho}\right| \leqslant \frac{C}{\rho} \quad \text { everywhere. }
$$

Using this $\chi_{\rho}$ we define

$$
v^{*}=\chi_{\rho}(x) v_{0}(0)+\left(1-\chi_{\rho}(x)\right) v_{0}(x) .
$$

Then

$$
\begin{equation*}
\nabla v^{*} \equiv 0 \quad \text { in } B_{K \rho}\left(\text { which contains } D_{\rho}\right), \quad \nabla v^{*}=\nabla v_{0} \quad \forall x \in \Omega \backslash \overline{B_{2 K \rho}}, \tag{2.5}
\end{equation*}
$$

and furthermore

$$
\begin{align*}
\left|\nabla v^{*}(x)\right|^{2} & =\left|\nabla \chi_{\rho}(x)\left(v_{0}(0)-v_{0}(x)\right)+\left(1-\chi_{\rho}(x)\right) \nabla v_{0}(x)\right|^{2} \\
& \leqslant 2\left(\left|\nabla \chi_{\rho}(x)\right|^{2}\left|v_{0}(0)-v_{0}(x)\right|^{2}+\left|1-\chi_{\rho}(x)\right|^{2}\left|\nabla v_{0}(x)\right|^{2}\right) \\
& \leqslant 2\left(C\left\|\nabla v_{0}\right\|_{C^{0}\left(\overline{B_{2 K \rho}}\right)}^{2}+\left\|\nabla v_{0}\right\|_{C^{0}\left(\overline{B_{2 K} \rho}\right)}^{2}\right), \tag{2.6}
\end{align*}
$$

for all $x \in B_{2 K \rho}$. The constant $C$ is independent of $\rho$ and $\gamma_{1, \rho}$. We note that $v^{*}(x)=v_{0}(x)$ for $x \in \partial \Omega$, and for $x \in \Omega \backslash \overline{B_{\delta}}$, and as a consequence of this and (2.5), (2.6),

$$
\begin{aligned}
2\left(E_{\rho}\left(v^{*}\right)-E_{0}\left(v_{0}\right)\right) & =\int_{\Omega}\left\langle\gamma_{\rho} \nabla v^{*}, \nabla v^{*}\right\rangle d x-\int_{\Omega}\left\langle\gamma_{0} \nabla v_{0}, \nabla v_{0}\right\rangle d x \\
& =\int_{B_{2 K \rho} \backslash B_{K \rho}}\left\langle\gamma_{0} \nabla v^{*}, \nabla v^{*}\right\rangle d x-\int_{B_{2 K \rho}}\left\langle\gamma_{0} \nabla v_{0}, \nabla v_{0}\right\rangle d x \\
& \leqslant \int_{B_{2 K \rho} \backslash B_{K_{\rho}}}\left\langle\gamma_{0} \nabla v^{*}, \nabla v^{*}\right\rangle d x \\
& \leqslant C \rho^{d}\left\|\nabla v_{0}\right\|_{C^{0}\left(\overline{B_{2 K \rho}}\right)}^{2} \leqslant C \rho^{d}\left(\|F\|_{L^{2}\left(\Omega \backslash \overline{\left.B_{\delta}\right)}\right.}^{2}+\|f\|_{H^{-1 / 2}(\partial \Omega)}^{2}\right),
\end{aligned}
$$

with $C$ independent of $\rho$ and $\gamma_{1, \rho}$. This verifies (2.3) in case $E_{\rho}\left(u_{\rho}\right)>E_{0}\left(v_{0}\right)$.
The case $\boldsymbol{E}_{\boldsymbol{\rho}}\left(\boldsymbol{v}_{\boldsymbol{\rho}}\right)<\boldsymbol{E}_{\mathbf{0}}\left(\boldsymbol{v}_{\mathbf{0}}\right)$. In this case

$$
\begin{equation*}
\left|E_{\rho}\left(v_{\rho}\right)-E_{0}\left(v_{0}\right)\right|=-E_{\rho}\left(v_{\rho}\right)+E_{0}\left(v_{0}\right), \tag{2.7}
\end{equation*}
$$

and to get an estimate of the type $C \rho^{d}\left(\|F\|_{L^{2}\left(\Omega \backslash \overline{B_{\delta}}\right)}^{2}+\|f\|_{H^{-1 / 2}(\partial \Omega)}^{2}\right)$ that is independent of $\gamma_{1, \rho}$, we shall introduce the dual variational principle. Let $V$ denote the set

$$
V=\left\{\sigma \in\left(L^{2}(\Omega)\right)^{d}: \nabla \cdot \sigma=F \text { in } \Omega, \sigma \cdot n=f \text { on } \partial \Omega\right\} .
$$

Then it is well known that

$$
\begin{align*}
E_{\rho}\left(v_{\rho}\right) & =-\frac{1}{2} \int_{\Omega}\left\langle\gamma_{\rho} \nabla v_{\rho}, \nabla v_{\rho}\right\rangle d x \\
& =\max _{\sigma \in V}-\frac{1}{2} \int_{\Omega}\left\langle\gamma_{\rho}^{-1} \sigma, \sigma\right\rangle d x \\
& \geqslant-\frac{1}{2} \int_{\Omega}\left\langle\gamma_{\rho}^{-1} \sigma^{*}, \sigma^{*}\right\rangle d x \quad \forall \sigma^{*} \in V . \tag{2.8}
\end{align*}
$$

Since

$$
E_{0}\left(v_{0}\right)=-\frac{1}{2} \int_{\Omega}\left\langle\gamma_{0} \nabla v_{0}, \nabla v_{0}\right\rangle d x
$$

it follows from (2.7) and (2.8) that

$$
\begin{equation*}
\left|E_{\rho}\left(v_{\rho}\right)-E_{0}\left(v_{0}\right)\right| \leqslant \frac{1}{2} \int_{\Omega}\left\langle\gamma_{\rho}^{-1} \sigma^{*}, \sigma^{*}\right\rangle d x-\frac{1}{2} \int_{\Omega}\left\langle\gamma_{0} \nabla v_{0}, \nabla v_{0}\right\rangle d x \tag{2.9}
\end{equation*}
$$

for any $\sigma^{*} \in V$. We proceed to construct $\sigma^{*} \in V$ for which $\int_{\Omega}\left\langle\gamma_{\rho}^{-1} \sigma^{*}, \sigma^{*}\right\rangle d x$ is near $\int_{\Omega}\left\langle\gamma_{0} \nabla v_{0}, \nabla v_{0}\right\rangle d x$. Let $W_{\rho}$ denote the solution to

$$
\begin{aligned}
& \Delta W_{\rho}=0 \quad \text { in } B_{2 K} \backslash \overline{B_{K}}, \\
& \frac{\partial W_{\rho}}{\partial n}=0 \quad \text { on } \partial B_{K}, \\
& \frac{\partial W_{\rho}}{\partial n}=\left(\gamma_{0} \nabla v_{0}(\rho x)\right) \cdot n \quad \text { on } \partial\left(B_{2 K}\right) .
\end{aligned}
$$

This problem has a solution, since $\int_{\partial\left(B_{\left.2 K_{\rho}\right)}\right)}\left(\gamma_{0} \nabla v_{0}\right) \cdot n d \sigma=0$. The solution is unique up to a constant, and it satisfies the estimate

$$
\left\|\nabla W_{\rho}\right\|_{L^{2}\left(B_{2 K} \backslash \overline{B_{K}}\right)}^{2} \leqslant C\left\|\nabla v_{0}\right\|_{C^{0}\left(\partial\left(B_{2 K_{\rho}}\right)\right)}^{2} \leqslant C\left(\|F\|_{L^{2}\left(\Omega \backslash \overline{B_{8}}\right)}^{2}+\|f\|_{H^{-1 / 2}(\partial \Omega)}^{2}\right) .
$$

It follows immediately by rescaling that $w_{\rho}=\rho W_{\rho}\left(\frac{x}{\rho}\right)$ satisfies

$$
\begin{array}{ll}
\Delta w_{\rho}=0 & \text { in } B_{2 K \rho} \backslash \overline{B_{K \rho}}, \\
\frac{\partial w_{\rho}}{\partial n}=0 & \text { on } \partial\left(B_{K \rho}\right), \\
\frac{\partial w_{\rho}}{\partial n}=\left(\gamma_{0} \nabla v_{0}\right) \cdot n \quad \text { on } \partial\left(B_{2 K \rho}\right)
\end{array}
$$

and

$$
\begin{equation*}
\left\|\nabla w_{\rho}\right\|_{L^{2}\left(B_{2 K \rho} \backslash \overline{\left.B_{K_{\rho}}\right)}\right.}^{2} \leqslant C \rho^{d}\left(\|F\|_{L^{2}\left(\Omega \backslash \overline{B_{\delta}}\right)}^{2}+\|f\|_{H^{-1 / 2}(\partial \Omega)}^{2}\right) \tag{2.10}
\end{equation*}
$$

with a constant $C$ that is independent of $\rho$ and $\gamma_{1, \rho}$. We now define the field $\sigma^{*}$ by the formula

$$
\sigma^{*}= \begin{cases}0 & \text { in } B_{K \rho}, \\ \nabla w_{\rho} & \text { in } B_{2 K \rho} \backslash \overline{B_{K \rho}}, \\ \gamma_{0} \nabla v_{0} & \text { in } \Omega \backslash \overline{B_{2 K \rho}}\end{cases}
$$

This field is clearly in $\left[L^{2}(\Omega)\right]^{d}$, and it satisfies $\nabla \cdot \sigma^{*}=F$ in $\Omega$ as well as $\sigma^{*} \cdot n=\left(\gamma_{0} \nabla v_{0}\right) \cdot n=f$ on $\partial \Omega$, i.e., $\sigma^{*}$ is an element of $V$. By using $\sigma^{*}$ as a test field in (2.9) we get

$$
\begin{aligned}
\left|E_{\rho}\left(v_{\rho}\right)-E_{0}\left(v_{0}\right)\right| & \leqslant \frac{1}{2} \int_{\Omega}\left\langle\gamma_{\rho}^{-1} \sigma^{*}, \sigma^{*}\right\rangle d x-\frac{1}{2} \int_{\Omega}\left\langle\gamma_{0} \nabla v_{0}, \nabla v_{0}\right\rangle d x \\
& =\frac{1}{2} \int_{B_{2 K \rho} \backslash B_{K \rho}}\left\langle\gamma_{0}^{-1} \nabla w_{\rho}, \nabla w_{\rho}\right\rangle d x-\frac{1}{2} \int_{B_{2 K \rho}}\left\langle\gamma_{0} \nabla v_{0}, \nabla v_{0}\right\rangle d x \\
& \leqslant \int_{B_{2 K \rho} \backslash B_{K \rho}}\left\langle\gamma_{0}^{-1} \nabla w_{\rho}, \nabla w_{\rho}\right\rangle d x \\
& \leqslant C \rho^{d}\left(\|F\|_{L^{2}\left(\Omega \backslash \overline{\left.B_{\delta}\right)}\right.}^{2}+\|f\|_{H^{-1 / 2}(\partial \Omega)}^{2}\right)
\end{aligned}
$$

with $C$ independent of $\rho$ and the conductivity $\gamma_{1, \rho}$ of the inhomogeneity $D_{\rho}$. For the last inequality we have used the estimate (2.10). This verifies (2.3) in case $E_{\rho}\left(u_{\rho}\right)<E_{0}\left(v_{0}\right)$, and thus completes the proof of Lemma 1.

Let $F, f$ and $\gamma_{\rho}$ be as in the preceding lemma. We easily calculate that

$$
-\int_{\Omega \backslash \overline{B_{\delta}}} F v_{\rho} d x+\int_{\partial \Omega} f v_{\rho} d \sigma=\int_{\Omega}\left\langle\gamma_{\rho} \nabla v_{\rho}, \nabla v_{\rho}\right\rangle d x
$$

$$
\begin{aligned}
& =-\int_{\Omega}\left\langle\gamma_{\rho} \nabla v_{\rho}, \nabla v_{\rho}\right\rangle d x-2 \int_{\Omega} F v_{\rho} d x+2 \int_{\partial \Omega} f v_{\rho} d \sigma \\
& =-2 E_{\rho}\left(v_{\rho}\right)
\end{aligned}
$$

and similarly

$$
\begin{aligned}
-\int_{\Omega \backslash \overline{B_{\delta}}} F v_{0} d x+\int_{\partial \Omega} f v_{0} d \sigma & =\int_{\Omega}\left\langle\gamma_{0} \nabla v_{0}, \nabla v_{0}\right\rangle d x \\
& =-\int_{\Omega}\left\langle\gamma_{0} \nabla v_{0}, \nabla v_{0}\right\rangle d x-2 \int_{\Omega} F v_{0} d x+2 \int_{\partial \Omega} f v_{0} d \sigma \\
& =-2 E_{0}\left(v_{0}\right)
\end{aligned}
$$

As a consequence

$$
\int_{\Omega \backslash \overline{B_{\delta}}} F\left(v_{\rho}-v_{0}\right) d x-\int_{\partial \Omega} f\left(v_{\rho}-v_{0}\right) d \sigma=2\left(E_{\rho}\left(v_{\rho}\right)-E_{0}\left(v_{0}\right)\right),
$$

and so, due to Lemma 1

$$
\begin{equation*}
\left|\int_{\Omega \backslash \overline{B_{\delta}}} F\left(v_{\rho}-v_{0}\right) d x-\int_{\partial \Omega} f\left(v_{\rho}-v_{0}\right) d \sigma\right| \leqslant C \rho^{d}\left(\|F\|_{L^{2}\left(\Omega \backslash \overline{B_{\delta}}\right)}^{2}+\|f\|_{H^{-1 / 2}(\partial \Omega)}^{2}\right), \tag{2.11}
\end{equation*}
$$

with $C$ independent of $\rho, F, f$ and $\gamma_{1, \rho}$. If we define the bounded linear operator $A_{\rho}:(F, f) \rightarrow\left(\left.\left(v_{\rho}-v_{0}\right)\right|_{\Omega \backslash \overline{B_{\delta}}}\right.$, $\left.-\left.\left(v_{\rho}-v_{0}\right)\right|_{\partial \Omega}\right)$ from $L^{2}\left(\Omega \backslash \overline{B_{\delta}}\right) \times H^{-1 / 2}(\partial \Omega)$ into $L^{2}\left(\Omega \backslash \overline{B_{\delta}}\right) \times H^{1 / 2}(\partial \Omega)$, then (2.11) simply asserts that

$$
\left|\left\langle A_{\rho}(F, f),(F, f)\right\rangle\right| \leqslant C \rho^{d}\left(\|F\|_{L^{2}\left(\Omega \backslash \overline{B_{\delta}}\right)}^{2}+\|f\|_{H^{-1 / 2}(\partial \Omega)}^{2}\right),
$$

where $\langle\cdot, \cdot\rangle$ denotes the natural duality between $L^{2}\left(\Omega \backslash \overline{B_{\delta}}\right) \times H^{1 / 2}(\partial \Omega)$ and $L^{2}\left(\Omega \backslash \overline{B_{\delta}}\right) \times H^{-1 / 2}(\partial \Omega)$. We note that $A_{\rho}$ is self-adjoint, and by "polarization" it now follows that

$$
\sup _{\|(F, f)\| \leqslant 1} \sup _{\|(G, g)\| \leqslant 1}\left|\left\langle A_{\rho}(F, f),(G, g)\right\rangle\right| \leqslant C \rho^{d},
$$

with $\|(F, f)\|=\left(\|F\|_{L^{2}\left(\Omega \backslash \overline{B_{\delta}}\right)}^{2}+\|f\|_{H^{-1 / 2}(\partial \Omega)}^{2}\right)^{1 / 2}$. In other words

$$
\left(\left\|v_{\rho}-v_{0}\right\|_{L^{2}\left(\Omega \backslash \overline{B_{\delta}}\right)}^{2}+\left\|v_{\rho}-v_{0}\right\|_{H^{1 / 2}(\partial \Omega)}^{2}\right)^{1 / 2}=\sup _{\|(G, g)\| \leqslant 1}\left|\left\langle A_{\rho}(F, f),(G, g)\right\rangle\right| \leqslant C \rho^{d}
$$

for all ( $F, f$ ) with $\|F\|_{L^{2}\left(\Omega \backslash \overline{B_{\delta}}\right)}^{2}+\|f\|_{H^{-1 / 2}(\partial \Omega)}^{2} \leqslant 1$, or

$$
\left(\left\|v_{\rho}-v_{0}\right\|_{L^{2}\left(\Omega \backslash \overline{B_{\delta}}\right)}^{2}+\left\|v_{\rho}-v_{0}\right\|_{H^{1 / 2}(\partial \Omega)}^{2}\right)^{1 / 2} \leqslant C \rho^{d}\left(\|F\|_{L^{2}\left(\Omega \backslash \overline{B_{\delta}}\right)}^{2}+\|f\|_{H^{-1 / 2}(\partial \Omega)}^{2}\right)^{1 / 2}
$$

with $C$ independent of $\rho, F, f$ and $\gamma_{1, \rho}$. Since $v_{\rho}-v_{0}$ solves the equation

$$
\nabla \cdot\left(\gamma_{0} \nabla\left(v_{\rho}-v_{0}\right)\right)=0 \quad \text { in } \Omega \backslash \overline{B_{\delta}}, \quad \text { with }\left(\gamma_{0} \nabla\left(v_{\rho}-v_{0}\right)\right) \cdot n=0 \text { on } \partial \Omega,
$$

elliptic regularity theory implies that the above estimate also holds for the Sobolev norm $\left(\left\|v_{\rho}-v_{0}\right\|_{H^{s}\left(\Omega \backslash \overline{B_{28}}\right)}^{2}+\right.$ $\left.\left\|v_{\rho}-v_{0}\right\|_{H^{s}(\partial \Omega)}^{2}\right)^{1 / 2}$, i.e.,

$$
\begin{aligned}
\left(\left\|v_{\rho}-v_{0}\right\|_{H^{s}\left(\Omega \backslash \overline{B_{2 \delta}}\right.}^{2}+\left\|v_{\rho}-v_{0}\right\|_{H^{s}(\partial \Omega)}^{2}\right)^{1 / 2} & \leqslant C \rho^{d}\left(\|F\|_{L^{2}\left(\Omega \backslash \overline{B_{\delta}}\right)}^{2}+\|f\|_{H^{-1 / 2}(\partial \Omega)}^{2}\right)^{1 / 2} \\
& \leqslant C \rho^{d}\left(\|F\|_{L^{2}\left(\Omega \backslash \overline{B_{2 \delta}}\right.}^{2}+\|f\|_{H^{-1 / 2}(\partial \Omega)}^{2}\right)^{1 / 2}
\end{aligned}
$$

for any $s \in \mathbb{R}_{+}$and any $F$ having support inside $\Omega \backslash \overline{B_{2 \delta}}$. Replacing $\delta$ with $\delta / 2$ we have therefore established

Theorem 1. Suppose $D_{\rho} \subset B_{K \rho}$ for some positive constant $K$, independent of $\rho$. Let $\gamma_{\rho}$ be given by (1.2), with $\gamma_{0} \in C_{+}^{\infty}(\bar{\Omega})$ and $\gamma_{1, \rho} \in L_{+}^{\infty}\left(D_{\rho}\right)$. For a fixed $\delta>0$, let $F$ be an element of $L^{2}(\Omega)$, with support inside $\Omega \backslash \overline{B_{\delta}}$, and let $f$ be an element of $H^{-1 / 2}(\partial \Omega)$, with $\int_{\Omega} F d x-\int_{\partial \Omega} f d \sigma=0$. Let $v_{\rho}$ and $v_{0}$ denote the solutions to (2.1) and (2.2) respectively, normalized by $\int_{\partial \Omega} v_{\rho} d \sigma=\int_{\partial \Omega} v_{0} d \sigma=0$. Given any $s \in \mathbb{R}_{+}$there exist a constant $\rho_{0}$, independent of $\gamma_{1, \rho}, F$ and $f$, and a constant $C$, independent of $\gamma_{1, \rho}, \rho, F$ and $f$, such that

$$
\left(\left\|v_{\rho}-v_{0}\right\|_{H^{s}\left(\Omega \backslash \overline{B_{\delta}}\right)}^{2}+\left\|v_{\rho}-v_{0}\right\|_{H^{s}(\partial \Omega)}^{2}\right)^{1 / 2} \leqslant C \rho^{d}\left(\|F\|_{L^{2}\left(\Omega \backslash \overline{B_{\delta}}\right)}^{2}+\|f\|_{H^{-1 / 2}(\partial \Omega)}^{2}\right)^{1 / 2},
$$

for all $\rho<\rho_{0}$. The constants $\rho_{0}$ and $C$ depend on $\gamma_{0}, \Omega, \delta$ and $K$.
Theorem 1 is of independent importance. However for the purpose of this paper it is two corollaries, both pertaining to the special case $F=0$, that are particularly relevant. The first corollary is of direct relevance to the estimation of the effectivity of approximate cloaks, as briefly discussed in Section 5.

Corollary 1. Suppose $D_{\rho} \subset B_{K \rho}$ for some positive constant $K$, independent of $\rho$. Let $\gamma_{\rho}$ be given by (1.2), with $\gamma_{0} \in C_{+}^{\infty}(\bar{\Omega})$ and $\gamma_{1, \rho} \in L_{+}^{\infty}\left(D_{\rho}\right)$. Let $f$ be an element of $H^{-1 / 2}(\partial \Omega)$, with $\int_{\partial \Omega} f d \sigma=0$. Let $u_{\rho}$ and $u_{0}$ denote the solutions to (1.3) and (1.1) respectively, normalized by $\int_{\partial \Omega} u_{\rho} d \sigma=\int_{\partial \Omega} u_{0} d \sigma=0$. Given any $s \in \mathbb{R}_{+}$, and any $\delta \in \mathbb{R}_{+}$, there exist a constant $\rho_{0}$, independent of $\gamma_{1, \rho}$ and $f$, and a constant $C$, independent of $\gamma_{1, \rho}, f$, and $\rho$, such that

$$
\left\|u_{\rho}-u_{0}\right\|_{H^{s}\left(\Omega \backslash \overline{B_{\delta}}\right)}+\left\|u_{\rho}-u_{0}\right\|_{H^{s}(\partial \Omega)} \leqslant C \rho^{d}\|f\|_{H^{-1 / 2}(\partial \Omega)} \quad \forall \rho<\rho_{0}
$$

The second corollary, which shall prove essential for our analysis in Section 3.2, estimates the combined perturbation caused by the small inhomogeneity and a change in the normal flux. In order to formulate this corollary we need some additional notation. Let $w_{\rho}$ be the solution to

$$
\begin{cases}\nabla \cdot\left(\gamma_{\rho} \nabla w_{\rho}\right)=0 & \text { in } \Omega,  \tag{2.12}\\ \left(\gamma_{\rho} \nabla w_{\rho}\right) \cdot n=g & \text { on } \partial \Omega\end{cases}
$$

normalized by $\int_{\partial \Omega} w_{\rho} d \sigma=0$. Here we assume that $g$ is an element of $H^{-1 / 2}(\partial \Omega)$, with $\int_{\partial \Omega} g d \sigma=0$. It follows immediately that

$$
\begin{align*}
\int_{\Omega \backslash D_{\rho}}\left\langle\gamma_{0} \nabla\left(w_{\rho}-u_{\rho}\right), \nabla\left(w_{\rho}-u_{\rho}\right)\right) d x & \leqslant \int_{\partial \Omega}(g-f)\left(w_{\rho}-u_{\rho}\right) d \sigma \\
& \leqslant\|g-f\|_{H^{-1 / 2}(\partial \Omega)}\left\|w_{\rho}-u_{\rho}\right\|_{H^{1 / 2}(\partial \Omega)} \\
& \leqslant C\|g-f\|_{H^{-1 / 2}(\partial \Omega)}\left\|w_{\rho}-u_{\rho}\right\|_{H^{1}\left(\Omega \backslash \overline{B_{\delta}}\right)} . \tag{2.13}
\end{align*}
$$

Due to the fact that $\int_{\partial \Omega} w_{\rho} d \sigma=\int_{\partial \Omega} u_{\rho} d \sigma=0$ we have

$$
\left\|w_{\rho}-u_{\rho}\right\|_{H^{1}\left(\Omega \backslash \overline{B_{\delta}}\right)} \leqslant C\left\|\nabla\left(w_{\rho}-u_{\rho}\right)\right\|_{L^{2}\left(\Omega \backslash \overline{B_{\delta}}\right)} .
$$

A combination of this with (2.13) immediately gives that there exist constants $\rho_{0}$ and $C$ such that

$$
\begin{equation*}
\left\|w_{\rho}-u_{\rho}\right\|_{H^{1}\left(\Omega \backslash \overline{B_{\delta}}\right)} \leqslant C\|g-f\|_{H^{-1 / 2}(\partial \Omega)}, \quad \text { for } \rho<\rho_{0} . \tag{2.14}
\end{equation*}
$$

The constants $\rho_{0}$ and $C$ are independent of $\gamma_{1, \rho}, f$ and $g$. If we decompose

$$
w_{\rho}-u_{0}=\left(w_{\rho}-u_{\rho}\right)+\left(u_{\rho}-u_{0}\right),
$$

and combine Corollary 1 with (2.14) we obtain
Corollary 2. Suppose $D_{\rho} \subset B_{K \rho}$ for some positive constant $K$, independent of $\rho$. Let $\gamma_{\rho}$ be given by (1.2), with $\gamma_{0} \in C_{+}^{\infty}(\bar{\Omega})$ and $\gamma_{1, \rho} \in L_{+}^{\infty}\left(D_{\rho}\right)$. Let $f, g \in H^{-\frac{1}{2}}(\partial \Omega)$ with $\int_{\partial \Omega} f d \sigma=\int_{\partial \Omega} g=0$, and let $u_{0}$ and $w_{\rho}$ in $H^{1}(\Omega)$ denote the solutions to (1.1) and (2.12), normalized by $\int_{\partial \Omega} u_{0} d \sigma=\int_{\partial \Omega} w_{\rho} d \sigma=0$. Given any $\delta>0$ there exist a constant $\rho_{0}$, independent of $\gamma_{1, \rho}, f$ and $g$, and a constant $C$, independent of $\gamma_{1, \rho}, f, g$ and $\rho$, such that

$$
\left\|w_{\rho}-u_{0}\right\|_{H^{1}\left(\Omega \backslash \overline{B_{\delta}}\right)} \leqslant C\left(\|g-f\|_{H^{-1 / 2}(\partial \Omega)}+\rho^{d}\|f\|_{H^{-1 / 2}(\partial \Omega)}\right),
$$

for all $\rho<\rho_{0}$.

## 3. The leading order asymptotics when $D_{\rho}=\rho D$

We shall now consider the case when the inhomogeneity $D_{\rho}$ is of the form $D_{\rho}=\rho D$, for some bounded, simply connected, smooth domain $D \subset B_{K}$. We shall examine issues related to the principal term of the expression

$$
\frac{1}{\rho^{d}}\left(u_{\rho}-u_{0}\right)
$$

as $\rho \rightarrow 0$. We briefly describe the structure of the expression

$$
\frac{1}{\rho^{d}}\left(u_{\rho}-u_{0}\right), \quad \rho \rightarrow 0
$$

a structure that (for $\gamma_{0}$ and $\gamma_{1, \rho}$ isotropic) is already well known, $c f$. [5]. What is not at all known, and what we shall prove here is that for inhomogeneities that are dilatations of a fixed set $D$, we can describe the expression $\left(u_{\rho}-u_{0}\right) / \rho^{d}$ by an explicit (bounded) formula that is asymptotically correct uniformly in $\gamma_{1, \rho}$. As pointed out in the introduction such a formula is not available for general $D_{\rho}$. For simplicity we shall restrict attention to the case

$$
\gamma_{\rho}(x)= \begin{cases}\gamma_{0} & \text { if } x \in \Omega \backslash \rho D, \\ \gamma_{1, \rho}(x) & \text { if } x \in \rho D,\end{cases}
$$

where $\gamma_{0}$ is a constant, symmetric, positive definite matrix, and $\gamma_{1, \rho}$ is an arbitrary symmetric (uniformly) positive definite matrix-valued function defined on $\rho D$, in other words

$$
\gamma_{1, \rho} \in L_{+}^{\infty}(\rho D)=\left(L^{\infty}(\rho D)\right)^{d \times d} \cap\{\gamma(x) \text { symmetric, positive definite, ess inf } \gamma>0\} .
$$

By a simple linear change of variables $x^{\prime}=L x, \gamma_{\rho}$ changes (up to a constant scalar multiple) into $L \gamma_{\rho} L^{T} \circ L^{-1}$, $D$ changes into $L(D)$, and $\Omega$ into $L(\Omega)$. Since we can choose $L$ such that $L \gamma_{0} L^{T}=I$ we may thus, without loss of generality, assume that $\gamma_{\rho}$ is of the form

$$
\gamma_{\rho}(x)= \begin{cases}I & \text { if } x \in \Omega \backslash \rho D  \tag{3.1}\\ \gamma_{1, \rho}(x) & \text { if } x \in \rho D\end{cases}
$$

where $\gamma_{1, \rho}$ is an arbitrary matrix-valued function in $L_{+}^{\infty}(\rho D)$. The novelty of the present results is the fact that $\gamma_{1, \rho}$ is an arbitrary matrix valued function in $L_{+}^{\infty}(\rho D)$, and the fact that all the estimates and convergence (approximation) statements are uniform with respect to $\gamma_{1, \rho} \in L_{+}^{\infty}(\rho D)$.

Let $\gamma_{\rho}^{*}$ denote the rescaled coefficient

$$
\gamma_{\rho}^{*}(z)= \begin{cases}I & \text { if } z \in \mathbb{R}^{d} \backslash D \\ \gamma_{1, \rho}(\rho z) & \text { if } z \in D\end{cases}
$$

and let $\phi_{k}$ be the solution to

$$
\begin{equation*}
\nabla \cdot\left(\gamma_{\rho}^{*} \nabla \phi_{k}\right)=0 \quad \text { in } \mathbb{R}^{d}, \quad \text { with } \phi_{k}(z)-z_{k} \rightarrow 0 \text { as }|z| \rightarrow \infty . \tag{3.2}
\end{equation*}
$$

We note that $\phi_{k}(z)=\psi_{k}(z)+z_{k}$, where $\psi_{k}$ satisfies

$$
\begin{cases}\Delta \psi_{k}=0 & \text { in } \mathbb{R}^{d} \backslash \bar{D},  \tag{3.3}\\ \nabla \cdot\left(\gamma_{1, \rho}(\rho \cdot) \nabla \psi_{k}\right)=-\nabla \cdot\left(\gamma_{1, \rho}(\rho \cdot) \nabla z_{k}\right) & \text { in } D, \\ \left.\frac{\partial \psi_{k}}{\partial n}\right|_{\text {ext }}-\left.\left(\gamma_{1, \rho}(\rho \cdot) \nabla \psi_{k}\right) \cdot n\right|_{\text {int }}=\left(\gamma_{1, \rho}(\rho \cdot) n\right)_{k}-n_{k} & \text { on } \partial D, \\ {\left[\psi_{k}\right]=0} & \text { on } \partial D,\end{cases}
$$

and $\psi_{k}(z) \rightarrow 0$ as $|z| \rightarrow \infty$. Here $[\psi]=\left.\psi\right|_{\text {ext }}-\left.\psi\right|_{\text {int }}$ denotes the jump of the function $\psi$ across $\partial D$. It is easy to see that the solution $\psi_{k}$ (up to a constant, for $d=2$ ) coincides with the unique solution to (3.3) in $W^{1}\left(\mathbb{R}^{d}\right)$, the existence of which is guaranteed by Proposition 4 in Appendix A. We define the function $L_{\rho}$ :

$$
\begin{equation*}
L_{\rho}(x)=\nabla_{y} \Phi(x, 0) \cdot \int_{D}\left(I-\gamma_{1, \rho}(\rho z)\right) \nabla \phi_{k}(z) d z \frac{\partial}{\partial x_{k}} u_{0}(0), \tag{3.4}
\end{equation*}
$$

and the function $W_{\rho}$ :

$$
\left\{\begin{array}{l}
\Delta W_{\rho}=0 \quad \text { in } \Omega  \tag{3.5}\\
\frac{\partial W_{\rho}}{\partial n}=-\frac{\partial L_{\rho}}{\partial n} \quad \text { on } \partial \Omega
\end{array}\right.
$$

normalized by $\int_{\partial \Omega} W_{\rho} d \sigma=-\int_{\partial \Omega} L_{\rho} d \sigma$. Here $\Phi(x, y)$ is the free space fundamental solution for the Laplacian

$$
\Phi(x, y)= \begin{cases}-\frac{1}{2 \pi} \ln |x-y| & \text { if } d=2 \\ \frac{1}{4 \pi|x-y|} & \text { if } d=3\end{cases}
$$

We note that $\psi_{k}, \phi_{k}, L_{\rho}$ and $W_{\rho}$ generically all depend on $\rho$; they would be independent of $\rho$ if we only considered $\gamma_{1, \rho} \in L_{+}^{\infty}(\rho D)$ of the form $\gamma_{1, \rho}(x)=\gamma_{1}(x / \rho)$ for a given fixed $\gamma_{1} \in L_{+}^{\infty}(D)$ (for instance if we considered inhomogeneities $\rho D$ of fixed constant conductivity $\left.\gamma_{1}\right)$. It is easy to see that the matrix $\int_{D}\left(I-\gamma_{1, \rho}(\rho z)\right)_{i j} \partial_{j} \phi_{k}(z) d z$ is symmetric.

In the case $\gamma_{1, \rho}$ is constant (but possibly dependent on $\rho$ ) we define the matrix

$$
\begin{equation*}
M_{j k}=\frac{1}{|D|} \int_{D} \frac{\partial \phi_{k}}{\partial z_{j}} d z \tag{3.6}
\end{equation*}
$$

We note that $M$ may depend on $\rho$, and that it is not necessarily symmetric (though ( $I-\gamma_{1, \rho}$ ) $M$ is). Then

$$
L_{\rho}(x)=|D|\left(I-\gamma_{1, \rho}\right)_{i j} M_{j k} \frac{\partial}{\partial x_{k}} u_{0}(0) \frac{\partial}{\partial y_{i}} \Phi(x, 0),
$$

and it is easy to see that

$$
\begin{equation*}
L_{\rho}(x)+W_{\rho}(x)=|D|\left(I-\gamma_{1, \rho}\right)_{i j} M_{j k} \frac{\partial}{\partial x_{k}} u_{0}(0) \frac{\partial}{\partial y_{i}} G(x, 0), \tag{3.7}
\end{equation*}
$$

where $G$ is the special Green's function introduced in (1.6). Here and in the future we use the Einstein summation convention, i.e., repeated indices (representing integers) in a single term implies summation from 1 to $d$.

Theorem 2. Suppose $f$ is in $H^{-1 / 2}(\partial \Omega)$ with $\int_{\partial \Omega} f d \sigma=0$, and $\gamma_{\rho}$ is given by (3.1) with $\gamma_{1, \rho} \in L_{+}^{\infty}(\rho D)$. Let $u_{0}$ and $u_{\rho}$ denote the solutions to (1.1) and (1.3), normalized by $\int_{\partial \Omega} u_{0} d \sigma=\int_{\partial \Omega} u_{\rho} d \sigma=0$. Let $L_{\rho}(x)$ and $W_{\rho}(x)$ be given by (3.4) and (3.5). Then for any fixed $\delta>0$,

$$
\lim _{\rho \rightarrow 0} \int_{\Omega \backslash B_{\delta}}\left|\frac{1}{\rho^{d}} \nabla\left(u_{\rho}-u_{0}\right)-\nabla L_{\rho}-\nabla W_{\rho}\right|^{2} d x=0 .
$$

The limiting process is uniform in $\gamma_{1, \rho} \in L_{+}^{\infty}(\rho D)$ and in $f \in\left\{\|f\|_{H^{-\frac{1}{2}}(\partial \Omega)} \leqslant 1, \int_{\partial \Omega} f d \sigma=0\right\}$. That is, for any $\epsilon>0$ and $\delta>0$, there exists a positive constant $\rho_{0}(\epsilon, \delta)$, such that

$$
\int_{\Omega \backslash B_{\delta}}\left|\frac{1}{\rho^{d}} \nabla\left[u_{\rho}-u_{0}\right]-\nabla L_{\rho}-\nabla W_{\rho}\right|^{2} d x<\epsilon,
$$

for all $\rho<\rho_{0}$, all $\gamma_{1, \rho} \in L_{+}^{\infty}(\rho D)$ and all $f \in\left\{\|f\|_{H^{-\frac{1}{2}(\partial \Omega)}} \leqslant 1, \int_{\partial \Omega} f d \sigma=0\right\}$. The term $\nabla L_{\rho}+\nabla W_{\rho}$ is bounded in $L^{2}\left(\Omega \backslash \overline{B_{\delta}}\right)$, uniformly with respect to $\rho, \gamma_{1, \rho} \in L_{+}^{\infty}(\rho D)$, and $f \in\left\{\|f\|_{H^{-\frac{1}{2}}(\partial \Omega)} \leqslant 1, \int_{\partial \Omega} f d \sigma=0\right\}$.

We may without loss of generality suppose that $\overline{B_{\delta}} \subset \Omega$ and that $K \rho_{0}<\delta / 2$. Then the function $\frac{1}{\rho^{d}}\left(u_{\rho}-u_{0}\right)-$ $\left(L_{\rho}+W_{\rho}\right)$ is harmonic in $\Omega \backslash \overline{B_{\delta / 2}}$, with $\frac{\partial}{\partial n}\left(\left(u_{\rho}-u_{0}\right)-\left(L_{\rho}+W_{\rho}\right)\right)=0$ on $\partial \Omega$. A combination of standard elliptic theory and the energy estimate of Theorem 2 therefore yields similar estimates in any $H^{s}\left(\Omega \backslash \overline{B_{\delta}}\right)$ (or $H^{s}(\partial \Omega)$ ) norm, as stated in the following corollary.

Corollary 3. Suppose $f$ is in $H^{-1 / 2}(\partial \Omega)$ with $\int_{\partial \Omega} f d \sigma=0$, and $\gamma_{\rho}$ is given by (3.1) with $\gamma_{1, \rho} \in L_{+}^{\infty}(\rho D)$. Let $u_{0}$ and $u_{\rho}$ denote the solutions to (1.1) and (1.3), normalized by $\int_{\partial \Omega} u_{0} d \sigma=\int_{\partial \Omega} u_{\rho} d \sigma=0$. Let $L_{\rho}(x)$ and $W_{\rho}(x)$ be given by (3.4) and (3.5), and normalized by $\int_{\partial \Omega}\left(L_{\rho}+W_{\rho}\right) d \sigma=0$. Then for any fixed $\delta>0$, and any $s \in \mathbb{R}_{+}$

$$
\left\|u_{\rho}-u_{0}-\rho^{d}\left(L_{\rho}+W_{\rho}\right)\right\|_{H^{s}\left(\Omega \backslash \overline{B_{\delta}}\right)}=\rho^{d} o(1),
$$

where the term o(1) tends to zero uniformly in $\gamma_{1, \rho} \in L_{+}^{\infty}(\rho D)$ and in $f \in\left\{\|f\|_{H^{-\frac{1}{2}(\partial \Omega)}} \leqslant 1, \int_{\partial \Omega} f d \sigma=0\right\}$ as $\rho \rightarrow 0$. As a consequence we also have

$$
\left\|u_{\rho}-u_{0}-\rho^{d}\left(L_{\rho}+W_{\rho}\right)\right\|_{H^{s}(\partial \Omega)}=\rho^{d} o(1)
$$

for any $s \in \mathbb{R}_{+}$. The term $L_{\rho}+W_{\rho}$ is bounded in $H^{s}\left(\Omega \backslash \overline{B_{\delta}}\right)$ (and in $H^{s}(\partial \Omega)$ ) uniformly with respect to $\rho$, $\gamma_{1, \rho} \in$ $L_{+}^{\infty}(\rho D)$, and $f \in\left\{\|f\|_{H^{-\frac{1}{2}}(\partial \Omega)} \leqslant 1, \int_{\partial \Omega} f d \sigma=0\right\}$.

As stated the terms $L_{\rho}$ and $W_{\rho}$ in general depend on $\rho$; Theorem 2 and Corollary 3 therefore do not assert the existence of a limit of $\left(u_{\rho}-u_{0}\right) / \rho^{d}$ as $\rho \rightarrow 0$. Due to the boundedness of the term $L_{\rho}+W_{\rho}$ we may arrive at a limit by extraction of a subsequence, much as was the case with the representation formulas in [4]. The boundedness of the term $L_{\rho}+W_{\rho}$ as stated in Theorem 2 and Corollary 3 is equivalent to the boundedness of the symmetric matrix $\int_{D}\left(I-\gamma_{1, \rho}(\rho z)\right)_{i j} \frac{\partial}{\partial z_{j}} \phi_{k}(z) d z$ as a function of $\rho$ and $\gamma_{1, \rho}$. The assumption that $\gamma_{0}$ be constant (the identity, after a linear change of variables) may also be relaxed. For smooth $\gamma_{0}$ we may carry out a "freezing of the coefficient"argument, much like in [5]. The formulation of Theorem 2 and Corollary 3 would not change, but the identity matrix appearing in the definition of $\gamma_{\rho}^{*}$ and in the formula (3.4) would be replaced by $\gamma_{0}(0)$, the first equation of (3.3) would become $\nabla \cdot\left(\gamma_{0}(0) \nabla \psi_{k}\right)=0$ in $\mathbb{R}^{d} \backslash \bar{D}$, and the transmission condition of (3.3) would be replaced by

$$
\left.\left(\gamma_{0}(0) \nabla \psi_{k}\right) \cdot n\right|_{\mathrm{ext}}-\left.\left(\gamma_{1, \rho}(\rho \cdot) \nabla \psi_{k}\right) \cdot n\right|_{\mathrm{int}}=\left(\gamma_{1, \rho}(\rho \cdot) n\right)_{k}-\left(\gamma_{0}(0) n\right)_{k} .
$$

Furthermore $\Phi$ would be replaced by a Green's function for the operator $\nabla \cdot\left(\gamma_{0} \nabla \cdot\right)$, and $W_{\rho}$ would satisfy $\nabla$. $\left(\gamma_{0} \nabla W_{\rho}\right)=0$ in $\Omega, \nabla W_{\rho} \cdot n=-\nabla L_{\rho} \cdot n$ on $\partial \Omega$. As mentioned earlier, the terms $L_{\rho}$ and $W_{\rho}$ are independent of $\rho$ if $\gamma_{1, \rho}$ is of the form $\gamma_{1, \rho}(x)=\gamma_{1}(x / \rho)$, with $\gamma_{1}$ independent of $\rho$. In that case it would indeed be possible to extend the results proven here to any order in $\rho$, in other words to prove that (for a single inhomogeneity of the form $\rho D$ ) one has an asymptotic expansion to any order (as already established in [1]) which is uniform in $\gamma_{1}$ and $f \in\left\{\|f\|_{H^{-\frac{1}{2}}(\partial \Omega)} \leqslant 1, \int_{\partial \Omega} f d \sigma=0\right\}$.

Before proceeding with the proof of Theorem 2 we introduce some auxiliary functions. The function $J$ is defined as follows: if $d=3$, then $J$ is the $W^{1}\left(\mathbb{R}^{3} \backslash \bar{D}\right)$ solution of

$$
\begin{cases}\Delta J=0 & \text { in } \mathbb{R}^{3} \backslash \bar{D} \\ \frac{\partial J}{\partial n}=1 & \text { on } \partial D\end{cases}
$$

if $d=2$, then $J=0$. The existence and uniqueness of $J$ is assured by Proposition 3 in Appendix A. The function $\hat{H}_{1, \rho}$ is the $W^{1}\left(\mathbb{R}^{d} \backslash \bar{D}\right)$ solution of

$$
\begin{cases}\Delta \hat{H}_{1, \rho}=0 & \text { in } \mathbb{R}^{d} \backslash \bar{D} \\ \hat{H}_{1, \rho}(x)=\frac{1}{\rho}\left(u_{0}(\rho x)-u_{0}(0)\right) & \text { on } \partial D\end{cases}
$$

for $d=2$ as well as $d=3$. The existence and uniqueness of $\hat{H}_{1, \rho}$ is assured by Proposition 2 in Appendix A. The function $\hat{H}_{1}$ is the $W^{1}\left(\mathbb{R}^{d} \backslash \bar{D}\right)$ solution of

$$
\begin{cases}\Delta \hat{H}_{1}=0 & \text { in } \mathbb{R}^{d} \backslash \bar{D}, \\ \hat{H}_{1}(x)=\nabla u_{0}(0) \cdot x & \text { on } \partial D,\end{cases}
$$

for $d=2$ as well as $d=3$. The existence and uniqueness of $\hat{H}_{1}$ is again assured by Proposition 2 in Appendix A. Since $\left(u_{0}(\rho x)-u_{0}(0)\right) / \rho \rightarrow \nabla u_{0}(0) \cdot x$ in $H^{1 / 2}(\partial D)$ as $\rho \rightarrow 0$, the estimate (A.1) from Proposition 2 gives that

$$
\begin{equation*}
\hat{H}_{1, \rho} \rightarrow \hat{H}_{1} \quad \text { in } W^{1}\left(\mathbb{R}^{d} \backslash \bar{D}\right) \text { as } \rho \rightarrow 0 \tag{3.8}
\end{equation*}
$$

We also define

$$
\begin{equation*}
\lambda_{\rho}=\frac{1}{|D|} \int_{\partial D} \frac{\partial \hat{H}_{1, \rho}}{\partial n} d \sigma \quad \text { and } \quad \lambda_{0}=\frac{1}{|D|} \int_{\partial D} \frac{\partial \hat{H}_{1}}{\partial n} d \sigma \tag{3.9}
\end{equation*}
$$

Due to the convergence (3.8) and the fact that both $\hat{H}_{1, \rho}$ and $\hat{H}_{1}$ are harmonic in $\mathbb{R}^{d} \backslash \bar{D}$ it follows that

$$
\begin{equation*}
\frac{\partial \hat{H}_{1, \rho}}{\partial n} \rightarrow \frac{\partial \hat{H}_{1}}{\partial n} \quad \text { in } H^{-\frac{1}{2}}(\partial D), \tag{3.10}
\end{equation*}
$$

and therefore, in particular

$$
\begin{equation*}
\lambda_{\rho} \rightarrow \lambda_{0} \quad \text { as } \rho \rightarrow 0 . \tag{3.11}
\end{equation*}
$$

The convergences in (3.8), (3.10) and (3.11) are uniform in $f \in\left\{\|f\|_{H^{-\frac{1}{2}(\partial \Omega)}} \leqslant 1, \int_{\partial \Omega} f d \sigma=0\right\}$, since all the involved quantities only depend on values of $u_{0}$ near $x=0$. Finally we define $u_{1, \rho} \in H^{1}(\Omega \backslash \overline{\rho D})$ to be the unique solution to

$$
\begin{cases}\Delta u_{1, \rho}=0 & \text { in } \Omega \backslash \overline{\rho D},  \tag{3.12}\\ \frac{\partial u_{1, \rho}}{\partial n}=f & \text { on } \partial \Omega, \\ u_{1, \rho}=u_{0}(0)+\rho \lambda_{\rho} J(\cdot / \rho) & \text { on } \partial \rho D .\end{cases}
$$

In order to study the behavior of $\frac{1}{\rho^{d}} \nabla\left(u_{\rho}-u_{0}\right)$ as required for the proof of Theorem 2 we divide the function $\frac{1}{\rho^{d}}\left(u_{\rho}-u_{0}\right)$ into two terms:

$$
\begin{equation*}
\frac{1}{\rho^{d}}\left(u_{\rho}-u_{0}\right)=\frac{1}{\rho^{d}} w_{1, \rho}+\frac{1}{\rho^{d}} w_{2, \rho}, \tag{3.13}
\end{equation*}
$$

with

$$
\begin{equation*}
w_{1, \rho}=u_{1, \rho}-u_{0} \tag{3.14}
\end{equation*}
$$

and

$$
\begin{equation*}
w_{2, \rho}=u_{\rho}-u_{1, \rho} . \tag{3.15}
\end{equation*}
$$

In the following two sections we shall study the behavior of $\frac{1}{\rho^{d}} w_{1, \rho}$ and $\frac{1}{\rho^{d}} w_{2, \rho}$.

### 3.1. A uniform estimate for the first remainder term

The function $w_{1, \rho}=u_{1, \rho}-u_{0} \in H^{1}(\Omega \backslash \overline{\rho D)}$ satisfies

$$
\begin{cases}\Delta w_{1, \rho}=0 & \text { in } \Omega \backslash \overline{\rho D} \\ \frac{\partial w_{1, \rho}}{\partial n}=0 & \text { on } \partial \Omega \\ w_{1, \rho}=\psi_{1, \rho}:=u_{0}(0)-u_{0}(\cdot)+\rho \lambda_{\rho} J(\cdot / \rho) & \text { on } \partial(\rho D)\end{cases}
$$

We define

$$
H_{1, \rho}=-\hat{H}_{1, \rho}+\lambda_{\rho} J \in W^{1}\left(\mathbb{R}^{d} \backslash \bar{D}\right)
$$

and

$$
H_{1}=-\hat{H}_{1}+\lambda_{0} J \in W^{1}\left(\mathbb{R}^{d} \backslash \bar{D}\right)
$$

The function $H_{1, \rho}$ satisfies

$$
\begin{cases}\Delta H_{1, \rho}=0 & \text { in } \mathbb{R}^{d} \backslash \bar{D} \\ H_{1, \rho}(x)=\frac{1}{\rho} \psi_{1, \rho}(\rho x) & \text { on } \partial D\end{cases}
$$

and due to the convergence results (3.8), (3.10), and (3.11) it follows that

$$
\begin{equation*}
H_{1, \rho} \rightarrow H_{1} \quad \text { in } W^{1}\left(\mathbb{R}^{d} \backslash \bar{D}\right), \quad \text { and } \quad \frac{\partial}{\partial n} H_{1, \rho} \rightarrow \frac{\partial}{\partial n} H_{1} \quad \text { in } H^{-1 / 2}(\partial D) \tag{3.16}
\end{equation*}
$$

as $\rho \rightarrow 0$. This convergence is uniform in $f \in\left\{\|f\|_{H^{-\frac{1}{2}(\partial \Omega)}} \leqslant 1, \int_{\partial \Omega} f d \sigma=0\right\}$. Applying Proposition 2 we get

$$
H_{1, \rho}(x)=\int_{\partial D} \frac{\partial}{\partial n_{y}} \Phi(x, y) H_{1, \rho}(y) d \sigma_{y}-\int_{\partial D} \Phi(x, y) \frac{\partial}{\partial n} H_{1, \rho}(y) d \sigma_{y}+C_{\rho}
$$

for some constant $C_{\rho}$. We note that, due to the particular choice of $\lambda_{\rho}$ (and (A.2) for $d=2$ )

$$
\int_{\partial D} \frac{\partial}{\partial n} H_{1, \rho} d \sigma=0
$$

Let $\Lambda_{D}$ denote the Neumann to Dirichlet map associated with the Laplacian on $D$. In other words: for any $\phi \in$ $H^{-1 / 2}(\partial D)$ with $\int_{\partial D} \phi d \sigma=0$, set $\Lambda_{D}(\phi)=\left.w\right|_{\partial D} \in H^{1 / 2}(\partial D)$, where $w$ is the solution to

$$
\Delta w=0 \quad \text { in } D, \quad \frac{\partial}{\partial n} w=\phi \quad \text { on } \partial D, \quad \int_{\partial D} w d \sigma=0
$$

With the use of Green's formula and this notation the above representation formula for $H_{1, \rho}$ may be rewritten

$$
H_{1, \rho}(x)=\int_{\partial D} \frac{\partial}{\partial n_{y}} \Phi(x, y)\left[H_{1, \rho}(y)-\Lambda_{D}\left(\frac{\partial}{\partial n} H_{1, \rho}\right)(y)\right] d \sigma_{y}+C_{\rho}
$$

for $x \in \mathbb{R}^{d} \backslash \bar{D}$. The rescaled function

$$
\begin{equation*}
v_{1, \rho}(x)=\rho H_{1, \rho}(x / \rho) \tag{3.17}
\end{equation*}
$$

may then be represented as

$$
\begin{aligned}
v_{1, \rho}(x) & =\rho \int_{\partial D} \frac{\partial}{\partial n_{y}} \Phi(x / \rho, y)\left[H_{1, \rho}(y)-\Lambda_{D}\left(\frac{\partial}{\partial n} H_{1, \rho}\right)(y)\right] d \sigma_{y}+\rho C_{\rho} \\
& =\rho^{d} \int_{\partial D} \frac{\partial}{\partial n_{y}} \Phi(x, \rho y)\left[H_{1, \rho}(y)-\Lambda_{D}\left(\frac{\partial}{\partial n} H_{1, \rho}\right)(y)\right] d \sigma_{y}+\rho C_{\rho}
\end{aligned}
$$

Due to the convergence result (3.16) and the continuity of the operator $\Lambda_{D}$ from $H^{-1 / 2}$ to $H^{1 / 2}$ it follows that

$$
H_{1, \rho}-\Lambda_{D}\left(\frac{\partial}{\partial n} H_{1, \rho}\right) \rightarrow H_{1}-\Lambda_{D}\left(\frac{\partial}{\partial n} H_{1}\right) \quad \text { in } H^{1 / 2}(\partial D)
$$

Thus

$$
\begin{equation*}
\lim _{\rho \rightarrow 0} \int_{\Omega \backslash B_{\delta}}\left|\frac{1}{\rho^{d}} \nabla v_{1, \rho}-\nabla L_{1}\right|^{2} d x=0 \tag{3.18}
\end{equation*}
$$

for any fixed $\delta>0$, and

$$
\begin{equation*}
\lim _{\rho \rightarrow 0} \frac{1}{\rho^{d}} \frac{\partial v_{1, \rho}}{\partial n}=\frac{\partial L_{1}}{\partial n}, \quad \text { in } H^{-1 / 2}(\partial \Omega) \tag{3.19}
\end{equation*}
$$

where

$$
L_{1}(x):=\nabla_{y} \Phi(x, 0) \cdot \int_{\partial D}\left(H_{1}-\Lambda_{D}\left(\frac{\partial}{\partial n} H_{1}\right)\right) n_{y} d \sigma_{y}, \quad x \in \Omega \backslash\{0\} .
$$

The convergence is uniform in $f \in\left\{\|f\|_{H^{-\frac{1}{2}}(\partial \Omega)} \leqslant 1, \int_{\partial \Omega} f d \sigma=0\right\}$. In order to complete the analysis of the behavior of $\frac{1}{\rho^{d}} w_{1, \rho}$ it only remains to examine

$$
\begin{equation*}
W_{1, \rho}:=\frac{1}{\rho^{d}}\left(w_{1, \rho}-v_{1, \rho}\right) \tag{3.20}
\end{equation*}
$$

For that purpose we shall make use of the following lemma.
Lemma 1. Suppose $f_{\rho} \in H^{-\frac{1}{2}}(\partial \Omega)$ and $f_{0} \in H^{-\frac{1}{2}}(\partial \Omega)$ with $\int_{\partial \Omega} f_{\rho}=\int_{\partial \Omega} f_{0}=0$, and suppose $f_{\rho} \rightarrow f_{0}$ in $H^{-\frac{1}{2}}(\partial \Omega)$ as $\rho \rightarrow 0$. Let $w_{\rho}$ and $w_{0}$ denote solutions to

$$
\left\{\begin{array} { l l } 
{ \Delta w _ { \rho } = 0 } & { \text { in } \Omega \backslash \overline { \rho D } , } \\
{ \frac { \partial w _ { \rho } } { \partial n } = f _ { \rho } } & { \text { on } \partial \Omega , } \\
{ w _ { \rho } = 0 } & { \text { on } \partial \rho D , }
\end{array} \quad \text { and } \quad \left\{\begin{array}{ll}
\Delta w_{0}=0 & \text { in } \Omega, \\
\frac{\partial w_{0}}{\partial n}=f_{0} & \text { on } \partial \Omega,
\end{array}\right.\right.
$$

respectively. Then

$$
\lim _{\rho \rightarrow 0} \int_{\Omega \backslash \overline{\rho D}}\left|\nabla w_{\rho}-\nabla w_{0}\right|^{2} d x=0
$$

The convergence is uniform in the sense that given any $\epsilon>0$ there exists $\tau(\epsilon)>0$ such that for any $f_{0} \in$ $\left\{\|f\|_{H^{-\frac{1}{2}}{ }_{(\partial \Omega)}} \leqslant 1, \int_{\partial \Omega} f d \sigma=0\right\}$,

$$
\rho<\tau(\epsilon), \quad \text { and } \quad f_{\rho} \in H^{-1 / 2}(\partial \Omega), \quad\left\|f_{\rho}-f_{0}\right\|_{H^{-1 / 2}(\partial \Omega)}<\tau(\epsilon)
$$

implies

$$
\int_{\Omega \backslash \overline{\rho D}}\left|\nabla w_{\rho}-\nabla w_{0}\right|^{2} d x<\epsilon
$$

Proof. Standard coercivity arguments (in this case, direct integration by parts) gives that

$$
\left\|\nabla w_{\rho}\right\|_{L^{2}(\Omega \backslash \overline{\rho D})} \leqslant C\left\|f_{\rho}\right\|_{H^{-1 / 2}(\partial \Omega)}
$$

Let $E_{f}(w)$ denote the energy

$$
\frac{1}{2} \int_{\Omega}|\nabla w|^{2} d x-\int_{\partial \Omega} f w d \sigma
$$

We extend $w_{\rho}$ to all of $\Omega$ by setting it to zero on $\rho D$. For simplicity we also call this $H^{1}(\Omega)$ extension $w_{\rho}$. It is well known that $w_{\rho}$ is the minimizer of $E_{f_{\rho}}(\cdot)$ in $H^{1}(\Omega) \cap\{w: w \equiv 0$ on $\rho D\}$, and that $w_{0}$ is the minimizer of $E_{f_{0}}(\cdot)$ in $H^{1}(\Omega)$. A simple calculation gives

$$
\begin{align*}
\int_{\Omega}\left|\nabla\left(w_{\rho}-w_{0}\right)\right|^{2} d x & =2\left[E_{f_{\rho}}\left(w_{\rho}\right)-E_{f_{0}}\left(w_{0}\right)\right]+2 \int_{\partial \Omega}\left(f_{\rho}-f_{0}\right) w_{\rho} d \sigma \\
& \leqslant 2\left[E_{f_{\rho}}\left(w_{\rho}\right)-E_{f_{0}}\left(w_{0}\right)\right]+C\left\|f_{\rho}-f_{0}\right\|_{H^{-1 / 2}(\partial \Omega)}\left\|\nabla w_{\rho}\right\|_{L^{2}(\Omega)} \\
& \leqslant 2\left[E_{f_{\rho}}\left(w^{*}\right)-E_{f_{0}}\left(w_{0}\right)\right]+C\left\|f_{\rho}-f_{0}\right\|_{H^{-1 / 2}(\partial \Omega)}\left\|f_{\rho}\right\|_{H^{-1 / 2}(\partial \Omega)} \tag{3.21}
\end{align*}
$$

for any $w^{*} \in H^{1}(\Omega) \cap\{w: w \equiv 0$ on $\rho D\}$. We proceed to construct an appropriate test function $w^{*}$. For simplicity assume $B_{1}$ is compactly contained in $\Omega$ and suppose $\rho D \subset B_{K \rho}$, with $K \rho<1$. Define

$$
\chi_{\rho}(x)= \begin{cases}0 & \text { if }|x|<K \rho \\ 1-\frac{\log |x|}{\log (K \rho)} & \text { if } K \rho<|x|<1, \\ 1 & \text { if } 1<|x|\end{cases}
$$

and set $\tilde{w}_{\rho}=\chi_{\rho} w_{0} \in H^{1}(\Omega) \cap\{w: w \equiv 0$ on $\rho D\}$. Then

$$
\begin{align*}
\int_{K \rho<|x|<1}\left|\nabla\left(\tilde{w}_{\rho}-w_{0}\right)\right|^{2} d x= & \frac{1}{(\log (K \rho))^{2}} \int_{K \rho<|x|<1}\left|\nabla\left(\log |x| w_{0}\right)\right|^{2} d x \\
\leqslant & \frac{C}{(\log (K \rho))^{2}}\left(\sup _{x \in B_{1}}\left|w_{0}(x)\right|^{2} \int_{K \rho<|x|<1} \frac{1}{|x|^{2}} d x\right. \\
& \left.+\sup _{x \in B_{1}}\left|\nabla w_{0}(x)\right|^{2} \int_{K \rho<|x|<1}(\log |x|)^{2} d x\right) \\
\leqslant & \frac{C}{(\log (K \rho))^{2}}\left(\sup _{x \in B_{1}}\left|w_{0}(x)\right|^{2}+\sup _{x \in B_{1}}\left|\nabla w_{0}(x)\right|^{2}\right)|\log (\rho)| \\
& \rightarrow 0 \text { as } \rho \rightarrow 0 . \tag{3.22}
\end{align*}
$$

The convergence is uniform on $\left\{\left\|f_{0}\right\|_{H^{-\frac{1}{2}(\partial \Omega)}} \leqslant 1, \int_{\partial \Omega} f_{0} d \sigma=0\right\}$. We also have

$$
\begin{aligned}
\int_{\Omega}\left|\nabla\left(\tilde{w}_{\rho}-w_{0}\right)\right|^{2} d x & =\int_{|x|<K \rho}\left|\nabla w_{0}\right|^{2} d x+\int_{K \rho<|x|<1}\left|\nabla\left(\tilde{w}_{\rho}-w_{0}\right)\right|^{2} d x \\
& \leqslant \int_{K \rho<|x|<1}\left|\nabla\left(\tilde{w}_{\rho}-w_{0}\right)\right|^{2} d x+C \rho^{d} \sup _{x \in B_{1}}\left|\nabla w_{0}(x)\right|^{2},
\end{aligned}
$$

and by combination with (3.22) we therefore get

$$
\left\|\nabla\left(\tilde{w}_{\rho}-w_{0}\right)\right\|_{L^{2}(\Omega)} \rightarrow 0 \quad \text { as } \rho \rightarrow 0 .
$$

The convergence is uniform on $\left\{\left\|f_{0}\right\|_{H^{-\frac{1}{2}}(\partial \Omega)} \leqslant 1, \int_{\partial \Omega} f_{0} d \sigma=0\right\}$. Since

$$
\left|\left\|\nabla \tilde{w}_{\rho}\right\|_{L^{2}(\Omega)}-\left\|\nabla w_{0}\right\|_{L^{2}(\Omega)}\right| \leqslant\left\|\nabla\left(\tilde{w}_{\rho}-w_{0}\right)\right\|_{L^{2}(\Omega)},
$$

it follows that $\left\|\nabla \tilde{w}_{\rho}\right\|_{L^{2}(\Omega)}$ is bounded uniformly in $\rho$ and in $f_{0} \in\left\{\|f\|_{H^{-\frac{1}{2}}(\partial \Omega)} \leqslant 1, \int_{\partial \Omega} f d \sigma=0\right\}$, and so

$$
\begin{aligned}
\left|\left\|\nabla \tilde{w}_{\rho}\right\|_{L^{2}(\Omega)}^{2}-\left\|\nabla w_{0}\right\|_{L^{2}(\Omega)}^{2}\right| & =\left|\left\|\nabla \tilde{w}_{\rho}\right\|_{L^{2}(\Omega)}-\left\|\nabla w_{0}\right\|_{L^{2}(\Omega)}\right|\left(\left\|\nabla \tilde{w}_{\rho}\right\|_{L^{2}(\Omega)}+\left\|\nabla w_{0}\right\|_{L^{2}(\Omega)}\right) \\
& \leqslant\left\|\nabla\left(\tilde{w}_{\rho}-w_{0}\right)\right\|_{L^{2}(\Omega)}\left(\left\|\nabla \tilde{w}_{\rho}\right\|_{L^{2}(\Omega)}+\left\|\nabla w_{0}\right\|_{L^{2}(\Omega)}\right) \\
& \rightarrow 0 \quad \text { as } \rho \rightarrow 0,
\end{aligned}
$$

uniformly on $\left\{\left\|f_{0}\right\|_{H^{-\frac{1}{2}(\partial \Omega)}} \leqslant 1, \int_{\partial \Omega} f_{0} d \sigma=0\right\}$. Due to the fact that $\tilde{w}_{\rho}=w_{0}$ on $\partial \Omega$ we have the estimate

$$
\begin{align*}
2\left[E_{f_{\rho}}\left(\tilde{w}_{\rho}\right)-E_{f_{0}}\left(w_{0}\right)\right] & =\left\|\nabla \tilde{w}_{\rho}\right\|_{L^{2}(\Omega)}^{2}-\left\|\nabla w_{0}\right\|_{L^{2}(\Omega)}^{2}+\int_{\partial \Omega}\left(f_{0}-f_{\rho}\right) w_{0} \\
& \leqslant\left\|\nabla \tilde{w}_{\rho}\right\|_{L^{2}(\Omega)}^{2}-\left\|\nabla w_{0}\right\|_{L^{2}(\Omega)}^{2}+C\left\|f_{\rho}-f_{0}\right\|_{H^{-1 / 2}(\partial \Omega)}\left\|f_{0}\right\|_{H^{-1 / 2}(\partial \Omega)} . \tag{3.23}
\end{align*}
$$

From 3.21 (with $w^{*}=\tilde{w}_{\rho}$ ) and (3.23) we now conclude that

$$
\begin{aligned}
\int_{\Omega}\left|\nabla\left(w_{\rho}-w_{0}\right)\right|^{2} d x \leqslant & {\left[E_{f_{\rho}}\left(\tilde{w}_{\rho}\right)-E_{f_{0}}\left(w_{0}\right)\right]+C\left\|f_{\rho}-f_{0}\right\|_{H^{-1 / 2}(\partial \Omega)}\left\|f_{\rho}\right\|_{H^{-1 / 2}(\partial \Omega)} } \\
\leqslant & \frac{1}{2}\left(\left\|\nabla \tilde{w}_{\rho}\right\|_{L^{2}(\Omega)}^{2}-\left\|\nabla w_{0}\right\|_{L^{2}(\Omega)}^{2}\right) \\
& +C\left\|f_{\rho}-f_{0}\right\|_{H^{-1 / 2}(\partial \Omega)}\left(\left\|f_{\rho}\right\|_{H^{-1 / 2}(\partial \Omega)}+\left\|f_{0}\right\|_{H^{-1 / 2}(\partial \Omega)}\right) \\
\rightarrow & 0 \quad \text { as } \rho \rightarrow 0
\end{aligned}
$$

Since the term $\left\|\nabla \tilde{w}_{\rho}\right\|_{L^{2}(\Omega)}^{2}-\left\|\nabla w_{0}\right\|_{L^{2}(\Omega)}^{2}$ converges uniformly with respect to $f_{0} \in\left\{\|f\|_{H^{-\frac{1}{2}(\partial \Omega)}} \leqslant 1, \int_{\partial \Omega} f d \sigma=0\right\}$ this last convergence is clearly uniform in the sense asserted in this lemma.

We now return to the estimation of $W_{1, \rho}:=\frac{1}{\rho^{d}}\left(w_{1, \rho}-v_{1, \rho}\right)$. This function is the unique solution to

$$
\begin{cases}\Delta W_{1, \rho}=0 & \text { in } \Omega \backslash \overline{\rho D} \\ \frac{\partial W_{1, \rho}}{\partial n}=-\frac{1}{\rho^{d}} \frac{\partial v_{1, \rho}}{\partial n}(x) & \text { on } \partial \Omega \\ W_{1, \rho}=0 & \text { on } \partial \rho D\end{cases}
$$

Let $W_{1}$ denote a solution to

$$
\begin{cases}\Delta W_{1}=0 & \text { in } \Omega \\ \frac{\partial W_{1}}{\partial n}=-\frac{\partial L_{1}}{\partial n} & \text { on } \partial \Omega\end{cases}
$$

According to (3.19) $\frac{1}{\rho^{d}} \frac{\partial v_{1, \rho}}{\partial n}$ converges to $\frac{\partial L_{1}}{\partial n}$ in $H^{-1 / 2}(\partial \Omega)$, uniformly with respect to $f \in\left\{\|f\|_{H^{-\frac{1}{2}}(\partial \Omega)} \leqslant 1\right.$, $\left.\int_{\partial \Omega} f d \sigma=0\right\}$, and so from Lemma 1 it follows that

$$
\begin{equation*}
\lim _{\rho \rightarrow 0} \int_{\Omega \backslash \overline{\rho D}}\left|\nabla W_{1, \rho}-\nabla W_{1}\right|^{2} d x=0 . \tag{3.24}
\end{equation*}
$$

The limit is uniform in $f \in\left\{\|f\|_{H^{-\frac{1}{2}}(\partial \Omega)} \leqslant 1, \int_{\partial \Omega} f d \sigma=0\right\}$. A combination of (3.18) with (3.24) now yields

$$
\begin{align*}
& \left(\int_{\Omega \backslash B_{\delta}}\left|\frac{1}{\rho^{d}} \nabla w_{1, \rho}-\nabla L_{1}-\nabla W_{1}\right|^{2} d x\right)^{1 / 2} \\
& \leqslant\left(\int_{\Omega \backslash B_{\delta}}\left|\frac{1}{\rho^{d}} \nabla\left(w_{1, \rho}-v_{1, \rho}\right)-\nabla W_{1}\right|^{2} d x\right)^{1 / 2}+\left(\int_{\Omega \backslash B_{\delta}}\left|\frac{1}{\rho^{d}} \nabla v_{1, \rho}-\nabla L_{1}\right|^{2} d x\right)^{1 / 2} \\
& =\left(\int_{\Omega \backslash B_{\delta}}\left|\nabla W_{1, \rho}-\nabla W_{1}\right|^{2} d x\right)^{1 / 2}+\left(\int_{\Omega \backslash B_{\delta}}\left|\frac{1}{\rho^{d}} \nabla v_{1, \rho}-\nabla L_{1}\right|^{2} d x\right)^{1 / 2} \\
& \rightarrow 0 \quad \text { as } \rho \rightarrow 0, \tag{3.25}
\end{align*}
$$

uniformly on $\left\{\|f\|_{H^{-\frac{1}{2}}(\partial \Omega)} \leqslant 1, \int_{\partial \Omega} f d \sigma=0\right\}$. Since all the involved functions are independent of $\gamma_{1, \rho}$ it follows immediately that the limit is also uniform with respect to $\gamma_{1, \rho} \in L_{+}^{\infty}(\rho D)$. This completes the study of the behavior of the first remainder term $\frac{1}{\rho^{d}} w_{1, \rho}$ as $\rho \rightarrow 0$.

### 3.2. A uniform estimate for the second remainder term

It remains to examine the behavior of the term the $\frac{1}{\rho^{d}} w_{2, \rho}=\frac{1}{\rho^{d}}\left(u_{\rho}-u_{1, \rho}\right)$ on $\Omega \backslash B_{\delta}$. For that purpose it will be convenient to extend the function $u_{1, \rho}$ to all of $\Omega$ by setting it equal to the constant $u_{0}(0)$ on $\rho D$. From (1.3) and (3.12) it now follows that $w_{2, \rho}$ is a solution to

$$
\begin{cases}\nabla \cdot\left(\gamma_{1, \rho} \nabla w_{2, \rho}\right)=0 & \text { in } \rho D, \\ \Delta w_{2, \rho}=0 & \text { in } \Omega \backslash \overline{\rho D}, \\ \frac{\partial w_{2, \rho}}{\partial n}=0 & \text { on } \partial \Omega, \\ \left.\frac{\partial w_{2, \rho}}{\partial n}\right|_{\text {ext }}-\left.\left(\gamma_{1, \rho} \nabla w_{2, \rho}\right) \cdot n\right|_{\text {int }}=-\left.\frac{\partial u_{1, \rho}}{\partial n}\right|_{\text {ext }} & \text { on } \partial \rho D, \\ {\left[w_{2, \rho}\right]=-\rho \lambda_{\rho} J(\cdot / \rho)} & \text { on } \partial \rho D .\end{cases}
$$

For brevity we shall use the notation $\psi_{2, \rho}:=-\left.\frac{\partial u_{1, \rho}}{\partial n}\right|_{\text {ext }}$ on $\partial \rho D$. Since $\psi_{2, \rho} \in H^{-\frac{1}{2}}(\partial \rho D), \int_{\partial \rho D} \psi_{2, \rho}=0$, and $\lambda_{\rho} J \in$ $H^{\frac{1}{2}}(\partial D)$, Proposition 4 guarantees the existence of $H_{2, \rho} \in W^{1}\left(\mathbb{R}^{d} \backslash \bar{D}\right) \times H^{1}(D)$, a solution to

$$
\begin{cases}\nabla \cdot\left(\gamma_{1, \rho}(\rho \cdot) \nabla H_{2, \rho}\right)=0 & \text { in } D, \\ \Delta H_{2, \rho}=0 & \text { in } \mathbb{R}^{d} \backslash \bar{D}, \\ \left.\frac{\partial H_{2, \rho}}{\partial n}\right|_{\text {ext }}-\left.\left(\gamma_{1, \rho}(\rho \cdot) \nabla H_{2, \rho}\right) \cdot n\right|_{\text {int }}=\psi_{2, \rho}(\rho \cdot) & \text { on } \partial D, \\ {\left[H_{2, \rho}\right]=-\lambda_{\rho} J} & \text { on } \partial D .\end{cases}
$$

This solution is unique for $d=3$, and it is unique modulo a constant for $d=2$. Moreover, $H_{2, \rho}$ may be represented as

$$
H_{2, \rho}(x)=\left.\int_{\partial D} \frac{\partial}{\partial n_{y}} \Phi(x, y) H_{2, \rho}\right|_{\mathrm{ext}} d \sigma_{y}-\left.\int_{\partial D} \Phi(x, y) \frac{\partial H_{2, \rho}}{\partial n}(y)\right|_{\mathrm{ext}} d \sigma_{y}+C_{\rho} .
$$

The rescaled function, $v_{2, \rho}=\rho H_{2, \rho}(x / \rho)$, may then be represented as

$$
\begin{align*}
v_{2, \rho}(x) & =\left.\rho \int_{\partial D} \frac{\partial}{\partial n_{y}} \Phi(x / \rho, y) H_{2, \rho}\right|_{\mathrm{ext}} d \sigma_{y}-\left.\rho \int_{\partial D} \Phi(x / \rho, y) \frac{\partial H_{2, \rho}}{\partial n}(y)\right|_{\mathrm{ext}} d \sigma_{y}+\rho C_{\rho} \\
& =\left.\rho^{d} \int_{\partial D}\left(\frac{\partial}{\partial n_{y}} \Phi\right)(x, \rho y) H_{2, \rho}\right|_{\mathrm{ext}} d \sigma_{y}-\left.\rho^{d-1} \int_{\partial D} \Phi(x, \rho y) \frac{\partial H_{2, \rho}}{\partial n}(y)\right|_{\mathrm{ext}} d \sigma_{y}+\rho C_{\rho} . \tag{3.26}
\end{align*}
$$

For the last identity we have (at least in the case $d=2$ ) used that

$$
\begin{equation*}
\left.\int_{\partial D} \frac{\partial H_{2, \rho}}{\partial n}\right|_{\text {ext }} d \sigma=0 \tag{3.27}
\end{equation*}
$$

which in turn (for $d=2$ as well as $d=3$ ) follows from the fact that

$$
\int_{\partial \rho D} \psi_{2, \rho}=-\left.\int_{\partial \rho D} \frac{\partial u_{1, \rho}}{\partial n}\right|_{\mathrm{ext}}=0 \quad \text { and }\left.\quad \int_{\partial D}\left(\gamma_{1, \rho}(\rho \cdot) \nabla H_{2, \rho}\right) \cdot n\right|_{\mathrm{int}}=0 .
$$

Using (3.27) once more we may rewrite (3.26) as

$$
\begin{align*}
v_{2, \rho}(x)= & \left.\rho^{d} \int_{\partial D}\left(\frac{\partial}{\partial n_{y}} \Phi\right)(x, \rho y) H_{2, \rho}\right|_{\mathrm{ext}} d \sigma_{y} \\
& -\left.\rho^{d-1} \int_{\partial D}(\Phi(x, \rho y)-\Phi(x, 0)) \frac{\partial H_{2, \rho}}{\partial n}(y)\right|_{\mathrm{ext}} d \sigma_{y}+\rho C_{\rho} . \tag{3.28}
\end{align*}
$$

We now study the asymptotic behavior of $\left.H_{2, \rho}\right|_{\text {ext }}$ and $\left.\frac{\partial H_{2, \rho}}{\partial n}\right|_{\text {ext }}$ on $\partial D$. To this end the definitions of $w_{1, \rho}$ and $W_{1, \rho}$, (3.14) and (3.20) respectively, yield that

$$
\begin{equation*}
u_{1, \rho}=u_{0}+w_{1, \rho}=u_{0}+\rho^{d} W_{1, \rho}+v_{1, \rho} \quad \text { in } \Omega \backslash \overline{\rho D} . \tag{3.29}
\end{equation*}
$$

Since $v_{1, \rho}(x)=\rho H_{1, \rho}(x / \rho)($ see (3.17))

$$
\frac{\partial v_{1, \rho}}{\partial n}(x)=\left(\frac{\partial H_{1, \rho}}{\partial n}\right)(x / \rho)
$$

and so

$$
\begin{equation*}
\left(\frac{\partial v_{1, \rho}}{\partial n}\right)(\rho x)=\frac{\partial H_{1, \rho}}{\partial n}(x), \tag{3.30}
\end{equation*}
$$

for $x \in \partial D$. We may without loss of generality suppose $\rho$ is sufficiently small that $\overline{B_{2 K \rho}} \subset \Omega$. From (3.24)

$$
\lim _{\rho \rightarrow 0} \int_{B_{2 K \rho} \backslash \rho D}\left|\nabla W_{1, \rho}-\nabla W_{1}\right|^{2} d x=0
$$

which implies that

$$
\lim _{\rho \rightarrow 0}\left(\int_{B_{2 K \rho} \backslash \rho D}\left|\nabla W_{1, \rho}\right|^{2} d x-\int_{B_{2 K \rho} \backslash \rho D}\left|\nabla W_{1}\right|^{2} d x\right)=0 .
$$

In particular

$$
\int_{B_{2 K} \rho \backslash \rho D}\left|\nabla W_{1, \rho}\right|^{2} d x \rightarrow 0 \quad \text { as } \rho \rightarrow 0
$$

The rescaled function

$$
\tilde{W}_{1, \rho}(x)=W_{1, \rho}(\rho x)
$$

satisfies $\Delta \tilde{W}_{1, \rho}=0$ in $B_{2 K} \backslash \bar{D}, \tilde{W}_{1, \rho}=0$ on $\partial D$,

$$
\rho^{d-2} \int_{B_{2 K} \backslash D}\left|\nabla \tilde{W}_{1, \rho}\right|^{2} d x=\int_{B_{2 K} \rho \backslash \rho D}\left|\nabla W_{1, \rho}\right|^{2} d x \rightarrow 0 \quad \text { as } \rho \rightarrow 0
$$

and

$$
\frac{\partial \tilde{W}_{1, \rho}}{\partial n}(x)=\rho\left(\frac{\partial W_{1, \rho}}{\partial n}\right)(\rho x) \quad \text { on } \partial D .
$$

Therefore

$$
\rho^{d}\left\|\left(\frac{\partial W_{1, \rho}}{\partial n}\right)(\rho x)\right\|_{H^{-\frac{1}{2}(\partial D)}}^{2}=\rho^{d-2}\left\|\frac{\partial \tilde{W}_{1, \rho}}{\partial n}\right\|_{H^{-\frac{1}{2}}(\partial D)}^{2} \leqslant C \rho^{d-2}\left\|\nabla \tilde{W}_{1, \rho}\right\|_{L^{2}\left(B_{2 K} \backslash \bar{D}\right)}^{2} \rightarrow 0,
$$

as $\rho \rightarrow 0$. The convergence is uniform with respect to $f \in\left\{\|f\|_{H^{-\frac{1}{2}}(\partial \Omega)} \leqslant 1, \int_{\partial \Omega} f d \sigma=0\right\}$, and since $W_{1, \rho}$ is independent of $\gamma_{1, \rho}$, this convergence is also uniform in $\gamma_{1, \rho} \in L_{+}^{\infty}(\rho D)$. It immediately follows (after multiplication by $\rho^{d}$ ) that

$$
\begin{equation*}
\lim _{\rho \rightarrow 0}\left\|\rho^{d}\left(\frac{\partial W_{1, \rho}}{\partial n}\right)(\rho \cdot)\right\|_{H^{-\frac{1}{2}}(\partial D)}=0 . \tag{3.31}
\end{equation*}
$$

By a combination of (3.29), (3.30), (3.31), and (3.16)

$$
\begin{align*}
\lim _{\rho \rightarrow 0} \psi_{2, \rho}(\rho x) & =-\lim _{\rho \rightarrow 0}\left(\left.\frac{\partial u_{1, \rho}}{\partial n}\right|_{\mathrm{ext}}\right)(\rho x) \\
& =-\lim _{\rho \rightarrow 0} \nabla u_{0}(\rho x) \cdot n-\lim _{\rho \rightarrow 0} \frac{\partial H_{1, \rho}}{\partial n}(x) \\
& =-\nabla u_{0}(0) \cdot n-\frac{\partial H_{1}}{\partial n}(x), \tag{3.32}
\end{align*}
$$

for $x \in \partial D$; the convergence takes place in $H^{-1 / 2}(\partial D)$ and is uniform in $\gamma_{1, \rho} \in L_{+}^{\infty}(\rho D)$ and $f \in\left\{\|f\|_{H^{-\frac{1}{2}}(\partial \Omega)} \leqslant 1\right.$, $\left.\int_{\partial \Omega} f d \sigma=0\right\}$. Let $\tilde{H}_{2, \rho} \in W^{1}\left(\mathbb{R}^{d} \backslash \bar{D}\right) \times H^{1}(D)$ denote the solution to

$$
\begin{cases}\nabla \cdot\left(\gamma_{1, \rho}(\rho \cdot) \nabla \tilde{H}_{2, \rho}\right)=0 & \text { in } D,  \tag{3.33}\\ \Delta \tilde{H}_{2, \rho}=0 & \text { in } \mathbb{R}^{d} \backslash \bar{D}, \\ \left.\frac{\partial \tilde{H}_{2, \rho}}{\partial n}\right|_{\text {ext }}-\left.\left(\gamma_{1, \rho}(\rho \cdot) \nabla \tilde{H}_{2, \rho}\right) \cdot n\right|_{\text {int }}=-\nabla u_{0}(0) \cdot n-\frac{\partial H_{1}}{\partial n} & \text { on } \partial D, \\ {\left[\tilde{H}_{2, \rho}\right]=-\lambda_{0} J} & \text { on } \partial D .\end{cases}
$$

We note that

$$
\int_{\partial D}\left(-\nabla u_{0}(0) \cdot n-\frac{\partial H_{1}}{\partial n}\right) d \sigma=\lim _{\rho \rightarrow 0} \rho^{-d+1} \int_{\partial \rho D} \psi_{2, \rho} d \sigma=0,
$$

and so the existence of $\tilde{H}_{2, \rho}$ is guaranteed by Proposition 4. $\tilde{H}_{2, \rho}$ is unique for $d=3$, and it is unique modulo a constant for $d=2$. We note that $\tilde{H}_{2, \rho}$ is independent of $\rho$ if $\gamma_{1, \rho}(x)$ is of the form $\gamma_{1, \rho}(x)=\gamma_{1}(x / \rho)$. Proposition 4 also yields that

$$
\int_{\mathbb{R}^{d} \backslash D}\left|\nabla \tilde{H}_{2, \rho}\right|^{2} d x \quad \text { is bounded }
$$

independently of $\rho, \gamma_{1, \rho} \in L_{+}^{\infty}(\rho D)$ and $f \in\left\{\|f\|_{H^{-\frac{1}{2}}(\partial \Omega)} \leqslant 1, \int_{\partial \Omega} f d \sigma=0\right\}$, and in combination with (3.32) and (3.11) it guarantees that

$$
\begin{aligned}
\int_{\mathbb{R}^{d} \backslash D}\left|\nabla\left(H_{2, \rho}-\tilde{H}_{2, \rho}\right)\right|^{2} d x & \leqslant C\left(\left\|\psi_{2, \rho}(\rho \cdot)+\nabla u_{0}(0) \cdot n+\frac{\partial H_{1}}{\partial n}\right\|_{H^{-1 / 2}(\partial \Omega)}+\left|\lambda_{\rho}-\lambda_{0}\right|\right) \\
& \rightarrow 0 \quad \text { as } \rho \rightarrow 0 .
\end{aligned}
$$

Here the constant $C$ is independent of $\gamma_{1, \rho}$, and so the convergence is uniform in $\gamma_{1, \rho} \in L_{+}^{\infty}(\rho D)$ and $f \in$ $\left\{\|f\|_{H^{-\frac{1}{2}}(\partial \Omega)} \leqslant 1, \int_{\partial \Omega} f d \sigma=0\right\}$. In particular we get that

$$
\begin{aligned}
& \left.H_{2, \rho}\right|_{\text {ext }}-\left.\tilde{H}_{2, \rho}\right|_{\text {ext }} \rightarrow 0 \text { in } H^{1 / 2}(\partial D), \quad \text { and } \\
& \left.\frac{\partial H_{2, \rho}}{\partial n}\right|_{\text {ext }}-\left.\frac{\partial \tilde{H}_{2, \rho}}{\partial n}\right|_{\text {ext }} \rightarrow 0 \quad \text { in } H^{-1 / 2}(\partial D)
\end{aligned}
$$

uniformly in $\gamma_{1, \rho} \in L_{+}^{\infty}(\rho D)$ and $f \in\left\{\|f\|_{H^{-\frac{1}{2}}(\partial \Omega)} \leqslant 1, \int_{\partial \Omega} f d \sigma=0\right\}$, with $\left.H_{2, \rho}\right|_{\text {ext }}, \tilde{H}_{2, \rho} l_{\text {ext }}$ and $\frac{\partial}{\partial n} H_{2, \rho} l_{\text {ext }}$, $\left.\frac{\partial}{\partial n} \tilde{H}_{2, \rho}\right|_{\text {ext }}$ uniformly bounded in $H^{1 / 2}(\partial D)$ and $H^{-1 / 2}(\partial D)$ respectively. The $H^{1 / 2}$ convergence and the boundedness of the functions $\left.H_{2, \rho}\right|_{\text {ext }},\left.\tilde{H}_{2, \rho}\right|_{\text {ext }}$ should be interpreted modulo constants. From (3.28) it now follows that

$$
\begin{equation*}
\lim _{\rho \rightarrow 0} \int_{\Omega \backslash B_{\delta}}\left|\frac{1}{\rho^{d}} \nabla v_{2, \rho}-\nabla L_{2, \rho}\right|^{2} d x=0, \tag{3.34}
\end{equation*}
$$

where $L_{2, \rho}$ denotes the function

$$
L_{2, \rho}(x)=\nabla_{y} \Phi(x, 0) \cdot \int_{\partial D}\left(-\left.\frac{\partial \tilde{H}_{2, \rho}}{\partial n}(y)\right|_{\mathrm{ext}} y+\left.\tilde{H}_{2, \rho}(y)\right|_{\mathrm{ext}} n_{y}\right) d \sigma_{y} \quad \forall x \in \Omega \backslash\{0\} .
$$

As a consequence of (3.34) and the fact that $v_{2, \rho}$ and $L_{2, \rho}$ are both harmonic in $\Omega \backslash \overline{B_{\delta}}$

$$
\begin{equation*}
\lim _{\rho \rightarrow 0}\left\|\frac{1}{\rho^{d}} \frac{\partial v_{2, \rho}}{\partial n}-\frac{\partial L_{2, \rho}}{\partial n}\right\|_{H^{-\frac{1}{2}}(\partial \Omega)}=0 . \tag{3.35}
\end{equation*}
$$

The convergence is uniform in $f \in\left\{\|f\|_{H^{-\frac{1}{2}(\partial \Omega)}} \leqslant 1, \int_{\partial \Omega} f d \sigma=0\right\}$ and $\gamma_{1, \rho} \in L_{+}^{\infty}(\rho D)$. We now consider $W_{2, \rho}=$ $\frac{1}{\rho^{d}}\left(w_{2, \rho}-v_{2, \rho}\right)$; this is a solution to

$$
\begin{cases}\nabla \cdot\left(\gamma_{\rho} W_{2, \rho}\right)=0 & \text { in } \Omega  \tag{3.36}\\ \frac{\partial W_{2, \rho}}{\partial n}=-\frac{1}{\rho^{d}} \frac{\partial v_{2, \rho}}{\partial n} & \text { on } \partial \Omega\end{cases}
$$

Problem (3.36) has a solution since, due to (3.27),

$$
\int_{\partial \Omega} \frac{\partial v_{2, \rho}}{\partial n} d \sigma=\left.\int_{\partial \rho D} \frac{\partial v_{2, \rho}}{\partial n}\right|_{\mathrm{ext}} d \sigma=\left.\rho^{d-1} \int_{\partial D} \frac{\partial H_{2, \rho}}{\partial n}\right|_{\mathrm{ext}} d \sigma=0 .
$$

$W_{2, \rho}$ is unique modulo a constant. A combination of (3.35) and Corollary 2 , the latter with $-\frac{1}{\rho^{d}} \frac{\partial}{\partial n} v_{2, \rho}$ and $-\frac{\partial}{\partial n} L_{2, \rho}$ in place of $g$ and $f$, yields that

$$
\begin{equation*}
\lim _{\rho \rightarrow 0} \int_{\Omega \backslash B_{\delta}}\left|\nabla W_{2, \rho}-\nabla \tilde{W}_{2, \rho}\right|^{2} d x=0, \tag{3.37}
\end{equation*}
$$

uniformly with respect to $\gamma_{1, \rho} \in L_{+}^{\infty}(\rho D)$ and $f \in\left\{\|f\|_{H^{-\frac{1}{2}}(\partial \Omega)} \leqslant 1, \int_{\partial \Omega} f d \sigma=0\right\}$. Here $\tilde{W}_{2, \rho}$ is a solution to

$$
\begin{cases}\Delta \tilde{W}_{2, \rho}=0 & \text { in } \Omega \\ \frac{\partial \tilde{W}_{2, \rho}}{\partial n}=-\frac{\partial L_{2, \rho}}{\partial n} & \text { on } \partial \Omega\end{cases}
$$

In order to obtain (3.37) from a combination of (3.35) and Corollary 2 we have also used that $\frac{\partial L_{2, \rho}}{\partial n}$ is bounded in $H^{-1 / 2}(\partial \Omega)$, uniformly in $\rho, \gamma_{1, \rho} \in L_{+}^{\infty}(\rho D)$ and $f \in\left\{\|f\|_{H^{-\frac{1}{2}}(\partial \Omega)} \leqslant 1, \int_{\partial \Omega} f d \sigma=0\right\}$. The convergence statements (3.34) and (3.37) now imply

$$
\begin{align*}
& \left(\int_{\Omega \backslash B_{\delta}}\left|\frac{1}{\rho^{d}} \nabla w_{2, \rho}-\nabla L_{2, \rho}-\nabla \tilde{W}_{2, \rho}\right|^{2} d x\right)^{1 / 2} \\
& \leqslant\left(\int_{\Omega \backslash B_{\delta}}\left|\frac{1}{\rho^{d}} \nabla\left(w_{2, \rho}-v_{2, \rho}\right)-\nabla \tilde{W}_{2, \rho}\right|^{2} d x\right)^{1 / 2}+\left(\int_{\Omega \backslash B_{\delta}}\left|\frac{1}{\rho^{d}} \nabla v_{2, \rho}-\nabla L_{2, \rho}\right|^{2} d x\right)^{1 / 2} \\
& =\left(\int_{\Omega \backslash B_{\delta}}\left|\nabla W_{2, \rho}-\nabla \tilde{W}_{2, \rho}\right|^{2} d x\right)^{1 / 2}+\left(\int_{\Omega \backslash B_{\delta}}\left|\frac{1}{\rho^{d}} \nabla v_{2, \rho}-\nabla L_{2, \rho}\right|^{2} d x\right)^{1 / 2} \\
& \rightarrow 0 \quad \text { as } \rho \rightarrow 0, \tag{3.38}
\end{align*}
$$

uniformly in $\gamma_{1, \rho} \in L_{+}^{\infty}(\rho D)$ and $f \in\left\{\|f\|_{H^{-\frac{1}{2}}(\partial \Omega)} \leqslant 1, \int_{\partial \Omega} f d \sigma=0\right\}$. This completes the study of the asymptotic behavior of the second remainder term $\frac{1}{\rho^{d}} w_{2, \rho}$ as $\rho \rightarrow 0$.

### 3.3. Proof of the main theorem

It follows directly from the decomposition (3.13) and the estimates (3.25) and (3.38) in the two preceding sections that

$$
\left(\int_{\Omega \backslash B_{\delta}}\left|\frac{1}{\rho^{d}} \nabla\left(u_{\rho}-u_{0}\right)-\nabla\left(L_{1}+L_{2, \rho}+W_{1}+\tilde{W}_{2, \rho}\right)\right|^{2} d x\right)^{1 / 2}
$$

$$
\begin{align*}
& \leqslant\left(\int_{\Omega \backslash B_{\delta}}\left|\frac{1}{\rho^{d}} \nabla w_{1, \rho}-\nabla\left(L_{1}+W_{1}\right)\right|^{2} d x\right)^{1 / 2}+\left(\int_{\Omega \backslash B_{\delta}}\left|\frac{1}{\rho^{d}} \nabla w_{2, \rho}-\nabla\left(L_{2, \rho}+\tilde{W}_{2, \rho}\right)\right|^{2} d x\right)^{1 / 2} \\
& \rightarrow 0 \quad \text { as } \rho \rightarrow 0 . \tag{3.39}
\end{align*}
$$

As a consequence of this and the fact that $\int_{\partial \Omega} u_{\rho} d \sigma=\int_{\partial \Omega} u_{0} d \sigma=0$ we also get that

$$
\left\|\frac{1}{\rho^{d}}\left(u_{\rho}-u_{0}\right)-\left(L_{1}+L_{2, \rho}+W_{1}+\tilde{W}_{2, \rho}+C\right)\right\|_{H^{1}\left(\Omega \backslash \overline{B_{\delta}}\right)} \rightarrow 0 \quad \text { as } \rho \rightarrow 0,
$$

with the constant $C$ given by

$$
C=-\frac{1}{|\partial \Omega|} \int_{\partial \Omega}\left(L_{1}+L_{2, \rho}+W_{1}+\tilde{W}_{2, \rho}\right) d \sigma
$$

Note that $C$ generically depends on $\rho$. Since the function $\frac{1}{\rho^{d}}\left(u_{\rho}-u_{0}\right)-\left(L_{1}+L_{2, \rho}+W_{1}+\tilde{W}_{2, \rho}+C\right)$ is harmonic near $\partial \Omega$, and since its normal derivative vanishes on $\partial \Omega$, it follows by local elliptic regularity theory that all norms tend to zero, i.e.,

$$
\left\|\frac{1}{\rho^{d}}\left(u_{\rho}-u_{0}\right)-\left(L_{1}+L_{2, \rho}+W_{1}+\tilde{W}_{2, \rho}+C\right)\right\|_{H^{s}\left(\Omega \backslash \overline{B_{\delta}}\right)} \rightarrow 0 \quad \text { as } \rho \rightarrow 0,
$$

for any real positive $s$. Just as in (3.39) the convergence is uniform in $\gamma_{1, \rho} \in L_{+}^{\infty}(\rho D)$ and $f \in\left\{\|f\|_{H^{-\frac{1}{2}(\partial \Omega)}} \leqslant 1\right.$, $\left.\int_{\partial \Omega} f d \sigma=0\right\}$. From continuity of the trace operator (supposing $\delta$ is sufficiently small) it follows that

$$
\left\|\frac{1}{\rho^{d}}\left(u_{\rho}-u_{0}\right)-\left(L_{1}+L_{2, \rho}+W_{1}+\tilde{W}_{2, \rho}+C\right)\right\|_{H^{s}(\partial \Omega)} \rightarrow 0 \quad \text { as } \rho \rightarrow 0,
$$

for any real positive number $s$, in the same uniform sense as above. Let $L_{\rho}$ denote the term $L_{\rho}=L_{1}+L_{2, \rho}$ and let $W_{\rho}=W_{1}+\tilde{W}_{2, \rho}+C$. Then

$$
L_{\rho}(x)=\nabla_{y} \Phi(x, 0) \cdot\left(\int_{\partial D}\left(H_{1}-\Lambda_{D}\left(\frac{\partial}{\partial n} H_{1}\right)\right) n d \sigma+\int_{\partial D}\left(-\left.\frac{\partial \tilde{H}_{2, \rho}}{\partial n}(z)\right|_{\mathrm{ext}} z+\left.\tilde{H}_{2, \rho}(z)\right|_{\mathrm{ext}} n_{z}\right) d \sigma_{z}\right),
$$

and $W_{\rho}$ is the harmonic function in $\Omega$, uniquely determined by the boundary conditions

$$
\frac{\partial}{\partial n}\left(W_{\rho}+L_{\rho}\right)=0 \quad \text { on } \partial \Omega, \quad \text { and } \quad \int_{\partial \Omega}\left(W_{\rho}+L_{\rho}\right) d \sigma=0
$$

There are several ways to deduce the $L^{2}\left(\Omega \backslash \overline{B_{\delta}}\right)$ boundedness of $\nabla\left(L_{\rho}+W_{\rho}\right)$. On the one hand it follows from (3.39) and the boundedness of $\left(u_{\rho}-u_{0}\right) / \rho^{d}$ asserted in Theorem 1; on the other hand, it also follows immediately from the formulas for $L_{\rho}$ and $W_{\rho}$, and the boundedness of $H_{1}$ and that of $\tilde{H}_{2, \rho}$, stated just before (3.34) in the previous section. In order to prove our main theorem, Theorem 2, it thus only remains to verify that

$$
\begin{align*}
& \int_{\partial D}\left(H_{1}-\Lambda_{D}\left(\frac{\partial}{\partial n} H_{1}\right)\right) n d \sigma+\int_{\partial D}\left(-\left.\frac{\partial \tilde{H}_{2, \rho}}{\partial n}(z)\right|_{\mathrm{ext}} z+\left.\tilde{H}_{2, \rho}(z)\right|_{\mathrm{ext}} n_{z}\right) d \sigma_{z} \\
& \quad=\int_{D}\left(I-\gamma_{1, \rho}(\rho z)\right) \nabla \phi_{k}(z) d z \frac{\partial}{\partial x_{k}} u_{0}(0) \tag{3.40}
\end{align*}
$$

where $\phi_{k}$ is the function defined by (3.2). In the following lemma we collect a number of identities that will be useful in order to establish this relationship.

Lemma 2. With notation as above,

$$
\begin{align*}
\left.\int_{\partial D} \frac{\partial \tilde{H}_{2, \rho}}{\partial n}(z)\right|_{\mathrm{ext}} z d \sigma_{z} & =\int_{D} \gamma_{1, \rho}(\rho \cdot) \nabla \tilde{H}_{2, \rho} d z-\int_{\partial D}\left(\nabla u_{0}(0) \cdot n_{z}+\frac{\partial H_{1}}{\partial n}\right) z d \sigma_{z},  \tag{3.41}\\
\left.\int_{\partial D} \tilde{H}_{2, \rho}(z)\right|_{\mathrm{ext}} n_{z} d \sigma_{z} & =\int_{D} \nabla \tilde{H}_{2, \rho} d z-\lambda_{0} \int_{\partial D} J n d \sigma, \tag{3.42}
\end{align*}
$$

and

$$
\begin{equation*}
\int_{\partial D}\left(H_{1}-\Lambda_{D}\left(\frac{\partial}{\partial n} H_{1}\right)\right) n d \sigma=-\int_{D} \nabla u_{0}(0) \cdot n_{z} z d \sigma_{z}+\lambda_{0} \int_{\partial D} J n d \sigma-\int_{\partial D} \frac{\partial H_{1}}{\partial n}(z) z d \sigma_{z} . \tag{3.43}
\end{equation*}
$$

Proof. From (3.33), one has

$$
\left.\int_{\partial D} \frac{\partial \tilde{H}_{2, \rho}}{\partial n}(z)\right|_{\mathrm{ext}} z d \sigma_{z}=\left.\int_{\partial D}\left(\gamma_{1}(\rho \cdot) \nabla \tilde{H}_{2, \rho}\right) \cdot n_{z}\right|_{\mathrm{int}} z d \sigma_{z}-\int_{\partial D}\left(\nabla u_{0}(0) \cdot n_{z}+\frac{\partial H_{1}}{\partial n}\right) z d \sigma_{z}
$$

Integration by parts and use of (3.33) yields

$$
\begin{aligned}
\left.\int_{\partial D}\left(\gamma_{1, \rho}(\rho \cdot) \nabla \tilde{H}_{2, \rho}\right) \cdot n_{z}\right|_{\mathrm{int}} z d \sigma_{z} & =\int_{D} \nabla \cdot\left(\gamma_{1, \rho}(\rho \cdot) \nabla \tilde{H}_{2, \rho}\right) z d z+\int_{D} \gamma_{1, \rho}(\rho \cdot) \nabla \tilde{H}_{2, \rho} d z \\
& =\int_{D} \gamma_{1, \rho}(\rho \cdot) \nabla \tilde{H}_{2, \rho} d z
\end{aligned}
$$

Thus it follows that

$$
\left.\int_{\partial D} \frac{\partial \tilde{H}_{2, \rho}}{\partial n}(z)\right|_{\operatorname{ext}} z d \sigma_{z}=\int_{D} \gamma_{1, \rho}(\rho \cdot) \nabla \tilde{H}_{2, \rho} d z-\int_{\partial D}\left(\nabla u_{0}(0) \cdot n_{z}+\frac{\partial H_{1}}{\partial n}\right) z d \sigma_{z},
$$

as stated in (3.41). From (3.33) one has

$$
\left.\int_{\partial D} \tilde{H}_{2, \rho}(z)\right|_{\operatorname{ext}} n_{z} d \sigma_{z}=\left.\int_{\partial D} \tilde{H}_{2, \rho}(z)\right|_{\text {int }} \frac{\partial z}{\partial n_{z}} d \sigma_{z}-\lambda_{0} \int_{\partial D} J n_{z} d \sigma_{z}
$$

At the same time

$$
\left.\int_{\partial D} \tilde{H}_{2, \rho}(z)\right|_{\text {int }} \frac{\partial z}{\partial n_{z}} d \sigma_{z}=\int_{D} \tilde{H}_{2, \rho} \Delta z d z+\int_{D} \nabla \tilde{H}_{2, \rho} d z=\int_{D} \nabla \tilde{H}_{2, \rho} d z,
$$

and so

$$
\left.\int_{\partial D} \tilde{H}_{2, \rho}(z)\right|_{\mathrm{ext}} n_{z} d \sigma_{z}=\int_{D} \nabla \tilde{H}_{2, \rho} d z-\lambda_{0} \int_{\partial D} J n_{z} d \sigma_{z} .
$$

In order to complete the proof of this lemma it only remains to verify (3.43). To that end we let $w$ denote the solution to

$$
\Delta w=0 \quad \text { in } D, \quad \frac{\partial}{\partial n} w=\frac{\partial}{\partial n} H_{1} \quad \text { on } \partial D, \quad \int_{\partial D} w d \sigma=0 .
$$

With this notation $\Lambda_{D}\left(\frac{\partial}{\partial n} H_{1}\right)=\left.w\right|_{\partial D}$, and thus

$$
\begin{aligned}
\int_{\partial D}\left(H_{1}-\Lambda_{D}\left(\frac{\partial}{\partial n} H_{1}\right)\right) n d \sigma & =-\int_{\partial D} \hat{H}_{1} n d \sigma+\lambda_{0} \int_{\partial D} J n d \sigma-\int_{\partial D} w(z) \frac{\partial}{\partial n_{z}} z d \sigma_{z} \\
& =-\int_{\partial D} \nabla u_{0}(0) \cdot z n_{z} d \sigma_{z}+\lambda_{0} \int_{\partial D} J n d \sigma-\int_{\partial D} \frac{\partial}{\partial n} w(z) z d \sigma_{z} \\
& =-\int_{\partial D} \nabla u_{0}(0) \cdot n_{z} z d \sigma_{z}+\lambda_{0} \int_{\partial D} J n d \sigma-\int_{\partial D} \frac{\partial H_{1}}{\partial n}(z) z d \sigma_{z},
\end{aligned}
$$

which is exactly (3.43).
Now the final step of the proof of Theorem 2. As a direct consequence of Lemma 2

$$
\begin{align*}
& \int_{\partial D}\left(H_{1}-\Lambda_{D}\left(\frac{\partial}{\partial n} H_{1}\right)\right) n d \sigma+\int_{\partial D}\left(-\left.\frac{\partial \tilde{H}_{2, \rho}}{\partial n}(z)\right|_{\mathrm{ext}} z+\left.\tilde{H}_{2, \rho}(z)\right|_{\mathrm{ext}} n_{z}\right) d \sigma_{z} \\
& \quad=\int_{D}\left(I-\gamma_{1, \rho}(\rho z)\right) \nabla \tilde{H}_{2, \rho}(z) d z . \tag{3.44}
\end{align*}
$$

Furthermore, the function $\psi_{k}(z) \frac{\partial u_{0}}{\partial x_{k}}(0)$ (with $\psi_{k}$ defined by (3.3)) may, up to a constant, be expressed compactly in terms of the functions $H_{1}$ and $\tilde{H}_{2, \rho}$

$$
\psi_{k}(z) \frac{\partial u_{0}}{\partial x_{k}}(0)+\text { constant }= \begin{cases}H_{1}(z)+\tilde{H}_{2, \rho}(z), & z \in \mathbb{R}^{d} \backslash \bar{D}, \\ -\nabla u_{0}(0) \cdot z+\tilde{H}_{2, \rho}(z), & z \in D\end{cases}
$$

In terms of $\phi_{k}(z)=\psi_{k}(z)+z_{k}$ the second equation asserts that

$$
\nabla \phi_{k}(z) \frac{\partial u_{0}}{\partial x_{k}}(0)=\nabla\left(\psi_{k}(z) \frac{\partial u_{0}}{\partial x_{k}}(0)+\nabla u_{0}(0) \cdot z\right)=\nabla \tilde{H}_{2, \rho}(z), \quad \text { for } z \in D,
$$

and therefore

$$
\int_{D}\left(I-\gamma_{1, \rho}(\rho z)\right) \nabla \phi_{k}(z) d z \frac{\partial}{\partial x_{k}} u_{0}(0)=\int_{D}\left(I-\gamma_{1, \rho}(\rho z)\right) \nabla \tilde{H}_{2, \rho}(z) d z
$$

A combination of the last identity and (3.44) leads to (3.40), and this completes the proof of Theorem 2.

## 4. Other inhomogeneities $\boldsymbol{D}_{\boldsymbol{\rho}}$

In this section we prove an analogue of Theorem 2 for inhomogeneities that are not exactly of the form $\rho D$, but close. As already pointed out in the introduction a result like Theorem 2 cannot hold for volumetrically small $D_{\rho}$ of arbitrary shape. We suppose the open set $D_{\rho}$ contains the origin, and that there exists a smooth, bounded domain $D$, star-shaped with respect to the origin, and such that

$$
\begin{equation*}
\left(1-r_{\rho}\right) \rho D \subset D_{\rho} \subset\left(1+r_{\rho}\right) \rho D \tag{4.1}
\end{equation*}
$$

with $r_{\rho}>0$, and $r_{\rho} \rightarrow 0$ as $\rho \rightarrow 0$. Let $\gamma_{\rho}$ be defined as in (3.1), but suppose furthermore $\gamma_{1, \rho}$ is constant and isotropic, i.e.,

$$
\gamma_{\rho}= \begin{cases}I & \text { in } \Omega \backslash D_{\rho},  \tag{4.2}\\ c I & \text { in } D_{\rho},\end{cases}
$$

for some scalar constant $c>0$. You may think of $c$ as varying with $\rho$, but for simplicity of notation we call it $c$, as opposed to $c_{\rho}$. If $E_{D_{\rho}}(v)$ denotes the energy expression

$$
E_{D_{\rho}}(v)=\frac{1}{2} \int_{\Omega}\left\langle\gamma_{\rho} \nabla v, \nabla v\right\rangle d x-\int_{\partial \Omega} f v d \sigma,
$$

then

$$
\begin{equation*}
E_{\left(1-r_{\rho}\right) \rho D}(v) \leqslant E_{D_{\rho}}(v) \leqslant E_{\left(1+r_{\rho}\right) \rho D}(v) \quad \forall v \in H^{1}(\Omega), \tag{4.3}
\end{equation*}
$$

for $c \geqslant 1$, and

$$
\begin{equation*}
E_{\left(1+r_{\rho}\right) \rho D}(v) \leqslant E_{D_{\rho}}(v) \leqslant E_{\left(1-r_{\rho}\right) \rho D}(v) \quad \forall v \in H^{1}(\Omega), \tag{4.4}
\end{equation*}
$$

for $0<c<1$. Let $u_{\rho}$ denote the solution to

$$
\nabla \cdot\left(\gamma_{\rho} \nabla u_{\rho}\right)=0 \quad \text { in } \Omega, \quad \frac{\partial u_{\rho}}{\partial n}=f \quad \text { on } \partial \Omega,
$$

with $\int_{\partial \Omega} u_{\rho} d \sigma=0$, and let $u_{\rho}^{( \pm)}$denote the solutions to the same problem, when $D_{\rho}$ in the definition of $\gamma_{\rho}$ is replaced by $\left(1 \pm r_{\rho}\right) \rho D$. The function $u_{\rho}$ is the minimizer of $E_{D_{\rho}}(v)$ in $H^{1}(\Omega) \cap\left\{\int_{\partial \Omega} v d \sigma=0\right\}$, and $u_{\rho}^{( \pm)}$are the $H^{1}(\Omega) \cap\left\{\int_{\partial \Omega} v d \sigma=0\right\}$ minimizers of $E_{\left(1 \pm r_{\rho}\right) \rho D}(v)$, respectively. From (4.3) and (4.4) we conclude that

$$
E_{\left(1-r_{\rho}\right) \rho D}\left(u_{\rho}^{(-)}\right) \leqslant E_{D_{\rho}}\left(u_{\rho}\right) \leqslant E_{\left(1+r_{\rho}\right) \rho D}\left(u_{\rho}^{(+)}\right),
$$

for $c \geqslant 1$, and

$$
E_{\left(1+r_{\rho}\right) \rho D}\left(u_{\rho}^{(+)}\right) \leqslant E_{D_{\rho}}\left(u_{\rho}\right) \leqslant E_{\left(1-r_{\rho}\right) \rho D}\left(u_{\rho}^{(-)}\right),
$$

for $0<c<1$. As a consequence

$$
\begin{equation*}
\left|E_{D_{\rho}}\left(u_{\rho}\right)-E_{\left(1-r_{\rho}\right) \rho D}\left(u_{\rho}^{(-)}\right)\right| \leqslant\left|E_{\left(1+r_{\rho}\right) \rho D}\left(u_{\rho}^{(+)}\right)-E_{\left(1-r_{\rho}\right) \rho D}\left(u_{\rho}^{(-)}\right)\right|, \tag{4.5}
\end{equation*}
$$

for any $c>0$. It is well know that

$$
\begin{equation*}
2 E_{D_{\rho}}\left(u_{\rho}\right)=-\int_{\partial \Omega} f u_{\rho} d \sigma \tag{4.6}
\end{equation*}
$$

and similarly

$$
\begin{equation*}
2 E_{\left(1 \pm r_{\rho}\right) \rho D}\left(u_{\rho}^{( \pm)}\right)=-\int_{\partial \Omega} f u_{\rho}^{( \pm)} d \sigma \tag{4.7}
\end{equation*}
$$

From Theorem 2 (or rather, Corollary 3) and the formula (3.7) we have the following asymptotic information about $u_{\rho}^{(-)}-u_{0}$ and $u_{\rho}^{(+)}-u_{\rho}^{(-)}$

$$
\begin{align*}
\frac{1}{\rho^{d}}\left(u_{\rho}^{(-)}-u_{0}\right)(x) & =\left(1-r_{\rho}\right)^{d}|D| \nabla_{y} G(x, 0) \cdot(1-c) M \nabla u_{0}(0)+o(1)(x) \\
& =|D| \nabla_{y} G(x, 0) \cdot(1-c) M \nabla u_{0}(0)+o(1)(x), \tag{4.8}
\end{align*}
$$

and

$$
\begin{align*}
\frac{1}{\rho^{d}}\left(u_{\rho}^{(+)}-u_{\rho}^{(-)}\right)(x)= & \left(1+r_{\rho}\right)^{d}|D| \nabla_{y} G(x, 0) \cdot(1-c) M \nabla u_{0}(0) \\
& -\left(1-r_{\rho}\right)^{d}|D| \nabla_{y} G(x, 0) \cdot(1-c) M \nabla u_{0}(0)+o(1)(x) \\
= & O\left(r_{\rho}\right)(x)+o(1)(x)=o(1)(x) \tag{4.9}
\end{align*}
$$

where $o(1)(\cdot)$ represents a term that tends to zero in any $H^{s}(\partial \Omega)$ norm, uniformly with respect to $c>0$ and $f \in$ $\left\{\|f\|_{H^{-\frac{1}{2}}(\partial \Omega)} \leqslant 1, \int_{\partial \Omega} f d \sigma=0\right\}$ as $\rho \rightarrow 0$. In the second identities of (4.8) and (4.9) we have used the uniform boundedness of $(1-c) M=(1-c) M(c)$ (see the discussion following Corollary 3). It follows immediately by a combination of (4.5), (4.7), and (4.9) that

$$
\begin{aligned}
\left|E_{D_{\rho}}\left(u_{\rho}\right)-E_{\left(1-r_{\rho}\right) \rho D}\left(u_{\rho}^{(-)}\right)\right| & \leqslant\left|E_{\left(1+r_{\rho}\right) \rho D}\left(u_{\rho}^{(+)}\right)-E_{\left(1-r_{\rho}\right) \rho D}\left(u_{\rho}^{(-)}\right)\right| \\
& =\frac{1}{2}\left|\int_{\partial \Omega} f\left(u_{\rho}^{(+)}-u_{\rho}^{(-)}\right) d \sigma\right| \\
& =\rho^{d} o(1),
\end{aligned}
$$

where the term $o(1)$ tends to zero, uniformly with respect to $c>0$ and $f \in\left\{\|f\|_{H^{-\frac{1}{2}}(\partial \Omega)} \leqslant 1, \int_{\partial \Omega} f d \sigma=0\right\}$ as $\rho \rightarrow 0$. A subsequent application of (4.6) and (4.7) yields

$$
\left|\int_{\partial \Omega} f\left(u_{\rho}-u_{\rho}^{(-)}\right) d \sigma\right|=2\left|E_{D_{\rho}}\left(u_{\rho}\right)-E_{\left(1-r_{\rho}\right) \rho D}\left(u_{\rho}^{(-)}\right)\right|=\rho^{d} o(1) .
$$

Due to the linear dependence of $u_{\rho}$ and $u_{\rho}^{(-)}$on $f$ we thus obtain

$$
\left|\int_{\partial \Omega} f\left(u_{\rho}-u_{\rho}^{(-)}\right) d \sigma\right| \leqslant \rho^{d} o(1)\|f\|_{H^{-1 / 2}(\partial \Omega)}^{2} \quad \forall f \in H^{-\frac{1}{2}} \cap\left\{\int_{\partial \Omega} f d \sigma=0\right\},
$$

where the term $o(1)$ tends to zero, uniformly with respect to $c>0$ and $f$ as $\rho \rightarrow 0$. Since the operator $f \rightarrow\left(u_{\rho}-\right.$ $\left.u_{\rho}^{(-)}\right)\left.\right|_{\partial \Omega}$ is self-adjoint, a standard polarization argument (as in the proof of Theorem 1) now gives

$$
\left|\int_{\partial \Omega} g\left(u_{\rho}-u_{\rho}^{(-)}\right) d \sigma\right| \leqslant \rho^{d} o(1)\|f\|_{H^{-1 / 2}(\partial \Omega)}\|g\|_{H^{-1 / 2}(\partial \Omega)}
$$

for all $f, g \in H^{-\frac{1}{2}} \cap\left\{\int_{\partial \Omega} f d \sigma=0\right\}$. Maximization over $g \in\left\{\|g\|_{H^{-\frac{1}{2}}(\partial \Omega)} \leqslant 1, \int_{\partial \Omega} g d \sigma=0\right\}$ yields

$$
\left\|u_{\rho}-u_{\rho}^{(-)}\right\|_{H^{\frac{1}{2}(\partial \Omega)}}=\rho^{d} o(1),
$$

where $o(1)$ tends to zero, uniformly with respect to $c>0$ and $f \in\left\{\|f\|_{H^{-\frac{1}{2}}(\partial \Omega)} \leqslant 1, \int_{\partial \Omega} f d \sigma=0\right\}$ as $\rho \rightarrow 0$. By a combination with (4.8) we finally arrive at the asymptotic representation

$$
\begin{equation*}
\frac{1}{\rho^{d}}\left(u_{\rho}-u_{0}\right)(x)=L_{\rho}+W_{\rho}+o(1)(x)=|D| \nabla_{y} G(x, 0) \cdot(1-c) M \nabla u_{0}(0)+o(1)(x), \tag{4.10}
\end{equation*}
$$

where the term $o(1)$ tends to zero in $H^{1 / 2}(\partial \Omega)$, uniformly in $c>0$ and $f \in\left\{\|f\|_{H^{-\frac{1}{2}}(\partial \Omega)} \leqslant 1, \int_{\partial \Omega} f d \sigma=0\right\}$ as $\rho \rightarrow 0$. If we had included a term of the form $\int_{\Omega} F v d x$ in the energy (as in Section 2) then we would immediately have shown that the $o(1)$ term also converges uniformly to zero in the norm $H^{1}\left(\Omega \backslash \overline{B_{\delta}}\right)$. Standard elliptic estimates now instantly (as in Section 2 ) shows that the $o(1)$ term actually converges uniformly to zero in any norm $H^{s}\left(\Omega \backslash \overline{B_{\delta}}\right)$ (or $H^{s}(\partial \Omega)$ ). In summary we have therefore established the following theorem.

Theorem 3. Suppose $f$ is in $H^{-1 / 2}(\partial \Omega)$ with $\int_{\partial \Omega} f d \sigma=0$, and suppose $\gamma_{\rho}$ is given by (4.2), with the bounded, open set $D_{\rho}$ satisfying (4.1). Let $u_{0}$ and $u_{\rho}$ be the solutions to (1.1) and (1.3), normalized by $\int_{\partial \Omega} u_{0} d \sigma=\int_{\partial \Omega} u_{\rho} d \sigma=0$. Let $L_{\rho}(x)$ and $W_{\rho}(x)$ be given by (3.4) and (3.5). Then for any fixed $\delta>0$ and $s \in \mathbb{R}_{+}$

$$
\lim _{\rho \rightarrow 0}\left\|\frac{1}{\rho^{d}}\left(u_{\rho}-u_{0}\right)-\left(L_{\rho}+W_{\rho}\right)\right\|_{H^{s}\left(\Omega \backslash \overline{B_{\delta}}\right)}=0,
$$

and as a consequence

$$
\lim _{\rho \rightarrow 0}\left\|\frac{1}{\rho^{d}}\left(u_{\rho}-u_{0}\right)-\left(L_{\rho}+W_{\rho}\right)\right\|_{H^{s}(\partial \Omega)}=0,
$$

for any $s \in \mathbb{R}_{+}$. Moreover, these limiting processes are uniform in $c>0$ and in $f \in\left\{\|f\|_{H^{-\frac{1}{2}(\partial \Omega)}} \leqslant 1, \int_{\partial \Omega} f d \sigma=0\right\}$.

## 5. Some remarks on cloaking

The main idea behind "cloaking by mapping" is that the Neumann to Dirichlet data map (or the Dirichlet to Neumann data map) of a domain is appropriately invariant under mappings that preserve points on the boundary. To be quite precise: if $\Psi$ is a continuous, piecewise smooth mapping that maps $\Omega$ injectively onto $\Omega$, and with $\Psi(x)=x$ for all $x \in \partial \Omega$, then the conductivities
$\gamma>0 \quad$ and $\quad \Psi_{*} \gamma=\frac{D \Psi \gamma D \Psi^{t}}{|\operatorname{det} D \Psi|} \circ \Psi^{-1}>0$
have the same Neumann to Dirichlet data map. What this means is that to any observer outside $\Omega, \gamma$ and $\Psi_{*} \gamma$ will look like the same conductivity. This of course does not contradict well-known uniqueness results for the isotropic conductivity in terms of a given Dirichlet to Neumann map [2,10,12,15], rather these uniqueness results may be interpreted as saying that the only $\Psi$, with $\left.\Psi\right|_{\partial \Omega}=i d$, for which $\gamma$ and $\Psi_{*} \gamma$ are simultaneously positive and isotropic is $\Psi=i d$ on all of $\Omega$. In the context of the conductivity problem the "push forward" construction (5.1) was introduced in [11], and originated from a discussion with L. Tartar.

In order to create a region inside $\Omega$ that is perfectly cloaked one selects a $\psi$ that opens up a single point to this finite sized region, as first discussed in [7,8] and later in [14]. Roughly speaking any conductivity, put inside the perfectly cloaked region, in the corresponding "pulled back" formulation "lives" at a point, and is thus invisible as far as the solution to the boundary value problem is concerned. A rigorous treatment of this phenomenon involves a discussion of what are appropriate (physical) solutions to elliptic problems with degenerate coefficients, since the conductivity cloak $\Psi_{* \gamma}$ becomes very degenerate when a point is opened up to a finite sized region. Such a rigorous discussion is found in [7] and [9]. To introduce regions that are approximately cloaked - by means of non-degenerate cloaks a natural procedure is now to "blow up" a very small region to a finite sized region. To answer the question, of exactly how good the approximate cloaking is, one must estimate the effect of a small inhomogeneity of completely arbitrary conductivity on the Neumann to Dirichlet data map. For more details about such estimates of the level of approximate cloaking associated with piecewise smooth mappings we refer to [9]. In that paper the authors used a monotonicity argument and information about the effect of small inhomogeneities of extreme (isotropic) conductivities, derived in [6]. The analysis could have been simplified if the estimate of Corollary 1 had been available. This corollary is also particularly well suited to the case, when the small domains are not exactly dilatations of a fixed domain, as happens when we consider approximately cloaked regions that are not balls. The results contained in Theorems 2 and 3 about the two principal terms of the asymptotic expansion of $u_{\rho}$ also have potential applications to approximate cloaks. These applications concern estimates of the level of approximate cloaking as well as questions of design. The result of Theorem 2 allows the identification of the exact level of cloaking associated with a particular object (the conductivity of which is the appropriate "push-forward" of $\gamma_{1, \rho}$ ). Since the asymptotic is uniform in $\gamma_{1, \rho}$, the principal terms could very efficiently be used to find the asymptotically most/least visible object for a given background field $\nabla u_{0}(0)$ (and the circular approximate cloak construction). Alternatively it could be used to determine the worst/best background field to identify a particular object that someone is attempting to cloak. Theorem 3 is of interest when it comes to approximate cloaks that are not of circular shape. A particular construction of such cloaks (by composition of mappings) is discussed in [9]. In that case the small inhomogeneity (that is mapped to the finite sized approximately cloaked region) is of the form $F\left(\rho B_{1}\right)$ for some smooth map $F$. For simplicity let us assume $F(0)=0$. Then we have exactly (by performing a Taylor expansion of $F$ around 0 ) that $(1-C \rho) \rho D F(0) B_{1} \subset F\left(\rho B_{1}\right) \subset(1+C \rho) \rho D F(0) B_{1}$, where $C$ depends on bounds of the second derivatives of $F$. We are thus exactly in the situation covered by Theorem 3, the domain $D$ being the ellipsoid $D F(0) B_{1}$. For a given background field $\nabla u_{0}(0)$ (or for a given family of background fields) the very precise information about the magnitude of the effect of the small inhomogeneity, described in Theorem 3, may be used to determine the best/worst ellipsoid from the point of view of approximate cloaking of a uniformly conducting object.

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## Appendix A. Auxiliary results for exterior domains

In this appendix we present some results concerning the solution of exterior problems that were used extensively in Sections 3.1 and 3.2. We first introduce some convenient notation. Let $U$ be a connected, smooth open region of $\mathbb{R}^{d}$ $(d=2,3)$ with a bounded complement (this includes $\left.U=\mathbb{R}^{d}\right)$. The space $W^{1}(U)$ is defined as follows

$$
W^{1}(U)=\left\{u \in L_{l o c}^{1}(U): \frac{u(x)}{\ln (2+|x|) \sqrt{1+|x|^{2}}} \in L^{2}(U) \text { and } \nabla u \in L^{2}(U)\right\},
$$

for $d=2$, and

$$
W^{1}(U)=\left\{u \in L_{l o c}^{1}(U): \frac{u(x)}{\sqrt{1+|x|^{2}}} \in L^{2}(U) \text { and } \nabla u \in L^{2}(U)\right\}
$$

for $d=3$. This definition is taken from [13, page 59]. We recall the following result (see e.g. [13, Section 2.5.4]).
Proposition 1. $W^{1}(U)$ is a Hilbert space with the scalar product

$$
\langle u, v\rangle_{W^{1}}=\int_{U}\left(\nabla u \cdot \nabla v+\frac{u(x) v(x)}{\ln ^{2}(2+|x|)\left(1+|x|^{2}\right)}\right) d x, \quad \text { for } d=2
$$

and

$$
\langle u, v\rangle_{W^{1}}=\int_{U}\left(\nabla u \cdot \nabla v+\frac{u(x) v(x)}{1+|x|^{2}}\right) d x, \quad \text { for } d=3
$$

For $d=3$ we may omit the zero'th order term, i.e., an equivalent scalar product on $W^{1}(U)$ is given by

$$
\langle u, v\rangle_{W^{1}}=\int_{U} \nabla u \cdot \nabla v d x, \quad \text { for } d=3
$$

Remark 1. For $d=2$ we cannot omit the zero'th order term and still obtain an equivalent scalar product, for the simple reason that constants lie in the set $W^{1}(U)$. On the other hand if $\mathfrak{N}(\cdot)$ is a continuous linear functional on $W^{1}(U)$ with the property that:

$$
c \text { constant and } \mathfrak{N}(c)=0 \Rightarrow c=0
$$

then the scalar product $\langle u, v\rangle_{W^{1}}=\int_{U} \nabla u \cdot \nabla v d x$ is equivalent to the scalar product $\langle u, v\rangle_{W^{1}}=\int_{U}(\nabla u \cdot \nabla v+$ $\left.\frac{u(x) v(x)}{\ln ^{2}(2+|x|)\left(1+|x|^{2}\right)}\right) d x$ on the closed, co-dimension 1 subspace

$$
W_{\mathfrak{N}}^{1}(U)=W^{1}(U) \cap\{u: \mathfrak{N}(u)=0\}
$$

see Theorem 2.5.13 of [13].
In the following we shall always assume that $D$ is a smooth, bounded, simply connected domain in $\mathbb{R}^{d}(d=2,3)$. We note that as a consequence $U=\mathbb{R}^{d} \backslash \bar{D}$ has only one connected component.

Proposition 2. Suppose $g \in H^{\frac{1}{2}}(\partial D)$. There exists a unique solution $V \in W^{1}\left(\mathbb{R}^{d} \backslash \bar{D}\right)$ to

$$
\begin{cases}-\Delta V=0 & \text { in } \mathbb{R}^{d} \backslash \bar{D} \\ V=g & \text { on } \partial D\end{cases}
$$

This solution satisfies

$$
\begin{equation*}
\|V\|_{W^{1}\left(\mathbb{R}^{d} \backslash \bar{D}\right)} \leqslant C\|g\|_{H^{\frac{1}{2}}(\partial D)} \tag{A.1}
\end{equation*}
$$

Additionally, in the case $d=2$,

$$
\begin{equation*}
\int_{\partial D} \frac{\partial V}{\partial n} d \sigma=0 \tag{A.2}
\end{equation*}
$$

For both $d=2$ and $d=3 V$ has the representation

$$
V(x)=\int_{\partial D} \frac{\partial}{\partial n_{y}} \Phi(x, y) V d \sigma_{y}-\int_{\partial D} \Phi(x, y) \frac{\partial V}{\partial n_{y}} d \sigma_{y}+C_{V}, \quad x \in \mathbb{R}^{d} \backslash \bar{D}
$$

where $C_{V}$ is a constant,

$$
\Phi(x, y)= \begin{cases}-\frac{1}{2 \pi} \ln |x-y| & \text { if } d=2, \\ \frac{1}{4 \pi|x-y|} & \text { if } d=3,\end{cases}
$$

and $n_{y}$ denotes the exterior unit normal vector to $D$ at $y \in \partial D$. The constant $C_{V}$ is equal to 0 in the case $d=3$.
Proof. We first consider the case $d=3$. The arguments leading to existence and uniqueness of $V$ are standard, and so is the estimate (A.1) for $V$. Since $V \in W^{1}\left(\mathbb{R}^{d} \backslash \bar{D}\right)$ one has

$$
\lim _{r \rightarrow \infty} \int_{B_{2 r} \backslash B_{r}}\left(|\nabla V|^{2}+\frac{|V|^{2}}{|x|^{2}}\right) d x=0
$$

On the other hand, for each $r$ (sufficiently large) there exists $R \in(r, 2 r)$ such that

$$
r \int_{\partial B_{R}}\left(|\nabla V|^{2}+\frac{|V|^{2}}{|R|^{2}}\right) d \sigma=\int_{B_{2 r} \backslash B_{r}}\left(|\nabla V|^{2}+\frac{|V|^{2}}{|x|^{2}}\right) d x .
$$

Therefore, there exists a sequence $R_{k}$ such that $\lim _{k \rightarrow \infty} R_{k}=\infty$ and

$$
\begin{equation*}
\lim _{k \rightarrow \infty} R_{k} \int_{\partial B_{R_{k}}}\left(|\nabla V|^{2}+\frac{|V|^{2}}{\left|R_{k}\right|^{2}}\right) d \sigma=0 . \tag{A.3}
\end{equation*}
$$

Given any $x \in \mathbb{R}^{d} \backslash \bar{D}$, Green's identity gives

$$
\begin{align*}
V(x)= & \int_{\partial D}\left(\frac{\partial}{\partial n_{y}} \Phi(x, y) V(y)-\Phi(x, y) \frac{\partial V}{\partial n_{y}}(y)\right) d \sigma_{y} \\
& +\int_{\partial B_{R_{k}}}\left(\Phi(x, y) \frac{\partial V}{\partial n_{y}}(y)-\frac{\partial}{\partial n_{y}} \Phi(x, y) V(y)\right) d \sigma_{y} . \tag{A.4}
\end{align*}
$$

Here $n_{y}$ denotes the normal vector directed into the exterior of $B_{R_{k}}$ or $D$ at the point $y \in \partial B_{R_{k}}$ or $y \in \partial D$. The second term in this formula satisfies the estimate

$$
\left|\int_{\partial B_{R_{k}}}\left(\Phi(x, y) \frac{\partial V}{\partial n_{y}}(y)-\frac{\partial}{\partial n_{y}} \Phi(x, y) V(y)\right) d \sigma_{y}\right| \leqslant C_{x} \int_{\partial B_{R_{k}}}\left(\frac{|\nabla V|}{R_{k}}+\frac{|V|}{R_{k}^{2}}\right) d \sigma .
$$

An application of Hölder's inequality yields

$$
\left|\int_{\partial B_{R_{k}}}\left(\Phi(x, y) \frac{\partial V}{\partial n_{y}}(y)-\frac{\partial}{\partial n_{y}} \Phi(x, y) V(y)\right) d \sigma_{y}\right| \leqslant C_{x}\left(\left(\int_{\partial B_{R_{k}}}|\nabla V|^{2} d \sigma\right)^{\frac{1}{2}}+\left(\int_{\partial B_{R_{k}}} \frac{|V|^{2}}{R_{k}^{2}} d \sigma\right)^{\frac{1}{2}}\right) .
$$

Letting $k$ tend to infinity, and using (A.3), we get

$$
\lim _{k \rightarrow \infty}\left|\int_{\partial B_{R_{k}}}\left(\Phi(x, y) \frac{\partial V}{\partial n_{y}}(y)-\frac{\partial}{\partial n_{y}} \Phi(x, y) V(y)\right) d \sigma_{y}\right|=0 .
$$

By inserting this into (A.4) we finally obtain

$$
V(x)=\int_{\partial D}\left(\frac{\partial}{\partial n_{y}} \Phi(x, y) V(y)-\Phi(x, y) \frac{\partial V}{\partial n_{y}}(y)\right) d \sigma_{y},
$$

as desired.

We now turn to the case $d=2$. The arguments leading to existence and uniqueness of $V$ are standard, and so is the estimate (A.1) for $V$. Since $V \in W^{1}\left(\mathbb{R}^{2} \backslash \bar{D}\right)$ we may analogously to (A.3) in this case prove that there exists a sequence $R_{k} \rightarrow \infty$ as $k \rightarrow \infty$, such that

$$
\lim _{k \rightarrow \infty} R_{k} \int_{\partial B_{R_{k}}}\left(|\nabla V|^{2}+\frac{|V|^{2}}{\ln ^{2} R_{k}\left|R_{k}\right|^{2}}\right) d \sigma=0,
$$

or equivalently

$$
\begin{align*}
& \lim _{k \rightarrow \infty} R_{k} \int_{\partial B_{R_{k}}}|\nabla V|^{2} d \sigma=0 \text { and }  \tag{A.5}\\
& \lim _{k \rightarrow \infty} R_{k} \int_{\partial B_{R_{k}}} \frac{|V|^{2}}{\ln ^{2} R_{k}\left|R_{k}\right|^{2}} d \sigma=0 . \tag{A.6}
\end{align*}
$$

The identity (A.2) follows from (A.5) if we let $k$ tend to $\infty$ in the estimate

$$
\left|\int_{\partial D} \frac{\partial V}{\partial n} d \sigma\right|=\left|\int_{\partial B_{R_{k}}} \frac{\partial V}{\partial n} d \sigma\right| \leqslant\left.\left.\left(2 \pi R_{k}\right)^{\frac{1}{2}}\right|_{\partial B_{R_{k}}}\left|\frac{\partial V}{\partial n}\right|^{2} d \sigma\right|^{\frac{1}{2}} .
$$

For $r_{1}<r_{2}$ sufficiently large (that $\bar{D} \subset B_{r_{1}}$ ) Green's identity applied to the annulus $B_{r_{2}} \backslash \overline{B_{r_{1}}}$ gives

$$
\int_{\partial B_{r_{1}}}\left(\frac{\partial}{\partial n_{y}} \Phi(0, y) V(y)-\Phi(0, y) \frac{\partial V}{\partial n_{y}}(y)\right) d \sigma_{y}=\int_{\partial B_{r_{2}}}\left(\frac{\partial}{\partial n_{y}} \Phi(0, y) V(y)-\Phi(0, y) \frac{\partial V}{\partial n_{y}}(y)\right) d \sigma_{y} .
$$

Since $\int_{\partial B_{r}} \frac{\partial V}{\partial n} d \sigma=\int_{\partial D} \frac{\partial V}{\partial n} d \sigma=0$ (as just proven above) and since $\frac{\partial}{\partial n_{y}} \Phi(0, y)$ and $\Phi(0, y)$ are both constant on $\partial B_{r}$, with $\frac{\partial}{\partial n_{y}} \Phi(0, y)=-\frac{1}{2 \pi r}$, it now follows that

$$
\frac{1}{2 \pi r_{1}} \int_{\partial B_{r_{1}}} V(y) d \sigma_{y}=\frac{1}{2 \pi r_{2}} \int_{\partial B_{r_{2}}} V(y) d \sigma_{y},
$$

for $r_{1}$ and $r_{2}$ sufficiently large. Thus the expression

$$
\begin{aligned}
C_{V} & =\int_{\partial B_{r}}\left(\Phi(0, y) \frac{\partial V}{\partial n_{y}}(y)-\frac{\partial}{\partial n_{y}} \Phi(0, y) V(y)\right) d \sigma_{y} \\
& =-\frac{1}{2 \pi} \log r \int_{\partial B_{r}} \frac{\partial V}{\partial n_{y}}(y) d \sigma_{y}+\frac{1}{2 \pi r} \int_{\partial B_{r}} V(y) d \sigma_{y} \\
& =\frac{1}{2 \pi r} \int_{\partial B_{r}} V(y) d \sigma_{y}
\end{aligned}
$$

does indeed define a constant, independent of $r$, for $r$ sufficiently large. It follows directly from Green's identity (see (A.4)) that

$$
\begin{align*}
& V(x)-C_{V}-\int_{\partial D}\left(\frac{\partial}{\partial n_{y}} \Phi(x, y) V(y)-\Phi(x, y) \frac{\partial V}{\partial n_{y}}(y)\right) d \sigma_{y} \\
& \quad=\int_{\partial B_{R_{k}}}\left((\Phi(x, y)-\Phi(0, y)) \frac{\partial V}{\partial n_{y}}(y)-\frac{\partial}{\partial n_{y}}(\Phi(x, y)-\Phi(0, y)) V(y)\right) d \sigma_{y} . \tag{A.7}
\end{align*}
$$

Since

$$
|\Phi(x, y)-\Phi(0, y)|=\frac{1}{2 \pi}|\log | \frac{x}{|y|}-\frac{y}{|y|}| | \leqslant C_{x} \frac{1}{|y|}
$$

and

$$
\left|\frac{\partial}{\partial n_{y}}(\Phi(x, y)-\Phi(0, y))\right|=\frac{1}{2 \pi}\left|\frac{|y|-x \cdot y /|y|}{|y-x|^{2}}-\frac{|y|}{|y|^{2}}\right| \leqslant C_{x} \frac{1}{|y|^{2}}
$$

on $\partial B_{R_{k}}$, we easily estimate

$$
\begin{align*}
& \left|\int_{\partial B_{R_{k}}}\left((\Phi(x, y)-\Phi(0, y)) \frac{\partial V}{\partial n_{y}}(y)-\frac{\partial}{\partial n_{y}}(\Phi(x, y)-\Phi(0, y)) V(y)\right) d \sigma_{y}\right| \\
& \quad \leqslant C_{x} \int_{\partial B_{R_{k}}}\left(\frac{|\nabla V|}{R_{k}}+\frac{|V|}{R_{k}^{2}}\right) d \sigma \\
& \quad \leqslant C_{x}\left(\frac{1}{\sqrt{R_{k}}}\left(\int_{\partial B_{R_{k}}}|\nabla V|^{2} d \sigma\right)^{1 / 2}+\frac{\ln R_{k}}{\sqrt{R_{k}}}\left(\int_{\partial B_{R_{k}}} \frac{|V|^{2}}{\ln ^{2} R_{k} R_{k}^{2}} d \sigma\right)^{1 / 2}\right) \\
& \quad \rightarrow 0 \quad \text { as } k \rightarrow \infty . \tag{A.8}
\end{align*}
$$

Here we have used (A.5)-(A.6) to obtain the final convergence. Insertion of (A.8) into (A.7) shows that

$$
V(x)=\int_{\partial D}\left(\frac{\partial}{\partial n_{y}} \Phi(x, y) V(y)-\Phi(x, y) \frac{\partial V}{\partial n_{y}}(y)\right) d \sigma_{y}+C_{V},
$$

exactly as desired. This completes the proof of Proposition 2.
Remark 2. Even though we shall not use it in this paper, we note that a simple argument shows that

$$
C_{V}=\lim _{R \rightarrow \infty} \frac{1}{2 \pi R} \int_{\partial B_{R}} V(y) d \sigma_{y}=\lim _{|x| \rightarrow \infty} V(x), \quad \text { for } d=2
$$

There is an analogue of Proposition 2 for the exterior Neumann problem. In this paper we shall only use this result in the case $d=3$. Its proof is entirely similar to the proof of Proposition 2, and is left to the reader.

Proposition 3. Suppose $d=3$ and $g \in H^{-\frac{1}{2}}(\partial D)$. There exists a unique solution $V \in W^{1}\left(\mathbb{R}^{3} \backslash \bar{D}\right)$ to

$$
\begin{cases}-\Delta V=0 & \text { in } \mathbb{R}^{3} \backslash \bar{D} \\ \frac{\partial V}{\partial n}=g & \text { on } \partial D\end{cases}
$$

This solution satisfies

$$
\|V\|_{W^{1}\left(\mathbb{R}^{3} \backslash \bar{D}\right)} \leqslant C\|g\|_{H^{-\frac{1}{2}}(\partial D)} .
$$

Moreover,

$$
V(x)=\int_{\partial D} \frac{\partial}{\partial n_{y}} \Phi(x, y) V d \sigma_{y}-\int_{\partial D} \Phi(x, y) \frac{\partial V}{\partial n_{y}} d \sigma_{y}, \quad x \in \mathbb{R}^{3} \backslash \bar{D},
$$

where

$$
\Phi(x, y)=\frac{1}{4 \pi|x-y|}
$$

and $n_{y}$ denotes the exterior unit normal vector to $D$ at $y \in \partial D$.

For $v \in C^{1}\left(\mathbb{R}^{d} \backslash D\right) \times C^{1}(\bar{D})$ we define

$$
[v]=\left.v\right|_{\text {ext }}-\left.v\right|_{\text {int }} \quad \text { on } \partial D .
$$

We note that this difference has a continuous extension to $W^{1}\left(\mathbb{R}^{d} \backslash \bar{D}\right) \times H^{1}(D)$. We use the notation $\left(H^{1}(D)\right)^{*}$ for the dual of $H^{1}(D)$, and given $f \in\left(H^{1}(D)\right)^{*}$ the action of $f$ on the function 1 is denoted by $\int_{D} f d x$.

Proposition 4. Let $\gamma$ be an element of

$$
L_{+}^{\infty}(D)=\left(L^{\infty}(D)\right)^{d \times d} \cap\{\gamma(x) \text { symmetric, positive definite, ess inf } \gamma>0\},
$$

and suppose $f \in\left(H^{1}(D)\right)^{*}, g \in H^{-\frac{1}{2}}(\partial D), h \in H^{\frac{1}{2}}(\partial D)$. In dimension $d=2$ suppose additionally $\int_{D} f d x+$ $\int_{\partial D} g d \sigma=0$. There exists a solution $V \in W^{1}\left(\mathbb{R}^{d} \backslash \bar{D}\right) \times H^{1}(D)$ to

$$
\begin{cases}\nabla \cdot(\gamma \nabla V)=f & \text { in } D, \\ \Delta V=0 & \text { in } \mathbb{R}^{d} \backslash \bar{D}, \\ \left.\frac{\partial V}{\partial n}\right|_{\mathrm{ext}}-\left.(\gamma \nabla V) \cdot n\right|_{\mathrm{int}}=g & \text { on } \partial D, \\ {[V]=h} & \text { on } \partial D .\end{cases}
$$

In dimension $d=3$ this solution is unique. In dimension $d=2$ the solution is unique modulo an additive constant we may make it unique by imposing the condition $\int_{\partial D} V d x=0$. Moreover,

$$
\begin{equation*}
V(x)=\left.\int_{\partial D} \frac{\partial}{\partial n_{y}} \Phi(x, y) V\right|_{\mathrm{ext}} d \sigma_{y}-\left.\int_{\partial D} \Phi(x, y) \frac{\partial V}{\partial n_{y}}\right|_{\mathrm{ext}} d \sigma_{y}+C_{V} \tag{A.9}
\end{equation*}
$$

$x \in \mathbb{R}^{d} \backslash \bar{D}$, where $C_{V}$ is a constant,

$$
\Phi(x, y)= \begin{cases}-\frac{1}{2 \pi} \ln |x-y| & \text { if } d=2, \\ \frac{1}{4 \pi|x-y|} & \text { if } d=3,\end{cases}
$$

and $n_{y}$ denotes the exterior unit normal vector to $D$ at $y \in \partial D$. The constant $C_{V}$ is equal to 0 in the case $d=3$. The solution $V$ depends linearly and continuously on the data $f, g$ and $h$. In the particular case when $f=0$ it satisfies the estimate

$$
\begin{equation*}
\|\nabla V\|_{L^{2}\left(\mathbb{R}^{d} \backslash \bar{D}\right)}+\left\|\gamma^{1 / 2} \nabla V\right\|_{L^{2}(D)} \leqslant C\left(\|g\|_{H^{-\frac{1}{2}}(\partial D)}+\|h\|_{H^{\frac{1}{2}}(\partial D)}\right), \tag{A.10}
\end{equation*}
$$

with a constant $C$ that is independent of $\gamma$ (and of $g$ and $h$ ).
Proof. A standard variational argument yields the uniqueness of $V$ (modulo a constant in the case $d=2$ ). We proceed to verify the existence. Applying the Lax-Milgram Lemma and Proposition 2 we may select $\tilde{W}=\left(\tilde{W}_{1}, \tilde{W}_{2}\right) \in$ $W^{1}\left(\mathbb{R}^{d} \backslash \bar{D}\right) \times H^{1}(D)$ by first requiring that

$$
\begin{cases}\nabla \cdot\left(\gamma \nabla \tilde{W}_{2}\right)=f & \text { in } D, \\ \left(\gamma \nabla \tilde{W}_{2}\right) \cdot n=\frac{1}{|\partial D|} \int_{D} f d x & \text { on } \partial D,\end{cases}
$$

and secondly requiring that

$$
\begin{cases}\Delta \tilde{W}_{1}=0 & \text { in } \mathbb{R}^{d} \backslash \bar{D}, \\ \tilde{W}_{1}=h+\tilde{W}_{2} & \text { on } \partial D\end{cases}
$$

We notice that if $f=0$ then we may select $\tilde{W}_{2}=0$ and, according to Proposition $2, \tilde{W}_{1}$ therefore satisfies the estimate

$$
\left\|\tilde{W}_{1}\right\|_{W^{1}\left(\mathbb{R}^{d} \backslash \bar{D}\right)} \leqslant C\|h\|_{H^{\frac{1}{2}}(\partial D)} .
$$

In combination with the fact that $\tilde{W}_{1}$ is harmonic in $\mathbb{R}^{d} \backslash \bar{D}$, this yields

$$
\begin{equation*}
\left\|\frac{\partial \tilde{W}_{1}}{\partial n}\right\|_{H^{-1 / 2}(D)} \leqslant C\|h\|_{H^{\frac{1}{2}(\partial D)}} \quad \text { when } f=0 \tag{A.11}
\end{equation*}
$$

with a constant $C$ that is independent of $\gamma$. For $d=2$ we have, according to Proposition 2, that $\int_{\partial D} \frac{\partial \tilde{W}_{1}}{\partial n} d \sigma=0$. We now decompose the function $V$ as $V=\tilde{V}+\tilde{W}$ where $\tilde{V} \in W^{1}\left(\mathbb{R}^{d} \backslash \bar{D}\right) \times H^{1}(D)$ is a solution to

$$
\begin{cases}\nabla \cdot(\gamma \nabla \tilde{V})=0 & \text { in } D, \\ \Delta \tilde{V}=0 & \text { in } \mathbb{R}^{d} \backslash \bar{D}, \\ \left.\frac{\partial \tilde{V}}{\partial n}\right|_{\text {ext }}-\left.(\gamma \nabla \tilde{V}) \cdot n\right|_{\text {int }}=g-\frac{\partial \tilde{W}_{1}}{\partial n}+\frac{1}{|\partial D|} \int_{D} f d x & \text { on } \partial D, \\ {[V]=0} & \text { on } \partial D .\end{cases}
$$

The existence of such a $\tilde{V}$ is again a classical consequence of the Lax-Milgram Lemma. It is also easy to see that $\tilde{V}$ satisfies the estimate

$$
\|\nabla \tilde{V}\|_{L^{2}\left(\mathbb{R}^{d} \backslash \bar{D}\right)}+\left\|\gamma^{1 / 2} \nabla \tilde{V}\right\|_{L^{2}(D)} \leqslant C\left\|g-\frac{\partial \tilde{W}_{1}}{\partial n}+\frac{1}{|\partial D|} \int f d x\right\|_{H^{-\frac{1}{2}}(\partial D)}
$$

with $C$ independent of $\gamma$. In the particular case when $f=0$ (and thus $\tilde{W}_{2}=0$ ) we get by a combination of this with (A.11)

$$
\begin{aligned}
\|\nabla V\|_{L^{2}\left(\mathbb{R}^{d} \backslash \bar{D}\right)}+\left\|\gamma^{1 / 2} \nabla V\right\|_{L^{2}(D)} & \leqslant C\left(\left\|g-\frac{\partial \tilde{W}_{1}}{\partial n}\right\|_{H^{-\frac{1}{2}}(\partial D)}+\|h\|_{H^{\frac{1}{2}}(\partial D)}\right) \\
& \leqslant C\left(\|g\|_{H^{-\frac{1}{2}}(\partial D)}+\|h\|_{H^{\frac{1}{2}}(\partial D)}\right)
\end{aligned}
$$

as stated in (A.10). Finally, the representation formula (A.9) is an immediate consequence of the analogous formula from Proposition 2.

Remark 3. Just as in Proposition 2 the constant $C_{V}$ may easily be shown to have the form

$$
C_{V}=\lim _{R \rightarrow \infty} \frac{1}{2 \pi R} \int_{\partial B_{R}} V(y) d \sigma_{y}=\lim _{|x| \rightarrow \infty} V(x),
$$

for $d=2$.

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