

Biokinetic process model diagnosis with shape-constrained spline functions

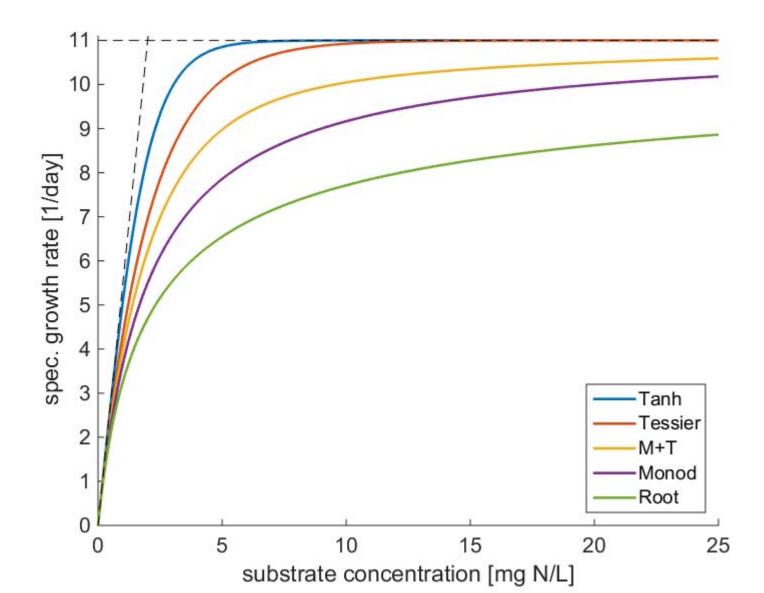
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Eawag: Swiss Federal Institute of Aquatic Science and Technology



Problem statement





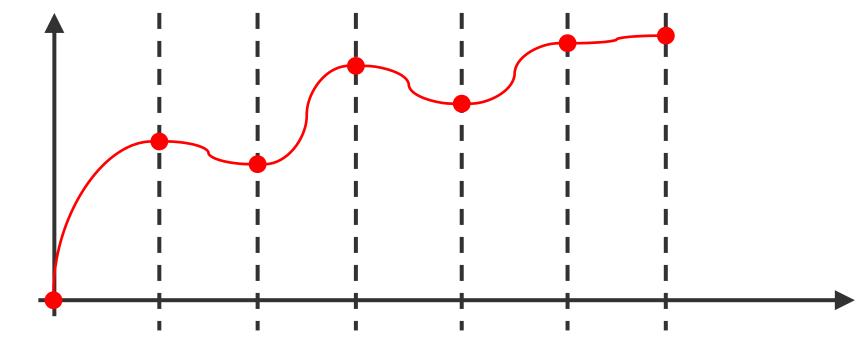
Problem statement

Can we find?

- A single kinetic rate law
- For all cases
- With a predetermined shape
- Based on experimental data



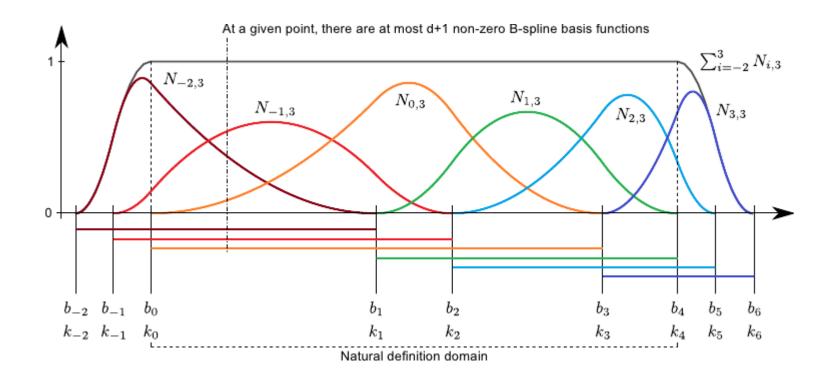
Method: Splines





Shape constrained spline (SCS) functions

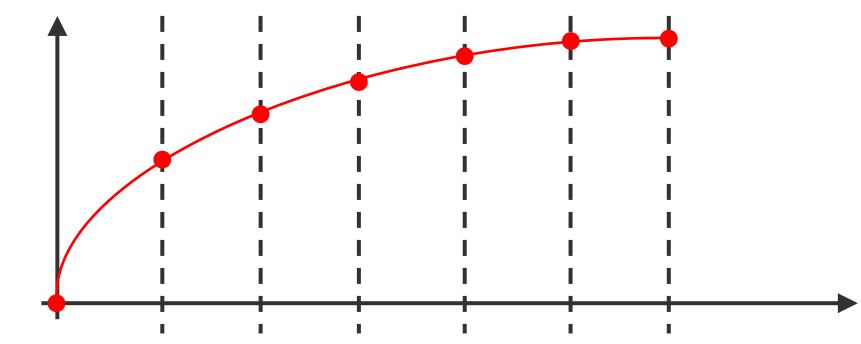
Defined by the number and location of knots.



 $r_{SCS}(S) = \boldsymbol{b}(S)^T \cdot \boldsymbol{\theta}$



Method: Shape Constrained Splines





Method: Shape Constrained Splines

Function

Cubic spline

$$r_{SCS}(S) = b_0(S)^T \cdot \theta$$

Shape constraints

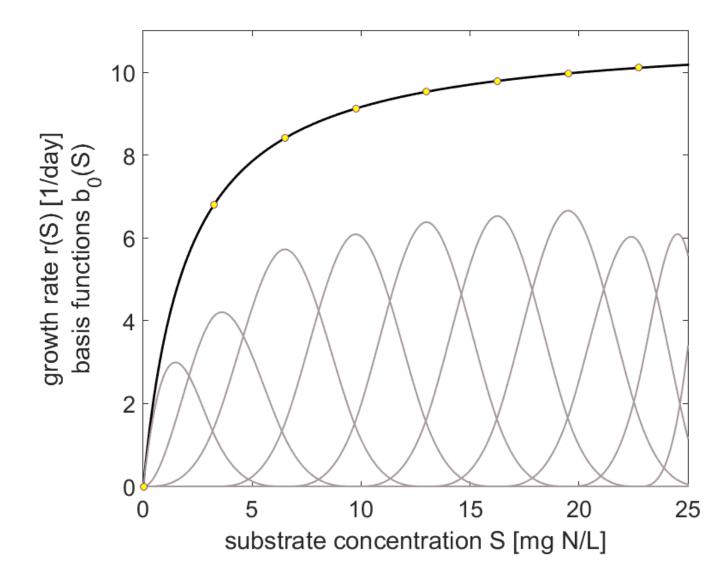
Often: linear in the parameters Example: concave profile

 $b_2(S_k)^T \cdot \theta \leq 0 \quad \forall k = 1, \dots, n_k$

Flexible Semi-parametric **Black-box** Prior knowledge Smoothness White-box



Method: Shape Constrained Splines





Method: what has changed?

Previous work

Current work

$$\dot{x}(t) = -f(x(t), \theta), \quad x(0) = 0$$
$$\tilde{y}(t) = c x(t) + d e(t)$$

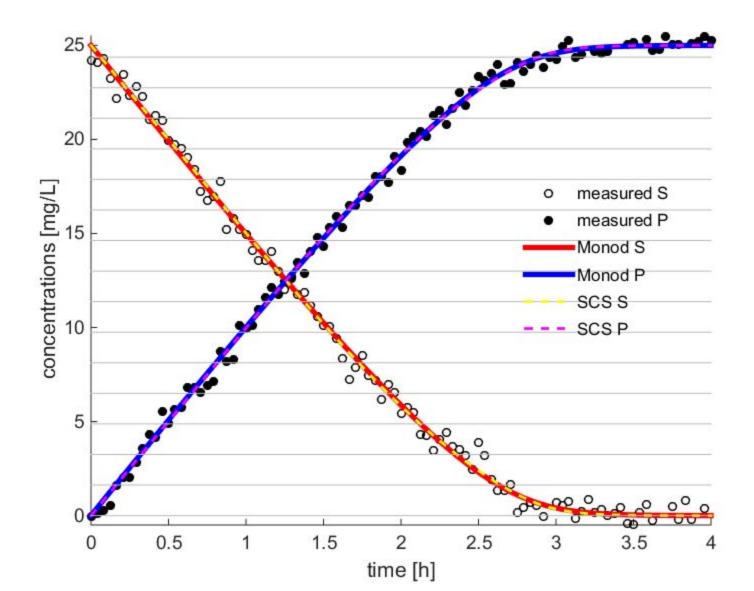
 $\boldsymbol{\theta} \in \boldsymbol{\Omega}$

$$\widetilde{\mathbf{y}}(t) = f(t, \boldsymbol{\theta}) + e(t)$$

 $\boldsymbol{\theta} \in \boldsymbol{\Omega}$

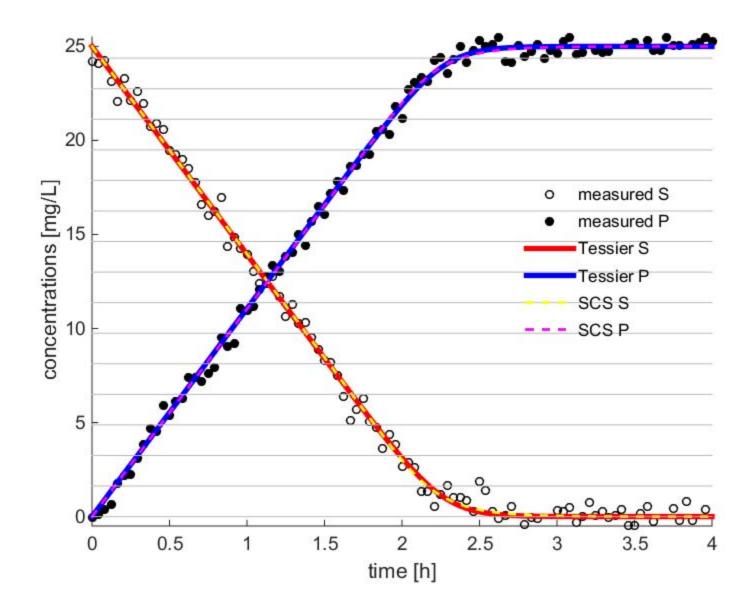


Results: Monod



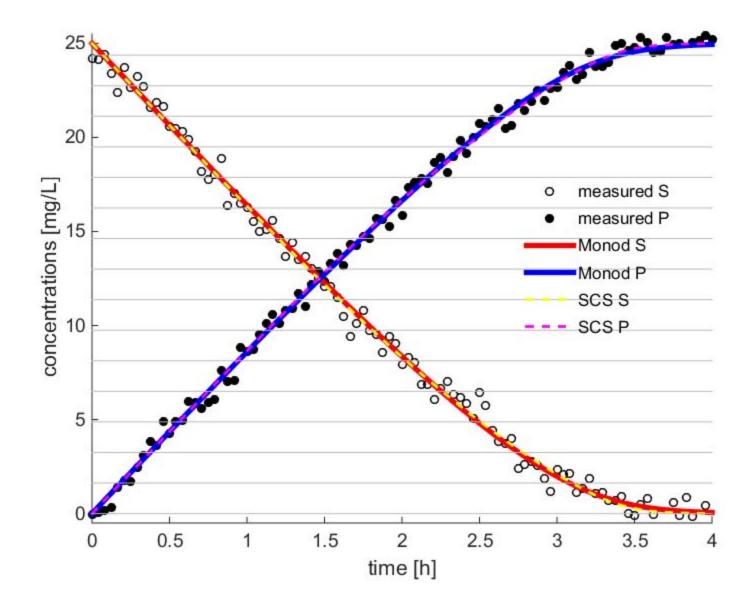


Results: Tanh



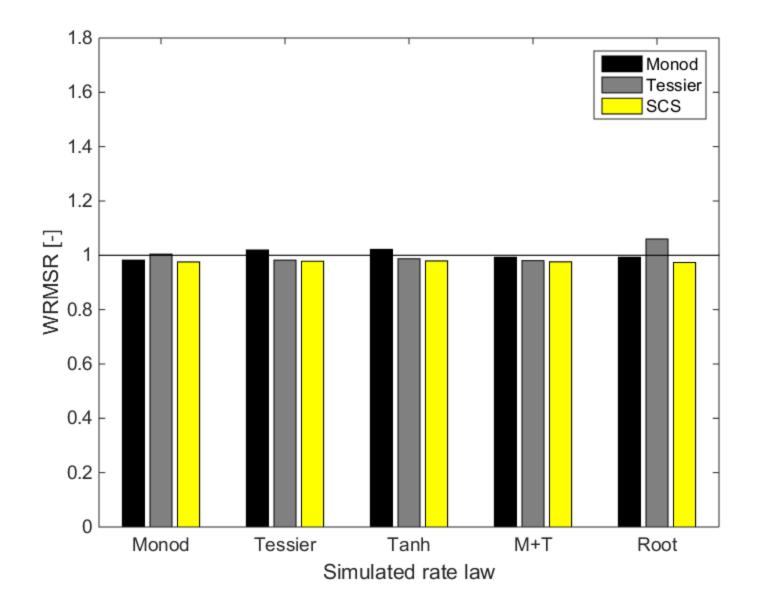


Results: Root





Comparing all: WRMSR





Conclusions / Perspectives

- Shape constrained spline functions as rate models
- Near-universal property
- Advantages
 - One-for-all model structure
 - Only one parameter optimization
- Coming up
 - Different shape (ecoSTP2016)
 - Laboratory experiment
 - Uncertainty analysis
 - Increased complexity



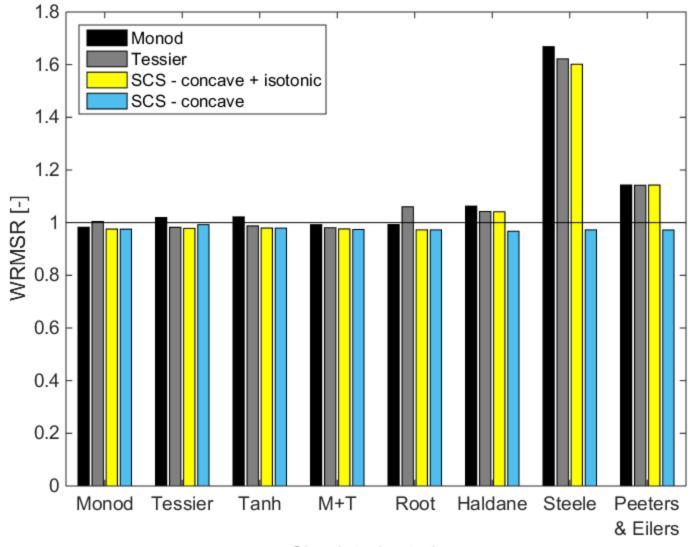
Summary

We found

- A single kinetic rate law
- For all (substrate affinity) cases
- With a predetermined shape
- Based on (simulated) experimental data



Different shape



Simulated rate law