

INT 145/88

PROGRAMME ISTART 4  
C o u r a n t d ' a c c r o c h a g e d ' u n g y r o t r o n  
t r a v a i l l a n t e n m o d e T E m p q

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MIT 140 GHz gyrotron ( $TE_{03}$ )	
42 GHz gyrotron ( $TE_{02}$ )	
CRPP 8 GHz gyrotron ( $TE_{01}$ )	
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Listage du programme (sur demande)	

## 1. BUT DU PROGRAMME ISTART4

Dessiner le courant d'accrochage en fonction du champ magnétique statique  $B$ , pour différents modes  $TE_{mpq}$ .

A la différence du code ISTART3, on tient compte cette fois de l'indice axial  $q$ .

## 2. MODELE ET EQUATIONS UTILISEES

Le calcul analytique est basé sur les hypothèses suivantes:

Champ électrique dans la cavité cylindrique [1, 2]:

$$\underline{E} = (E_r \hat{r} + E_\phi \hat{\phi}) e^{i(\omega t + \psi)} \quad \text{avec:}$$

$$\begin{cases} E_r = i \frac{m}{k_{\perp} r} E_0 g(z) J_m(k_{\perp} r) e^{-im\phi} \\ E_\phi = E_0 g(z) J'_m(k_{\perp} r) e^{-im\phi} \end{cases}$$

A un instant donné, le champ électrique physiquement mesurable est la partie réelle de  $\underline{E}$ .

$$k_{\perp} = \frac{\nu_{mp}}{a} ; \quad \nu_{mp} : p^{\text{ième}} \text{ zéro non nul de } J'_m(x)$$

$a$  = rayon de la cavité

Le champ  $E$  a un profil sinusoïdal selon  $z$ , l'axe du faisceau d'électrons:

$$g(z) = \sin(k_{\parallel} z) \quad \text{avec } k_{\parallel} = \frac{q\pi}{L}$$

$L$  = longueur de la cavité ( $\neq L$  du programme ISTART3)

$L = 3/2 \cdot \text{FWHM}$  de  $g(z)$

La pulsation propre de la cavité est donnée par

$$\left(\frac{\omega}{c}\right)^2 = k^2 = k_{\perp}^2 + k_{\parallel}^2 \quad \text{d'où } \omega = c \sqrt{\left(\frac{\nu_{mp}}{a}\right)^2 + \left(\frac{q\pi}{L}\right)^2}$$

[1] Generalized Nonlinear Harmonic Gyrotron Theory, B.G. Danly and R.J. Temkin, PFC, MIT, April 85.

[2] High Frequency Gyrotrons and Their Application to Tokamak Plasma Heating, K.E. Kreisher and R.J. Temkin, Infrared and MM Waves, Vol. 7, chap. 8, 1983.

Le faisceau électronique est caractérisé par sa tension  $V_0$ , son anisotropie  $\alpha = \beta_{\perp}/\beta_{\parallel}$ , son rayon  $R_e$ .

$$\gamma_0 = 1 + \frac{eV_0}{mc^2} \quad ; \quad \beta_{\parallel} = \frac{w}{c} = \sqrt{\frac{1 - \gamma_0^{-2}}{1 + \alpha^2}} \quad ; \quad \beta_{\perp} = \frac{u}{c} = \alpha \beta_{\parallel}$$

Pulsation de Larmor non relativiste:  $\Omega_0 = \frac{eB_0}{m_e}$

Condition de résonance:  $\omega - \underline{k} \cdot \underline{v} = \Omega_0 / \gamma_0$

Soit, en projection:  $\omega + k_{\parallel} u = \Omega_0 / \gamma_0$

Il est alors d'usage de définir  $x = \frac{\Omega_0 / \gamma_0 - \omega}{k_{\parallel} u}$

Il y a résonance lorsque:  $\begin{cases} x = -1 & \text{avec l'onde progressive} \\ x = +1 & \text{avec l'onde rétrograde.} \end{cases}$

Bien que dans la cavité, l'onde stationnaire doit être une superposition de ces 2 ondes, c'est la condition  $x = -1$  qui est intéressante en pratique. (Voir la discussion dans [1].)

En fonction de  $x$ , le champ magnétique s'écrit:  $B_0 = \frac{m_e \gamma_0}{e} (\omega + x k_{\parallel} u)$

Le courant d'accrochage en Ampères est alors donné par

$$I = \frac{\epsilon_0 m_e}{e} \frac{\omega}{Q_{mpq}} |P_0|^2 \frac{(k_{\parallel} u)^2}{G(R_e)} \left[ \beta_{\perp}^2 \frac{dF_c}{dx} - 2 F_c \right]$$

avec:

$$|P_0|^2 = \frac{\pi L}{2} k^{-2} (\gamma_{mp}^2 - m^2) J_m^2(\gamma_{mp})$$

$$G(R_e) = J_{m\pm 1}^2(k_{\perp} R_e)$$

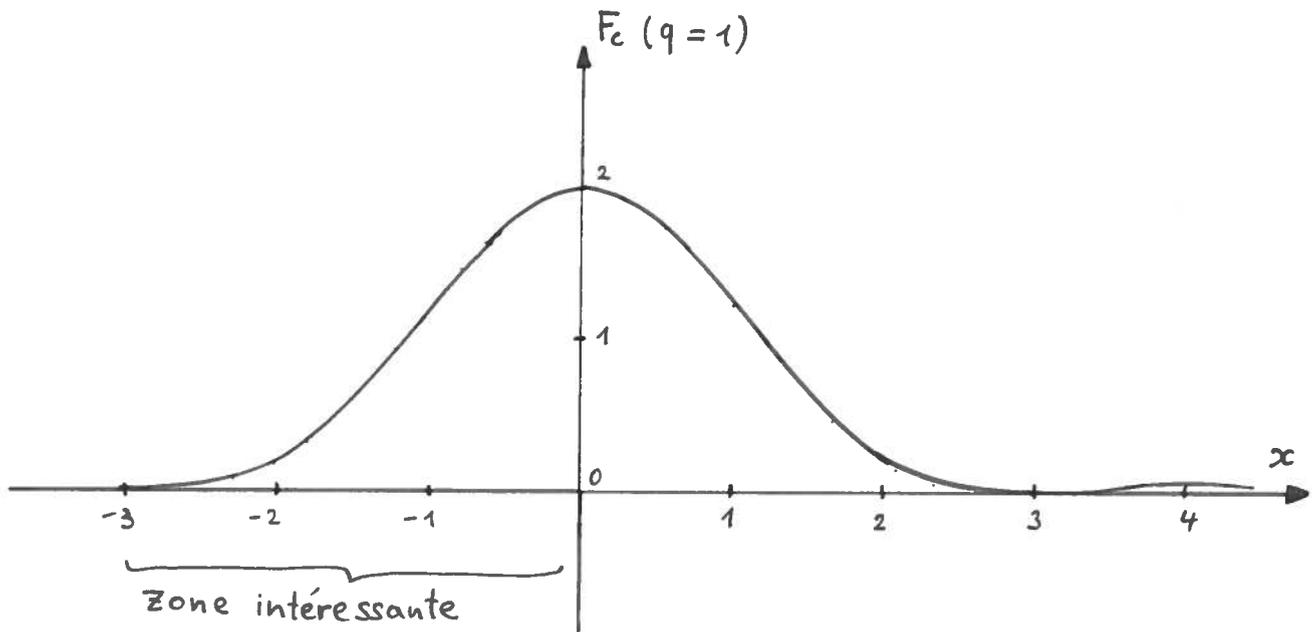
$$F_c(x, q) = \frac{2}{(1-x^2)^2} \sin^2 \frac{(x+1)\pi q}{2}$$

$$s = \frac{\Omega_0}{\gamma_0 k_{\parallel} u}$$

$Q_{mpq}$  = facteur de qualité du mode  $TE_{mpq}$

$J_{m\pm 1}$  : le signe dépend de la polarisation du mode ( $\pm im\phi$ ).  
Donc pour  $m \neq 0$ , il y aura 2 courbes  $I(B_0)$ .

Allure de  $F_c(x, q)$  :



En posant  $F_c = 2f^2$  avec  $f = \frac{1}{1-x^2} \sin \frac{(x+1)\pi q}{2}$

On a  $\lim_{x \rightarrow -1} f = \frac{\frac{x+1}{2} \pi q}{(1+x)(1-x)} = \lim_{x \rightarrow -1} \frac{\pi q}{2} \frac{1}{1-x} = \frac{\pi q}{4}$  d'où  $\lim_{x \rightarrow -1} F_c = \frac{\pi^2 q^2}{8}$

$$F' = 4ff'$$

$$\lim_{x \rightarrow -1} f' = \frac{\pi q}{2} \lim_{x \rightarrow -1} \left( \frac{1}{1-x} \right)' = \lim_{x \rightarrow -1} \frac{\pi q}{2} \frac{1}{(1-x)^2} = \frac{\pi q}{8}$$

$$\text{d'où } \lim F'_c = 4 \frac{\pi q}{4} \frac{\pi q}{8} = \frac{\pi^2 q^2}{8}$$

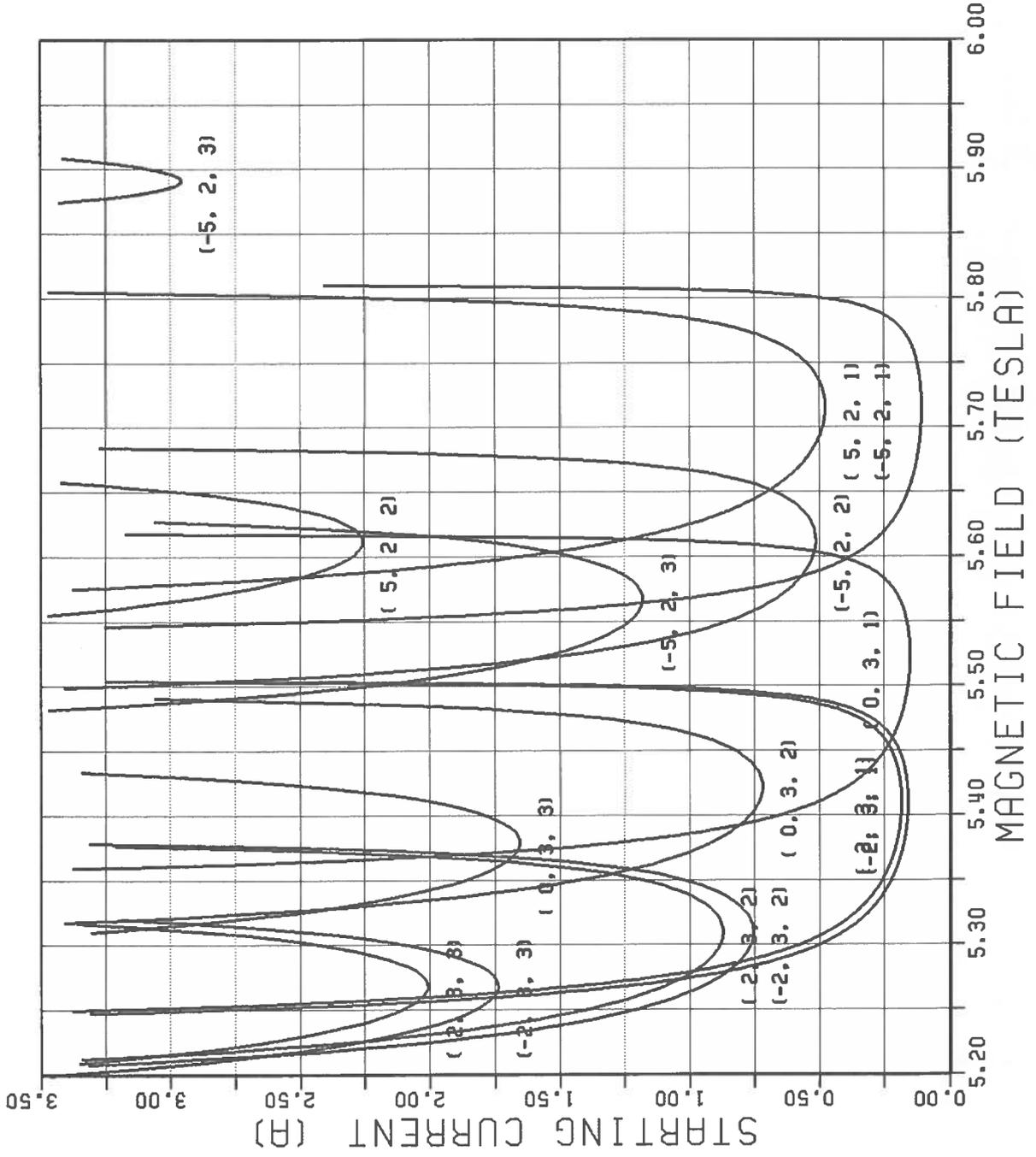
Pour  $x \rightarrow +1$ :  $\lim f = -\frac{\pi q}{4}$  ;  $\lim F_c = \frac{\pi^2 q^2}{8}$  ;  $\lim F' = -\frac{\pi^2 q^2}{8}$  .



MIT 140 GHZ GYROTRON  
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CRPP - 88/07/11. 14.31.25.  
 GYROTRON PROJECT

STARTING CURRENT VERSUS STATIC MAGNETIC FIELD PROGRAM ISTART4



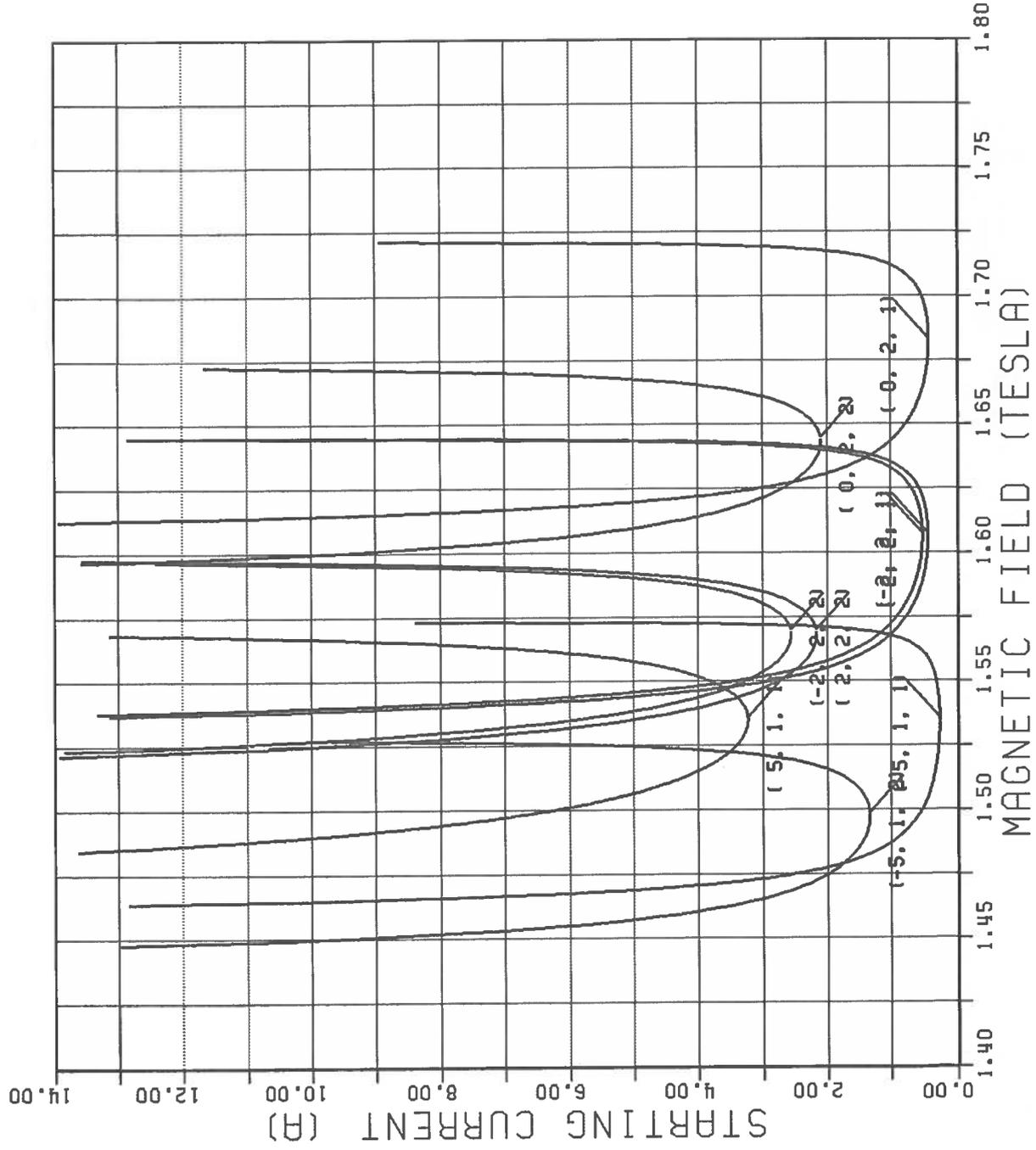
MODE	L [CM]	Q	FREQUENCY [GHZ]
TE (0, 3, 1)	15.0	1450.	140.244
TE (0, 3, 2)	15.0	963.	141.309
TE (0, 3, 3)	15.0	161.	143.064
TE (2, 3, 1)	15.0	1400.	137.447
TE (2, 3, 2)	15.0	350.	138.532
TE (2, 3, 3)	15.0	156.	140.323
TE (5, 2, 1)	15.0	1300.	144.996
TE (5, 2, 2)	15.0	325.	146.025
TE (5, 2, 3)	15.0	144.	147.725

RESONATOR RADIUS: 3.47 MM  
 GAMMA: 1.1272  
 ALPHA: 1.5000  
 BEAM VOLTAGE: 65.00 KV  
 ANNULAR BEAM RADIUS: 1.82 MM  
 HARMONIC #: 1

42 GHz Gyrotron  
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CRPP - 88/07/09. 10.45.06.  
 GYROTRON PROJECT

STARTING CURRENT VERSUS STATIC MAGNETIC FIELD PROGRAM ISTART4



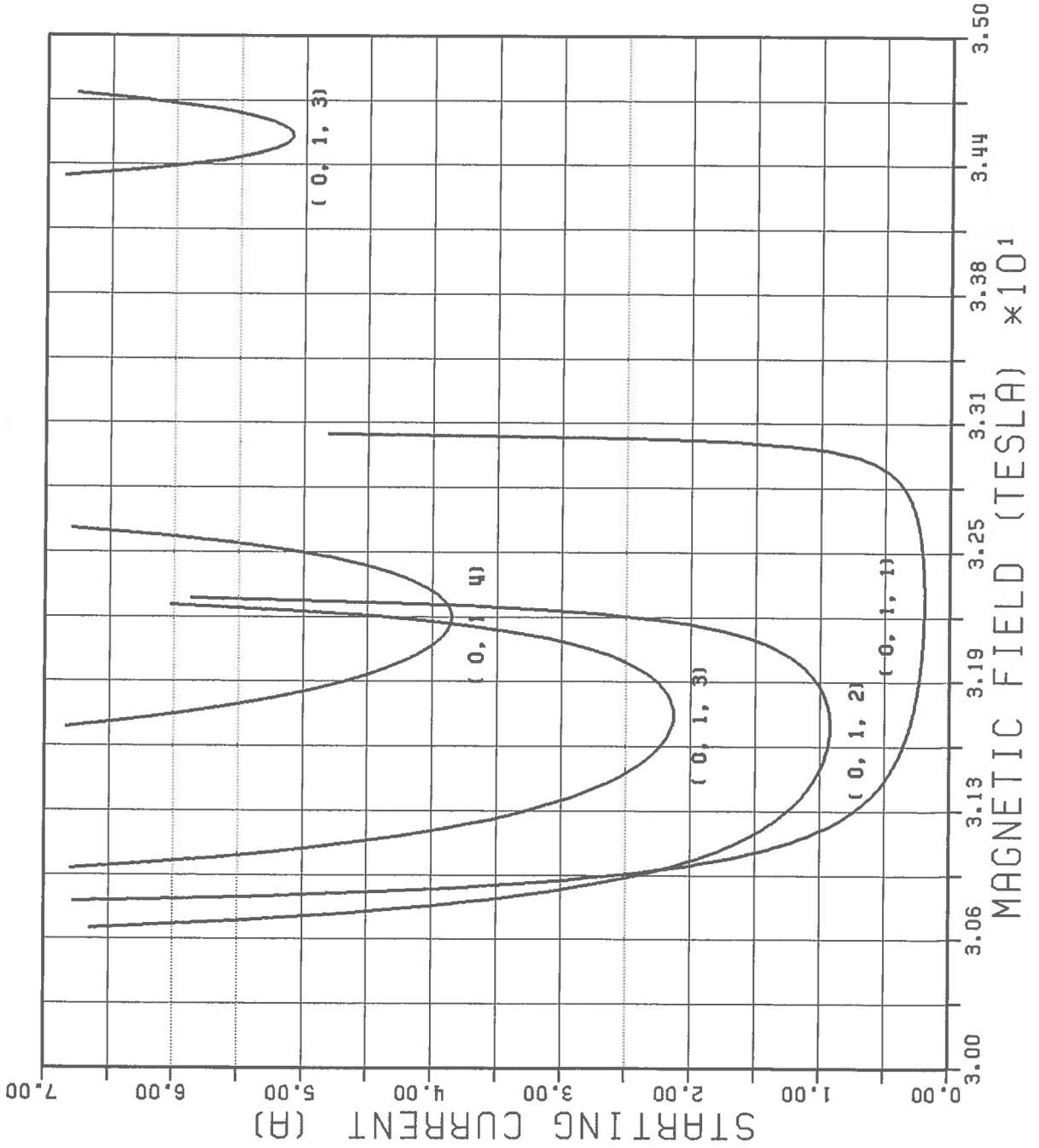
RESONATOR RADIUS: 8.00 MM  
 GAMMA: 1.1566  
 ALPHA: 1.5000  
 BEAM VOLTAGE: 80.00 KV  
 ANNULAR BEAM RADIUS: 6.00 MM  
 HARMONIC #: 1

MODE	L [MM]	Q	FREQUENCY [GHZ]
(0, 2, 1)	40.0	618.	42.010
(0, 2, 2)	40.0	155.	42.508
(2, 2, 1)	40.0	556.	40.172
(2, 2, 2)	40.0	139.	40.693
(5, 1, 1)	40.0	503.	38.447
(5, 1, 2)	40.0	126.	38.991

8 GHz GYROTRON

CAPP - 88/07/11. 14.20.52.  
GYROTRON PROJECT

STARTING CURRENT VERSUS STATIC MAGNETIC FIELD PROGRAM ISTART4



RESONATOR RADIUS: 22.80 MM  
GAMMA0: 1.1566  
ALPHA: 1.8900  
BEAM VOLTAGE: 80.00 KV  
ANNULAR BEAM RADIUS: 11.18 MM  
HARMONIC # : 1

MODE	L [MM]	Q	FREQUENCY [GHZ]
( 0, 1, 1)	164.0	227.	8.071
( 0, 1, 2)	164.0	57.	8.224
( 0, 1, 3)	164.0	25.	8.474
( 0, 1, 4)	164.0	14.	8.813

PROGRAM ISTART4 (INPUT, OUTPUT, TAPES=INPUT, TAPE6=OUTPUT)  
 COMPUTATION OF THE STARTING CURRENT OF A CONVENTIONAL GYROTRON  
 OPERATING NEAR THE FUNDAMENTAL OF THE LARMOR FREQUENCY

PLOT ON VERSATEC (CYBER)

- MODE TE(M,P,G) (SIMPLE CAVITY)
- ANALYTICAL APPROXIMATION (LINEAR REGIME)
- MKSA UNITS
- DOCUMENTATION: INT 145/88

ANDRE PERRENOD CRPP/EPFL VERSION 1 09 JULY 1988

PARAMETERS

NMAX MAX NUMBER OF MODES (M,P)  
 NPOINT MAX NUMBER OF B FIELD POINTS  
 MMAX MAX AZYMUTHAL INDEX ( MMAX < 51 )  
 IPMAX MAX RADIAL INDEX  
 IGMAX MAX AXIAL INDEX

INPUT DATA

NCAS NUMBER OF (M,P) MODES TO BE CONSIDERED  
 MAXG TOTAL NUMBER OF CCOMPUTED URVES WILL BE NCAS\*MAXG  
 MM(1... NCAS) AZYMUTHAL INDEX  
 PP(1... NCAS) RADIAL INDEX  
 QQ(1... NCAS) QUALITY FACTOR OF MODE TE(M,P,1)  
 LL(1... NCAS) CAVITY LENGTH OF MODE TE(M,P,1)  
 A RADIUS OF RESONATOR (CYLINDRICAL CAVITY)  
 BMIN LOWEST VALUE OF B FIELD ( " " )  
 BMAX HIGHEST VALUE OF B FIELD ( " " )  
 IAMAX HIGHEST VALUE OF CURRENT ( " " )  
 VO BEAM VOLTAGE  
 ALPHA BEAM ANISOTROPY (VPERP/VPARA)  
 RE BEAM RADIUS

PARAMETER (NMAX=10, NPOINT=300, MMAX=5, IPMAX=5, IGMAX=5)  
 INTEGER P, PP  
 REAL IAMAX, IA, MUO, L, LL, LAMBDA, KRE, KPERP, KPARA,  
 \* KPU, NUMP, JMNUMP, JMPN  
 DIMENSION BO(NPOINT), IA(NPOINT), BJZP(MMAX+1, IPMAX), BJ(50)  
 CHARACTER DATE\*10, TIME\*10, DATE1\*10, TIME1\*10, LABEL\*80

COMMON /TITRE1/ LABEL(2)  
 COMMON /TITRE2/ DATE1, TIME1  
 COMMON /BEAM/ VO, ALPHA, RE, GAMMAO  
 COMMON /CAVITY/ A, M, P, IQ, ISIG, MAXG  
 COMMON /MODE/ NCAS, MM(NMAX), PP(NMAX), QQ(NMAX), LL(NMAX),  
 \* FREQ(NMAX, IGMAX)  
 COMMON /PAGE/ XA4, YA4, DXL, DXR, DYU, DYD, CH, XO, YO, AXEX, AXEY

NAMELIST /GYRO/ NCAS, MM, PP, QQ, LL, MAXG, BMIN, BMAX, IAMAX,  
 \* VO, ALPHA, RE, A

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60 C 1. CAS STANDARD (BENCHMARK)
61 DATA LABEL(1) / 'M I T 1 4 0 G H Z G Y R O T R O N' /
62 DATA LABEL(2) / '======' /
63 DATA NCAS/1/, MAXG/3/
64 DATA MM(1), PP(1), GG(1), LL(1)/0, 3, 1450., 0.0150/
65 DATA MM(2), PP(2), GG(2), LL(2)/2, 3, 1400., 0.0150/
66 DATA MM(3), PP(3), GG(3), LL(3)/5, 2, 1300., 0.0150/
67 DATA VO, ALPHA, RE, A/ 65000., 1.5, 1.82E-03, 3.47E-03/
68 DATA BMIN, BMAX, IMAX/ 5.2, 6.0, 7.0/
69
70 C
71 DO 10 NC= NCAS+1, NMAX
72 MM(NC)=0
73 PP(NC)=0
74 GG(NC)=0.
75 LL(NC)=0.
76
77 C
78 C 2. CONSTANTS
79
80 DATA CLIGHT/2.99792458E+08/
81 DATA EMASS,ECHARG/9.1093897E-31, 1.60217733E-19/
82 PI = ACOS(-1.)
83 MUO = 4.E-07*PI
84 EPSO = 1./ (MUO*CLIGHT**2)
85
86 DATE1=DATE()
87 TIME1=TIME()
88 WRITE(6,100) DATE1, TIME1
89 FORMAT('1///', 'PROGRAM ISTART4',4X,2A10/
90 * '======'//)
91
92 C
93 WRITE (6,105)
94 FORMAT ('ZEROS OF DERIVATIVES OF BESSEL FUNCTIONS')
95 CALL BEPZERO(BJZP,MMAX,IPMAX)
96
97 C
98 C 3. READ INPUT DATA
99
100 REWIND (5)
101 READ (5,'(A)') LABEL
102 WRITE (6,'(/1X,A/1X,A/)') LABEL
103 READ (5,GYRO)
104 WRITE (6,GYRO)
105
106 GAMMAO = 1. + (ECHARG*VO)/(EMASS*CLIGHT**2)
107 BPARA = SQRT ((1.-1./GAMMAO**2)/(1.+ALPHA**2))
108 BPERP = ALPHA * BPARA
109 WRITE (6,110) 'GAMMAO =', GAMMAO
110 FORMAT (1X,A,G14.6)
111 WRITE (6,110) 'BETA PERP =', BPERP
112 WRITE (6,110) 'BETA PARA =', BPARA
113
114 CF = EPSO*EMASS/ECHARG
115 WRITE (6,110) 'CONST =', CF
116
117 C
118 C 4. CALCULS
119
120 IF (MAXQ.GT. IQMAX) STOP 'AXIAL INDEX Q TOO LARGE'
IFIRST = 1

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C
SUBROUTINE CFCQ(X, IQ, PI, FC, DFC)
    PIQ2 = 0.5*PI*IQ
    UNPX = 1. +X
    UNMX = 1. -X
    IF (ABS(UNPX).LT.0.001) THEN
        F = 0.5*PIQ2
        DF = 0.5*F
    ELSE IF (ABS(UNMX).LT.0.001) THEN
        F = 0.5*PIQ2
        DF = -0.5*F
    ELSE
        UNMX2 = UNPX*UNMX
        F = SIN(PIQ2*UNPX) / UNMX2
        DF = (PIQ2*COS(PIQ2*UNPX) + 2. *X*F) / UNMX2
    ENDIF
    FC = 2. *F*F
    DFC = 4. *F*DF
END
C
    
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1 SUBROUTINE BEPZERO(BJZP, M, N)
2
3 C COMPUTES THE ZEROES OF THE DERIVATIVES OF BESSEL FUNCTION
4 C OF INTEGER ORDER (M=0, 1, 2, . . . 5)
5 C
6 C ON RETURN: BJZP(K+1, L) = LTH ZERO OF J'K(X) (L = 1, 2 3. . . N)
7 C
8 C PARAMETER (EPS=1.E-12, MMAX=5, IPMAX=5)
9 C
10 C DIMENSION BJZP(MMAX+1, IPMAX), BJ(50)
11 C
12 C PI =ACOS(-1.)
13 C IF (M.GE.0 .AND. M.LE.MMAX) GOTO 5
14 C WRITE (6,1) M
15 C FORMAT (' SUBROUTINE BEPZERO CALLED WITH M=', I3)
16 C STOP
17 C IF (N.GE.1 .AND. N.LE.IPMAX) GOTO 10
18 C WRITE (6,2) N
19 C FORMAT (' SUBROUTINE BEPZERO CALLED WITH N=', I3)
20 C STOP
21 C
22 C FIND ROOTS USING NEWTON ALGORITHM FOR J'M(X)=0
23 C
24 C DO 30 IM=0, M
25 C DO 30 IN=1, -1
26 C
27 C IF (IN.GE.N-1) THEN
28 C
29 C     X0 = PI/4. * (2*IM + 4*IN -3)
30 C     IF (IM.EQ.0) X0 = X0 + PI
31 C     ELSE
32 C     X0 = 2*BJZP(IM+1, IN+1) - BJZP(IM+1, IN+2)
33 C     ENDIF
34 C     ITER=0
35 C
36 C     NEWTON SCHEME: X1 = X0 - JM'(X0)/JM''(X0)
37 C
38 C CALL BESSEL(IM+2, X0, BJ)
39 C BJM = BJ(IM+1)
40 C BJMP = -BJ(IM+2) + IM/X0*BJM
41 C BJMP1P = -BJ(IM+3) + (IM+1)/X0*BJ(IM+2)
42 C BJM2P = -BJMP1P + IM/X0*(BJMP - BJM/X0)
43 C X1 = X0 - BJMP/BJM2P
44 C ITER = ITER + 1
45 C IF (ABS(X1-X0) .LT. EPS) GOTO 20
46 C X0=X1
47 C IF (ITER.LT.50) GOTO 15
48 C WRITE (6,16) IM, IN
49 C FORMAT (' NO CONVERGENCE REACHED FOR M=', I3, ' N=', I3)
50 C X1=0.
51 C BJZP(IM+1, IN)=X1
52 C WRITE (6,17) IM, IN, X1, ITER
53 C FORMAT (' J'(', I3, ', ', I3, ') = ', F12.8, ' ITER=', I3)
54 C CONTINUE
55 C END

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```

1 SUBROUTINE BESSEL(LMAX, X, BJ)
2
3 C
4 CALCULATE BESSEL FUNCTIONS BY BACKWARD RECURSION
5
6 C
7 ON RETURN: BJ(1)=JO(X), BJ(2)=J1(X), ... BJ(LMAX+1)=BJLMAX(X)
8
9 C
10 PARAMETER (XMIN=.00001, XMAX=100., MSTART=200, DEL=1.E-60)
11 DIMENSION TEMP(MSTART), BJ(*)
12
13 C
14 IF ( LMAX .GT. 50 ) STOP 'BESSEL: ORDER TOO BIG'
15 IF (ABS(X).GT.XMAX) STOP 'BESSEL: ARGUMENT TOO BIG'
16 IF (ABS(X).GT.XMIN) GOTO 20
17 BJ(1)=1.
18 IF (LMAX.EQ.0) RETURN
19 DO 10 L=1, LMAX
20 BJ(L+1)=X/FLOAT(2*L)*BJ(L)
21 RETURN
22
23 C
24 LSTART=2*(5*INT(ABS(X))+(LMAX+1)/2+10)+1
25 ORDER OF HIGHEST BESSEL FUNCTION IS EVEN TO GUARANTEE CORRECT
26 C..... PARITY (JN(X) = (-1)**N *JN(-X) )
27 IF (LSTART.GT.MSTART) LSTART=MSTART
28 TEMP(LSTART)=DEL
29 TEMP(LSTART-1)=DEL*FLOAT(2*(LSTART-2))/X
30 DO 30 L=LSTART-1, 2, -1
31 TS=TEMP(LSTART)**2
32 TEMP(L-1)=FLOAT(2*(L-1))/X*TEMP(L)-TEMP(L+1)
33 TS=1./SQRT(TEMP(L)**2)
34 DO 40 L=1, LMAX+1
35 BJ(L)=TS*TEMP(L)
36 RETURN
37 END

```

```

1  SUBROUTINE PLOTST(BO,IA,J, BMIN,BMAX,IAMAX,IFIRST)
2
3  COMMON /PAGE/  XA4,YA4,DXL,DXR,DYU,DYD, CH, XO,YO,AXEX,AXEY
4
5  REAL BO(*), IA(*), IAMAX, IAKM1
6  INTEGER P
7  CHARACTER T*20
8
9  COMMON /CAVITY/ A, M, P, IQ, ISIG, MAXQ
10
11  DATA XA4,YA4/29.,21./, DXL,DXR,DYU,DYD/3.,2.,2.5,3./, CH/O.2/
12  DATA XO,YO,AXEX,AXEY/3.,2.5,16.,14./
13
14  IF (IFIRST.EQ.O) GOTO 25
15  CALL PLOTS ('VERSATEC',100.,8224,0,1)
16
17  CALL FRAME(BMIN,BMAX,O.,IAMAX, XO,YO,AXEX,AXEY)
18  CALL CHPEN(3)
19  IFIRST=O
20
21  CONTINUE
22  IPEN=3
23  IPL = 0
24  DO 30 K=1,J
25  CURR=IA(K)
26  IF (CURR.LT.O. .OR. CURR.GT. IAMAX) THEN
27  IPEN=3
28  IPL =0
29  IAKM1=IAMAX+1.
30  ELSE
31  XX = XO + (BO(K)-BMIN)/(BMAX-BMIN) * AXEX
32  YY = YO + CURR/IAMAX * AXEY
33  CALL PLOT(XX,YY,IPEN)
34  DIA = CURR-IAKM1
35  IAKM1=CURR
36  IF (DIA.GT.O. .AND. IPL.EQ.O .AND. IPEN.EQ.2) THEN
37  WRITE MODE #
38  XYP = XX - 1.2
39  YYP = YY - 0.5
40  IF (YYP.LT.(YO+0.5)) YYP = YYP + 1.
41  WRITE (T,50) ISIG*M, P, IQ
42  FORMAT( ',I2,',',I2,',',I2,',',I2,',')
43  CALL SYMBOL(XXP,YYP,O.2,T,O.,10)
44  IPL = 1
45  CALL PLOT(XX,YY,3)
46  ENDIF
47  IPEN=2
48  ENDIF
49  CONTINUE
50  END

```

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1 SUBROUTINE FRAME(BMIN,BMAX,ISMIN,ISMAX)
2 COMMON /PAGE/ XA4, YA4, DXL, DXR, DYU, DYD, CH, XO, YO, AXEX, AXEY
3
4 REAL ISMIN, ISMAX
5
6 DATA MASK/0"5252525252525252525252"/
7
8 CH = CHARACTER HEIGHT
9
10 A4 FRAME
11 CALL CHPEN(2)
12 CALL PLOT(O, 1, 3)
13 CALL PLOT(O, 0, 2)
14 CALL PLOT(1, 0, 2)
15 CALL PLOT(XA4-1, 0, 3)
16 CALL PLOT(XA4, 0, 2)
17 CALL PLOT(XA4, 1, 2)
18 CALL PLOT(XA4-1, YA4, 3)
19 CALL PLOT(XA4, YA4, 2)
20 CALL PLOT(XA4, YA4-1, 2)
21 CALL PLOT(O, YA4-1, 3)
22 CALL PLOT(O, YA4, 2)
23 CALL PLOT(1, YA4, 2)
24
25 AXES AND GRID
26
27 DB=(BMAX-BMIN)/AXEX
28 CALL AXIS(XO, YO, AXEX, O, BMIN, DB, 'MAGNETIC FIELD (TESLA)', 22)
29
30 DIS=(ISMAX-ISMIN)/AXEY
31 CALL AXIS(XO, YO, AXEY, 90, ISMIN, DIS, 'STARTING CURRENT (A)', -20)
32 CALL CHPEN(3)
33 CALL PLOT(XO, YO, 3)
34 CALL PLOT(XO, YO+AXEY, 2)
35 CALL PLOT(XO+AXEX, YO+AXEY, 2)
36 CALL PLOT(XO+AXEX, YO, 2)
37 CALL PLOT(XO, YO, 2)
38 CALL CHPEN(1)
39 IAXEX=AXEX
40 IAXEY=AXEY
41 CALL GRID(XO, YO, IAXEX, 1, IAXEY, 1, MASK)
42 CALL CHPEN(2)
43 RETURN
44 END
45

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1  SUBROUTINE TITLE
2
3  C
4  PARAMETER (NMAX=10, IQMAX=5)
5  COMMON /PAGE/ XA4, YA4, DXL, DXR, DYU, DYD, CH, XO, YO, AXEX, AXEY
6  COMMON /TITRE1/ LABEL(2)
7  COMMON /TITRE2/ DATE1, TIME1
8  COMMON /BEAM/ VO, ALPHA, RE, GAMMAO
9  COMMON /CAVITY/ A, M, P, IQ, ISIG, MAXG
10 COMMON /MODE/ NCAS, MM(NMAX), PP(NMAX), QQ(NMAX), LL(NMAX),
11 * FREQ(NMAX, IQMAX)
12
13 C
14 INTEGER P, PP
15 REAL LL
16 CHARACTER T*80, DATE1*10, TIME1*10, LABEL*80
17 YTOP=YA4-DYU
18 CALL CHPEN(2)
19 CALL SYMBOL(DXL, YTOP, CH, LABEL(1), O., 80)
20 CALL SYMBOL(DXL, YTOP-2., *CH, CH, LABEL(2), O., 80)
21 WRITE(T, 100)
22 FORMAT('STARTING CURRENT VERSUS STATIC MAGNETIC FIELD', 5X,
23 * 'PROGRAM ISTART4')
24 CALL SYMBOL(DXL, YTOP-5., *CH, CH, T, O., 66)
25
26 C
27 WRITE(T, 1) DATE1, TIME1
28 FORMAT('CRPP - ', 2A10)
29 CALL SYMBOL(O.8*XA4, YTOP, O.8*CH, T, O., 27)
30 WRITE(T, 2)
31 FORMAT('GYROTRON PROJECT')
32 CALL SYMBOL(O.8*XA4, YTOP-2., *CH, O.8*CH, T, O., 16)
33
34 XT=XO+AXEX+1.
35 YT=YO+AXEY
36 WRITE(T, 3) A*1000.
37 FORMAT('RESONATOR RADIUS: ', F7.2, ' MM')
38 CALL SYMBOL(XT, YT, CH, T, O., 27)
39 YT=YT-2.*CH
40 WRITE(T, 7) GAMMAO
41 FORMAT('GAMMAO: ', F7.4)
42 CALL SYMBOL(XT, YT, CH, T, O., 14)
43 YT=YT-2.*CH
44 WRITE(T, 8) ALPHA
45 FORMAT('ALPHA: ', F7.4)
46 CALL SYMBOL(XT, YT, CH, T, O., 14)
47 YT=YT-2.*CH
48 WRITE(T, 9) VO/1000.
49 FORMAT('BEAM VOLTAGE: ', F6.2, ' KV')
50 CALL SYMBOL(XT, YT, CH, T, O., 22)
51 YT=YT-2.*CH
52 WRITE(T, 10) RE*1000.
53 FORMAT('ANNULAR BEAM RADIUS: ', F6.2, ' MM')
54 CALL SYMBOL(XT, YT, CH, T, O., 29)
55 YT=YT-2.*CH
56 WRITE(T, 11) 1
57 FORMAT('HARMONIC # : ', I2)
58 CALL SYMBOL(XT, YT, CH, T, O., 14)
59
60 C
61 YT=YT-3.*CH
62 T=' MODE
63 CALL SYMBOL(XT, YT, CH, T, O., 35)
64
65 C
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60 YT=YT-2.*CH
61 T=TE
62 CALL SYMBOL(XT, YT, CH, T, O., 35)
63 DO 20 NC=1, NCAS
64 DO 20 IGG=1, MAXG
65 YT=YT-2.*CH
66 WRITE (T, 21) MM(NC), PP(NC), IGG, LL(NC)*1000., GG(NC)/IGG**2,
67 * FORMAT(' ', I2, ', ', I2, ', ', I2, ', ', I2, ', ', F7.1, F7.0, F9.3)
68 CALL SYMBOL(XT, YT, CH, T, O., 34)
69
70 RETURN
71 END
72

```

21  
20  
C