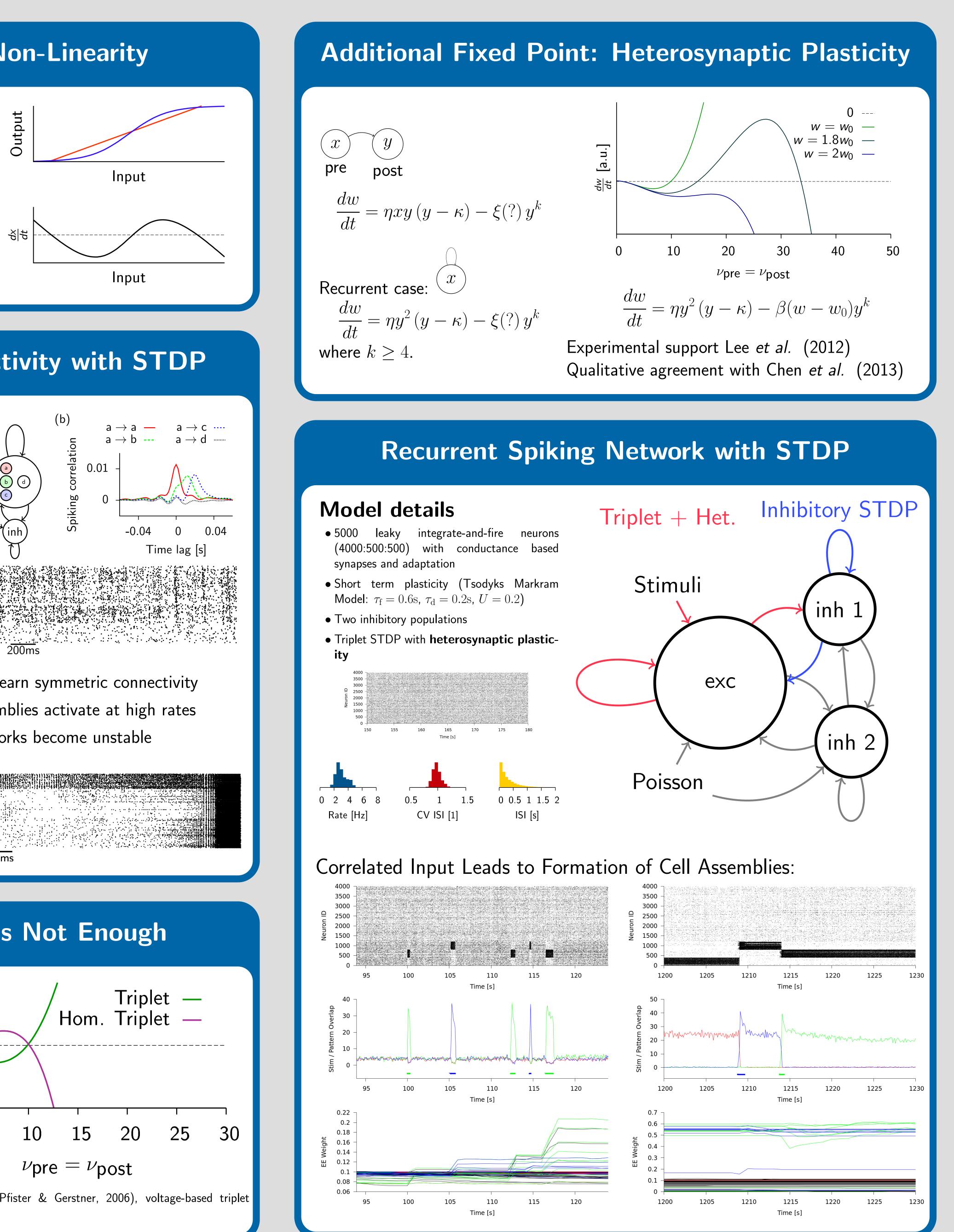


imulated using the uryn simulator github.com/fzenke/auryn

Multi-Stability Needs Non-Linearity

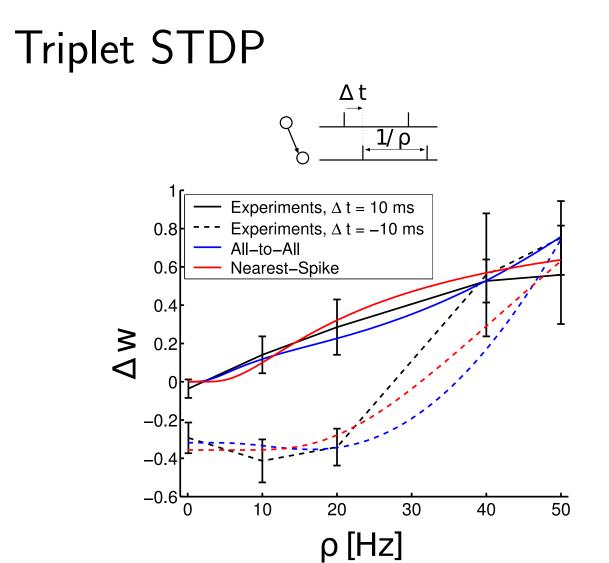
Ingredients

- Excitatory recurrent feed-back (Hopfield, 1982) (x)
- Non-linearity (e.g. inhibitory feedback (Amit & Brunel, 1997) and STP (Mongillo *et al.*, 2012))



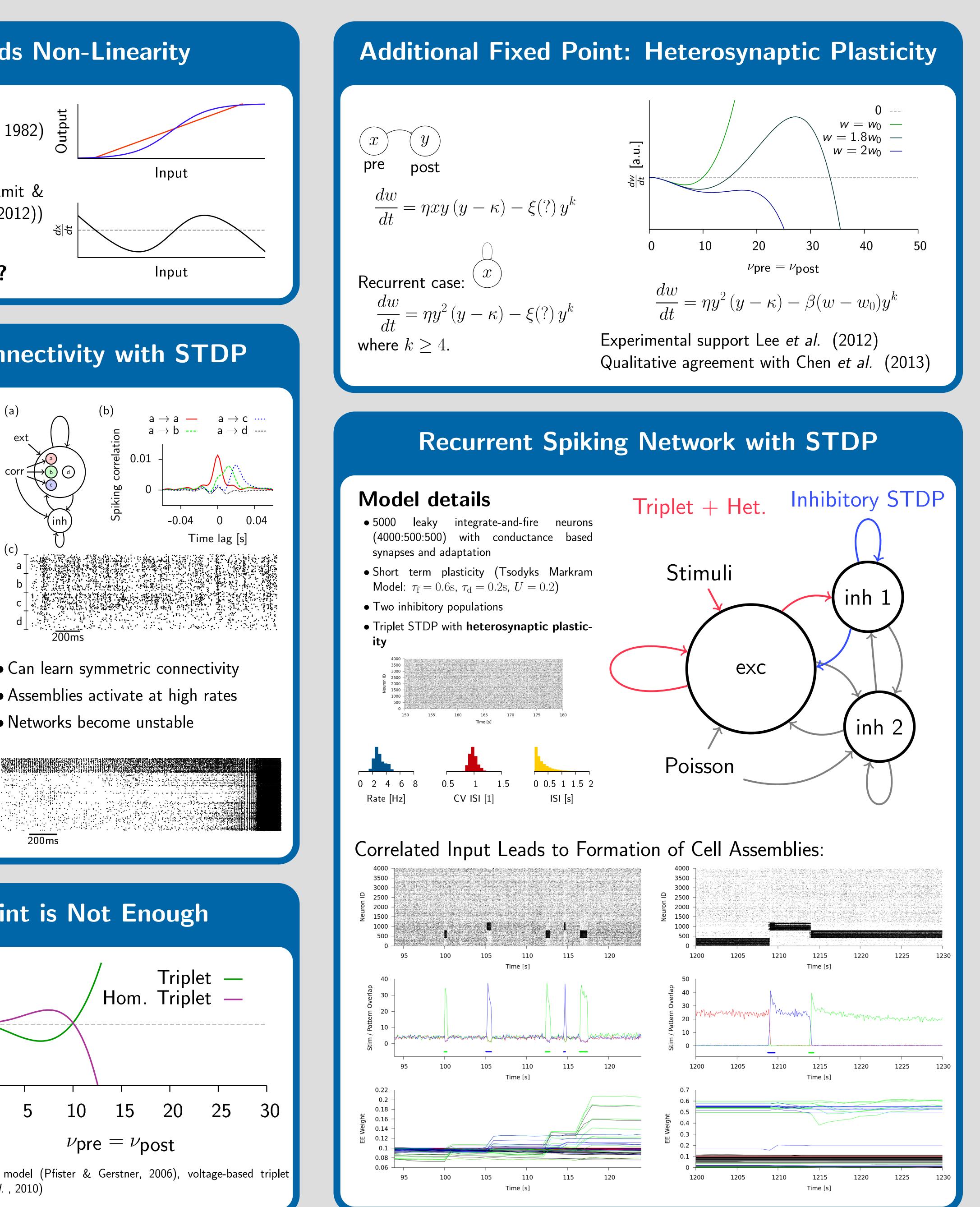
Question: How is the connectivity learned?

Learning Symmetric Connectivity with STDP

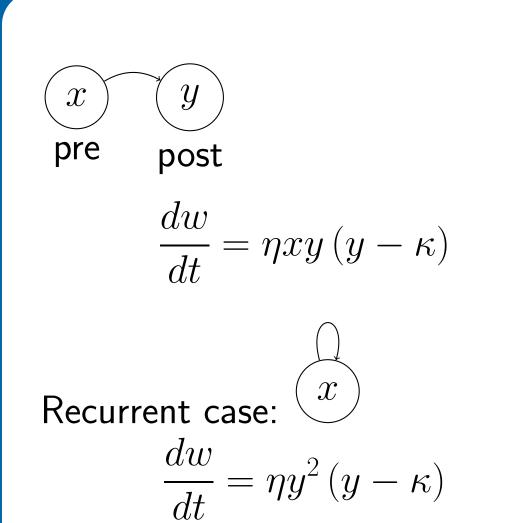


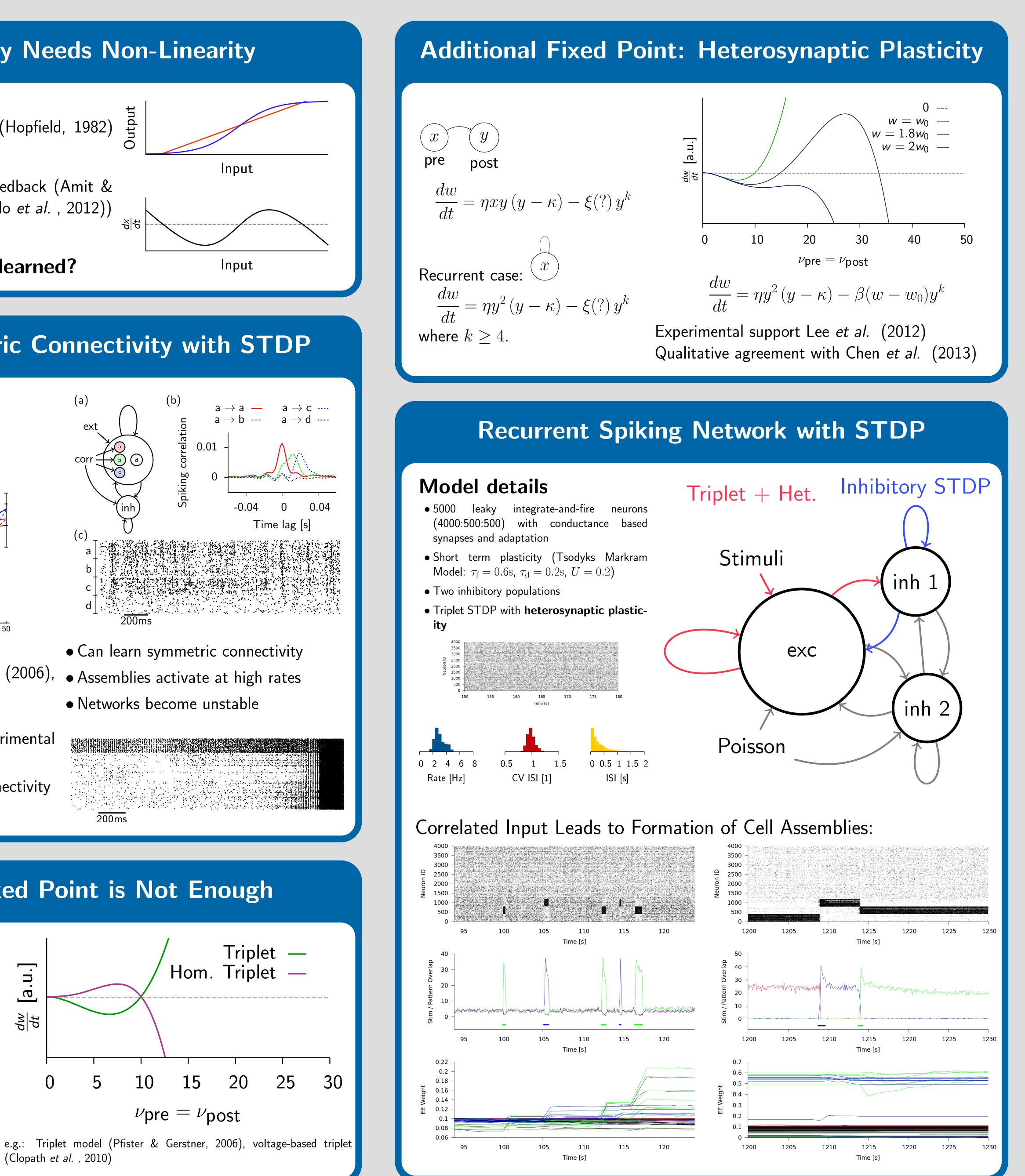
Adapted from Pfister & Gerstner (2006) Data from Sjöström *et al.* (2001)

- Triplet Models describe experimental data
- Can account for symmetric connectivity



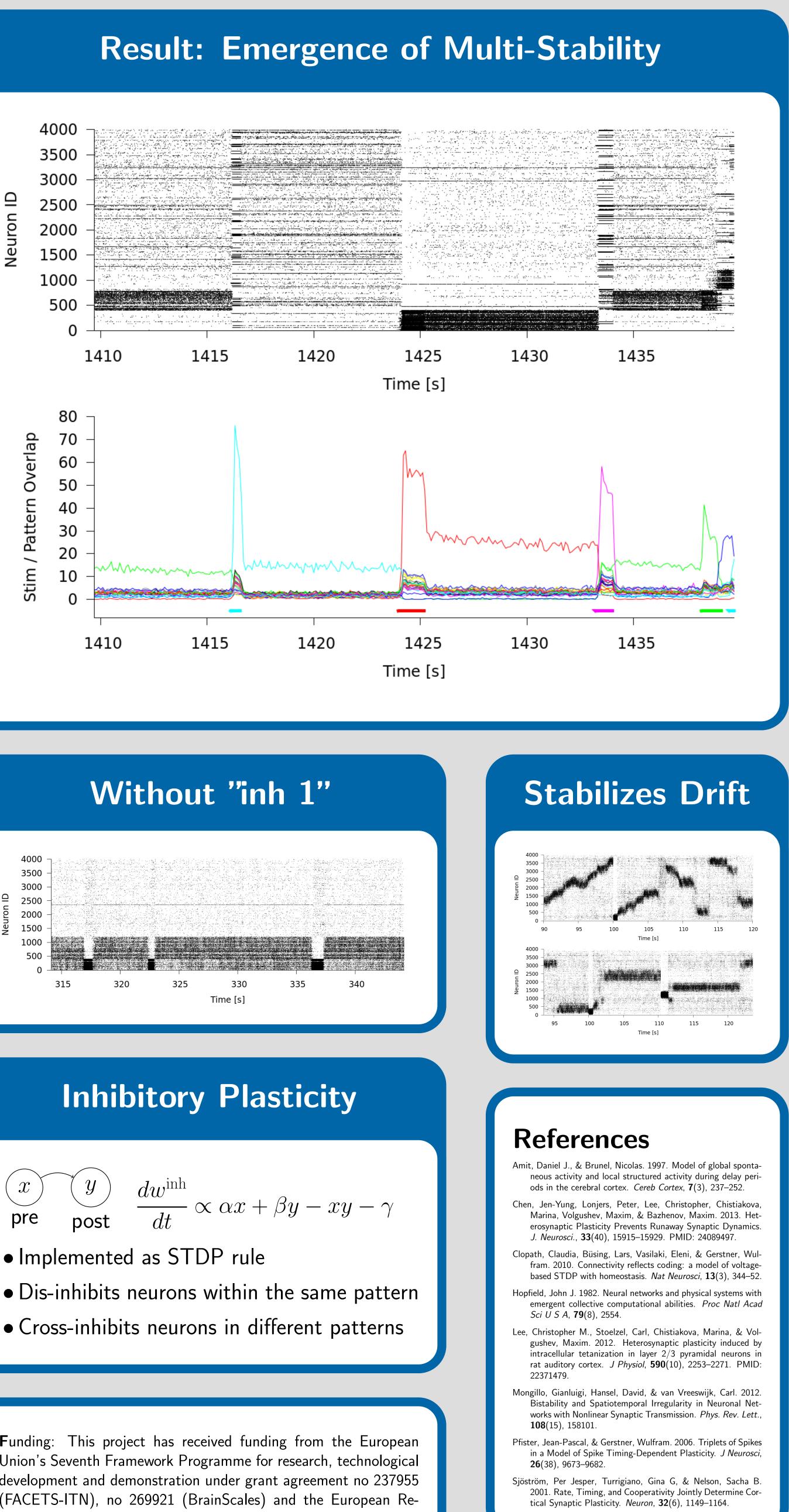
One Stable Fixed Point is Not Enough

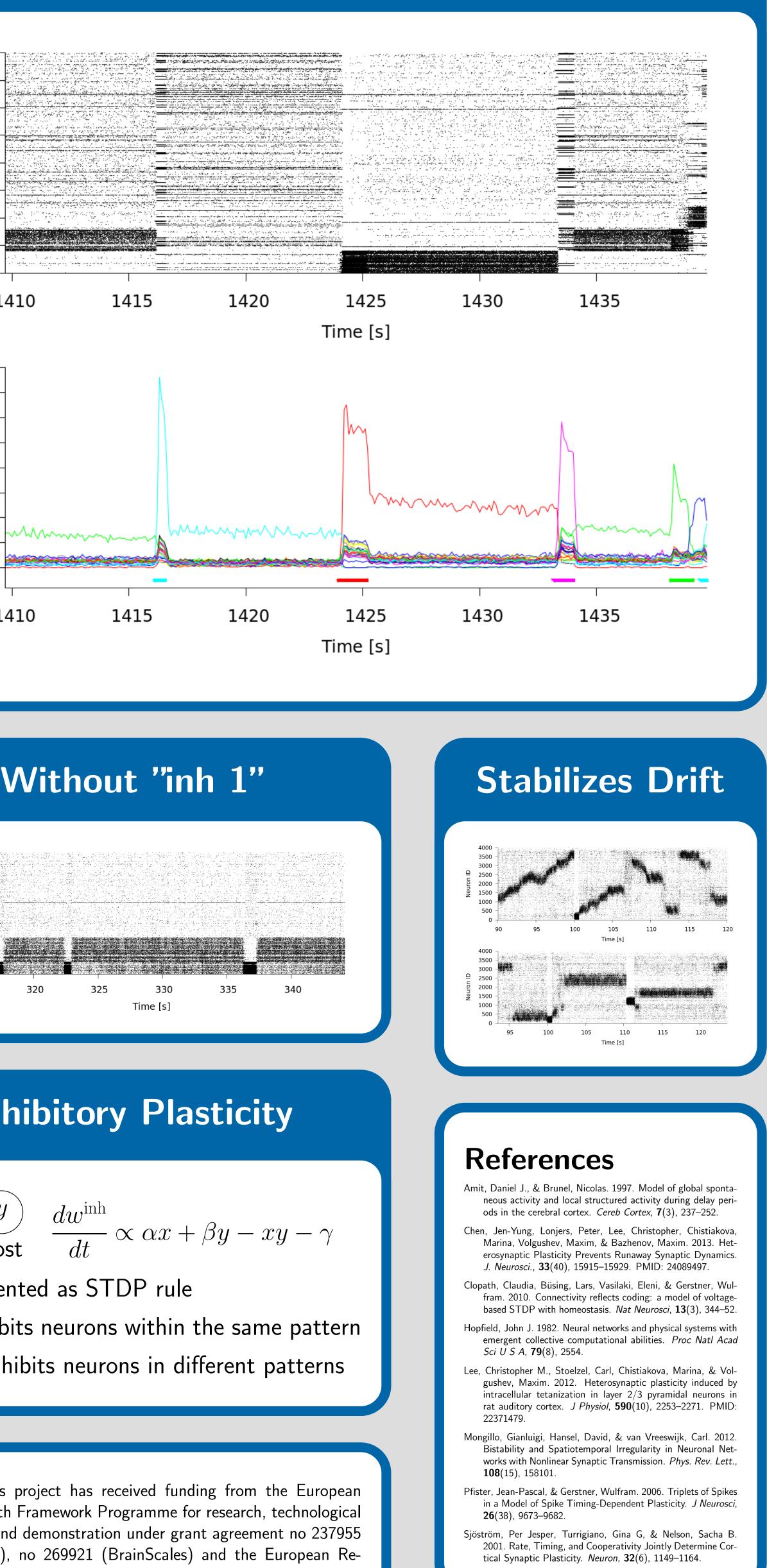


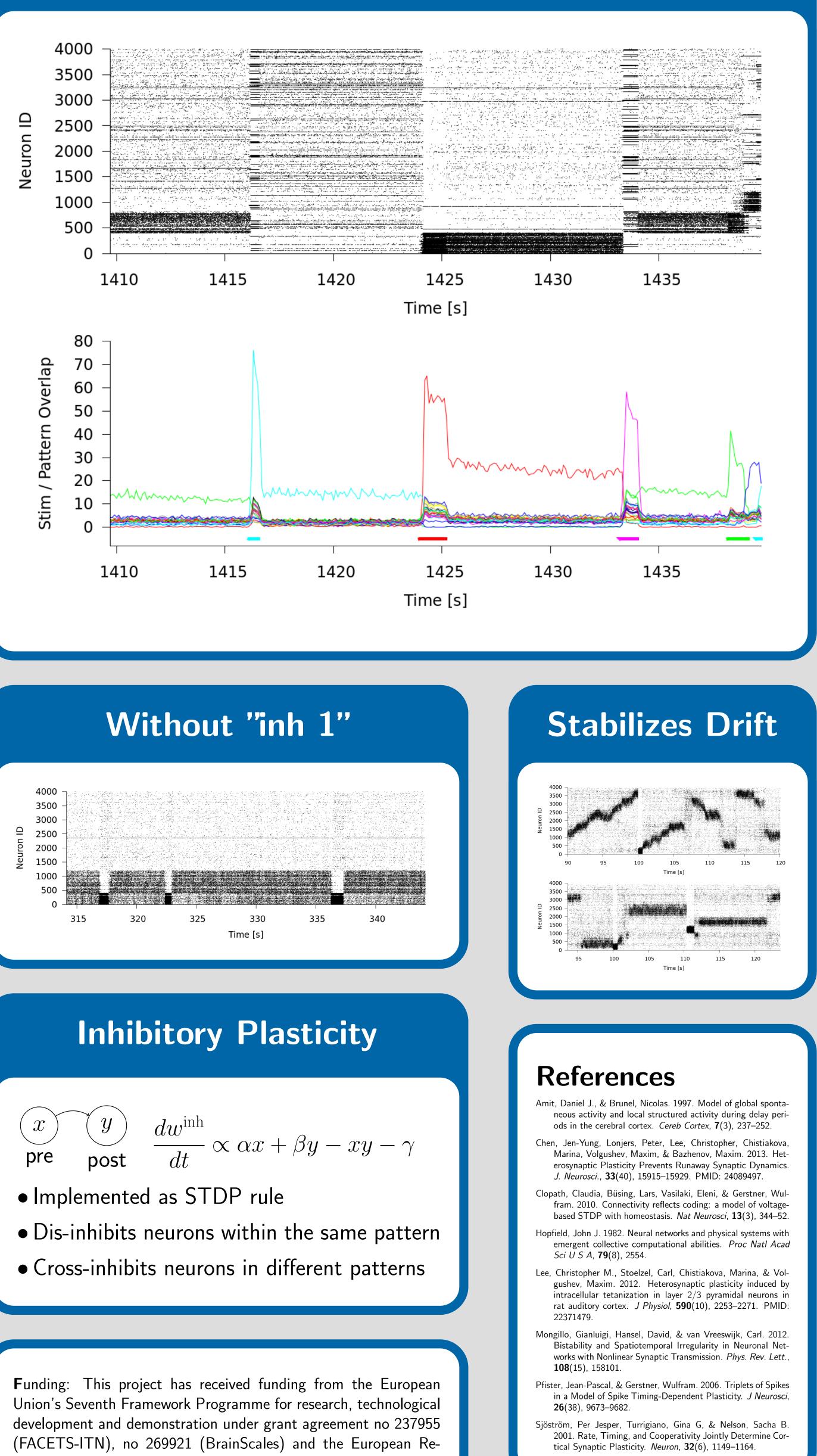


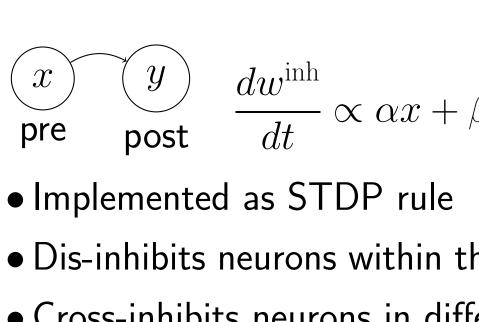
(Clopath *et al.* , 2010)

Learning Multi-Stability in Plastic Neural Networks F. Zenke, E. J. Agnes, W. Gerstner









search Council under grant agreement no. 268689 (MultiRules).

