Real-Time Disruption Recovery in Berth Allocation Problem

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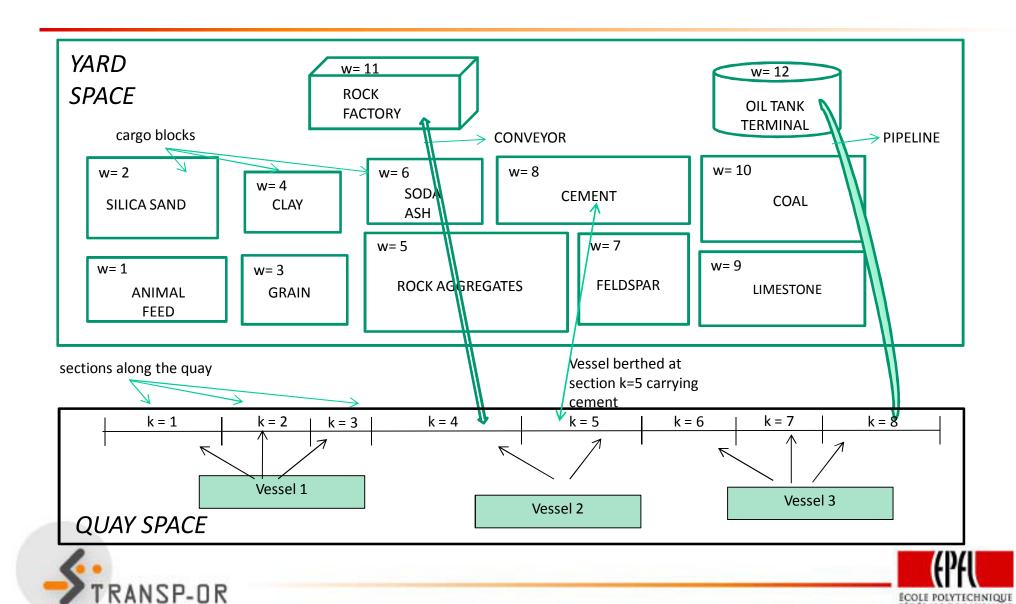
Motivation

- International shipping tonnage in solid bulk and liquid bulk trade has registered an increase by 52% and 48% respectively. The total volume of dry bulk cargoes loaded in 2008 stood at 5.4 billion tons, accounting for 66.3 per cent of total world goods loaded (UNCTAD, 2009)
- > Bulk port terminals have received significantly less attention than container terminals in the field of large scale optimization
- High level of uncertainty in bulk port operations due to weather conditions, mechanical problems etc.
 - > Disrupt the normal functioning of the port
 - > Require quick real time action.
- Very few studies address the problem of real time recovery in port operations, while the problem has not been studied at all in context of bulk ports.
- Our research problem derives from the realistic requirements at the SAQR port, Ras Al Khaimah, UAE





Schematic Diagram of a Bulk Terminal



Research Objectives

- Study the crucial problems of
 - Berth Allocation : scheduling and assignment of vessels to sections along the quay
 - Yard Assignment: assignment of vessels and cargo types to specific locations on the yard
- Large Scale Integrated Planning: Integration of the berth allocation and yard assignment for better coordination between berthing and yard activities
- Develop **real time** and **robust optimization algorithms** to account for uncertainties in arrival times and handling times of vessels, and other unforeseen disruptions and delays in operations.
- The focus of this talk is solving the berth allocation problem in real time for a given baseline schedule.





Research Objectives

- Develop real time algorithms for disruption recovery in berth allocation problem (BAP)
- For a given baseline berthing schedule, minimize the total realized costs of the updated schedule as actual arrival data is revealed. The total realized costs include
 - The total service cost of all vessels berthing at the port which is the sum total of the handling times and berthing delays of all vessels berthing in the planning horizon.
 - Inconsistent cost of rescheduling over space and time to account for the cost of re-allocating human labor, handling equipment and availability of cargo.





Literature Review

- Very scarce studies on real time and robust algorithms in container terminals . To the best of our knowledge, no literature on bulk ports.
- Comprehensive literature surveys on BAP in container terminals can be found in Steenken et al. (2004), Stahlobock and Voss (2007), Bierwirth and Meisel (2010).
- OR literature related to BAP under uncertainty in container terminals

Pro-active Robustness

- Stochastic programming approach used by Zhen et al. (2011), Han et al. (2010)
- Define surrogate problems to define the stochastic nature of the problem: Moorthy and Teo (2006), Zhen and Chang (2012), Xu et al. (2012) and Hendriks et al. (2010)
- Reactive approach or disruption management
 - Zeng et al.(2012) and Du et al. (2010) propose reactive strategies to minimize the impact of disruptions.

Baseline Schedule

 Any feasible berthing assignment and schedule of vessels along the quay respecting the spatial and temporal constraints on the individual vessels

 Best case: Optimal solution of the deterministic berth allocation problem (without accounting for any uncertainty in arrival information)





Deterministic BAP: Problem Definition

Find

Optimal assignment and schedule of vessels along the quay (without accounting for any uncertainty in arrival information)

Given

- Expected arrival times of vessels
- Handling times dependent on
 - Cargo type on the vessel (the relative location of the vessel along the quay with respect to the cargo location on the yard)
 - Number of cranes operating on the vessel

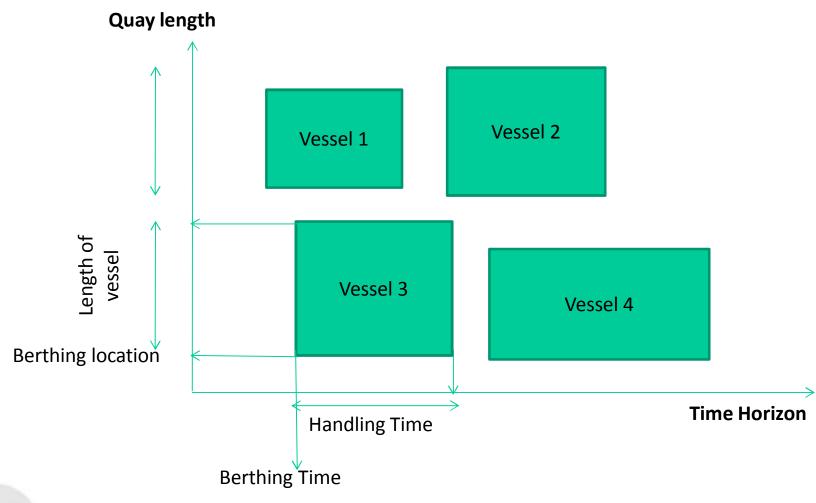
. Objective

 Minimize total service times (waiting time + handling time) of vessels berthing at the port





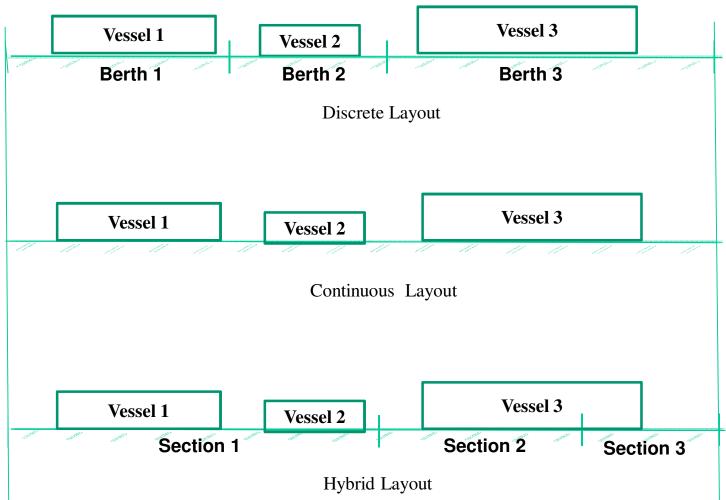
BAP Solution







Discretization







Objective Function

$$\min \sum_{i \in N} (m_i - A_i + C_i)$$

Decision variables:

 m_i starting time of handling of vessel $i \in N$;

 c_i total handling time of vessel $i \in N$;





Dynamic vessel arrival constraints

$$m_i - A_i \ge 0$$

$$\forall i \in N$$
,

Non overlapping constraints

$$\sum_{k \in M} (b_k s_k^j) + B(1 - y_{ij}) \ge \sum_{k \in M} (b_k s_k^i) + L_i$$

$$\forall i, j \in N, i \neq j,$$

$$m_j + B(1 - z_{ij}) \ge m_i + c_i$$

$$\forall i, j \in N, i \neq j$$

$$y_{ij} + y_{ji} + z_{ij} + z_{ji} \ge 1$$

$$\forall i, j \in N, i \neq j$$





Section covering constraints

$$\begin{split} \sum_{k \in M} s_k^i &= 1 & \forall i \in N, \\ \sum_{k \in M} (b_k s_i^k) + L_i &\leq L & \forall i \in N, \\ \sum_{k \in M} (d_{ilk} s_l^i) &= x_{ik} \ \forall i \in N, \forall k \in M, \end{split}$$

Draft Restrictions

$$(d_k - D_i)x_{ik} \ge 0 \qquad \forall i \in N, \forall k \in M,$$





Determination of Handling Times

- Given an input vector of unit handling times for each combination of cargo type and section along the quay
- Specialized facilities (conveyors, pipelines etc.) also modeled as cargo types
- All sections occupied by the vessel are operated simultaneously

$$c_i \ge h_k^w p_{ilk} Q_i s_l^i$$
 $\forall i \in N, \forall k \in M, \forall l \in M, \forall w \in W_i$

- Q_i quantity of cargo to be loaded on or discharged from vessel i
- h_k^w handling time for unit quantity of cargo $w \in W$ and vessel berthed at section $k \in M$;
- $p_{i|k}$ fraction of cargo handled at section $k \in M$ when vessel i is berthed at starting section $l \in M$





GSPP Model

- Used in context of container terminals by Christensen and Holst (2008)
- Generate set P of columns, where each column $p \in P$ represents a feasible assignment of a single vessel in both space and time
- Generate two matrices
 - Matrix A = (A_{ip}) ; equal to 1 if vessel $i \in N$ is the assigned vessel in the feasible assignment represented by column $p \in P$
 - Matrix B = (b_p^{st}) ; equal to 1 if section $s \in M$ is occupied at time $t \in H$ in column $p \in P$







GSPP Formulation: A simple example



- |N| = 2, |M| = 3, |H| = 3
- Vessel 1 cannot occupy section 3 owing to spatial constraints (does not have conveyor facility), vessel 2 arrives at time t = 1
- Constraint matrix P has 4 feasible assignments:

Vessel 1	1	1	0	0
Vessel 2	0	0	1	1
Section 1, Time 1	1	0	0	0
Section 1, Time 2	1	1	1	0
Section 1, Time 3	0	1	1	0
Section 2, Time 1	1	0	0	0
Section 2, Time 2	1	1	1	1
Section 2, Time 3	0	1	1	1
Section 3, Time 1	0	0	0	0
Section 3, Time 2	0	0	0	1
Section 3, Time 3	0	0	0	1





GSPP Model Formulation

Objective Function:

$$\min \sum_{p \in P} (d_p \lambda_p + h_p \lambda_p)$$

Constraints:

$$\sum_{p \in P} (A_{ip} \lambda_p) = 1 \qquad \forall i \in N$$

$$\sum_{p \in P} (b_p^{st} \lambda_p) \leq 1 \qquad \forall s \in M, \forall t \in H$$

 d_p : delay in service associated with assignment $p \in P$

 h_n : handling time associated with assignment $p \in P$

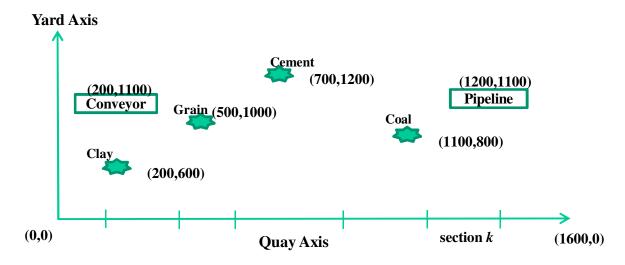
 λ_p : binary parameter, equal to 1 if assignment $p \in P$ is part of the optimal solution





Generation of Instances

- Instances based on data from SAQR port with quay length of 1600 meters and vessel lengths in the range 80-260 meters.
- Generate 6 instances sizes with |N| = 10, 25 and 40 vessels, and |M| = 10 and 30 sections, with 9 instances for each instance size.
- Handling times generated for 6 cargo types.



• Drafts of all vessels D_i are less than the minimum draft along the quay.





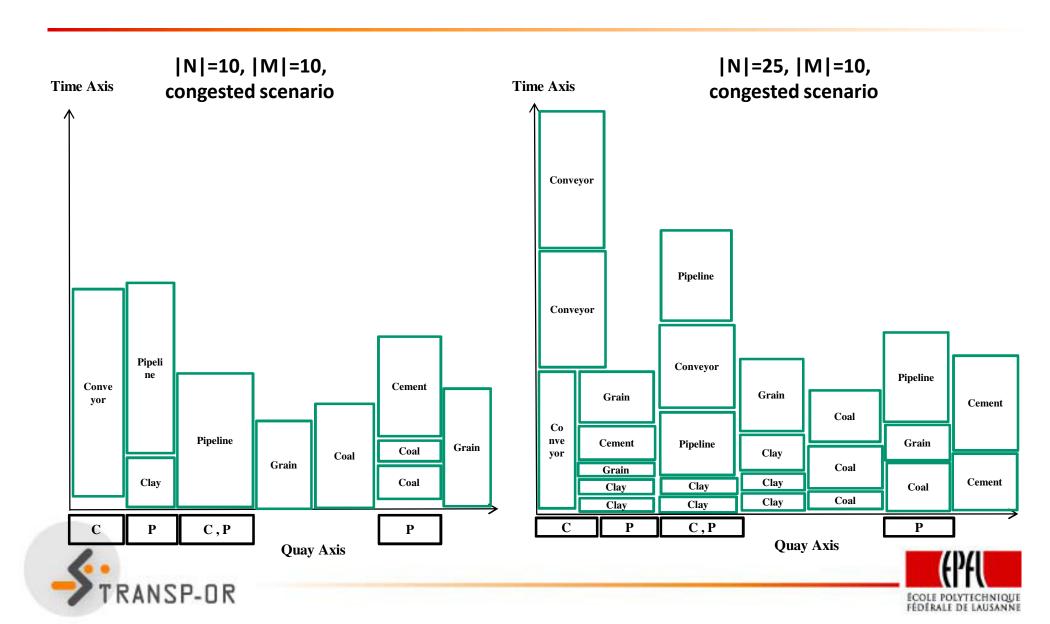
Computational Results

- Instances based on data from SAQR port
- All tests were run on an Intel Core i7 (2.80 GHz) processor and used a 32-bit version of CPLEX 12.2.
- Results inspired by port data show that the problem is complex!
- MILP formulation fails to produce optimal results for even small instances with |N| = 10 vessels within CPLEX time limit of 2 hours.
- The performance of the GSPP model is quite remarkable!
 - Can solve instances up to |N| = 40 vessels
 - Limitations: For larger instances, or longer horizon H solver runs out of memory (use dynamic column generation!)
- Alternate heuristic approach based on squeaky wheel optimization (SWO) performs reasonably well for not so large instances. Optimality gap is less than 10% (with respect to exact solution obtained from GSPP approach) averaged over all tested instances.





Results Analysis



Real Time Recovery in Berth Allocation Problem





 Objective: For a given baseline berthing schedule, minimize the total realized costs including the total actual service costs and total cost of rescheduling in space and time

$$\min Z = \sum_{i \in N_u} (m_i - A_i + h_i) + \sum_{i \in N_u} (c_1 | b_i(k') - b_i(k) | + c_2 \mu_i | e'_i - e_i |)$$

 N_{ij} : set of unassigned vessels

c₁: cost coefficient of shifting berthing location

 $b_i(k')$: actual berthing location of vessel i

 $b_i(k)$: estimated berthing location of vessel i

 c_2 : cost coefficient of departure delay

 μ_i : service priority assigned to vessel i

e;': actual departure time of vessel i

e; estimated departure time of vessel i





- Solving the BAP as arrival delay information is released in real time
 - For each vessel $i \in N$, we are given an expected arrival time A_i which is known in advance.
 - The expected arrival time of a given vessel may be updated |P| times during the planning horizon of length |H| at time instants t_{i1} , t_{i2} ... t_{iP} such that

$$0 \le t_{i1} < t_{i2} < t_{i3} \dots t_{i(P-1)} < t_{iP} < a_i$$

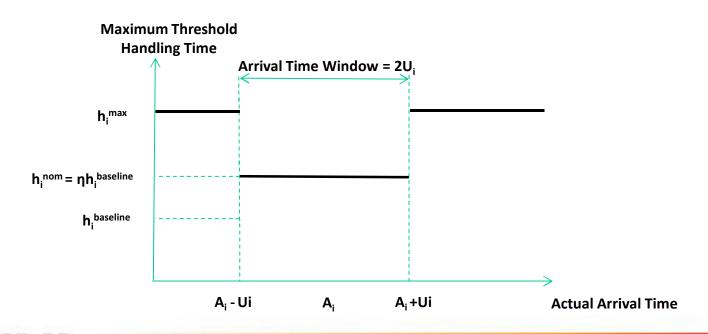
where a_i is the actual arrival time of the vessel, and the corresponding arrival time update at time instant t_{ip} is A_{ip} for all $i \in N$.





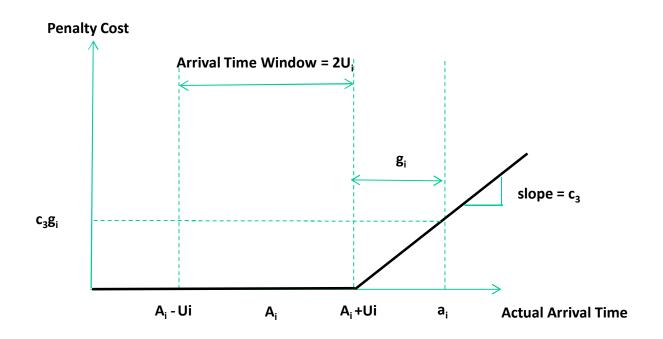
To maximize revenues earned by the port while guaranteeing a minimum level of service, we propose that the bulk terminal managers adopt and implement certain strategic measures

• Handling Time Restrictions: Impose an upper bound on the maximum handling time of a vessel $i \in N$ if it arrives within a pre-defined arrival time window $[A_i - U_i, A_i + U_i]$





• Penalty Cost on late arriving vessels: Impose a penalty fees on vessels arriving beyond the right end of the arrival window, A_i+U_i







Solution Algorithms

Optimization based recovery algorithm

- Re-optimize the berthing schedule of all unassigned vessels (whose actual or expected arrival time is known) using set-partitioning approach every time the arrival time of any vessel is updated and it deviates from its previous expected value.
- the berthing assignment of a vessel is frozen and unchangeable after the vessel has arrived and the estimated berthing time as per the latest optimization run is within a certain time difference from the current time.

Heuristic based recovery algorithm

- If a vessel has arrived and current time in the planning horizon is greater than or equal to the
 estimated berthing time of the vessel (as per baseline schedule), assign it to the section(s) at
 which the total realized cost of all unassigned vessels at that instant is minimized
- Assumption: All other unassigned vessels (whose actual or expected arrival time is known) are assigned to the estimated berthing sections as per the baseline schedule

$$\min Z = \sum_{i \in N_u} (m_i - A_i + h_i) + \sum_{i \in N_u} (c_1 | b_i(k') - b_i(k) | + c_2 \mu_i | e'_i - e_i |)$$

Optimization based Recovery Algorithm

```
Require: Baseline schedule of set N of vessels, set M of sections
    Initialize set N_{ij} of unassigned vessels to N
    Initialize counter = 0
    while |N_{ij}| > 0 and counter \leq |H| do
           Set boolean shouldOptimize = false
           for berthing Schedule: b do
                 if b.arrivalUpdated = true and new exp arr time(b.vessel) \neq old exp arr time(b.vessel) then
                        Set shouldOptimize = true
                 end if
                 if b.hasArrived = true and actual arr time(b.vessel) ≠ exp arr time(b.vessel) then
                        Set shouldOptimize = true
                 end if
           end for
           if shouldOptimize then
                  Re-optimize for all i \in N_{i,j}
           end if
           for berthing Schedule: b do
                 if !b.isAssigned AND b.hasArrived AND b.estimatedStartTime - counter ≤ frozen time then
                        Assign (b.vessel, b.estimatedStartSection)
                        Set N_{ii} to N_{ii} - \{i\}
                 end if
           end for
           counter++
    end while
```



Heuristic based Recovery Algorithm

```
Require: Baseline schedule of set N of vessels, set M of sections
    Initialize counter = 0
    while counter ≤ /H/ do
          for berthing Schedule: b do
                 if b.hasArrived AND !b.isAssigned then
                       Set minimum section cost = bigM
                       Set assigned_start_section = bigM
                       Set boolean foundSection = false
                       for k = 1 to M do
                             if isStartSectionAvailable(b.vessel,k) then
                                   foundSection = true;
                                   if(HeuristicCost(b.vessel,k)<minimum section cost)</pre>
                                          minimum_section_cost = HeuristicCost(b.vessel, k)
                                         assigned start section = k;
                                   end if
                             end if
                       end for
                       if foundSection AND counter ≥ b.estimatedBerthingTime then
                             Assign (b.vessel, assigned start section)
                       end if
                 end if
          end for
          counter++
    end while
```



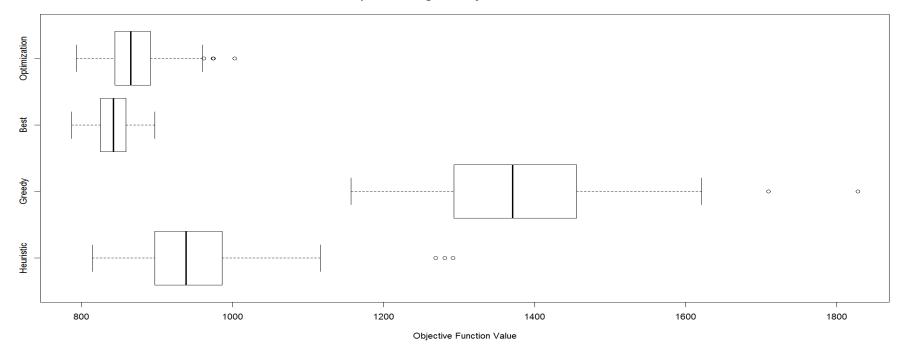
Disruption Scenario

Vessel	EAT		
0	18	Vessel 0: 23(21) ATA:26	
1	4	Vessel 1: 9(2) 14(4) 17(5) ATA:8	
2	19	Vessel 2: 24(3) 31(7) 15(9) 21(12) 24(13) 16(14) 30(15) 32(16) 21(17) 20(18) 20(19) 21(20) ATA:21
3	10	Vessel 3: 22(8) ATA:10	
4	6	Vessel 4: 16(1) 16(2) ATA:6	
5	9	Vessel 5: 19(8) 12(10) 15(13) 24(14) 24(15) 18(16) 20(17) 24(18) 22(19) 22(20) ATA:21	
6	1	Vessel 6: 15(8) ATA:16	
7	17	Vessel 7: 3(1) 10(6) 13(7) 19(10) 32(11) 23(12) 22(13) 19(14) 26(15) 32(16) 31(17) 31(18) 29(19) 21(20)
8	19	ATA:21	
9	10	Vessel 8: 29(1) 20(2) 19(4) 9(5) ATA:7	
10	1	Vessel 9: 3(2) ATA:20	
11	11	Vessel 10: 10(1) 15(6) 8(7) 14(8) 13(9) 16(10) ATA:11 Vessel 11: 23(6) 18(7) 15(9) 12(10) 16(11) 20(12) ATA:13	
12	16	Vessel 11: 25(0) 15(7) 15(9) 12(10)10(11)20(12)ATA.13 Vessel 12: 29(1) ATA:10	
13	2	Vessel 13: 5(0) 8(6) ATA:9	
14	19	Vessel 14: 17(2) 27(4) 13(9) 26(15) 22(16) 27(17) 27(18) 33(19) 25(20) 23(21) 34(22) ATA	A:23
15	15	Vessel 15: 19(2) 12(4) 7(5) 7(6) 29(7) 29(9) 16(10) 20(11) 20(12) 24(13) 28(14) ATA	
16	14	Vessel 16: 15(6) 10(8) 11(9) 28(10) 27(11) 29(12) 16(13) 15(14) ATA:15	
17	0	Vessel 17: ATA:-12	
18	19	Vessel 18: 29(8) 13(9) 25(10) 30(12) 34(13) 18(14) 25(15) 20(16) 29(17) 34(18) 34(19) ATA	4:20
19	0	Vessel 19: ATA:-15	
20	14	Vessel 20: ATA:-1	
21	12	Vessel 21: 7(6) 20(9) 25(14) 24(19) 22(20) 27(21) 23(22) 26(23) ATA:24	
22	8	Vessel 22: 12(0) ATA:5	
23	12	Vessel 23: 21(5) 14(6) 13(7) 10(8) 10(9) 24(13) 19(14) 17(15) 27(16) ATA:17	
2 4	10	Vessel 24: ATA:-1	(4241
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Preliminary Results

• |N|=25 vessels, |M|=10 sections, $c_1=1.0$, $c_2=0.002$, $U_i=8$ hours, $\tau=5$ hours, $\eta=1.2$, $D_v=5$

Interquantile Ranges of Objective Function Value



Mean Gap with respect to the best solution

Greedy Approach	Optimization based Approach	Heuristic based Approach		
64.91 %	3.66 %	12.52 %		

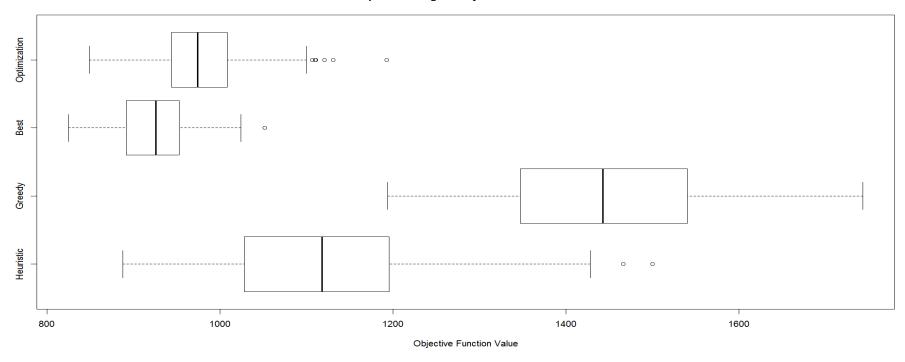




Preliminary Results

• |N|=25 vessels, |M|=10 sections, $c_1=1.0$, $c_2=0.002$, $U_i=8$ hours, $\tau=5$ hours, $\eta=1.2$, $D_v=15$

Interquantile range of objective function value



Mean Gap with respect to the best solution

Greedy Approach	Optimization based Approach	Heuristic based Approach		
56.87 %	6.49 %	22.36 %		





Summary of Results

- Modeled and solved the dynamic, hybrid berth allocation problem in bulk ports
- Addressed the problem of recovering a baseline berthing schedule in bulk ports in real time as actual arrival data is revealed.
- Discussed strategies that the port can adopt and implement to maximize their revenues while ensuring a desired level of service
- Developed solution algorithms to solve the BAP in real time in bulk ports with the objective to minimize the total realized costs of the updated schedule.
- Conducted simple numerical experiments to validate the efficiency of the algorithms..





Ongoing and Future Work

- More extensive numerical analysis to study the impact of
 - parameter values related to rescheduling of vessels including cost of shifting the vessel along the quay and cost of departure delay of a vessel
 - bounds on the maximum handling times for vessels arriving within the prescribed arrival window.
 - penalty cost function dependent on the late arriving vessels for arrival delay beyond the prescribed arrival window of the vessel
- Develop a robust formulation of the berth allocation problem in bulk ports with a certain degree of anticipation of variability in information.





Thank you!



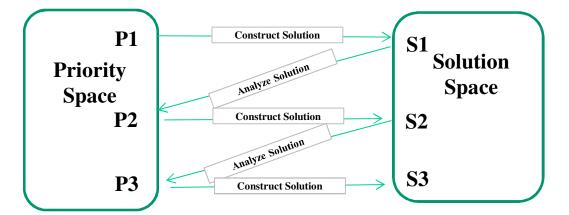


SWO Heuristic Approach

• Introduced by Clements (1997), typically successful in problems where it is possible to quantify the contribution of each single problem element to the overall solution quality

 Construct/ Analyze/ Prioritize: Solution generated at each successive iteration is constructed and analyzed, results of analysis used to generate a new priority

order



 Moves in search space are motivated by the weak performing elements and not the overall objective function value





SWO Heuristic Approach

- Construction heuristic: Returns a feasible berthing assignment for given priority order of vessels
- Initial Solution: First-Cum-First-Served ordering based on arrival times of vessels
- Algorithm: In each successive iteration, a new priority order is constructed based on the service quality measure of each berthing vessel in the previous solution
 - Service time of the vessel in the solution found in the last iteration
 - Deviation of service time of vessel from the minimum service time possible for that vessel (zero delay + minimum handling time)
 - Sum of service times of the vessel in all iterations completed so far!
- If a priority order is already evaluated, introduce randomization by swapping two
 or more vessels, until we obtained a priority order that has not been evaluated so
 far
- Algorithm terminates after a preset number of iterations and best solution is selected as the final solution





Results and Analysis

|N| = 10 vessels, and |M| = 10 sections

Instance	MILP				GSPP		FCFS		swo		
	OFV	Gap	Time	OFV	Time (H=150, h=1)	OFV	RE	OFV	RE	Time	
A1	230.21	0.01%	67.67	231.21	5.94	262.09	13.36%	230.48	-0.32%	15.81	
A2	237.35	0.01%	15.31	238.49	5.54	250.44	5.01%	239.08	0.25%	16.66	
А3	223.99	0.01%	9.58	226.61	5.96	280.04	23.58%	225.33	-0.57%	16.97	
A4	227.12	0.01%	10.31	227.22	5.68	240.91	6.03%	228.00	0.35%	16.60	
A5	234.20	0.01%	5.60	234.22	5.43	251.09	7.20%	234.47	0.11%	16.30	
A6	233.12	0.01%	11.06	234.06	6.85	262.61	12.20%	233.12	-0.40%	16.90	
A7	203.23	0.00%	0.56	203.23	4.99	208.44	2.57%	203.38	0.07%	15.95	
A8	218.87	0.00%	0.56	219.99	5.29	220.90	0.41%	218.87	-0.51%	16.72	
А9	198.03	0.00%	0.60	199.89	5.16	214.17	7.14%	198.03	-0.93%	17.53	
Mean							8.61%		-0.22%		





/N/ = 10 vessels, and /M/ = 30 sections

Instance		MILP		GSPP		FCFS		swo		
	OFV	Gap	Time	OFV	Time (H=150, h=1)	OFV	RE	OFV	RE	Time
B1	188.39	0.01%	15.80	189.73	94.552	216.56	14.14%	192.81	1.62%	49.95
B2	178.07	0.01%	15.78	179.10	86.08	186.41	4.08%	178.08	-0.57%	48.42
В3	200.16	0.01%	1094.61	202.33	101.93	230.14	13.74%	216.14	6.82%	49.79
В4	182.57	0.01%	3.04	184.27	89.58	224.00	21.56%	182.80	-0.80%	47.73
B5	178.48	0.01%	10.97	179.23	85.01	185.60	3.55%	179.01	-0.12%	48.37
В6	199.82	0.01%	87.78	201.17	96.19	240.09	19.35%	223.37	11.04%	48.83
В7	173.02	0.01%	1.30	173.02	86.00	175.72	1.56%	175.30	1.32%	48.61
B8	162.51	0.00%	1.57	162.81	81.67	169.20	3.92%	166.20	2.08%	50.29
В9	175.29	0.00%	1.39	175.81	95.74	192.41	9.44%	191.26	8.79%	50.27
Mean							10.15%		3.35%	





|N| = 25 vessels, and |M| = 10 sections

Instance		MILP		GSPP		FCFS		swo		
	OFV	Gap	Time	OFV	Time (H=150, h=1)	OFV	RE	OFV	RE	Time
C1	812.32	33.08%	1	819.22	14.09	976.49	19.20%	869.31	6.11%	22.29
C2	783.45	30.27%	1	781.72	11.70	924.35	18.25%	825.92	5.65%	22.58
С3	903.51	33.39%	1	900.43	20.19	1107.59	23.01%	929.32	3.21%	22.24
C4	795.71	23.18%	1	791.18	15.26	877.90	10.96%	852.03	7.69%	23.28
C5	751.19	27.47%	1	747.88	10.41	846.26	13.15%	774.17	3.51%	22.16
C6	874.53	24.50%	-	863.86	19.38	979.26	13.36%	898.44	4.00%	23.19
С7	735.13	19.72%	1	741.16	15.91	840.85	13.45%	806.23	8.78%	22.54
C8	689.37	22.26%	1	699.14	11.23	761.48	8.92%	735.46	5.20%	22.32
C9	800.00	22.76%	-	793.24	12.82	936.55	18.07%	872.76	10.03%	23.56
Mean							15.37%		6.02%	





|N| = 25 vessels, and |M| = 30 sections

Instance		MILP			GSPP		FCFS		swo		
	OFV	Gap	Time	OFV	Time (H=150, h=1)	OFV	RE	OFV	RE	Time	
D1	690.79	23.14%	1	670.42	219.04	857.99	27.98%	785.91	17.23%	105.36	
D2	617.31	34.23%	1	591.06	185.44	723.13	22.34%	667.20	12.88%	96.03	
D3	809.55	30.75%	1	784.94	387.40	984.28	25.40%	866.82	10.43%	105.66	
D4	657.48	20.62%	1	636.19	220.40	778.50	22.37%	728.60	14.53%	100.95	
D5	560.65	25.96%	1	556.37	172.09	622.14	11.82%	614.72	10.49%	91.35	
D6	754.87	21.97%	-	739.44	253.67	909.53	23.00%	836.23	13.09%	102.34	
D7	581.54	8.36%	-	590.24	194.80	731.55	23.94%	706.82	19.75%	100.82	
D8	510.80	16.20%	ı	506.30	167.09	565.87	11.77%	565.87	11.77%	111.46	
D9	704.76	19.18%	ı	677.97	200.63	848.97	25.22%	778.67	14.85%	99.87	
Mean							21.54%		13.89%		





|N| = 40 vessels, and |M| = 10 sections

Instance	MILP				GSPP	FCFS		SWO		
	OFV	Gap	Time	OFV	Time (H=150, h=1)	OFV	RE	OFV	RE	Time
E1	1243.64	63.77%	1	1140.60	41.73	1536.78	34.73%	1289.88	13.09%	28.24
E2	1193.05	59.69%	ı	1138.16	18.80	1571.07	38.04%	1273.09	11.86%	28.44
E3	1341.65	67.35%	ı	1249.06	139.47	1878.78	50.42%	1416.54	13.41%	31.50
E4	1113.36	59.53%	-	1051.50	30.87	1408.95	33.99%	1137.20	8.15%	30.11
E5	1105.34	56.98%	-	1063.85	19.06	1447.39	36.05%	1202.50	13.03%	32.06
E6	1361.62	68.15%	-	1160.05	167.58	1903.39	64.08%	1330.64	14.71%	34.01
E7	1011.20	55.47%	-	946.35	26.04	1291.11	36.43%	1148.14	21.32%	31.69
E8	1013.41	53.02%	ı	953.24	20.03	1183.57	24.16%	1094.15	14.78%	32.01
E 9	1181.97	64.95%	1	1071.46	94.88	1500.71	40.06%	1296.79	21.03%	35.64
Mean							39.77%		14.60%	





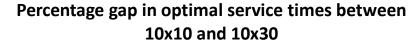
|N| = 40 vessels, and |M| = 30 sections

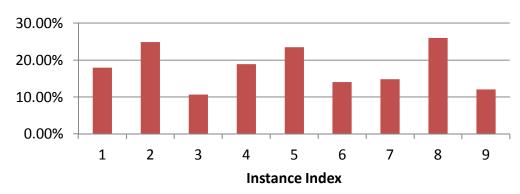
Instance		MILP		GSPP		FCFS		SWO		
	OFV	Gap	Time	OFV	Time (H=150, h=2)	OFV	RE	OFV	RE	Time
F1	1193.42	70.56%	1	920.73	506.02	1278.04	38.81%	1092.44	18.65%	169.53
F2	913.59	62.66%	1	863.43	127.91	1168.60	35.34%	911.47	5.56%	159.28
F3	+	+	+	1089.48	932.56	1784.98	63.84%	1411.24	29.53%	173.89
F4	902.74	59.15%	1	856.41	3341.62	1143.59	33.53%	1035.72	20.94%	160.113
F5	881.37	61.20%	1	786.27	137.91	973.94	23.87%	857.47	9.06%	163.41
F6	1121.14	66.39%	-	1015.53	2281.78	1628.76	60.39%	1286.73	26.71%	265.29
F7	922.04	62.05%	1	777.06	829.88	932.34	19.98%	932.34	19.98%	166.52
F8	728.48	52.93%	1	679.58	131.81	774.12	13.91%	745.00	9.63%	160.49
F9	934.35	58.59%	1	920.29	1767.57	1458.45	58.48%	1214.66	31.99%	171.97
Mean							38.68%		19.12%	





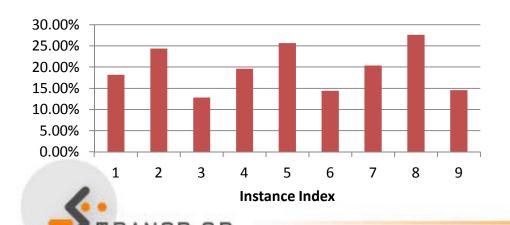
Results Analysis

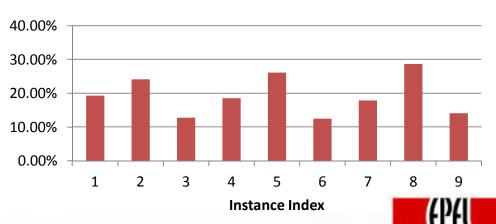




Percentage gap in optimal service times between 25x10 and 25x30

Percentage gap in optimal service times between 40x10 and 40x30





Disruption: Arrival Delay Scenario

Vessel	EAT	AAT
0	3	-1
1	3	-3
2	3	1
3	2	4
4	2	-2
5	2	4
6	2	4
7	1	0
8	4	12
9	2	1
10	2	4
11	0	4
12	1	-2
13	0	-2
14	1	-8
15	4	-4
16	4	-2
17	5	1
18	1	2
19	0	9
20	3	9
21	3	5
22	5	1
23	0	-2
24	1	10



