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Analysis of shear-transfer actions on one-way RC members based on measured cracking pattern and failure kinematics

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Shear in one-way reinforced concrete (RC) members is transferred in cracked concrete members by a number of actions such as aggregate interlock, residual tensile stresses, dowelling action, inclination of compression chord and transverse reinforcement (if available). The amount of shear transferred by each action is significantly influenced by the cracking pattern (shape of shear cracks) and by the kinematics at failure (opening and sliding of the cracks). In this paper, the activation of the various shear-transfer actions is investigated for one-way RC members. This is done by using a set of detailed measurements on the cracking pattern and actual kinematics at failure recorded on a number of specimens (beams) with a very low amount of transverse reinforcement. The amount of shear transferred by each action is estimated on the basis of available physical models and compared for the various specimens. The results show rather good predictions in terms of strength by following this approach. Consistent explanations of the shear transferred by each action are provided.

Notation

- $A_s$: concrete surface
- $A_w$: sum of projections of contact surfaces ($a_w$) between aggregates normal to crack
- $A_\Delta$: sum of projections of contact surfaces ($\Delta_\alpha$) between aggregates tangential to crack
- $a$: shear span (distance between axis of load and support)
- $\bar{a}_w$: projection of contact surface between aggregates normal to crack
- $\bar{a}_\Delta$: projection of contact surface between aggregates tangential to crack
- $b$: width of member
- $c$: concrete cover thickness of flexural reinforcement
- $c_1, c_2$: fracture energy constants
- $d$: effective depth of member
- $d_b$: diameter of reinforcing bar
- $d_{stw}$: diameter of stirrup
- $d_g$: maximum aggregate size
- $E_s$: modulus of elasticity of steel (flexural reinforcement)
- $E_{hw}$: modulus of hardening of steel (web reinforcement)
- $E_{rw}$: modulus of elasticity of steel (web reinforcement)
- $F_s$: force leading to tension rupture of an embedded (bonded) stirrup
- $F_w$: tension force in an embedded (bonded) stirrup
- $F_{yw}$: force leading to yielding of an embedded (bonded) stirrup
- $f_c$: compressive strength of concrete (cylinder)
- $f_{c,\text{cube}}$: compressive strength of concrete (cube)
- $f_{ct}$: tensile strength of concrete (measured in cylinder)
- $f_{c,28}$: tensile strength of concrete at 28 days (cylinder)
- $f_{tw}$: tensile strength of steel (web reinforcement)
- $f_F$: yield strength of steel (flexural reinforcement)
- $f_{yw}$: yield strength of steel (web reinforcement)
- $G_F$: fracture energy
- $h$: height of member
- $L$: span length of tested member
- $L_{\text{dow}}$: distance from critical shear crack to edge of support plate
- $l_{\text{tot},i}$: contributory length for calculation of crack width
- $N_{\text{agg}}$: horizontal component of aggregate interlock action
- $N_{\text{ch}}$: horizontal component of inclined compression chord
- $N_i$: horizontal component of shear-transfer action $i$
- $N_{\text{res}}$: horizontal component of the residual tensile strength of concrete
- $N_s$: tension force in flexural reinforcement
- $s_{i-1,i}$: distance between crack $i - 1$ and crack $i$
Introduction

Shear-transfer actions in one-way reinforced concrete members

After concrete cracks, a number of actions can transfer shear forces in the concrete member. Kani (1964, 1966) investigated this phenomenon by considering the strength of the concrete teeth between two flexural cracks. In a general manner (Muttoni and Fernández Ruiz, 2008), shear can be transferred by the concrete teeth through actions such as cantilever action (Figure 1(a)), aggregate interlock action (Figure 1(b)) or dowel action of the flexural reinforcement (Figure 1(c)). These actions cause a state of stress in the member such that flexural cracks propagate into shear cracks (Figure 1(d)), thus reducing their load-carrying capacity or completely disabling some of them (with the residual strength of concrete in tension after cracking potentially playing a role in this situation). However, even after the development of an inclined shear crack, shear can still be transferred and this accounts for the inclination of the compression chord (whose strength depends on the aggregate interlock capacity (Muttoni and Fernández Ruiz, 2008)), which allows the development of arching action (direct strutting of loads (see Figure 1(e))).

When the strength provided by these actions is insufficient for the acting loads, shear reinforcement can be provided to increase the strength and deformation capacity of the member. Shear reinforcement helps to limit crack widths (thus increasing the efficiency of the previous shear-carrying actions) and may be used to carry shear forces directly in combination with aggregate interlocking and/or arching actions (see Figure 1(f)).

Shear-carrying actions have been investigated by a number of authors. Fenwick and Paulay (1968) were among the first to...
investigate the role of the cracking pattern on shear-transfer actions by testing a number of pre-cracked specimens under various configurations. Other researchers have focused on developing physical models to assess the amount of shear force that can be transferred (locally or by a structural member) under a specific shear-transfer action (or a combination of them) assuming given kinematics at failure. Some significant works in this field have been performed on the aggregate interlock action (Dei Poli et al., 1987; Paulay and Loeber, 1974; Sagaseta and Vollum, 2011; Taylor, 1970; Ulaga, 2003; Walraven, 1980; Zararis, 1997), the dowelling action (Chana, 1987; Dei Poli et al., 1992, 1993; Jelic et al., 1999; Krefeld and Thurston Charles, 1966a, 1966b; Paulay et al., 1974; Taylor, 1969; Zararis, 2003), the influence of the residual tensile strength of concrete (Bazant and Kazemi, 1991; Bazant and Yu, 2005a, 2005b, 2009; Hillerborg, 1983; Hordijk, 1992; Kotsovos, 1983, 1986) and the contribution of the compression zone to carry shear forces (Tureyen and Frosch, 2003).

In this paper, the amount of shear transferred by the various actions is estimated for three specimens tested by the authors. All beams were 400 mm high and were provided with a very small amount of transverse reinforcement ($\rho_w = 0.063\%$) – lower than the minimum amount required by design codes (ACI, 2008; CEN, 2004; fib, 2011). The tests were performed to provide very accurate measurements on the crack patterns and kinematics at failure in order to allow application of a set of physical models available for each shear-transfer action to the measured kinematics in order to calculate the shear transferred by each action. The low amount of transverse reinforcement was provided in order to control crack development – members without transverse reinforcement can lead to sudden crack propagation (Fernández Ruiz et al., 2009), thus not allowing accurate readings to be taken. In addition, members with very low transverse reinforcement (lower than the minimal) are among the most interesting from a phenomenological point of view as they usually show larger scatter in terms of strength, shape of the critical shear crack and deformation capacity. This is justified because the various shear-transfer actions can contribute in a different manner and with varying intensity depending on the actual crack shapes

Figure 1. Beam shear-transfer actions in cracked RC members.
(a) Cantilever action. (b) Aggregate interlock action. (c) Dowel action. (d) Propagation of flexural crack due to tensile stresses in concrete. (e) Final cracking pattern and critical shear crack. (f) Behaviour of RC members with transverse reinforcements
and kinematics. This was observed in the tested specimens and will be explained and justified in this paper on the basis of the performed measurements.

**Experimental programme**
The investigated specimens had a rectangular cross-section of $300 \times 400$ mm (see Figure 2(a)). Specimens SC12 and SC13 were cast in normal-strength concrete (NSC) and the other two specimens (SC16 and SC17) were cast in self-compacting concrete (SCC). Maximum aggregate size $d_g$ was 16 mm for both types of concrete and the granulometry was roughly similar (see Table 1). Cylindrical concrete compressive strength at the day of the test ($f_c$) was 41.2–43.1 MPa for NSC specimens and 55.7–57.2 MPa for SCC specimens. The concrete tensile strength $f_{ct,28}$, measured at 28 days by direct tension tests on cylinders of diameter 160 mm, was 2.93 MPa for NSC specimens and 3.17 MPa for SCC specimens.

The nominal flexural reinforcement ratio for specimens SC12 and SC16 was $\rho = 1.53\%$ (three bars of diameter 26 mm) and $\rho = 1.09\%$ (three bars of diameter 22 mm) for specimens SC13 and SC17. The longitudinal reinforcement was hot rolled with a well-defined yield plateau ($f_y = 580$ MPa for both diameters of 22 and 26 mm) (see Figures 2(b) and 2(c)). The nominal concrete cover was $c = 40$ mm, thus the nominal effective depth $d$ was 347 mm for specimens SC12 and 349 mm for specimens SC13 and SC17.

A sketch of the test setup is shown in Figure 2(a). The simply supported beams were loaded (under controlled displacements) in three-point bending, with a span length $L = 2440$ mm. The concentrated load was applied at mid-span. The nominal shear span-to-effective depth ratio $a/d$ (where $a = L/2$ refers to the distance between the axis of the load and of the support) was

<table>
<thead>
<tr>
<th>Composition of concrete (per cubic metre)</th>
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<tbody>
<tr>
<td>Water</td>
</tr>
<tr>
<td>Cement</td>
</tr>
<tr>
<td>Sand (0–4 mm)</td>
</tr>
<tr>
<td>Fine gravel (4–8 mm)</td>
</tr>
<tr>
<td>Coarse gravel (8–16 mm)</td>
</tr>
</tbody>
</table>

Table 1.

![Figure 2. (a) Test setup. Measured stress–strain relationship for reinforcement; (b) flexural bars (diameter 26 mm); (c) flexural bars (diameter 22 mm); (d) stirrups (diameter 6 mm).](image-url)
equal to 3.5. The loading plate under the hydraulic jack had dimensions of $300 \times 80 \times 25$ mm and was fixed horizontally. Two bearing plates (dimensions $300 \times 200 \times 40$ mm) were placed over the support rollers and allowed free horizontal movements as well as rotations.

Two failures were obtained for each specimen, giving a total of eight tests. The first failure (called failure ‘a’) was obtained on the side of the specimen without transverse reinforcement. The specimens were then strengthened by the addition of external steel plates and threaded bars and reloaded again. This led to a second failure (failure ‘b’) developing in the side with transverse reinforcement ($\rho_w = 0.063\%$). This low value of $\rho_w$ was obtained by using 6 mm C-shaped pins placed at 150 mm (placing of the horizontal branches was alternate for two consecutive stirrups, leading to a symmetrical geometry for the specimen; see Figure 2(a)). The steel used for the stirrups was cold worked with a yield strength $f_{yw}$ of 497 MPa (0.2% residual strain; see Figure 2(d)).

All details concerning the properties of specimens (material properties and tests results) are summarised in Table 2. The measured load–deflection curves for the eight tests are presented in Figures 3(a)–3(d). The shapes of the critical shear cracks are compared for failures in the side without transverse reinforcement in Figure 3(e) and with transverse reinforcement in Figure 3(f).

**Discussion of test results**

The results for the tests without transverse reinforcement show higher normalised shear strengths for the two members cast in NSC than those cast in SCC for the same amount of flexural reinforcement. This tendency is, however, not observed for members with transverse reinforcement, where the shear strength depends most on the amount of flexural reinforcement (with larger shear strengths for larger amounts of flexural reinforcement) and shows no significant correlation to the type of concrete used.

The deformation capacity consistently increased for members with stirrups as a function of the increase in shear strength of the member (increasing capacities of deformation for increasing shear strengths). A change in the load–deflection slope (softer response and thus larger deformation capacities) occurred prior to failure. This happened at load levels higher than those leading to shear failures for the corresponding tests without shear reinforcement, and was particularly significant for test SC16b. This behaviour is explained by the development and significant opening of an inclined shear crack (eventually leading to the shear failure) increasing the rotations (and deflections) of the member. More details on shear crack kinematics (opening) and its implications on the behaviour of the member will be discussed later in the paper.

For members without transverse reinforcement, the location and shape of the critical shear cracks were broadly similar (Figure 3(e)). On the contrary, the critical shear cracks on the side with transverse reinforcement showed two possibilities (Figure 3(f)) – a critical shear crack located at the level of the flexural reinforcement close to the support edge (tests SC13b and SC16b) or a critical shear crack shifted further from the support (tests SC12b and SC17b) and with a region (close to the flexural reinforcement) with a steeper slope. The location of the cracks seems to be influenced by that of the stirrups, with the top and bottom ends of the steepest part of each shear crack located in between two stirrups. This thus leads to the two observed shapes, where the bottom part of the critical shear crack corresponds respectively to the second or third stirrup from the edge of the support. However, no clear trend was observed between the type of concrete or amount of reinforcement and the shape and location of the shear cracks (see Figure 3(f)).

The shape, location and kinematics of the shear cracks imply that, for members with low transverse reinforcement, the contribution provided by each shear-transfer action may potentially be rather different. For these tests, the complete crack patterns at the last measurement step before failure and at failure are shown in Figure 4. In the following sections, tests SC12b, SC13b and SC16b (failures in the side with transverse reinforcement) will be investigated based on measured crack kinematics with the aim of

<table>
<thead>
<tr>
<th>Specimen</th>
<th>Concrete</th>
<th>$b_1$: mm</th>
<th>$b_2$: mm</th>
<th>$d$: mm</th>
<th>$\rho_1$: %</th>
<th>$d_2$: mm</th>
<th>$f_{cl,28}$: MPa</th>
<th>$f_y$: MPa</th>
<th>Test</th>
<th>$\rho_w$: %</th>
<th>$f_{c}$: MPa</th>
<th>$f_{yw}$: MPa</th>
<th>$V_{\text{max}}$: kN</th>
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<tbody>
<tr>
<td>SC12</td>
<td>NSC</td>
<td>302</td>
<td>405</td>
<td>354</td>
<td>1.51</td>
<td>16</td>
<td>2.93</td>
<td>580</td>
<td>a</td>
<td>0</td>
<td>41.2</td>
<td>—</td>
<td>148</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td>b 0.063</td>
<td>41.5</td>
<td>497</td>
<td>176</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>SC13</td>
<td>NSC</td>
<td>303</td>
<td>403</td>
<td>354</td>
<td>1.07</td>
<td>16</td>
<td>2.93</td>
<td>580</td>
<td>a</td>
<td>0</td>
<td>43.0</td>
<td>—</td>
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<td></td>
<td></td>
<td></td>
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<td>150</td>
<td></td>
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<tr>
<td>SC16</td>
<td>SCC</td>
<td>302</td>
<td>402</td>
<td>346</td>
<td>1.53</td>
<td>16</td>
<td>3.17</td>
<td>580</td>
<td>a</td>
<td>0</td>
<td>55.7</td>
<td>—</td>
<td>115</td>
</tr>
<tr>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td>b 0.063</td>
<td>56.0</td>
<td>497</td>
<td>199</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>SC17</td>
<td>SCC</td>
<td>304</td>
<td>404</td>
<td>350</td>
<td>1.09</td>
<td>16</td>
<td>3.17</td>
<td>580</td>
<td>a</td>
<td>0</td>
<td>56.7</td>
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<tr>
<td></td>
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<td></td>
<td>b 0.063</td>
<td>57.2</td>
<td>497</td>
<td>153</td>
<td></td>
<td></td>
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</table>

Table 2. Summary of geometry, materials properties and strength of tested specimens
calculating the shear carried by each shear-transfer action. Test SC17b is not considered because two inclined cracks developed at failure in the measurement area (see Figures 4(d) and 2(h)), thus preventing determination of the actual kinematics (opening and sliding) of each crack.

**Measurement of crack kinematics**

Discrete measurements were performed on one side of the specimen to track the development of cracking during testing. These measurements were manually performed at different load steps with a Demec device (high-precision distance measurement device) on metallic measuring targets glued to the concrete surface. These targets were arranged as a grid of equilateral triangular elements with a nominal side length of 100 mm (see Figure 2(a)). The measurements were performed at selected load levels. The last measurement step (see Figures 4(a)–4(c)) was performed at a load level \( (V_{\text{p}}) \) corresponding to 99% of the maximum applied shear load \( (V_{\text{max,a}}) \) for test SC12b, 100% of \( V_{\text{max,b}} \) for test SC13b and 88% of \( V_{\text{max,b}} \) for test SC16b. These load levels correspond to the maximum load of the measurement step (the measurements were only started after the load stabilised, at a slightly lower level than the maximum load of the measurement step). As shown in Figures 4(a)–4(c), the critical cracks defining the rigid bodies for these tests were sufficiently developed at the last load level where Demec measurements were performed.

Accurate Demec measurements were essential for the analysis presented in this paper, since all the results were obtained from these measurements. In order to improve accuracy, ten readings of each measurement were performed (they were automatically acquired by the measurement device within 1 s). The standard deviation of the readings was checked and the measurement was validated if its standard deviation was lower than 0.002 mm (for the measurement length of 100 mm). The readings were later corrected to minimise measuring errors. This was done by using a finite-element analysis of a truss model reproducing the measuring targets where the measured relative displacements were introduced as imposed strains in the mesh allowing for consistency of readings (all members of the truss having same stiffness). The performed Demec measurements allow determination of the kinematics of each crack in detail as it is possible to calculate the opening \( (w) \) measured along the axis \( y' \) normal to the crack and the sliding \( (\Delta) \) measured along the axis \( x' \) tangential to the crack) of each point of the crack based on them. The procedure adopted for this calculation is presented in the Appendix and its results will be presented and discussed in the following.

**Analysis of shear-transfer actions**

The investigation of shear-transfer actions at failure is performed by considering the free bodies shown in Figures 4(a)–4(c). The forces potentially acting on them are illustrated in Figure 5.
value of each force depends on the actual shape of the critical crack defining the rigid body and on its kinematics. As shown in Figure 5, the total shear force \((V_{\text{tot}})\) that can be transferred through the critical crack can be considered to be the sum of:

- the vertical component of aggregate interlock action, \(V_{\text{agg}}\)
- forces developed in the stirrups, \(V_{\text{sw}}\)
- the vertical component of concrete residual tensile strength, \(V_{\text{res}}\)
- the dwelling action of the flexural bars, \(V_{\text{dow}}\)
- the vertical component of the inclined compression chord, \(V_{\text{ch}}\).

In addition, the following horizontal forces are also considered to satisfy the equilibrium of the rigid body:

\[
 V_{\text{p max, b0}} = 0.99 V_{\text{max, b}} / H_{11005}
\]

\[
 V_{\text{p max, b1}} = 1.00 V_{\text{max, b}} / H_{11005}
\]

\[
 V_{\text{p max, b2}} = 0.88 V_{\text{max, b}} / H_{11005}
\]

\[
 V_{\text{p max, b3}} = 0.93 V_{\text{max, b}} / H_{11005}
\]
tension force in the flexural bars, $N_t$
- the horizontal component of aggregate interlock action, $N_{agg}$
- the horizontal component of the inclined compression chord, $N_{h}$
- the horizontal component of the concrete residual tensile strength, $N_{res}$.

The dowel action of the transverse reinforcement and the inner forces in the compression reinforcement are neglected in this analysis.

The analysis of the inner forces acting on the free bodies is performed by first estimating the aggregate interlock action ($V_{agg}$, $N_{agg}$), the shear reinforcements action ($V_{s}$, $N_{s}$) on the basis of the measured kinematics and by using a number of mechanical models detailed later. Once these actions are determined, forces $N_t$ and $N_h$ are calculated in order to satisfy both moment and horizontal equilibrium conditions. This may require, if an inclination of the compression chord ($\theta$) is considered, obtaining the result by iterations. In addition, iterations may be required to compute the dowelling force ($V_{d}$) in the case that the flexural reinforcement yields under the combined action of normal ($N_t$) and shear forces ($V_{s}$).

**Aggregate interlock action**

In the literature, many approaches have been proposed to calculate the aggregate interlock stresses based on the relative displacements of the surfaces of a crack. Notable analytical developments were performed in the 1980s by Walraven (1980) and Dei Poli et al. (1987). In this paper, the model proposed by Walraven (1980) is selected due to its generality and physical basis. This model allows association of the relative displacements between the surfaces of a crack (opening $w$ and sliding $\Delta$) with the transferred compression ($\sigma_{agg}$) and shear ($\tau_{agg}$) stresses. This allows, by integration of the stresses along the crack surface, calculation of the shear and compression forces ($V_{agg}$ and $N_{agg}$) acting along the crack. The interface stresses are calculated (Walraven, 1980) as

$$\bar{\sigma}_{agg} = \begin{bmatrix} \sigma_{agg} \\ \tau_{agg} \end{bmatrix} = \begin{bmatrix} \sigma_{agg}(w, \Delta) \\ \tau_{agg}(w, \Delta) \end{bmatrix} = \begin{bmatrix} \sigma_{pu} \cdot (A_{\Delta} - \mu A_{w}) \\ -\sigma_{pu} \cdot (A_{w} + \mu A_{\Delta}) \end{bmatrix} \geq 0.$$  

where $\sigma_{pu} = 6.39 f_{c}^{0.56}$ is the compressive plastic strength of cement matrix $f_{c}^{0.56}$ is the concrete compressive strength measured on a cube (in MPa), $\mu = 0.4$ is the coefficient of friction, and $A_{\Delta}$ and $A_{w}$ are the sum of projections ($\bar{a}_{\Delta}$ and $\bar{a}_{w}$) of the contact surfaces between aggregates and matrix on both axis normal and tangential to the crack (see Figure 6(a)). Values of $A_{w}$ and $A_{\Delta}$ are functions of the kinematics of the crack, the maximum aggregate size ($d_{a}$) and the relative aggregate volume fraction ($p_{k}$) (Walraven, 1980). The latter parameter defines the probability that an arbitrary point in the concrete is located inside an aggregate and is thus equal to the ratio between the total volume of the aggregate and the volume of the concrete. This ratio was calculated for both types of concrete (average density of aggregates equal to 2600 kg/m$^3$ and density of cement equal to 2800 kg/m$^3$) to be $p_{k} = 0.76$ for NSC and $p_{k} = 0.65$ for SCC. It is interesting to note that SCC has a lower value of $p_{k}$ than NSC, thus leading to a lower interlock contribution for the same kinematics and maximum aggregate size ($d_{a} = 16$ mm for the investigated specimens).

With respect to the crack kinematics, Walraven (1980) assumes that all crack opening ($w$) develops prior to crack sliding ($\Delta$) (see Figure 6(b)). The crack kinematics adopted by Walraven have been generalised by Guidotti (2010) by accounting only for a fraction of the total crack opening ($w_{0}$) developing prior to crack sliding, followed by an increase in both crack opening and sliding (displacement $\delta$) at an angle $\gamma$ with respect to the crack plane (see Figures 6(a) and 6(b)). Other kinematics can be found in the scientific literature with application to shear problems (such as Ulaga (2003) where $w_{0} = 0$, $\gamma = \arctan(w/\Delta)$) but these can be considered (as can that of Walraven, $w_{0} = w$, $\gamma = 0$) as particular cases of the one proposed by Guidotti (2010).

A comparison of the computed stresses for various kinematics and as a function of crack opening and sliding is shown in Figures 6(c) and 6(d). The kinematics proposed by Walraven (1980) (dashed curves) represent an upper bound of aggregate interlock contribution while those proposed by Ulaga (2003) (dotted curves) represent a lower bound. The kinematics proposed by Guidotti (2010) (continuous curves) generate intermediate stress values.

Using the measured crack shape and kinematics (Figure 7(a)), the interlock stresses ($\bar{\sigma}_{agg}$) can be estimated (Figure 7(b)). Integration of $\bar{\sigma}_{agg}$ then yields the vertical and horizontal components of the aggregate interlock forces ($V_{agg}$ and $N_{agg}$, Figure 7(b)). For calculation of the aggregate interlock contribution, the crack shape is approximated by a spline whose key points are spaced at a maximal distance equal to the aggregate size $d_{a}$. This spline is corrected with additional key points if the distance between the spline and the actual crack becomes larger than half the aggregate size (loss of contact between lips of the crack). This strategy was adopted as Walraven’s model (Walraven, 1980) already accounts for the local (micro) roughness of the crack.

With respect to crack kinematics, the approach of Guidotti (2010) was used. A value of $w_{0}$ was calculated for each point of the critical crack in order to obtain the best fit to the measured kinematics (minimum square root criterion, see Figure 6(b)). The obtained results of these calculations are summarised in Table 3. The distributions of the compressive interlock stress and the
resulting forces are shown in Figure 7(b). Almost all aggregate interlock action develops in the steepest part of the critical crack, since the measured crack sliding is larger in these regions (see Figure 7(a)). The obtained results differ depending on the shape of the crack, providing a rather high contribution for test SC12b (with steeper and curved cracks) and a lower contribution for tests SC13b and SC16b (flatter and rather linear cracks).

Transversal reinforcement contribution
For a concrete member provided with stirrups, opening of an inclined shear crack leads to their activation. The stresses that can be mobilised are, however, significantly influenced by the bond and development conditions of the reinforcement (Fernández Ruiz and Muttoni, 2009).

A simple and consistent way to investigate the behaviour of transverse reinforcement embedded in concrete is by assuming rigid–plastic bond behaviour at their interface (see Figure 8(b)). This methodology has been proved to be applicable before and after bar yielding and can be applied to a number of bond-related problems (Fernández Ruiz et al., 2010; Sigrist, 1995) including unloading (Muttoni and Fernández Ruiz, 2007). According to this approach, all tension force is carried by the steel at the location of the cracks and decreases in the regions where it is bonded to...
concrete. Prior to bar yielding, the bond stress is constant (Sigrist, 1995) ($\tau_{bo} = 2f_{ct}$) and thus the decrease of the steel stress (tension stiffening) is linear with the distance to the crack (Figure 8(a)). After bar yielding, plastic strains localise in a zone near the crack where bond stresses are reduced (for tensile forces (Sigrist, 1995) $\tau_{ml} = f_{ct}$; other cases can be found elsewhere (Fernández Ruiz et al., 2007)).

If concrete strains are neglected (in comparison to steel strains), the crack width ($w_i$) can be obtained by integration of the steel strains

$$w_i = \int_{\varepsilon_{max}} \varepsilon_s \, dv$$

Using this relationship, one can calculate the profile of stresses in a bar for a given crack width (Fernández Ruiz et al., 2007; Sigrist, 1995) (or vice versa). For vertical transverse reinforcement, the shear force carried by a given stirrup ($V_{swi}$) can be calculated as

$$V_{swi} = \frac{\sigma_{sw}d_{bw}^2\pi}{4}$$

where $\sigma_{sw}$ is the value of the stress at the location of the crack with a given vertical opening ($v_{sw}$) and $d_{bw}$ refers to the diameter of the bar (all bars were fully developed in the vertical part of the stirrups; see Figure 2(a)).

In the tests presented here, and accounting for the small diameter of the stirrups ($d_{bw} = 6$ mm), the properties of the steel used (yield strength $f_{yw} = 497$ MPa, measured tensile strength $f_{tw} = 595$ MPa, modulus of elasticity $E_{sw} = 205$ GPa and hardening modulus calculated as the slope of the stress–strain diagram between failure and yielding, $E_{shw} = 1560$ MPa) and the concrete tensile strength ($f_{ct} = 3$ MPa), it can be noted (see Figure 8(c)) that even a small crack opening of $v_{swy} \approx 0.3$ mm is sufficient to yield the bar. Tensile rupture occurs theoretically for a larger opening ($v_{swy} \approx 3.4$ mm), but is still limited.

Calculation of the contribution of the stirrups to the shear strength for the specimens investigated in this paper was performed on the basis of the measured crack widths and crack locations. For each stirrup, the locations at which it is intercepted by cracks are determined along with their vertical openings (openings along the axis of the stirrup), taking advantage of the Demec measurements. On that basis, and accounting for the bond model previously introduced, the stresses and forces of the stirrups are determined. The obtained results of these calculations are summarised in Table 3 (sum of contribution of each stirrup). The resulting forces are shown in Figure 8(d). For this action, the results again depend strongly on the crack shape and kinematics.
The efficiency of the stirrups is nevertheless opposite that of the aggregate interlock as flatter cracks (SC13b and SC16b) intercept a larger number of stirrups, leading to larger contributions. It can be noted that for test SC16b, the stirrup closest to the support plate is not accounted for because it is intercepted by a horizontal branch of the crack and will thus be considered (as will be explained later) as a dowelling contribution.

Concrete residual tensile strength contribution

As shown by Hillerborg (1983), after the development of a crack, concrete exhibits a softening residual strength ($\sigma_{\text{res}}$). In the fracture process zone (FPZ) (Hillerborg, 1983), this residual strength allows the transfer of forces through the crack. The vertical component of this force for beams ($F_{\text{res}}$) can thus transfer a certain amount of shear and the horizontal component of this force ($N_{\text{res}}$) is to be considered in the equilibrium of forces acting on the free body.

The concrete softening behaviour can be modelled using a number of approaches (fib, 2011; Hordijk, 1992). In this paper the proposal of Hordijk (1992) (which shows good correlation with the behaviour of NSC) is used. Figure 9(a) shows the relationship between the residual tensile strength ($\sigma_{\text{res}}$) and the crack opening ($w$), which is defined by

$$\sigma_{\text{res}} = f_c \left(1 + \left(\frac{w}{w_c}\right)^3\right) e^{-\frac{w}{c_1 w_c}} - \frac{w}{w_c} \left(1 + \frac{w}{w_c}\right) e^{-\frac{w}{c_2 w_c}}$$

where $w_c = 5.14(G_{\text{fr}}/f_c^2)$ represents the maximum crack width for stress transfer and $c_1 (=3.0)$ and $c_2 (=6.93)$ are constants of the model (Hordijk, 1992). For calculation of the fracture energy $G_{\text{fr}}$, the proposal of Model Code 2010 (fib, 2011) was used: $G_{\text{fr}} = 73 f_c^{0.18}$, where $f_c$ is the concrete compressive strength in MPa.

It should be noted that the detrimental influence of the compression stresses developing in the investigated region (compression chord of the member) on the tensile strength of concrete (Kupfer et al., 1969) is neglected (this assumption will be discussed later). The input data used to apply this model are the measured openings ($w$) of the crack at each point of the critical crack (see Figure 9(b)). Unfortunately, no valid measurements were available for test SC16b in this zone (where $w < w_c$; see Figure 9(b)) and the analysis is thus limited to tests SC12b and SC13b.

The results of these calculations are shown in Table 3 and the resulting stresses and forces are shown in Figure 9(c). It can be seen that, due to the size of the members and values of crack widths, the residual tensile strength has a rather low contribution.
to shear strength. When the detrimental influence of the compressive stresses on tensile strength is accounted for, its contribution will even be lower. For thinner specimens (thus developing smaller crack widths) the contribution of this action may be more significant.

Dowelling action of flexural reinforcement

Another action reported in the scientific literature is the dowelling strength provided by flexural bars (Chana, 1987; Dei Poli et al., 1992, 1993; Jelic et al., 1999; Krefeld and Thurston Charles, 1966a, 1966b; Paulay et al., 1974; Taylor, 1969; Zararis, 2003). This action depends mostly on the diameter of the flexural bars, the presence of transverse reinforcement, the concrete cover and its strength, and the distance of the critical shear crack to the support plate. Despite the significant number of studies performed in this field, a numerical model (see Figure 10(a)) has been specifically developed by the authors to investigate this action. The model allows accounting for the distance of the critical shear crack to the edge of the support and for the actual location and behaviour (elastic–plastic bonded, see Figure 10(b)) of the stirrups as well as for the elastic–plastic behaviour of the flexural bar.

The numerical model corresponds to a cohesive crack model accounting for the residual tensile strength of concrete and the

Figure 8. Transverse reinforcement contribution. (a) Relationship between cracks opening and steel strain and stresses in a RC tie. (b) Assumed rigid–plastic bond behaviour. (c) Behaviour of an embedded (bonded) vertical stirrup. (d) Application to investigated specimens: observed kinematics, calculated stresses and transferred shear forces
location of the support and the transverse reinforcement (Figure 10(a)). The bar is dowelled according to the measured location of the critical shear crack (when it intercepts the level of the flexural reinforcement), and its relative vertical displacement ($v_{dow}$) is obtained from the Demec measurements (Figure 10(a)). Concrete is simulated through non-linear springs (accounting for their tributary area) reproducing concrete behaviour before and after cracking (for the latter following the FPZ approach; see Figure 10(c)). Stirrups are also simulated as non-linear springs, reproducing the elastic and plastic bonded behaviour of the bar. Typical dowelling curves obtained using this approach are shown in Figure 11 (corresponding to $v_{dow} = 0.5$ mm). This figure shows that the parameter most influencing the response is the distance from the critical shear crack to the edge of the support plate ($L_{dow}$). The stirrups also show a certain contribution, although it is secondary with respect to the crack location.

Figure 10(d) shows a summary of the recorded values for $v_{dow}$ and $L_{dow}$ for the various specimens of the experimental programme. On that basis, the dowelling action can be calculated (see Table 3). The results show a significant dependency on the location of the crack. Thus, for test SC12b, where the crack is far from the support plate and first intercepted stirrup, this action is almost negligible. On the contrary, for test SC13b and particularly for test SC16b, the crack develops close to the bearing plate and the shear force that can be transferred through dowelling action becomes very significant.

**Contribution of inclined compression chord**

Another potential action for carrying shear forces is the inclination of the compression chord ($V_{ch}$; see Figure 12(a)). This is shown in Figures 12(b) and 12(c) where two truss models are presented (Leonhardt and Mönnig, 1974). The first (Figure 12(b))
has both flexural chords (in compression and tension) parallel. Thus, all the shear force is transferred by means of the inclined struts of the web in equilibrium with the transverse reinforcement. As a consequence, the forces in the compression and tension flexural chords decrease with distance to the loading point. Other equilibrium solutions are possible, implying inclination of the compression chord ($\alpha_{ch}$; Figure 12(c)). In this case, a fraction of the shear force is carried by the compression chord ($V_{ch} = N_{ch} \tan \alpha_{ch}$) and the stirrups and web struts only have to equilibrate the remaining part. In this case, the flexural lever arm diminishes and the forces to be carried by the flexural chords increase with respect to those of Figure 12(b).

By detailed analysis of the cracking pattern of the investigated specimens, for tests SC13b and SC16b, the thickness of the compression zone is rather limited – 37 mm for SC13b (Figure 4(c)) and 28 mm for SC16b (Figure 4(e)) – and is followed by a quasi-horizontal crack approximately at the level of the compression reinforcement. This implies that the amount of shear that can be transferred by an inclined compression strut should also be somewhat limited and can be neglected. The potential dowelling force of the compression reinforcement also seems to be negligible, accounting for the significant distance between the tip of the quasi-horizontal crack and the loading plate as well as the small diameter (10 mm) of the compression bars.

For test SC12b, the thickness of the compression zone and the slope of the critical shear crack in the investigated region (72 mm) are larger. This indicates that this action could potentially be more significant for this specimen. However, the still
limited depth of the investigated region compared to the measurement grid (Figure 2(a)) does not allow for sufficiently detailed measurements to estimate this effect suitably and thus, for this test, the potential contribution of the compression chord to the shear strength will not be calculated.

Discussion of results

Figure 13 and Table 3 show all contributions for the three investigated specimens as well as the horizontal forces required to satisfy equilibrium conditions. A very reasonable agreement between the sum of the estimated contributions \( V_{\text{tot}} \) and the acting shear load \( V \) is observed, with only a moderate overestimation for test SC12b. The difference for this latter specimen could be due to an overestimate of the aggregate interlock action, as Walraven’s model is quite sensitive for rather steep slopes (crack kinematics).

Interesting results can be obtained by analysis and comparison of the results for the various shear-carrying actions in the three specimens (Figure 14).

- The significance of the various actions is different for each specimen. This is explained by the quite different crack shapes (Figure 3(f)) and measured kinematics (Figure 7(a)).
- Aggregate interlock action is dominant (72%) for test SC12b and still quite significant (44%) for test SC13b. On the contrary, the wide opening and rather linear shape of the critical shear crack implies that this contribution is very limited (20%) for test SC16b.
- Dowelling action is most significant for test SC16b (45%) due to the limited distance between the critical shear crack and the edge of the support. For crack geometries where aggregate interlock action is more active (steeper cracks and thus at larger distances from the edge of the support), this contribution decreases and is almost negligible (5% and 10% for tests SC12b and SC13b, respectively).
- Transverse reinforcement allows the carrying of a significant fraction of the total shear force. The amount depends on the crack shape and is higher for flat cracks intercepting a larger number of stirrups (38% and 35% for tests SC13b and SC16b, respectively) than for steep cracks (18% for test SC12b).
- The residual tensile strength of concrete shows a rather limited contribution for the investigated members. This is mostly due to the crack widths and size of the members.
- The inclination of the compression chord also seems to be of secondary significance for tests SC13b and SC16b. For test SC12b, no measurements are available to estimate this action suitably.

As has been demonstrated, the critical shear crack shape and its kinematics (opening and sliding) may differ notably (see Figure 7(a)). This potentially leads to different amounts of shear that can
be carried by each shear-transfer action. However, the results are somewhat compensated – for flatter cracks with lower aggregate interlock action, the dowelling and stirrups contributions increase. For members without transverse reinforcement, the aggregate interlock action is thus expected to be dominant as the stirrup contribution is not available and the dowelling action is reduced (refer to Figure 11 and to the crack patterns in Figure 3(e), in agreement with some theoretical works (Muttoni and Fernández Ruiz, 2008)).

Conclusions

This work investigated the shear transferred in one-way reinforced concrete members with small amounts of transverse reinforcement. A number of analyses have been performed on the basis of detailed measurements of cracking patterns and actual kinematics at failure of three beams. The main conclusions are as follows.

- The amount of shear transferred by the various potential actions (aggregate interlock, transverse reinforcement, residual tensile strength, dowelling action, inclination of compression chord) is highly dependent on the shape and associated kinematics of the critical shear crack, which may significantly vary for members with low transverse reinforcement.
- The amount of shear carried by each action can be suitably investigated on the basis of refined kinematical measurements and by using mechanical models describing the local transfer of shear forces.
- For the investigated specimens, almost all shear force is carried by a combination of aggregate interlock, dowelling action and stirrup contribution. The rest of the actions are negligible. For geometries or sizes different to those investigated here, other actions (such as the residual tensile strength or the compression zone) may, however, become more significant.
- Aggregate interlock is dominant for steep critical shear cracks, whereas dowelling and stirrup contributions are dominant for flat cracks. However, the sum of the various contributions leads to similar strength results.
- For members without transverse reinforcement, the aggregate interlock action is expected to be dominant as the stirrup contribution is not available and dowelling action is reduced.

Appendix

The measurements performed allow determination of the kinematics of each crack. This can be performed, as shown in Figure 15, by calculating the displacement fields of two rigid bodies located at both sides of the investigated crack ($w_1(x, y)$ and $w_2(x, y)$). Each displacement field was calculated by using the measured coordinates of a couple of targets (P1–P2 for the first crack’s side and P3–P4 for the second side) of the Demec grid. The displacement of each target is described by both the undeformed position $(P_1^{0}, P_2^{0}, P_3^{0}, P_4^{0})$ and the deformed position at a given load step $(P_1^{def}, P_2^{def}, P_3^{def}, P_4^{def})$

$$\begin{align*}
   w_1(x, y) &= \begin{cases} 
   a_1 - e_1 \cdot x \\
   b_1 + e_1 \cdot y 
   \end{cases} \\
   w_2(x, y) &= \begin{cases} 
   a_2 - e_2 \cdot x \\
   b_2 + e_2 \cdot y 
   \end{cases}
\end{align*}$$
Figure 15. Measurements for calculation of crack kinematics: (a) undeformed configuration; (b) deformed configuration

where

\[
\begin{bmatrix}
  a_1 \\ b_1 \\ e_1
\end{bmatrix} = \left( A_1^T \cdot A_1 \right)^{-1} \cdot (A_1^T \cdot e_1)
\]

6a.

\[
\begin{bmatrix}
  a_2 \\ b_2 \\ e_2
\end{bmatrix} = \left( A_2^T \cdot A_2 \right)^{-1} \cdot (A_2^T \cdot c_2)
\]

6b.

\[
A_1 = \begin{bmatrix}
  1 & 0 & -P_{1x}^0 \\
  0 & 1 & P_{1y}^0 \\
  1 & 0 & -P_{2x}^0 \\
  0 & 1 & P_{2y}^0
\end{bmatrix}
\]

7a.

\[
A_2 = \begin{bmatrix}
  1 & 0 & -P_{3x}^0 \\
  0 & 1 & P_{3y}^0 \\
  1 & 0 & -P_{4x}^0 \\
  0 & 1 & P_{4y}^0
\end{bmatrix}
\]

7b.

\[
c_1 = \begin{bmatrix}
P_{1x}^{def} - P_{1x}^0 \\
P_{1y}^{def} - P_{1y}^0 \\
P_{2x}^{def} - P_{2x}^0 \\
P_{2y}^{def} - P_{2y}^0
\end{bmatrix}
\]

7c.

\[
c_2 = \begin{bmatrix}
P_{3x}^{def} - P_{3x}^0 \\
P_{3y}^{def} - P_{3y}^0 \\
P_{4x}^{def} - P_{4x}^0 \\
P_{4y}^{def} - P_{4y}^0
\end{bmatrix}
\]

7d.

The relative displacement \( \bar{u} = \begin{bmatrix} u \\ v \end{bmatrix} \) between two points of the crack \( f_2 \) and \( f_1 \), for which the initial position \( f(x, y) \) is the same, can be calculated as the difference between the two displacement fields

\[
\bar{u} = \begin{bmatrix} u \\ v \end{bmatrix} = w_2(x, y) - w_1(x, y)
\]

8.

The relative displacement \( \bar{u} = \begin{bmatrix} u \\ v \end{bmatrix} \) between two points of the crack \( f_2 \) and \( f_1 \), for which the initial position \( f(x, y) \) is the same, can be calculated as the difference between the two displacement fields

\[
\bar{u} = \begin{bmatrix} u \\ v \end{bmatrix} = w_2(x, y) - w_1(x, y)
\]

9.

\[
\bar{w} = \begin{bmatrix} \Delta y \\ \Delta x \end{bmatrix} = \begin{bmatrix} \cos \alpha & \sin \alpha \\ -\sin \alpha & \cos \alpha \end{bmatrix} \cdot \bar{u}
\]

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