Analyse de données en grande dimension sur graphes et réseaux

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Graphs for Data Modeling



2010: 980 exabytes of new digital information Big Data



"Neuronal" Network



Ubiquitous sensing





Graphs for Data Modeling

To process or analyze one typically extracts "features" or apply transforms

Local multi-scale averages or multi-scale differentials (wavelets)



The localization/scale properties often induces interesting effects such as sparsity:







- Wavelets on (undirected) graps
 - Definitions, implementation
 - Localization
- Schematic application to (transductive) learning





Graphs, Laplacian and Spectral Theory

G = (V, E, w) weighted, undirected graph

Non-normalized Laplacian: $\mathcal{L} = D - A$ Real, symmetric

$$(\mathcal{L}f)(i) = \sum_{i \sim j} w_{i,j}(f(i) - f(j))$$

Why Laplacian ? \mathbb{Z}^2 with usual stencil

$$(\mathcal{L}f)_{i,j} = 4f_{i,j} - f_{i+1,j} - f_{i-1,j} - f_{i,j+1} - f_{i,j-1}$$

In general, graph laplacian from nicely sampled manifold converges to Laplace-Beltrami operator

Remark:

$$\mathcal{L}^{norm} = D^{-1/2} \mathcal{L} D^{-1/2} = I - D^{-1/2} A D^{-1/2}$$





Graphs, Laplacian and Spectral Theory

eigen decomposition of Laplacian \square Spectral Graph Theory

$$\{\chi_l\}_{l=0,1,\dots,N-1} \qquad 0 = \lambda_0 < \lambda_1 \le \lambda_2 \dots \le \lambda_{N-1} := \lambda_{\max}$$

The Graph Laplacian induces a convenient Fourier-like transform

$$\hat{f}(\ell) := \langle f, \chi_l \rangle = \sum_{n=1}^N \chi_\ell^*(n) f(n)$$

$$\mu := \max_{\substack{\ell \in \{0,1,\dots,N-1\}\\i \in \{1,2,\dots,N\}}} |\langle \chi_{\ell}, \delta_i \rangle| \in \left[\frac{1}{\sqrt{N}}, 1\right]$$





Smoothness via Laplacian

Example (Belkin, Niyogi)

Affinity between data points represented by edge weights (affinity matrix W)

measure of smoothness: $\Delta f = \sum_{i,j\in X} \mathbf{W}_{ij} (f(x_i) - f(x_j))^2$ = $\mathbf{f}^t L \mathbf{f} \quad L = W - D$

Revisit ridge regression: $\|\mathbf{X}_{S}^{t}\beta - \mathbf{y}\|_{2}^{2} + \alpha \|\beta\|_{2}^{2} + \gamma \beta^{t} \mathbf{X} L \mathbf{X}^{t} \beta$

Solution is smooth in graph "geometry"

discrete Sobolev semi-norm on $\,G\,$



$$\|f\|_{G,2s}^2 = \sum_l \lambda_l^{2s} |\hat{f}(\lambda_l)|^2$$

LTS



$$\widehat{f_*}(\ell) = \frac{\tau}{\tau + 2\lambda_\ell^r} \hat{y}(\ell) \quad \text{``Low pass'' filtering}$$

Simple linear features: $\hat{f}(\ell)\hat{g}(\lambda_{\ell};p) \Rightarrow g(\mathcal{L};p)$





"Convolutions" and "Translations"

$$(f * g)(n) := \sum_{\ell=0}^{N-1} \hat{f}(\ell) \hat{g}(\ell) \chi_{\ell}(n)$$

Inherits a lot of properties of the usual convolution associativity, distributivity, diagonalized by GFT

$$g_0(n) := \sum_{\ell=0}^{N-1} \chi_\ell(n) \quad \square \qquad f * g_0 = f$$

LTS

EPF

$$\mathcal{L}(f \ast g) = (\mathcal{L}f) \ast g = f \ast (\mathcal{L}g)$$

Use convolution to induce translations

$$(T_i f)(n) := \sqrt{N} (f * \delta_i)(n) = \sqrt{N} \sum_{\ell=0}^{N-1} \hat{f}(\ell) \chi_{\ell}^*(i) \chi_{\ell}(n)$$

Spectral Graph Wavelets

G=(E,V) a weighted undirected graph, with Laplacian $\mathcal{L}=D-A$

Dilation operates through operator: $T_g^t = g(t\mathcal{L})$

Translation (localization):

Define $\psi_{t,j} = T_g^t \delta_j$ response to a delta at vertex j $\psi_{t,j}(i) = \sum_{\ell=0}^{N-1} g(t\lambda_\ell) \chi_\ell^*(j) \chi_\ell(i) \qquad \mathcal{L}\chi_\ell(j) = \lambda_\ell \chi_\ell(j)$ $\psi_{t,a}(u) = \int_{\mathbb{R}} d\omega \, \hat{\psi}(t\omega) e^{-j\omega a} e^{j\omega u}$

And so formally define the graph wavelet coefficients of f:

$$W_f(t,j) = \langle \psi_{t,j}, f \rangle \qquad \qquad W_f(t,j) = T_g^t f(j) = \sum_{\ell=0}^{N-1} g(t\lambda_\ell) \hat{f}(\ell) \chi_\ell(j)$$





Frames



<u>A simple way to get a tight frame:</u>

$$\gamma(\lambda_{\ell}) = \int_{1/2}^{1} \frac{dt}{t} g^2(t\lambda_{\ell}) \implies \tilde{g}(\lambda_{\ell}) = \sqrt{\gamma(\lambda_{\ell}) - \gamma(2\lambda_{\ell})}$$

for any admissible kernel g





Scaling & Localization







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Example

















Sparsity and Smoothness on Graphs



scaling functions coeffs







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Polynomial Localization

Given a spectral kernel g, construct the family of features:

$$\phi_n(m) = (T_n g)(m) \qquad \phi_n(m) = \sqrt{N} \sum_{\ell=0}^{N-1} \hat{g}(\lambda_\ell) \chi_\ell^*(m) \chi_\ell^*(n)$$

Are these features localized ?

Suppose the GFT of the kernel is smooth enough (K+1 different.):

$$B = \sup_{x} |\hat{g}^{(K+1)}(x)|$$

Construct an order K polynomial approximation:

$$\sup_{\ell} |\hat{g}(x) - P_K(x)| \le \frac{B}{2^K (K+1)!}$$





Polynomial Localization

$$\sup_{\ell} |\hat{g}(x) - P_K(x)| \le \frac{B}{2^K (K+1)!}$$

Now consider:

$$\phi_n(m) = \langle \delta_m, g(\mathcal{L}) \delta_n \rangle$$

 $\phi'_n(m) = \langle \delta_m, P_K(\mathcal{L}) \delta_n \rangle$ Exactly localized in a K-ball around n

The original feature is well-localized in a K-ball around n:

$$B_{\hat{g}}(K) = \inf_{\widehat{p_k}} \left\{ \sup_{\lambda \in [0, \lambda_{\max}]} |\hat{g}(\lambda) - \widehat{p_k}(\lambda)| \right\}$$



$$d_{in} > K \quad |(T_i g)(n)| \le \sqrt{N} B_{\hat{g}}(d_{in} - 1)$$



Bounds on Localization

Example: for the heat kernel $\hat{g}(\lambda) = e^{-\tau\lambda}$

$$\frac{|(T_i g)(n)|}{\|T_i g\|_2} \le \frac{2\sqrt{N}}{d_{in}!} \left(\frac{\tau \lambda_{\max}}{4}\right)^{d_{in}} \le \sqrt{\frac{2N}{d_{in}\pi}} e^{-\frac{1}{12d_{in}+1}} \left(\frac{\tau \lambda_{\max} e}{4d_{in}}\right)^{d_{in}}$$







Remark on Implementation

Not necessary to compute spectral decomposition for filtering

Polynomial approximation :
$$g(t\omega) \simeq \sum_{k=0}^{K-1} a_k(t) p_k(\omega)$$

ex: Chebyshev, minimax

Then wavelet operator expressed with powers of Laplacian:

$$T_g^t \simeq \sum_{k=0}^{K-1} a_k(t) \mathcal{L}^k$$

And use sparsity of Laplacian in an iterative way





Remark on Implementation

$$\tilde{W}_f(t,j) = \left(p(\mathcal{L})f^{\#}\right)_j \qquad |W_f(t,j) - \tilde{W}_f(t,j)| \le B||f||$$

sup norm control (minimax or Chebyshef)

$$\tilde{W}_f(t_n, j) = \left(\frac{1}{2}c_{n,0}f^\# + \sum_{k=1}^{M_n} c_{n,k}\overline{T}_k(\mathcal{L})f^\#\right)_j$$

$$\overline{T}_k(\mathcal{L})f = \frac{2}{a_1}(\mathcal{L} - a_2I)\left(\overline{T}_{k-1}(\mathcal{L})f\right) - \overline{T}_{k-2}(\mathcal{L})f$$

Computational cost dominated by matrix-vector multiply with (sparse) Laplacian matrix. In particular $O(\sum_{n=1}^{N} M_n |E|)$ http://wiki.epfl

http://wiki.epfl.ch/sgwt

Note: "same" algorithm for adjoint !





Let X be an array of data points $x_1, x_2, ..., x_n \in \mathbb{R}^d$

Each point has a desired class label $y_k \in Y$ (suppose binary)

At training you have the labels of a subset S of X |S| = l < n

Getting data is easy but labeled data is a scarce resource

GOAL: predict remaining labels

<u>Rationale</u>: minimize empirical risk on your training data such that

- your model is predictive
- your model is simple, does not overfit
- your model is "stable" (depends continuously on your training set)









Transductive Learning

Ex: Linear regression $y_k = \beta \cdot x_k + b$ Empirical Risk: $\|\mathbf{X}^t \beta - \mathbf{y}\|_2^2 \longrightarrow \beta = (\mathbf{X}\mathbf{X}^t)^{-1}X\mathbf{y}$

if not enough observations, regularize (Tikhonov):

$$\|\mathbf{X}^t\beta - \mathbf{y}\|_2^2 + \alpha \|\beta\|_2^2 \implies \beta = (\mathbf{X}\mathbf{X}^t + \alpha \mathbf{I})^{-1}X\mathbf{y}$$

Ridge Regression

Questions:

How can unlabeled data be used ?

More general linear model with a dictionary of features ?

$$\|\mathbf{\Phi}_X \boldsymbol{\beta} - \mathbf{y}\|_{2,S}^2 + \alpha \mathcal{S}(\boldsymbol{\beta})$$

dictionary depends on data points

 $simplifies/stabilizes\ selected\ model$





Learning on/with Graphs

How can unlabeled data be used ?

Assumption:

target function is not globally smooth but it is locally smooth over regions of data space that have some geometrical structure



Use graph to model this structure





Transduction & Representation

More general linear model with a dictionary of features ?

- Φ_X dictionary of features on the complete data set (data dependent)
- M restricts to labeled data points (mask)

$$\arg\min_{\beta} \|\mathbf{y} - \mathbf{M} \mathbf{\Phi}_X \beta\|_2^2 + \alpha \mathcal{S}(\beta)$$

$$\underbrace{\mathsf{Empirical Risk}}_{\text{Empirical Risk}}$$

Model Selection penalty, sparsity ? Smoothness on graph ?

<u>Important Note:</u> our dictionary will be data dependent but its construction is not part of the above optimization





Sparsity and Transduction

$$\arg\min_{\beta} \|\mathbf{y} - \mathbf{M} \mathbf{\Phi}_X \beta\|_2^2 + \alpha \mathcal{S}(\beta)$$

Since sparsity = smoothness on graph, why not simple LASSO ?

$$\arg\min_{\beta} \|\mathbf{y} - \mathbf{M} \mathbf{\Phi}_X \beta\|_2^2 + \alpha \|\beta\|_1$$

Bad Idea:

We *know* there are strongly correlated coefficients (LASSO will kill some of them)





Scaling functions not sparse are optimized separately

Group potentially correlated variables (scales)



Few groups should be active = local smoothness Inside group, all coefficients can be active Formulate with mixed-norms $\|\beta\|_{p,q}$ Simple model, no overlap, optimized like LASSO





Preliminary Results



2-class USPS

Simulation results from Gavish et al, ICML 2010





5% labeled

recovered







Conclusions

- Processing data on graphs is still an emerging field.
- Interesting connections with other areas
- How to scale computations ?
- Diverse applications:
 - fMRI [Leonardi, Van de Ville, 2012], cortical smoothing
 - Network Analysis [Tremblay, Borgnat, 2012]
 - Learning, Distributed regularization [Shuman et al, 2012]



