

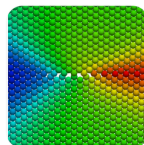
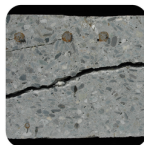
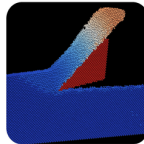
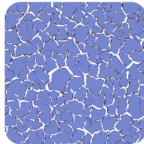
# Investigation of the size of plastic zones in nano indentation and nano scratching

Till Junge

J.-F. Molinari

W. Curtin

J. Song



# Outline

## Motivation

Description

Why look at plasticity in friction?

## Molecular Dynamics/Statics Approach

Virtual Experimental Setup

Method

Preliminary Results

## Extension to larger Systems

CADD

Requirements for CADD 3D

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Why look at plasticity in friction?

Molecular Dynamics/Statics Approach

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# Motivation

## Description

Friction converts mechanical Work  $W$  in

Heat  $Q$



Plastic work  $W_{pl}$



## Questions

- ▶ Role of plasticity in friction?
- ▶ Proportion of  $W$  ending up as  $W_{pl}$ ?

# Motivation

## Why look at plasticity in friction?

### Situation

Plastic effects are an important factor in friction, but

- ▶ they are **poorly understood**
- ▶ they are **rarely investigated**
- ▶ they are **hard to quantify**

# Motivation

## Why look at plasticity in friction?

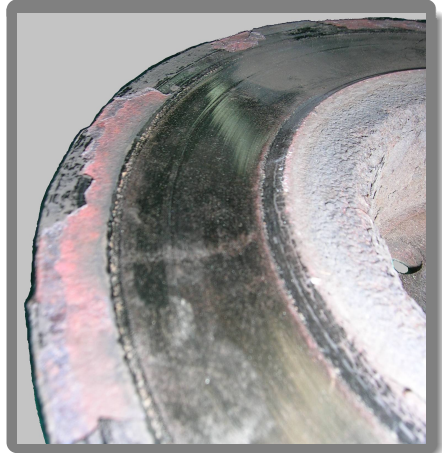
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Plastic effects are an important factor in friction, but

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### Interest

Plasticity in friction is the **source of wear and tear**



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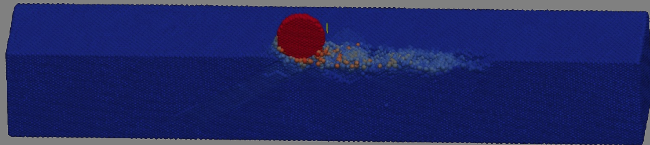
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# Molecular Dynamics/Statics Approach

## Virtual Experimental Setup

### Molecular Dynamics Scratching Simulation at $\sim 0$ K



### Advantages

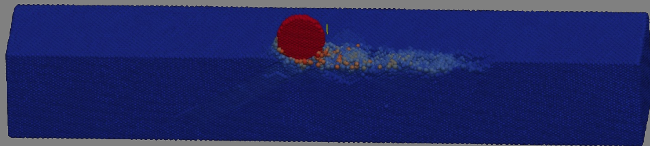
- ▶ very few a priori assumptions
- ▶ deep understanding because of complete knowledge of each atom in the simulation box



# Molecular Dynamics/Statics Approach

## Virtual Experimental Setup

### Molecular Dynamics Scratching Simulation at $\sim 0$ K



### Advantages

- ▶ very few a priori assumptions
- ▶ deep understanding because of complete knowledge of each atom in the simulation box

### Main Drawback

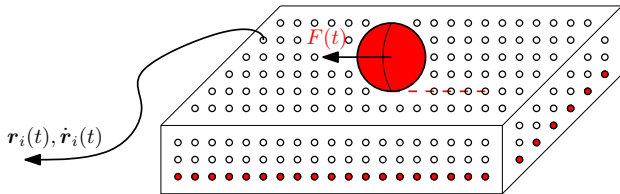
Very limited simulation box size and simulation time

# Molecular Dynamics/Statics Approach

## Method — Part I: the MD simulation

### Setup

- ▶ fixed boundary conditions for bottom atoms
- ▶ prescribed indenter path  $x(t)$

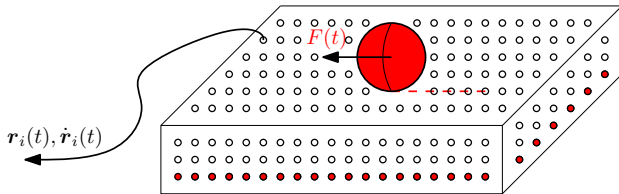


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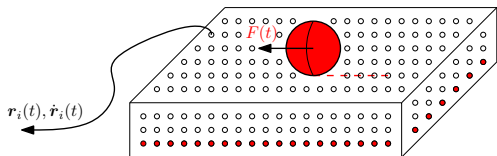


### At different time steps $t$

- ▶ Evaluate Force  $F(t)$  acting on the indenter,
- ▶ Save positions  $r_i(t)$  and velocities  $\dot{r}_i(t)$

# Molecular Dynamics/Statics Approach

## Method — Part II: the energy balance

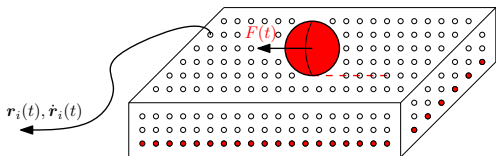


Energy influx

$$E_{\text{in}}(t) = \int_0^t F(t) dl$$

# Molecular Dynamics/Statics Approach

## Method — Part II: the energy balance



### Energy influx

$$E_{\text{in}}(t) = \int_0^t F(t) dl$$

### Stored as

$$\begin{aligned} E(t) &= E[\mathbf{r}_1(t), \dots, \mathbf{r}_N(t), \dot{\mathbf{r}}_1(t), \dots, \dot{\mathbf{r}}_N(t)] \\ &= \sum_{i,j,k,\dots} E_{\text{pot}}(\mathbf{r}_i, \mathbf{r}_j, \mathbf{r}_k, \dots) + \sum_i E_{\text{kin}}(\dot{\mathbf{r}}_i) \end{aligned}$$

# Molecular Dynamics/Statics Approach

## Method — Part II: the energy balance

### Stored Energy

$$E = \sum_{i,j,k,\dots} E_{\text{pot}}(\mathbf{r}_i, \mathbf{r}_j, \mathbf{r}_k, \dots) + \sum_i E_{\text{kin}}(\dot{\mathbf{r}}_i)$$

### Potential Energy

- ▶ empirical interatomic potential function
- ▶ here EAM potential for Cu:

$$E_{\text{pot}i} = F_{\alpha} \left( \sum_{i \neq j} \rho_{\alpha}(r_{ij}) \right) + \frac{1}{2} \sum_{i \neq j} \phi_{\alpha\beta}(r_{ij})$$

### Kinetic Energy

- ▶ Classic mechanics:

$$E_{\text{kin}i} = \frac{1}{2} m_i \dot{\mathbf{r}}_i^2$$

- ▶ summed over all atoms

# Molecular Dynamics/Statics Approach

## Method — Part II: the energy balance

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- ▶ summed over all atoms

**But we won't use this!**

# Molecular Dynamics/Statics Approach

## Method — Part III: Minimizing the potential energy

### Main Idea

Monitor variation of potential energy at 0 K:  $\Delta E_{\text{pot}}(0 \text{ K}) = W_{\text{pl}}$

### Problem

MD Snapshots  $\{r_i, \dot{r}_i\}(t)$  are **close** to Static Equilibrium ( $\sim 0 \text{ K}$ )



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### Solution

Molecular Statics:

$$E_{\text{pot}}^{\text{min}}(t) = \min_{\mathbf{R}=(\mathbf{r}_1, \dots, \mathbf{r}_N)} E_{\text{pot}}(\mathbf{R}(t))$$

$$W_{\text{pl}}(t) = E_{\text{pot}}^{\text{min}}(t) - E_{\text{pot}}^{\text{min}}(0)$$

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### Advertisement

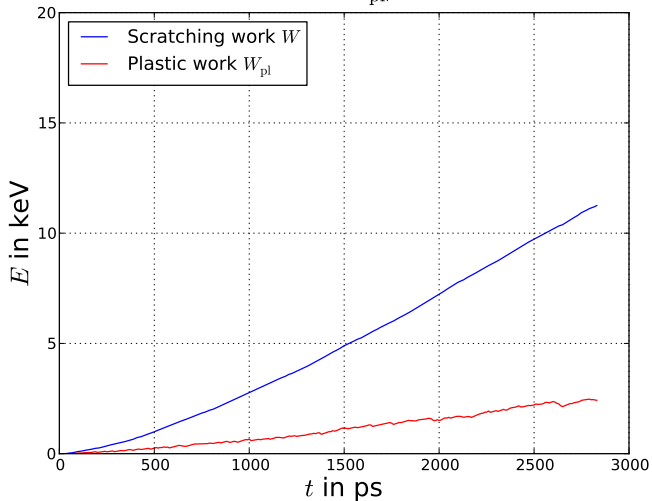
All molecular simulations:  
modified LAMMPS (**L**arge-scale  
**A**tomical/**M**olecular **M**assively  
**P**arallel **S**imulator):

**Libmultiscale**  
lsms.epfl.ch

# Molecular Dynamics/Statics Approach

## Preliminary Results — Plastic Energy

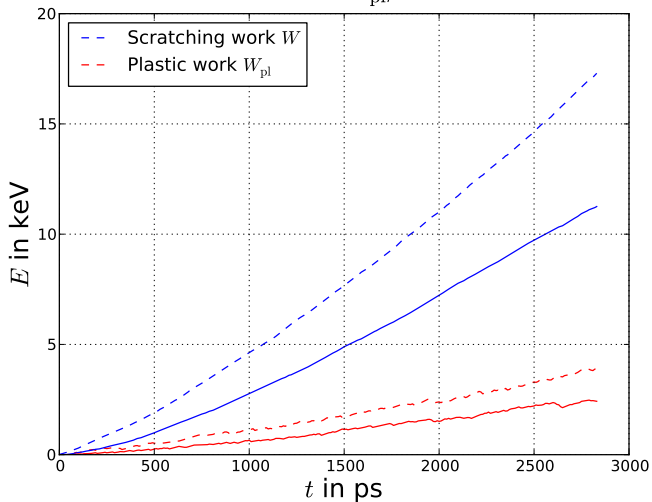
Scratch at 1 Å:  $W_{pl}/W=23.0\%$



# Molecular Dynamics/Statics Approach

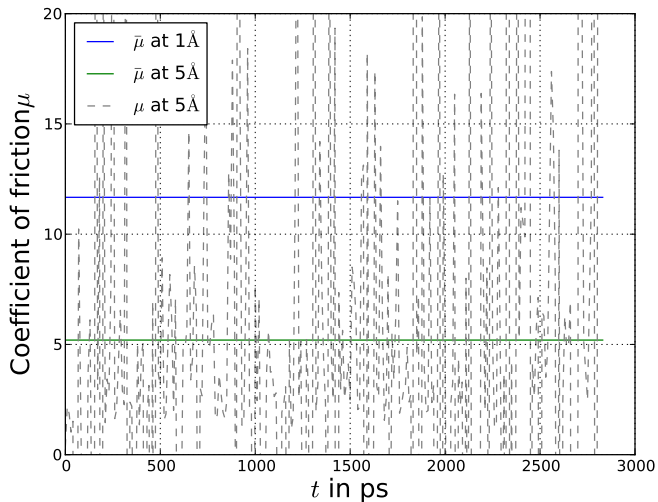
## Preliminary Results — Plastic Energy

Scratch at 5 Å:  $W_{pl}/W=23.8\%$



# Molecular Dynamics/Statics Approach

## Preliminary Results — Friction Coefficient



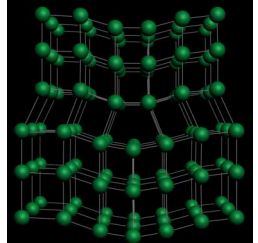
# Molecular Dynamics/Statics Approach

## Interlude - Preliminary Results — Dislocations

**Dislocation:** the “unit” of crystal plasticity

**Luan and Robbins** [Tribology Letters, 2009]:

$W_{pl} \sim \text{Count plastic events}$



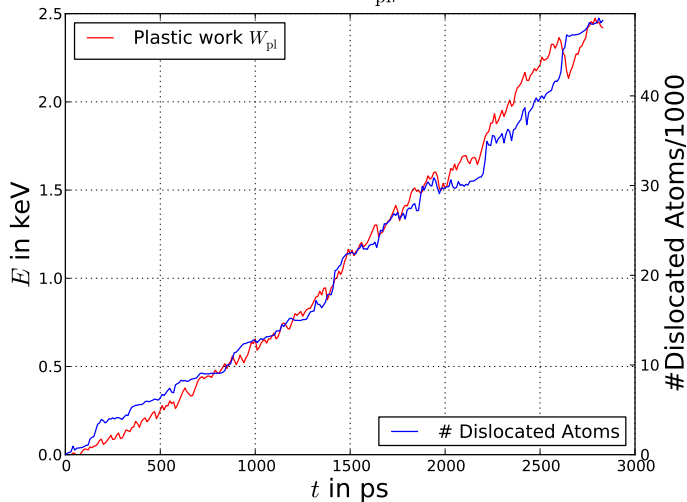
### Test

1. Count #atoms  $N$  which changed nearest neighbours
2. Plot  $N(t)$  over  $W_{pl}(t)$

# Molecular Dynamics/Statics Approach

## Preliminary Results

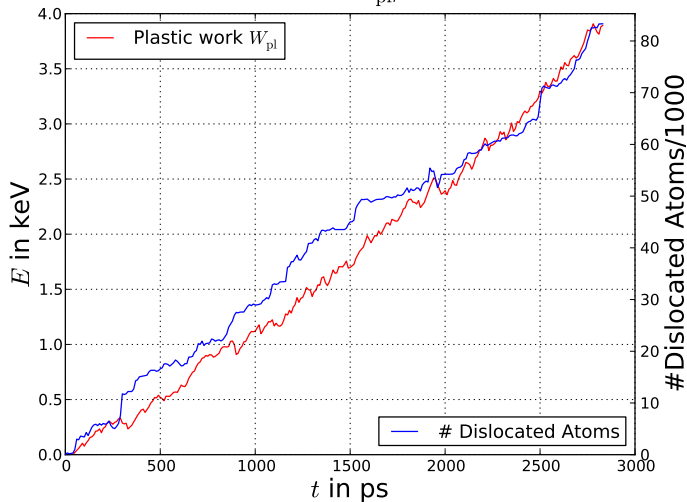
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# Molecular Dynamics/Statics Approach

## Preliminary Results

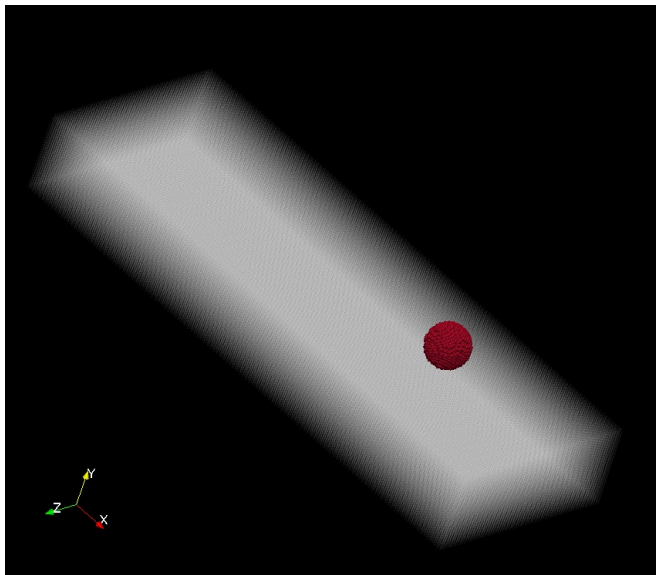
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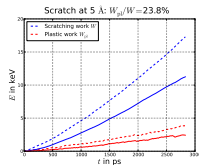
# Molecular Dynamics/Statics Approach

## Preliminary Results



### ► Method

Allows to **quantify**  $W_{pl}$  for a special case

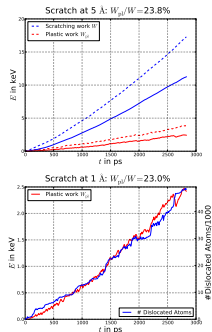


### ► Method

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### ► Results

Physically **intuitive**

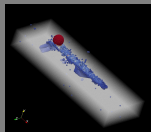
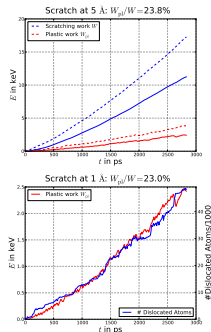


### ► Method

Allows to **quantify**  $W_{pl}$  for a special case

### ► Results

Physically **intuitive**



### ► But

Simulations are too small!

# Conclusions

- ▶ **The method is functional**  
It allows a clean separation between plastic and kinetic energy.
- ▶ **Dislocations get trapped at the sim box boundary**  
Inherent problem of Molecular Simulations
- ▶ **Limited to  $\sim 0\text{K}$  simulations**  
Thermal expansion prohibits mixed use of Molecular Dynamics  
**and** Statics

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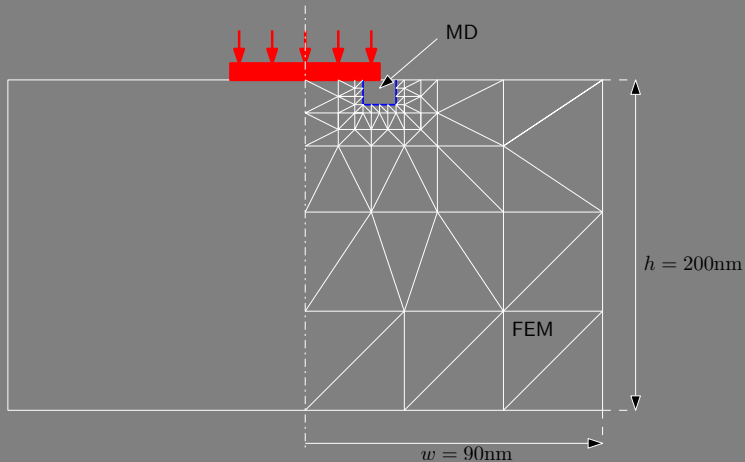
CADD

Requirements for CADD 3D

# Extension to larger Systems

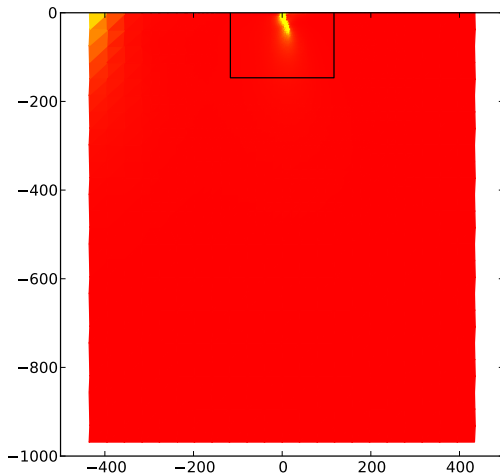
CADD

## Coupled Atomistics and Discrete Dislocations



# Extension to larger Systems

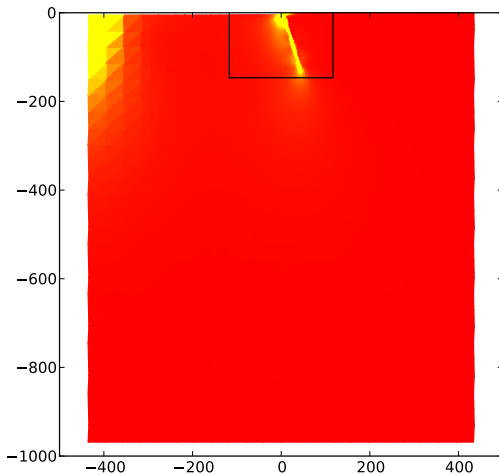
CADD





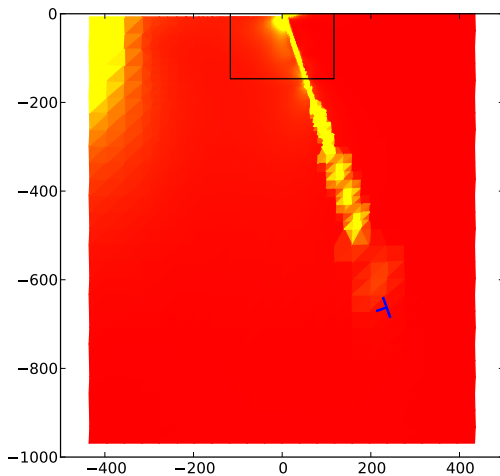
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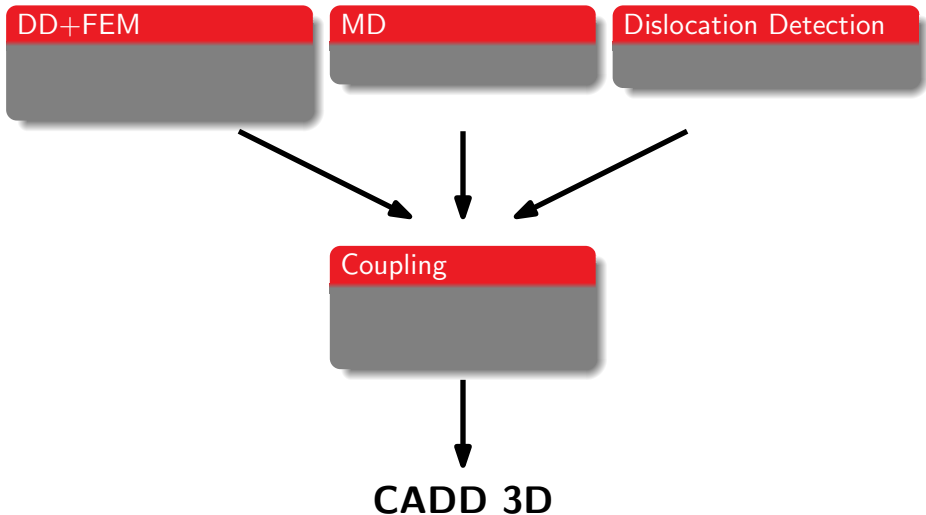
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# Extension to larger Systems

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# Extension to larger Systems

## Requirements for CADD 3D

DD+FEM

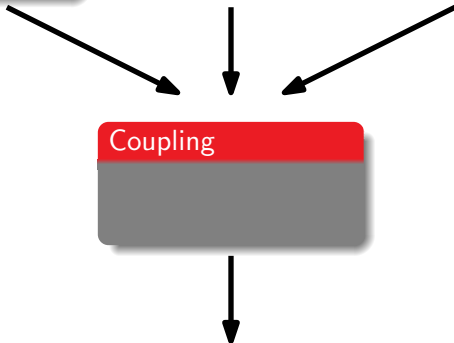
Weygand, Gumbsch  
2006

MD

Dislocation Detection

Coupling

CADD 3D



# Extension to larger Systems

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```
graph TD; A[DD+FEM] --> C[Coupling]; B[MD] --> C; D[Dislocation Detection] --> C; C --> E[CADD 3D]
```

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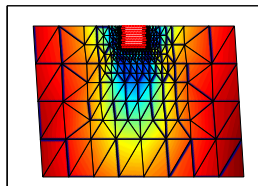
Libmultiscale  
lsms.epfl.ch

**CADD 3D**

# Extension to larger Systems

## Outlook

- ▶ **Couple MD to FEM/DD to avoid dislocation trapping**  
Requires 3D CADD [Curtin et al. JMPS 2008]



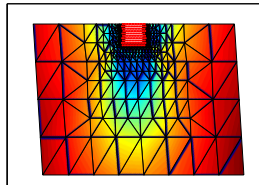


# Extension to larger Systems

## Outlook

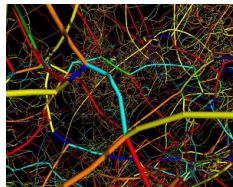
- ▶ **Couple MD to FEM/DD to avoid dislocation trapping**

Requires 3D CADD [Curtin et al. JMPS 2008]



- ▶ **Extension to finite  $T$  by computing dislocation self-energy**

Requires finding dislocation loops



Source: ParaDiS