The Vehicle Routing Problem with Discrete Split Delivery and Time Windows

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Outline

- Problem description and applications
- MILP formulation and Column Generation approach
- Branch & Price algorithm
- Computational experiments
- Conclusion

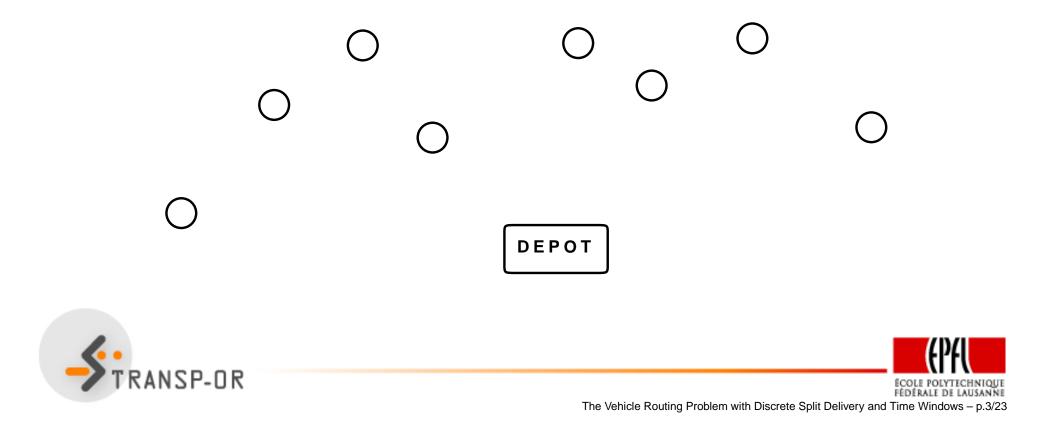




The Vehicle Routing Problem (VRP)

Given

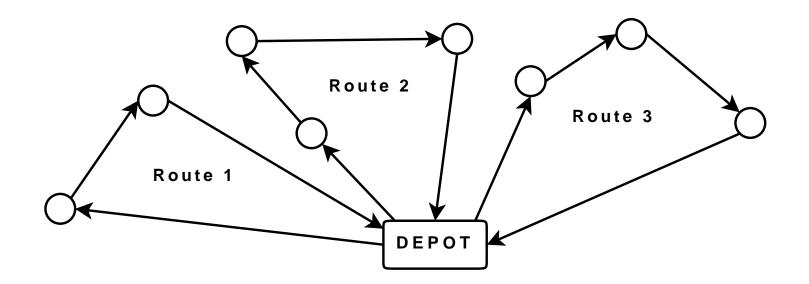
- set of customers with demands to be served (within time windows: VRPTW);
- set of capacitated vehicles available at a single depot;



The Vehicle Routing Problem (VRP)

Objective

- design the optimal minimum-cost routes for vehicles,
- such that every customer is visited exactly once.



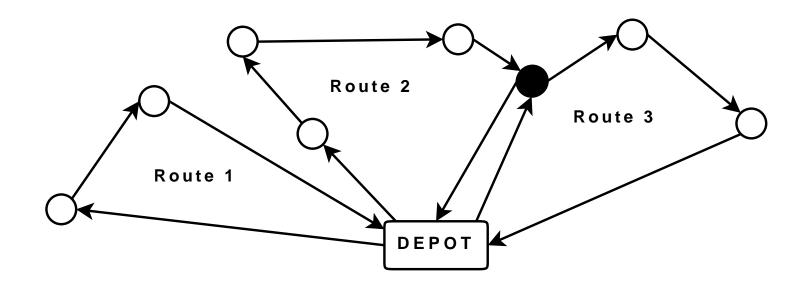




VRP with Split Delivery (SDVRP)

Splittable demand

- demand can be split and thus served by more than one vehicle;
- customers can be visited more than once.





VRP with Discrete Split Delivery (DSDVRP)

Nakao & Nagamochi (2007); Ceselli, Righini & Salani (2009)

- variant of VRP with split delivery;
- demand is discretized;
- the demand of each customer is represented by a set of items;
- items are grouped and delivered in orders (combinations of items);
- demand can be split but items cannot;
- service times depend on the quantity delivered;
- some combinations of items are not allowed.





Xu & Chiu (2001)

Problem description

- different types of jobs which require different skills;
- each technician is specialized in a field with certain skills;
- time windows on job starting and completion;
- assignment problem (jobs to technicians) + scheduling problem, where the duration of a job depends on the assignment.

Objective

• maximize the number of jobs completed within a time frame.





TBAP with QC assignment in container terminals

Giallombardo, Moccia, Salani & Vacca (2009)

Problem description

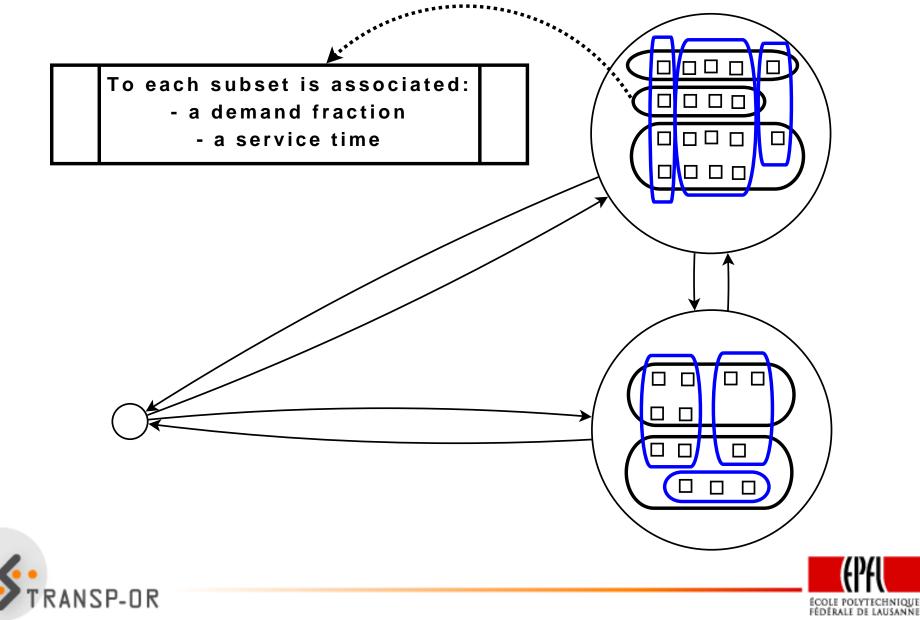
- Tactical Berth Allocation Plan (TBAP): assignment and scheduling of ships to berths;
- Quay-Cranes (QC) assignment: a QC profile (number of QCs per shift) is assigned to each ship;
- feasible profiles can vary in length (number of shifts dedicated to the ship) and in size (number of QCs dedicated to the ship in each active shift);
- time windows on ship arrival and on berth availabilities.

Objective

• maximize the value of chosen profiles.







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- G = (V, E) complete graph with $V = \{0\} \cup N$;
- (c_{ij}, t_{ij}) : cost and travel time of arc $(i, j) \in E$;
- N : set of customers $\{1, ..., n\}$; node $\{0\}$ represents the depot;
- K: set of vehicles with identical capacity Q;
- R: set of items; $R = \bigcup_{i \in N} R_i, R_i \cap R_j = \emptyset \ \forall i \neq j, i, j \in N;$
- C: set of combinations of items; $C = \bigcup_{i \in N} C_i, \ C_i \cap C_j = \emptyset \ \forall i \neq j, \ i, j \in N;$
- e_c^r : 1 if item $r \in R$ belongs to combination $c \in C$;
- t_c : service time of combination $c \in C$ such that $\max_{r \in R} e_c^r t^r \leq t_c \leq \sum_{r \in R} e_c^r t_r$;
- q_c : size of combination $c \in C$; $q_c = \sum_{r \in R} e_c^r t^r$;
- $[a_i, b_i]$: time window for customer $i \in N$.





Decision variables

- x_{ij}^k binary: 1 if arc $(i, j) \in E$ is used by vehicle $k \in K$, 0 otherwise;
- y_c^k binary: 1 if vehicle $k \in K$ delivers combination $c \in C$, 0 otherwise;
- $T_i^k \ge 0$: time when vehicle $k \in K$ arrives at customer $i \in N$.

Objective function

• minimize the total traveling costs:

$$z^* = \min \sum_{k \in K} \sum_{(i,j) \in E} c_{ij} x_{ij}^k$$

Constraints

- flow and precedence constraints;
- demand-satisfaction constraints;
- time-windows constraints;
- capacity constraints.





Flow and linking constraints

$$\sum_{j \in V} x_{0j}^k = 1 \qquad \forall k \in K,$$
(1)

$$\sum_{j \in V} x_{ij}^k - \sum_{j \in V} x_{ji}^k = 0 \qquad \forall k \in K, \, \forall i \in V,$$
(2)

$$\sum_{j \in V} x_{ij}^k = \sum_{c \in C_i} y_c^k \qquad \forall k \in K, \, \forall i \in N,$$
(3)

Covering constraints

$$\sum_{k \in K} \sum_{c \in C} e_c^r y_c^k = 1 \qquad \forall r \in R,$$

$$\sum_{c \in C_i} y_c^k \le 1 \qquad \forall k \in K, \forall i \in N,$$
(4)
(5)



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Precedence constraints

$$T_i^k + \sum_{c \in C_i} t_c y_c^k + t_{ij} - T_j^k \le (1 - x_{ij}^k)M \qquad \forall k \in K, \, \forall i \in N, \, \forall j \in V, \quad (6)$$
$$T_i^k - t_{0i} \ge (1 - x_{0i}^k)M \qquad \forall k \in K, \, \forall i \in N, \quad (7)$$

Time windows

$$T_i^k \ge a_i \sum_{j \in V} x_{ij}^k \qquad \forall k \in K, \, \forall i \in N,$$
(8)

$$T_i^k + \sum_{c \in C_i} t_c y_c^k \le b_i \sum_{j \in V} x_{ij}^k \qquad \forall k \in K, \, \forall i \in N,$$
(9)

Capacity constraints

NSP-OR

$$\sum_{c \in C} q_c y_c^k \le Q \qquad \forall k \in K.$$
(10)



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Dantzig-Wolfe reformulation

- *P* : set of feasible routes;
- c_p : cost of route $p \in P$;
- e_p^r : binary parameter equal to 1 if item $r \in R$ is delivered in route $p \in P$;
- λ_p : binary decision variable equal to 1 if route $p \in P$ is chosen;

Master problem

$$\min \sum_{p \in P} c_p \lambda_p \tag{11}$$

$$\sum_{p \in P} e_p^r \lambda_p = 1 \qquad \forall r \in R,$$
(12)

$$\sum_{p \in P} \lambda_p \le |K|,\tag{13}$$

$$\lambda_p \ge 0 \qquad \forall p \in P. \tag{14}$$





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Column generation scheme

Pricing subproblem

$$p^* = \arg\min_{p \in P} \{\tilde{c}_p\} = \arg\min_{p \in P} \{c_p - \sum_{r \in R} \pi_r e_p^r - \pi_0\}$$
(15)

where π_r are the dual variables associated to constraints (12) and π_0 is the dual variable associated to constraint (13).

Column generation

- if $\tilde{c}_{p^*} < 0$, then column p^* is added to the (restricted) master problem;
- otherwise, the current master problem solution is proven to be optimal.





Column generation scheme

Remarks

- the pricing subproblem is an Elementary Resource Constrained Shortest Path Problem (ERCSPP);
- the underlying network has one node for each order and transit time $(t_{ij} + t_c)$; Ceselli et al. 2009: one node for each item.





Branch & Price for the DSDVRPTW

- column generation approach;
- exact algorithm based on Branch&Price;
- pricing solved using bi-directional dynamic programming (Righini & Salani, 2006);
- branching rules:
 - 1. total number of vehicles;
 - 2. number of vehicles visiting a customer;
 - 3. flow on arcs.
- no additional cuts at master level.





Instances

- derived from Solomon's data sets R1, C1 and RC1 for the VRPTW;
- N = 25, 50 customers;
- Q = 30, 50, 100;
- the demand of each customer is discretized in 12 items;
- we generated 3 scenarios:

scenario	orders	description
А	3	full, 50-50%;
В	5	full, 50-50%, 75-25%;
С	7	full, 50-50%, 75-25%, 90-10%;
0	1	full order (unsplit case).





Computational results: 25 customers

			А		В		С	
class	nb_inst	Q	nb_solved	t	nb_solved	t	nb_solved	t
R1	12	30	12	87	10	694	6	1554
		50	11	342	6	463	5	522
		100	9	16	10	129	9	551
C1	9	50	9	273	0	Х	0	x
		100	3	947	0	Х	0	x
RC1	8	30	8	317	0	Х	0	Х
		100	8	222	2	1542	0	х





Computational results: 50 customers

			А		В		С	
class	nb_inst	Q	nb_solved	t	nb_solved	t	nb_solved	t
R1	12	30	1	3011	0	Х	0	х
		50	1	1527	0	Х	0	х
		100	2	120	2	509	1	93
RC1	8	50	7	723	0	Х	0	х
		100	1	1953	0	Х	0	х





Summing up

- time limit: 1 hour;
- 69% (A), 32% (B) and 23% (C) instances solved for 25 customers;
- 14% (A), 2% (B) and 1% (C) instances solved for 50 customers;
- difficulty increases with the number of customers and with the number of orders;
- split deliveries are more frequent with small values of Q;
- in some cases, split deliveries not only decrease the total traveling costs but also allow to save one vehicle.





Conclusions

- finding optimal solutions is difficult, already with a small number of orders;
- only a limited number of instances with 50 customers could be solved;
- the bottleneck is the pricing problem:
 - the underlying network is huge (one node per each order!)
 - how to efficiently handle this feature of the problem?





Thanks for your attention!





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