

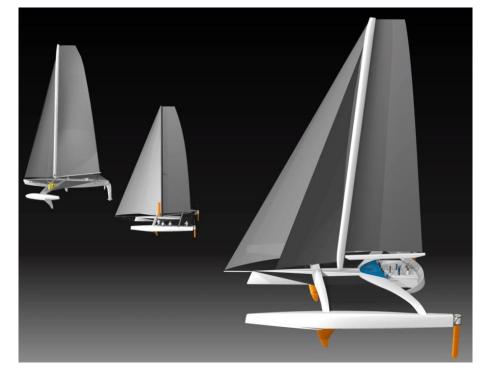
# HOW MULTIDISCIPLINARY SCIENTIFIC RESEARCH MAY HELP BREAK THE SAILING SPEED RECORD



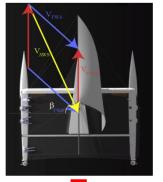
M. Calmon & al., EPFLHydroptère Design Team

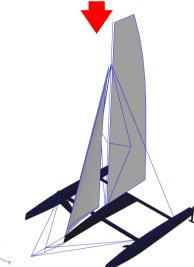
- l'Hydroptère
  - □Lift of hydrofoils, complete balance of weight □Drag reduction, high performances
- Sailing speed records
  - □Channel, 2005
  - □Outright 500m & 1NM
  - □Back to offshore
- ■Complex problems to solve
  - □Trans-disciplinary project
  - □EPFL scientific partnership
- New challenges
  - □Versatility
  - □Reliability
- Future projects
  - □l'Hydroptère.ch
  - □l'Hydroptère Maxi



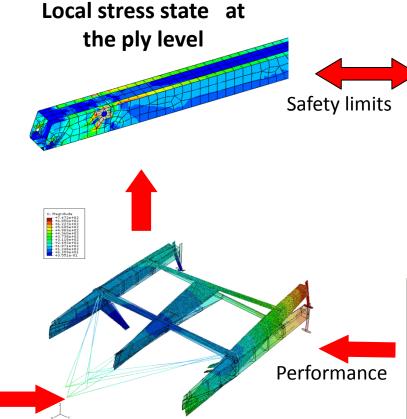


## Load case & sailing conditions

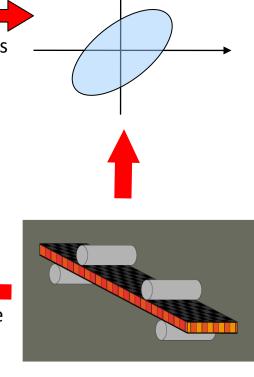




**CAD & FE Model** 



Global deformations & vibration modes

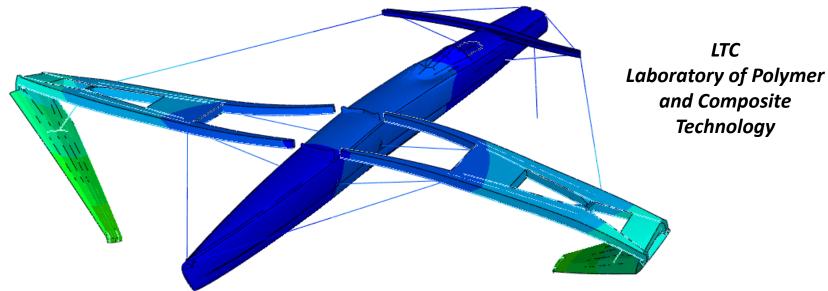


Failure criteria

Material design & mechanical testing

LMAF
Laboratory of Applied Mechanics
and Reliability Analysis

l'Hydroptère Design Team



CVLab
Computer Vision Laboratory

LMH Hydraulic Machines Laboratory

#### ■4 sub-systems:

- □Stress & positioning sensors (HBM digiCLIP)
- □Navigation unit (B&G WTP2)
  □Inertial unit (IXSEA Octans)
- □Video system (Cosworth Pi VIDS2)
- **■**CAN-bus
- ■Data logger & ruggedized computer
  - □Cosworth Pi Sigma LLB
  - □Lemer Pax Posibox
- Motivation
  - □Real-time load analysis
  - □Feedback on dynamic behavior

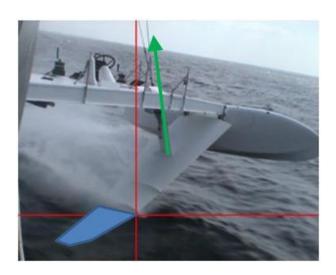


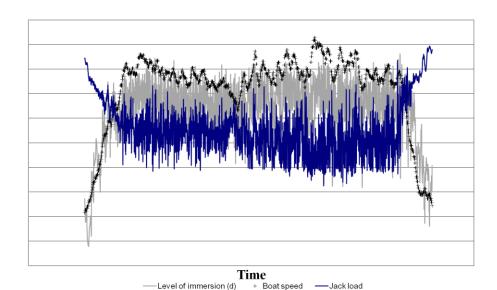




## Foil Immersion Detection

- Motivation
  - □Platform motions with reference to water surface
  - □Refined foil loads
- Measurement system integration
  - □Synchronization





## Foil Immersion Detection

- ■Refraction-based principle

  □Move along the foil leading edge

  □Look for a change of slope
- Algorithm keypoints
  - □Functional maximization □Kullback-Leibler divergence

$$F(d,\theta) = \frac{D_{KL}(P,Q) + D_{KL}(Q,P)}{2}$$
$$= \frac{1}{2} \sum_{i=0}^{255} P(i) \log \frac{P(i)}{Q(i)} + Q(i) \log \frac{Q(i)}{P(i)}$$

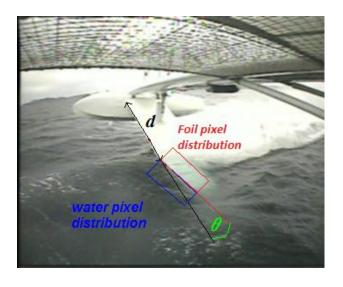


- □Changing light conditions
- □ Reflections
- □Blurred images by spray drops

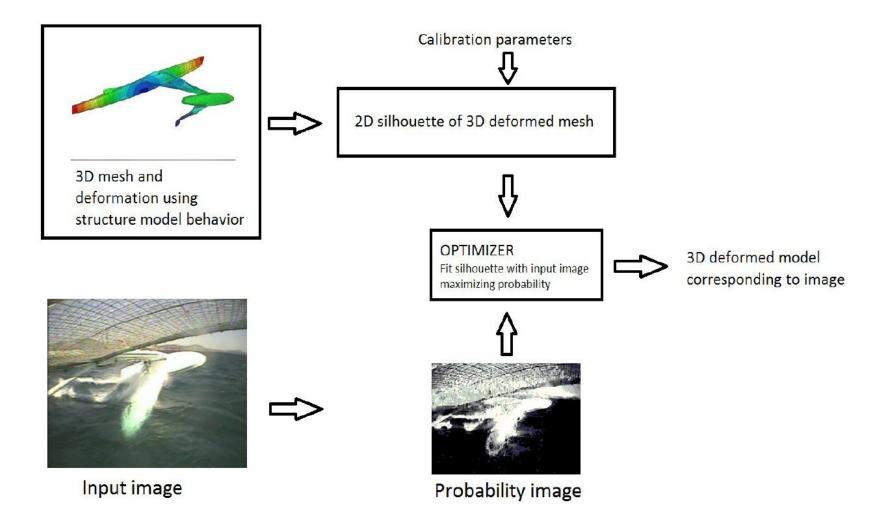








## **Cross-Beam Torsion**



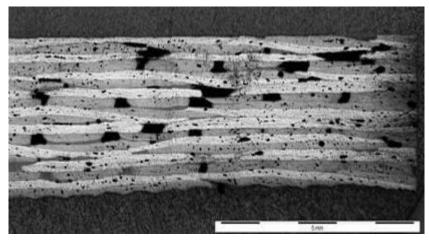
## Manufacturing Processes

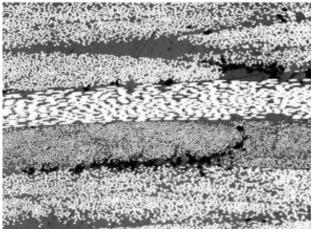
- Shipyard practice (Decision SA)
- Processing methods studies
  - □Heating rate
  - □Applied pressure
  - Draping sequence
- ■Part quality control
  - □Micrographic visual inspection □Curing stage (DSC, DMA)

#### Sound composite



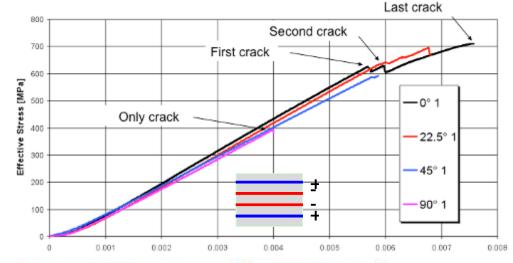
#### **Process-induced porosity**





## **Monolithic Parts**

- Off-axis plies in thick laminates
- ■Role on failure mechanisms
- ■4-pt bending
- Design rules



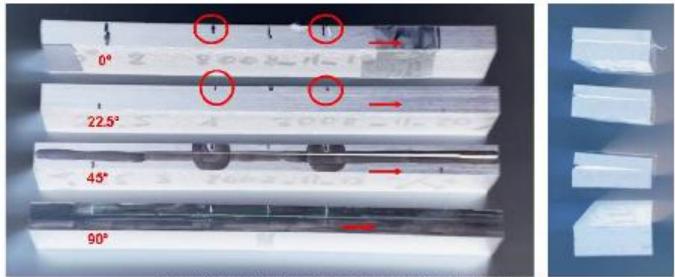
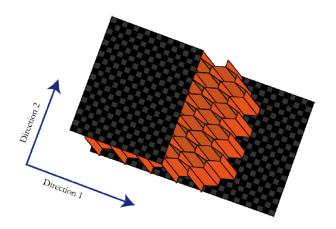


Figure 6-4: Examples of some of the specimens tested. Front and side views

## Sandwich Structures

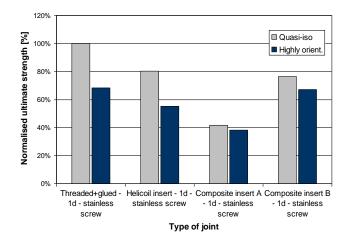
- Behaviour identification
- Anisotropic honeycomb (Nomex Flexcore)
- Preliminary tests
  - □Tension, compression and shear for the skins
- ■4-pt bending
  - □Several span lengths
  - □Core shear modulus
- Structural model updating



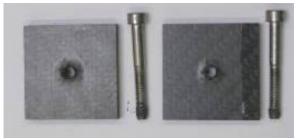


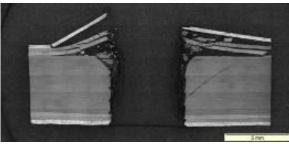
## **Threaded Joints**

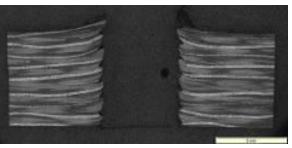
- Joining metallic to composite parts
- Joint strength influenced by:
  - □Stacking sequence
  - □Insert
  - □Screw
  - **□Glue**
  - ■Thread length
- Special testing device
  - □Screw pulling-out

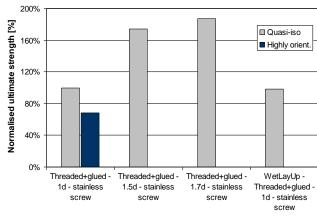










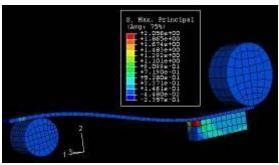


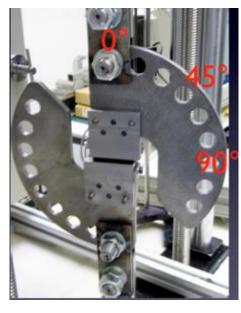
## **Bonding**

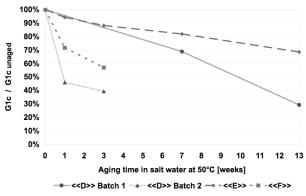
- Joining Titanium to composite parts
- Surface treatment investigations
- Fracture strength measurements

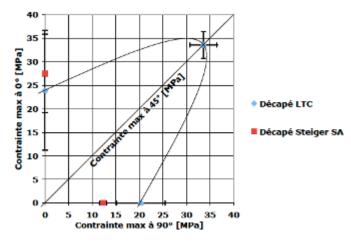
  □ Griffith's critical strain energy release rate  $G_{lc}$
- Accelerated aging tests
- ■Cohesive zone model in Abaqus
  - □Previous fracture test
  - □Extended failure criteria test











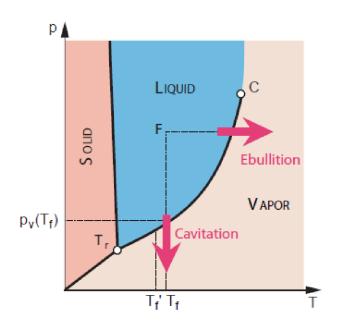
## Hydrodynamic Phenomena

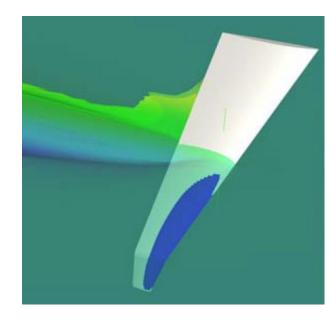
#### Cavitation

- □Formation of vapour cavities in low pressure zones
- □Almost impossible to avoid with high speeds
- □Alteration of hydrodynamic performances
- □Vibrations

#### ■Ventilation

□Air from above the free surface sucked into low pressure zones below the surface □Drop in lift



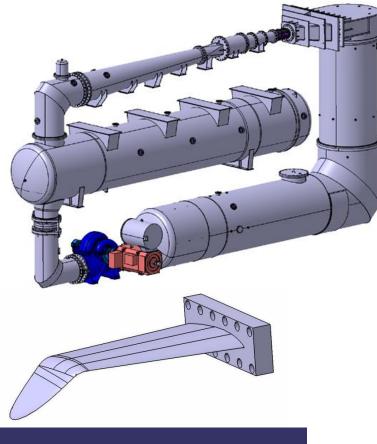


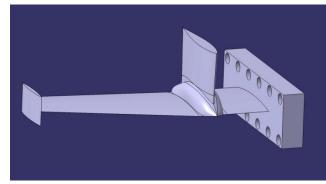
$$\sigma = \frac{p - p_y}{\frac{1}{2}\rho V^2}$$

## **Experimental Context**

- EPFL high speed cavitation tunnel
  - □150mm square test section
  - □Pressure controlled from 0.02 to 1.6MPa
  - □Inlet flow velocity up to 50m/s
  - □Angle of attack control
  - □5-axis balance for force measurement
  - □Strobe, digital camera
  - □Flash lamps, high speed video camera
- ■l'Hydroptère specific tests
  - □1/10<sup>th</sup> scaled models of foil and rudder/stabilizer
  - □Developed turbulent boundary layer (V>15m/s)
    □ adjustment for cavitation similitude above 50kt

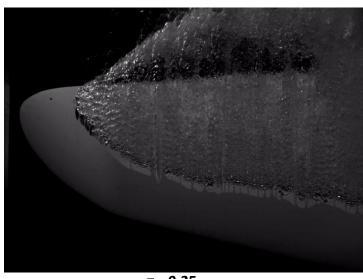


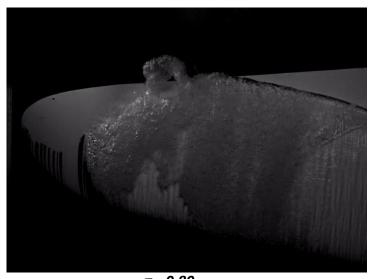




## **Experimental Cavitation**

- Attached cavitation
- Angle of attack dependence
- ■Low angles (left):
  - □Long thin cavity starting downstream leading edge (sheet cavitation)
  - "Smooth" flow, low vibrations
- High angles (right):
  - $\Box$ Cavitation inception even for higher  $\sigma$
  - □Cavity detachment moves upstream until leading edge
  - □Pulsed cavities (cloud cavitation)
  - □Lift fluctuations, high vibrations





 $\sigma$  = 0.25

### Simulated Cavitation

#### Numerical context

□3D RANS solvers ANSYS FLUENT & CFX

 $\square$ Realizable k- $\varepsilon$  turbulence model

□Multi-phase simulation with VOF method

#### Cavitation models

□Low pressure "contouring"

**DEFLUENT Mixture model** 

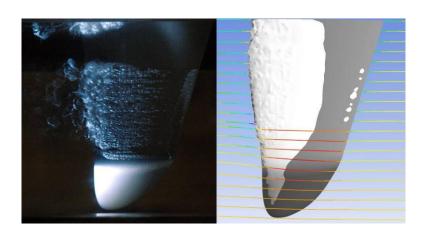
□CFX three phase flow model

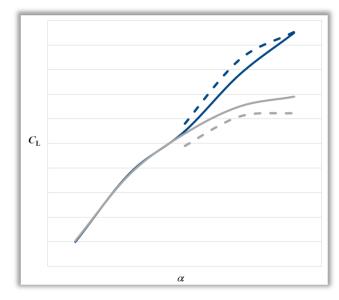
#### Simulation validations

□Experimental tests in EPFL cavitation tunnel

□Visual comparisons

□Hydrodynamic loads variations

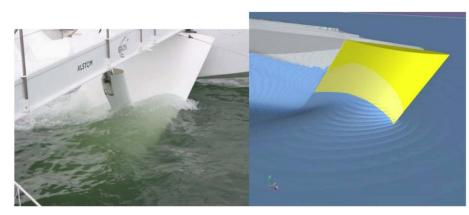


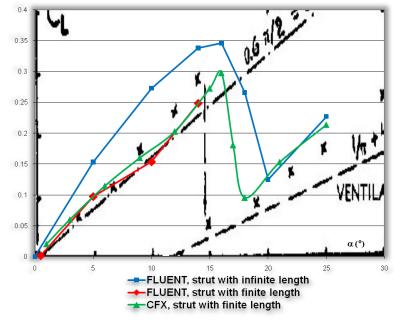


High  $\sigma$ =0.49 and low cavitation (—) Low  $\sigma$ =0.31 and strong cavitation (—) (- - - Simulation, — Experiments)

### Simulated Ventilation

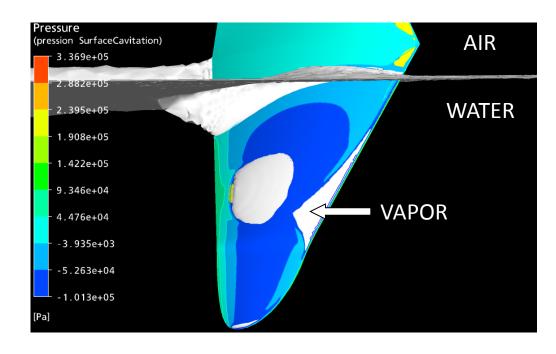
- Numerical context
  - □3D RANS solvers ANSYS FLUENT & CFX
  - $\square$ Realizable k- $\varepsilon$  turbulence model
  - □Multi-phase simulation with VOF method
- Simulation validations
  - ■No new experimental tests
  - □Visual comparisons during sea trials
  - □Bibliography test case
- ■Hoerner, Fluid-Dynamic Drag, 1965
  - □Dingee experiments, 1953
  - Davidson Laboratory, NJ, USA
  - □Slender surface-piercing strut
  - □Loads variation according to angle of yaw





## Simulated Real Case

- •Numerical context
  - □3D RANS solver ANSYS CFX
  - $\square$ Realizable k- $\varepsilon$  turbulence model
  - □Multi-phase simulation with VOF method
- Three-phase simulations
  - □Cavitation
  - □Flat free surface (ventilation)
  - □Steady state conditions
- Optimization process
  - ■Manual iterations
  - □High lift/drag ratio
  - □Low tendency to ventilation
  - □Low tendency to cavitation

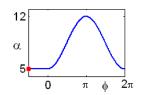


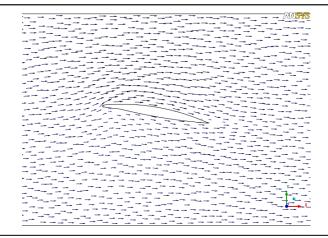
## Foil shape optimization

- Optimization process
  - □Multi-objective procedure
  - □Evolutionary algorithms
  - □Towards a more tolerant design
- Numerical context
  - □3D URANS solver ANSYS CFX
  - □Single phase flow
  - SST turbulence model
- Test case
  - □2D hydrofoil in tunnel test section
  - □Constant upstream velocity
  - □Pitch motion
- Optimization parameters
  - □Lift/drag ratio in nominal conditions
  - □Tendency to separation
  - □Tendency to cavitation









## **Optimization Validations**

#### Experimental validation

□Lift and drag measurements

□2 profiles: initial, Pareto-optimal solution

#### Observations

□Qualitative agreement

 $\Box$ Drag increase postponed to higher  $\alpha$ 

□Quantitative discrepancies

□Drag underestimated

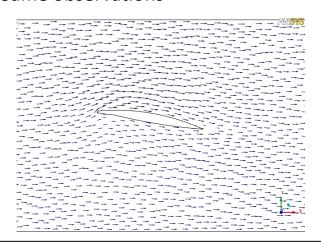
□Too late stall

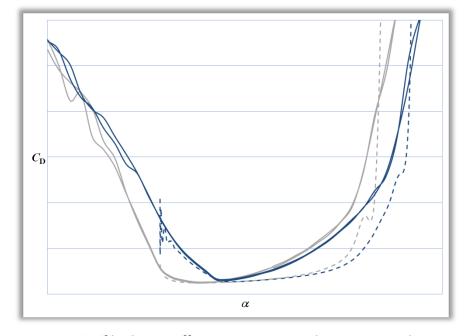
#### Further tests

□RANS/exp. comparisons

□NACA0009 profile

□Same observations





Profile drag coefficient; comparison between initial profile (—) and Pareto-optimal profile (—)

(- - - URANS simulation, — experiment)

## Large Eddy Simulation (LES)

#### •Numerical context

□OpenFOAM solver □Large scales of the flow □α=11°, V=5m/s

#### Observations

□Unsteady detached flow and vortex streets □From the leading edge and far before stall

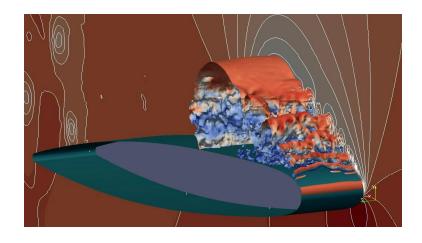
#### ■Validation

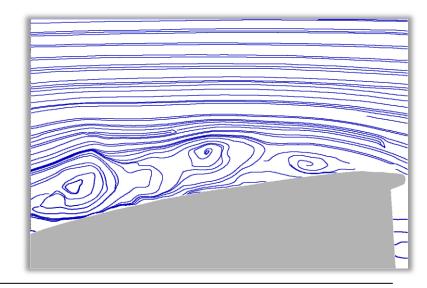
□Cavitation visualization

□PIV

□Drag value







- Optimization simulations with HPC
  - □Licensing constraints
  - □Open-source software solutions (OpenFOAM...)
- Fluid-structure interaction
  - □Dynamic behaviour of sandwich structures in waves (slamming)
- Fluid-structure instabilities (divergence, flutter)
  - □Foil alone
  - □Whole platform
- Advanced Measurements systems
  - □Visual cross beam torsion finalization
  - □FBGS use investigations
  - Identification and monitoring developments
  - Dynamic stability visual alarms







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