Formal Semantics for Refinement Verification of Entreprise Models

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PAR

Irina RYCHKKOVA

Master of Applied Mathematics and Physics, Moscow Institute of Physics and Technology, Russie
et de nationalité russe

acceptée sur proposition du jury:
Dr M. Rajman, président du jury
Prof. A. Wegmann, directeur de thèse
Dr T. Baar, rapporteur
F. Bouchet, rapporteur
Prof. V. Kuncak, rapporteur
To Valentin
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Abstract

In this dissertation we investigate how Business/IT alignment in enterprise models can be enhanced by using a software engineering stepwise refinement paradigm.

To have an IT system that supports an enterprise and meets the enterprise business needs, management seeks to align business system with IT systems. Enterprise Architecture (EA) is the discipline that addresses the design of aligned business and IT systems. SEAM is an Enterprise Architecture method, developed in the Laboratory of Systemic Modeling (LAMS) at EPFL. SEAM defines a visual language for building an enterprise model of an organization. In this work, we develop a theory and propose a technique to validate an alignment between the system specifications expressed in the SEAM language.

We base our reasoning on the idea that each system (an organization, a business system, or an IT system) can be modeled using a set of hierarchical specifications, explicitly related to each other. Considering these relations as refinement relations, we transform the problem of alignment validation into the problem of refinement verification for system specifications: we consider that two system specifications are aligned if one is correctly refines the other.

Model-driven engineering (MDE) defines refinement as a transformation between two visual (or program) specifications, where a specification is gradually refined into an implementation. MDE, however, does not formalize refinement verification. Software engineering (SE) formalizes refinement for program specifications. It provides a theory and techniques for refinement verification.

To benefit from the formal theories and the refinement verification techniques defined in SE, we extend the SEAM language with additional concepts (e.g. preconditions, postconditions, invariants, etc). This extension enables us to increase the precision of the SEAM visual specifications. Then we define a formal semantics for the extended SEAM modeling language. This semantics is based on first-order logic and set theory; it allows us to reduce the problem of refinement verification to the validation of a first-order logic formula.

In software engineering, the tools for the automated analysis of program specifications are defined. To use these tools for refinement verification, we define a translation from SEAM visual specifications to formal specification languages.

We apply, using case studies, our theory and technique in several problem areas to verify: (1) if a business process design and re-design correspond to high level business process specifications; (2) if a service implementation corresponds to its specifications. These case studies have been presented to a group of domain experts who practice business/IT alignment. This inquiry has shown that our research has a potential practical value.

Key words: Business/IT alignment, visual modeling, formal semantics, refinement, refinement verification, SEAM, Alloy, Jahob.
Résumé

Dans cette thèse nous étudions comment l'alignement Business/IT dans des modèles d'entreprise peut être améliorée en utilisant le 'raffinement par étapes' – un paradigme développé en génie logiciel.

Pour obtenir un système informatique qui répond aux besoins de l'entreprise, la direction vise à aligner les systèmes informatiques avec le métier. L’Architecture d’Entreprise (EA) est la discipline qui étudie et développe des théories et méthodes pour cet alignement. SEAM est une méthode d’architecture d’entreprise, développée dans le Laboratoire de modélisation systémique (LAMS) à l’EPFL. Dans cette thèse, nous développons une théorie et proposons une technique de validation d’alignement entre les spécifications exprimées dans le langage de modélisation SEAM.

Nous fondons notre raisonnement sur l'idée que chaque système (une organisation, un système d'entreprise, ou un système d'information) peut être modélisé en utilisant un ensemble de spécifications hiérarchiques, explicitement liés les uns aux autres. En repensant ces relations comme des ‘relations de raffinement’, nous transformons le problème de l'alignement entre spécifications au problème de validation de raffinement entre ces spécifications. Nous considérons que deux spécifications du système sont alignées si ce raffinement est correct.

Le concept de raffinement est défini en Model-Driven engineering (MDE) comme une transformation entre deux spécifications visuelles où une spécification est progressivement affinée et détaillée jusqu’au niveau d’implémentation. Cependant, les règles de la vérification pour le raffinement ne sont pas formalisées en MDE. Le concept de raffinement pour logiciel a été formalisé en génie logiciel. Le génie logiciel fournit, d'ailleurs, une théorie et des techniques pour la vérification du raffinement. Pour bénéficier de ces théories et techniques, nous étendons SEAM avec des concepts de modélisation supplémentaires. Cette extension nous permet d'augmenter la précision de nos spécifications visuelles. Nous définissons une sémantique formelle pour le langage visuelle de SEAM. Cette sémantique est basée sur la logique de premier ordre et sur la théorie des ensembles. Elle nous permet de réduire le problème de la vérification de raffinement à la validation d’une formule de premier ordre.

Pour utiliser les outils d'analyse automatique des spécifications de logiciels dans le contexte des spécifications visuelles, nous définissons une traduction des spécifications SEAM dans un langage de spécifications formelle.

Nous appliquons la théorie et les techniques que nous avons développées à plusieurs domaines: (1) à la vérification des processus métier par rapport aux spécialisations d’organisation de haut niveau; (2) à la vérification d'une implémentation de service par rapport à ses spécifications. Ces études de cas ont été présentées à un groupe d'experts du domaine qui pratiquent l’alignement Business et IT. Cette enquête a montré que notre recherche a potentiellement une valeur pratique.

Mots-clés: alignement Business/IT, spécifications visuelles, sémantique formelle, raffinement, vérification de raffinement, SEAM, Alloy, Jahob.
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Chapter 1

Introduction

In providing services to stakeholders, many organizations depend heavily on their IT infrastructure. Insuring that IT does what business needs is a very important issue for management and is achieved by Business-IT alignment. Business-IT alignment is defined in [110] as “... an ongoing process that will optimize the relational mechanisms between the business and IT organization by working on the IT effectiveness of the organization in order to maximize the business value from IT.”

Enterprise Architecture (EA) is the discipline that addresses the design of aligned business systems and IT systems. Enterprise Architecture methods provide techniques, tools, and guidelines for building an enterprise model of an organization.

Traditionally, an enterprise model is a set of visual specifications of an organization that has a hierarchical structure. Each hierarchical level specifies an organization from different perspectives, e.g. business, organizational, or IT. The main challenge of enterprise modeling is to insure that the specifications representing an organization at the IT level correspond to the specifications at the higher levels, where the value for this organization is defined.

1.1 Business /IT Alignment vs. Stepwise Refinement

Enterprise models are mostly represented in graphical form that we call visual specifications. The main advantage of visual specifications is that they enable discussion about the model among different stakeholders. However, the lack of precision and formally-defined semantics makes a further analysis (such as a comparison of different versions of the model, or an alignment validation between models) complicated, if at all possible.

Software Engineering (SE) provides an underlying theory and a set of techniques for program specification analysis. Program specifications, similarly to visual specifications, are used to describe systems: their construction and functionality.

Stepwise refinement is a paradigm for semantic program construction, originally proposed by Dijkstra [31] and Wirth [111]. It is based on the idea that a program can be developed through a sequence of refinement steps starting from an abstract specification. At each step, the refined (‘concrete’) specification is proven to be a correct refinement of the ‘abstract’ specification.

In this dissertation, we make a correspondence between program specifications in SE and visual system specifications in order to benefit from theories and tools exist for program specification analysis.

We explore the idea that, similarly to program specifications, each visual specification can be seen as a refinement of another visual specification. This describes the organization at a more abstract organizational level.

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1 In this work, we will use the generic term system to discuss organizations, business systems, IT systems, and their alignment.
As a main contribution of this dissertation, we reduce the problem of alignment verification in enterprise visual specifications to the problem of refinement verification, defined for program specifications in SE.

1.2 Verification of Refinement

Refinement correctness for programs is validated by establishing simulation relations [65] between the abstract and concrete specifications. In other terms, the refinement is correct if the concrete specification simulates the abstract specification.

A simulation relation R (also called a refinement relation) puts into correspondence the states of abstract and the concrete specifications. The concrete specification is said to be a correct refinement of the abstract specification when, starting at the corresponding initial states, both specifications will terminate in the corresponding final states (Fig. 1-1).

![Refinement verification by simulation.](image)

The same way, we define semantics for visual system specifications in terms of states and transitions between them. Therefore, the refinement verification schema, illustrated in Fig. 1-1, is also valid for visual specifications. We proceed with an automated validation of refinement, providing a mapping of visual specifications to a formal language, for which tools for automated analysis already exist.

1.3 The SEAM Method for Enterprise Architecture

We implement the theory of refinement verification in order to validate the alignment between systems specified in SEAM [108]. SEAM is an Enterprise Architecture (EA) method that provides a visual notation for modeling systems, including business and IT systems.

In SEAM, a system is represented by a working object. A SEAM model of a system contains a set of specifications of the working object structured in two hierarchies: an organizational level hierarchy and a functional level hierarchy.

A working object, modeled as a whole at one organizational level, can be represented as a composite on the next organizational level. This maintains the explicit traceability between organizational levels.

Fig. 1-2 (a) illustrates a working object WObject1 as a whole; Fig. 1-2 (b) illustrates this working object on the next organizational level (i.e., seen as a composite).

A working object, as a whole, has properties and localized actions; A working object, as a composite, has component working objects and joint or distributed actions between them.
A property or an action, modeled as a whole at one functional level, can be represented as a composite on the next functional level. This maintains the explicit traceability between functional levels:

**1.4 Alignment Validation vs. Refinement Verification in SEAM**

This work applies the paradigm of stepwise refinement for SEAM specifications and describes how SEAM specifications can be aligned and how this alignment can be validated.

To rigorously reason about SEAM specifications and their refinements, we provide a formal semantics for SEAM specifications and their refinements, based on set theory and first-order logic (FOL). To formalize the criteria of refinement correctness, we use a theory of data refinement from [72][51][101] and more generalized form of refinement from [15][16].

Based on the formal semantics, we specify a mapping of SEAM visual specifications to the specification languages (e.g. Alloy [59], Jahob [63]) for further refinement verification. We interpret the result of refinement verification as the validity of the alignment between visual specifications.

The contributions of this dissertation can be summarized as follows:

- Formalization of the initial set of SEAM modeling concepts using first-order logic;
- Classification of SEAM refinements;
- Identification of the modeling concepts, missing in the current version of SEAM and required for refinement verification (i.e. action preconditions, postconditions etc.);
- Formalization of the initial set of SEAM modeling concepts;
- Definition of refinement correctness for SEAM using a forward simulation for data refinement from [72][65] and generalized forward simulation from [16];

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2 FOL is a system of formal reasoning also known as a first-order predicate calculus [53][18].
• Mapping of SEAM specifications to the Alloy specification language [59] for the validation of refinement using the Alloy Analyzer tool;
• Mapping of SEAM specifications to the Jahob formulae [63] in order to generate a formal proof of refinement correctness using the Jahob formDecider.

1.5 The Structure of this Document

In Chapter 2 of this document, we analyze the state of the art. It comprises (a) theoretical foundations in specification development using refinement, formal refinement verification, and visual modeling and (b) practical applications of modeling techniques developed in academia and in the industry.

In Chapter 3 we present the SEAM method. This work extends the original set of SEAM modeling concepts. In this chapter, we specify the graphical notation and semantics for the extended SEAM language.

In Chapter 4 we present the formalization of SEAM modeling concepts using first-order logic (FOL).

In Chapter 5 we classify refinements in SEAM and specify correctness for each refinement type. We use forward simulation for data refinement and generalized forward simulation, defined in the ASM refinement method, as proof methods for refinement correctness. We reduce a problem of refinement verification in SEAM to a proof of validity of a corresponding FOL-formula.

In Chapter 6 we present two techniques for the automated refinement verification in SEAM: The first technique is based on use of the Alloy Analyzer - a tool for analyzing models written in the Alloy specification language; the second technique is a formal proof of refinement correctness in the Jahob verification system.

In Chapter 7 we present the practical impact of the developed theory. In this chapter, we discuss in detail two examples that illustrate how the achievements of this thesis can be implemented to verify:

(1) If business process design and re-design correspond to the high level business process specification (Book Store example);
(2) If service implementation corresponds to its specification (SIG example).

In Chapter 8 we present our conclusion and discuss a future work.

At the beginning of each chapter, we give an overview of the chapter’s content.

For the reader interested in business / IT alignment and the practical aspects of the proposed theory, we recommend reading Chapter 2: it provides a state of the art. Then read briefly Chapters 3 and 6, where the SEAM notation and the rules of transformation of SEAM models to formal specifications are explained. And then proceed with Chapters 7 and 8: they illustrate our technique on the examples and provide a practical feedback.

For the reader interested in modeling languages and their semantics, we recommend reading Chapters 2, 3, 4 of this document, then proceed with Chapters 6 and 7.

For the reader interested in formal methods and their implementation, we recommend reading Chapters 3, 4, 5, 6, and 7 of this document.
Chapter 2

The State of the Art

This dissertation reports the results of an interdisciplinary research that involves the following areas of information science, and computer science: Enterprise Architecture, Model Driven Engineering, Visual Modeling Languages, and Formal Methods and Languages.

In the first part of this chapter we make an overview of the work, which describes the theoretical foundations of this Ph.D:

In Section 2.1 we introduce the term of model transformation as it is defined in Model Driven Engineering (MDE). In Section 2.2 we provide an overview of the existing theories and the approaches to refinement verification: model checking and theorem proving. In Section 2.3 we give a definition of the semantics for visual modeling languages and explain the role of formal semantics in the process of refinement verification.

In the second part of this chapter, we study how model transformations (namely, model refactoring and refinement) are (1) specified in different visual modeling methods and (2) how they are supported by different modeling tools used in Software and Enterprise modeling:

In Section 2.4 we define a comparative framework for visual modelling upon which we analyse five methods developed in the area of Enterprise and Software modelling. In Section 2.5 we define a comparative framework for the modeling tools. Tools, compared to methods, are more user-oriented: some of them (mostly commercial tools) are based on best-practices, whereas the others (research prototypes developed in an academia) implement the theoretical methodologies. We analyse four commercial tools and seven tools, developed in academia. We explore how the automated refinement and the refinement verification are supported by these tools.

In Section 2.6 we apply the same frameworks to evaluate the SEAM modelling method and tool.

2.1 Theoretical Foundations of this Work

2.1.1 Model Transformations

Model-Driven Engineering (MDE) is a discipline that defines a set of methods and tools for the software development, where a model plays a central role. Model evolution and elaboration in MDE is described as a result of model transformations.

The best known MDE initiative is the Model-Driven Architecture (MDA) software design approach [75]. MDA describes a model evolvement from abstract specifications to their implementations (code). The separation of design from architecture is one of the main principles of MDA. Kleppe et al. [62] provide the following definition of a model transformation: “A transformation is the automatic generation of a target model from a source model, according to a transformation definition. A transformation definition is a set of transformation rules that together describe how a model in the source language can be transformed into a model in the target language. A transformation rule is a description of
how one or more constructs in the source language can be transformed into one or more constructs in the target language.”

Source and target models, in model transformation, are expressed in corresponding languages and are said to be conforming to metamodels. The term metamodel is often associated with a set of rules and definitions, provided by the modelling language.

[70] proposes the following dimensions for the categorization of transformations: endogenous/exogenous and horizontal/vertical.

A transformation is endogenous if the source and the target models conform to the same metamodel (are expressed in the same language). If the source and the target metamodels are different, then the transformation is exogenous. Exogenous transformations can be also called translations from one language to another.

A transformation is horizontal if the source and the target model reside at the same abstraction level. A vertical transformation, respectively, is a transformation, where the source and the target model reside in different abstraction levels. The taxonomy of model transformations is presented in [70].

![Figure 2-1: Classification of model transformations in context of Visual modeling.](image)

In context of visual modeling, we distinguish the transformations of visual specifications to executable program specifications, and the transformations of visual specifications to visual specifications. Former transformations are exogenous; latter transformations can be endogenous (if both models are expressed in the same visual modeling language) or exogenous (if a language of the target model is different from the language of the source model).

In Fig. 2-1, transformations T1 and T2 specify transformations from a visual specification to a program specification – they are exogenous; T0 specifies a transformation between two visual specifications, where one conforms to a metamodel MM1 and another to a metamodel MM2. If MM1 = MM2 then T0 is an endogenous transformation.

Examples of transformations are:

- **Synthesis** of a higher level (more abstract) specification into a lower-level (more concrete) specification. The result of synthesis of a visual specification is typically a code generation.
- **Generation of an abstract specification from its implementation** (also called a reverse engineering). This transformation is the opposite of a synthesis. The result of reverse engineering is typically a visual specification generated from the program specification.

Synthesis and reverse engineering aim at increasing or decreasing the abstraction level of a model; these transformations are *vertical transformations* (Table 2-1).

- **Language migration** is an exogenous transformation that specifies a translation of a visual (or a program) specification expressed in one language to a visual (or a program) specification expressed in the other language, keeping the same level of abstraction. Language migration is a *horizontal transformation*. (Table 2-1).

In this work, we consider two endogenous transformations: refactoring and refinement. Both refinement and refactoring specify transformations between two visual (or program) specifications expressed in the same language. Refinement changes the internal structure of a specification while keeping the same level of abstraction. Refactoring is a *horizontal transformation*. Refinement is a transformation, where a specification is gradually *refined* into an implementation [70]. Refinement is a *vertical transformation*.

The design process in SEAM can be seen as a sequence of the transformations of visual specifications. Based on our classification, the transformations of SEAM specifications are refinements and/or refactorings.

Table 2-1 summarizes transformation types along two classifications: exogenous/endogenous and vertical/horizontal.

<table>
<thead>
<tr>
<th>Table 2-1 Classification of Model Transformations</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>HORIZONTAL</strong> (level of abstraction does not change)</td>
</tr>
<tr>
<td>ENDOGENOUS (MMs = MMt)</td>
</tr>
<tr>
<td>EXOGENOUS (MMs ≠ MMt)</td>
</tr>
</tbody>
</table>

Model Driven Engineering provides a classification of model transformations, however it does not provide a theory for reasoning about these transformations. Such a theory can be found in domain of Software Engineering.

### 2.1.2 Refinement and Refactoring in Software Engineering

Transformations of refactoring and refinement are also defined in Software Engineering (SE) to specify transformations of programs.

[42] defines **refactoring** as “*the process of changing a software system in such a way that it does not alter the external behavior of the code yet improves its internal structure.*” Refactoring can be considered as a series of atomic behavior-preserving transformations (also refactorings) which in combination may result in substantial reorganization of the code. Refactoring does not consider transformations, which change a state space of the model.

In the domain of software modeling, refactorings for UML class diagrams annotated by OCL constraints are systematized and formalized in [68].
Refinement [111] is a more general technique that specifies a stepwise development of the program by adding details or eliminating nondeterminism. As opposed to refactoring, refinement can change a state space and an observable behavior of a model (e.g. adding, removing a field or a method of a class). Thus, refinement specifies a wider class of transformations than refactoring does (see www.refactoring.org).

In Software Engineering, the criteria of refactoring/refinement correctness are well specified; therefore these transformations can be verified.

Refinement verification techniques are often used to verify refactoring correctness [23], [85]. The semantic correctness of the refactorings for UML class diagrams is presented in [6].

In this work, we formalize all types of transformations defined for SEAM visual specifications as refinements.

2.1.3 Refinement and Refinement Verification

Stepwise refinement is a well-known paradigm for semantic program constructions originally proposed in [31] and [111]. It is based on the idea that a program can be developed through a sequence of refinement steps starting from an abstract specification. Different notions of refinement can be found in the literature (see [88] for an overview). We list only a few.

A method of program construction based on stepwise data refinement together with proof of refinement correctness was proposed by Hoare [51].

Data refinement and techniques to prove its correctness are presented in [93].

In [15], the Abstract State Machine method of abstract refinable system specifications is introduced. In [16], the Abstract State Machine refinement method is presented. The ASM refinement method generalizes the notion of refinement for an arbitrary number of transitions (run segments) between the initial and the final specification states.

Refinement verification is largely based on the use of simulation techniques [65]. By the simulation we understand a correspondence between the states of two systems, where one system is considered a specification and another – its implementation. The simulation proof is based on the establishing of this correspondence. The fact that a simulation between two systems exists shows that any behavior of one system can also be exhibited (simulated) by the other system.

The research literature contains a large number of different types of simulations, such as forward simulation, backward simulation, hybrid simulations (i.e. forward-backward and backward-forward simulations) [65][112][50][27], refinement mappings [1], and a generalized forward simulation [15][16][98]. These simulations are differentiated based on the way they relate system specifications and their implementations: for example, forward simulation matches each step of the system implementation with a corresponding step forward of its specification; whereas the backward simulation matches each step of the system implementation with the corresponding step backward of its specification. The simulation techniques will be presented in detail in Chapter 5.

In contrast to refinement techniques where an intermediate specification is first proposed and then proved (for example, by simulation) to be a correct refinement of its antecedent, there exists a refinement technique based on calculation [72]. The refinement calculus by Back [7] is an underlying theory of this technique. According to this technique, every intermediate specification can be calculated from the previous one by using refinement laws. The application of these laws enables the reduction of proof obligations and assures refinement correctness.

In the context of visual modeling methods, incremental software construction using refinement diagrams is proposed in [8]. Here refinement calculus is used as logic for reasoning on software systems and their evolution. Pons defines in [85] the UML refinement
patterns grounded on Object-Z. In [6] refinement for the UML class diagrams and corresponding OCL contracts is specified.

### 2.1.4 Model Verification

When a model (a program or a visual specification) is created or obtained by refining another model, it is important to validate that it is constructed correctly: for example, that it has a certain property. This can be done by formal verification.

There are two main approaches to formal verification: model checking [20] and theorem proving based on logical inference [47] [64].

**Model checking** is an approach for verifying the requirements and design for a vast class of systems. A system, specified as a Kripke structure, is checked against some logical formula that expresses a desired property or requirement of this system. Typically, formal specification languages are used to specify the system, its properties, and requirements.

A model $M$ of the system can be considered in model checking as a finite state machine (FSM). A FSM consists of nodes, representing system states, and vertices, presenting transitions between their states. Desired properties of the system are specified as logical formulas. To find out whether the model $M$ with the initial state $s$ satisfies some property $\phi$, (denoted $M, s \models \phi$) the state space and all transitions of the model are systematically and exhaustively explored.

The major drawback of the model checking is a state explosion problem, which originates from the fact that for real systems the size of the state space grows exponentially with the number of processes [21]. To avoid the state explosion, model checkers implement specific techniques, such as symbolic algorithms and binary decision diagrams (BDD) [54], bounded algorithms [3], counter-example guided abstraction refinement [52], and algorithms based on partial order reduction, or on abstraction.

Model checking approaches largely use the counterexample-based algorithms to validate properties of a system, specified as logical formulas. Such algorithms explore the system state space looking for the case, where this formula is violated. This case is called a counter-example; the occurrence of a counter-example demonstrates that the formula is invalid. However, the fact that no counterexample is found does not prove the validity of the formula, because the state space under the exploration is limited.

The second approach is an automated theorem proving based on logical inference. Within this approach, the fact that the system specification (a model) satisfies a certain property is expressed as a logical formula. The task is to prove the validity of this formula, deducing it from a set of axioms that exist for the underlying logic (e.g. first-, second-, higher-order logic etc.), and hypotheses made about the system.

Depending on the underlying logic, the problem of deciding the validity of a theorem varies from trivial to impossible. Theorem proving for the first-order logic (FOL) is widely represented in the literature (see for example [100][99]).

Higher-order logic (HOL) operates on predicates and functions of higher order (a higher-order predicate is a predicate that takes one or more other predicates as arguments). It is more expressive and appropriate for a wider range of problems then first-order logic. However the theorem proving procedures for HOL are more complicated [48][74][82].

Despite the fact that automated theorem proving is complex and requires a lot of involvement from the modeler, its application is promising; this approach is not limited by the state explosion problem (the main limitation of model checkers) and can handle the infinite number of states.
2.1.5 Formal Semantics for Visual Modeling Languages

To prove the desired properties of specifications, or to verify the refinement correctness of a visual specification, these specifications should be translated to a formal specification language, accepted by a model checker or an automated theorem prover. Translation (or mapping) rules for a visual specification language can be defined as its formal semantics.

The semantics of a visual language L gives a meaning to the constructs and the expressions in this language and can be defined in two ways [10]: “(1) By providing a way in which expressions (and constructs) of L are made (2) By translating the expressions (and constructs) of L into expressions of another language that is already known”.

Fig. 2-2 illustrates the refinement of a visual specification and its verification. Here M1 and M2 are visual specifications conforming to a source metamodel MMs. T0 is a transformation that specifies a refinement between M1 and M2. We say 'M2 refines M1'. Transformations T1 and T2 specify translations of M1 and M2 to specifications P1 and P2, written in a formal specification languages and defined by formal semantics. We also say that P1 and P2 conform to a target metamodel MMt. Specifications P1 and P2 are formalizations of M1 and M2 in the target language.

We identify the refinement between M1 and M2 with the refinement between P1 and P2. For P1 and P2 we can check the refinement correctness using formal verification tools. We interpret the obtained result for M1 and M2: M2 correctly refines M1 if and only if P2 correctly refines P1.

There is a gap between visual modeling languages and formal specification languages: Whereas visual languages are practice-oriented and tend to specify the system avoiding exhaustive details, formal specification languages demand a high precision in model definition. This gap makes translations between specifications complicated. To define formal semantics for visual specifications, the level of precision of these specifications should be increased by introducing new elements to the visual modeling language.

2.2 Visual Modeling Methods and their Consideration of Refinement

Many modeling frameworks and methods in the domain of enterprise modeling, system modeling, and software modeling have emerged in the last decades. See for example [77][78][81][32][114][35][45]. Some of those are discussed and compared in [97]. In this section we analyze some of the methods that we consider the most relevant to the problem of refinement verification.
2.2.1 Classification Framework for Modeling Methods

Visual modeling methods in Software and Enterprise modeling can be classified based on the way they organize their specifications and guide the modeling process: Some methods define several types of highly specialized diagrams, whereas the others use one diagram type; some methods keep their diagrams explicitly related (aligned) and provide mechanisms for this alignment, and the others define loosely coupled sets of specifications, leaving the relationships between these specifications to a modeler’s consideration.

These characteristics of modeling methods affect the way these methods support refinement. We develop the following criteria to classify different modeling methods:

1. Diagram Types
We distinguish the modeling methods that define one diagram type for its specifications and those that define many specific diagrams (e.g. UML).

2. Model Structure
We distinguish a plain or hierarchical model structure. A hierarchical structure enables ‘zooming in and out’ into model details by switching hierarchical levels. In the plain model, the system is represented by a collection of complementary views that capture different aspects of the system.

3. Traceability
Traceability is a relationship between elements in different specifications, which enables a designer to carry out an impact analysis. For the model with a plain structure, the traceability between different views is important to maintain the model consistency. When the model is structured hierarchically, the traceability between specifications at different levels helps to verify the refinement correctness.

4. Refactoring/Refinement Rules
We distinguish the methods that specify the rules of refinement or refactoring for their specifications, and those that do not restrict the modeler and leave the refinement process to the modeler’s discretion.

2.2.2 Modeling Methods Overview

We consider in detail the following modeling methods:
- UML2.0 and its extension SysML;
- BPMN
- DEMO
- OPM
- ADORA

UML 2.0 [77] is a de-facto standard for software development. UML proposes 13 diagram types that enable modeling various system aspects. These diagrams are divided in three groups: structure, behavior, and interaction diagrams. Structure diagrams include:
- Class diagram
- Component diagram
- Composite structure diagram
- Deployment diagram
- Object diagram
- Package diagram +

Behavior diagrams are:
- Activity diagram +
- State Machine diagram +
- Use case diagram +

Interaction diagrams relate a system structure defined in the structure diagrams with its behavior, specified in behavior diagrams. These diagrams include:
- Communication diagram
- Interaction overview diagram
- Sequence diagram
- UML Timing Diagram

There is a semantic relationship between the UML diagrams of different types, i.e. they are complementary. Some diagrams in addition have a hierarchical structure (they are marked with ‘+’ in the list). For example, a state machine diagram defines state machines and submachines; activities are composed of activity nodes that can be also activities, etc.

Different UML diagrams are complementary but self-contained, which implies that any relationships between the elements in different diagrams have no semantic effect on the model. Traceability in UML can be expressed using traceability relationships. An implementation of traceability typically depends on the tool. IBM Rational software architect [87], for example, provides diagrams and table views of related model elements, broken relationships between model elements, and implied dependencies between model elements. UML 2.0 specification [77] does not address explicitly the traceability issue.

UML defines an abstraction relationship between its model elements. This relationship in UML can be used to model stepwise refinement. No explicit refinement rules or classification of refinements is specified in the original UML documentation. It is left to the discretion of the UML practitioners or tools, implementing UML.

The official list of UML-based modeling tools is available at http://uml-directory.omg.org/vendor/list.htm. At the time of this work, there are more than 40 products.

Systems Modeling Language (SysML) [79] was developed by OMG and based on UML. SysML targets the design of large industrial systems (e.g. aircraft, power plants, etc). It defines nine diagram types; four of them are inherited from UML.

SysML defines blocks as modular units of system description. Blocks group both structural and behavioral features (properties, states, operations) to describe a system of interest. The Block Definition Diagram in SysML defines features of a block and relationships between blocks. The Internal Block Diagram in SysML captures the internal structure of a block. Blocks can be decomposed into parts that are also blocks.

Business Process Modeling Notation (BPMN) [78] provides a visual notation and formalism for business process model development. This notation is mostly focused on the representation of a system’s behavior and proposes a variety of model elements for its realistic specification. BPMN specifies one diagram type called business process diagram (BPD). In a BPD, two hierarchies can be captured: by using combinations of swim lanes, a hierarchical structure of organizations can be modeled; and by using combinations of BPMN processes, sub-processes, and tasks, organization behavior can be modeled with different levels of details.

Traceability between tasks and activities in BPD is explicit and maintained by the sequence and message flows (connections).

Modeling expanded sub-processes can be considered as a functional refinement of the business process model. BPMN defines rules for sub-process definition to guarantee that it is consistent with the main process. They can be considered as refinement rules. Swim lanes
specify the process participants. Therefore, the definition of multiple lanes for one pool is equivalent to the organizational refinement.

At the time of this work, there are 44 existing and 4 planned implementations of BPMN. The complete list of tools is available at http://www.bpmn.org/.

Design & Engineering Methodology for Organizations (DEMO) [29] is an EA framework based on the organizational theory called Language/Action Perspective. The DEMO methodology takes its theoretical origin from the works of Habermas on communicative action [49]. This methodology provides a set of methods for capturing and visualizing business processes and the actors involved in the activities comprising these business processes. DEMO defines its organizational levels based on a communication paradigm. Functional levels are defined in DEMO based on the view of business processes as transactions.

DEMO specifies four aspect models (construction, process, state, and action models) and five diagram types for these models (actor - transaction diagram, actor - bank diagram, process - structure diagram, objects - fact diagram, action - rule specification).

The construction model specifies the construction of the organization in terms of the transactions, actors, information banks, and information links between them. The process model and the state model are considered as the next detailing level of the construction model – they describe each transaction as a set of states and transitions. The action model specifies the action rules and can be seen as the second detailing level of the construction model. Traceability between modeled aspects is captured in DEMO using cross-model tables.

DEMO defines functional and constructional decompositions as techniques for dealing with the complexity of the modeled system. Decompositions can be seen as corresponding refinement types.

Object-Process Methodology (OPM) [34][35] proposes a method for the complete integration of the systems’ states and behaviors within a single graphical model. OPM defines one diagram type for its models called object process diagram (OPD). The system model in OPM is represented by a collection of OPDs structured as a directed acyclic graph with the top-level system diagram in its root. This diagram is considered at detail level zero. Each node of this graph is an OPD, which specifies in more detail a process from the higher level OPD (a zoomed-in process). Relationships between diagrams can be defined explicitly by specifying a control flow.

OPM defines the abstracting and refining of its specifications as subtypes of the process called scaling. There are three modes of refinement in OPM: in-zooming, unfolding, and expressing. OPM defines the rules for refining/abstracting processes.

In OPM, there exist three types of hierarchies, defined with respect to the first three fundamental structural relations: aggregation-participation, exhibition-characterization, and generalization-specialization. These hierarchies are equally applicable to objects and to processes.

The object-oriented modeling method for software called ADORA (Analysis and Description of Requirements and Architecture) is presented in [44][45]. Models in ADORA are composed of hierarchically structured abstract views. ADORA defines a base view and four aspect views for its models (structural, behavior, user, and context views). The base view specifies the hierarchical structure of the objects of the modeled system. Aspect views are generated by combining the base view with the information that is relevant for the selected aspect. All views are integrated in one coherent model.
The mechanism of hierarchical decomposition is applied to views. A view transition in ADORA is a sequence of steps that guarantees the well-formedness of a new view. View transitions for structural, behavioral, and user aspect views are specified [113] and can be considered as refinement rules. View transitions enable an explicit traceability between model elements [113]. ADORA defines a formal refinement calculus semantic for the structural, behavioral, and user views.

2.2.3 A Comparison of Modeling Methods
We have analysed the methods from 2.2.2 based on the classification framework defined in 2.2.1. A summary of this evaluation is presented in Table 2-2.

<table>
<thead>
<tr>
<th></th>
<th></th>
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</tr>
</thead>
<tbody>
<tr>
<td>UML 2.0</td>
<td>13 diagram types</td>
<td>Hierarchical for some (not all) diagrams</td>
<td>Can be modeled using traceability relationship, implicit; no semantic impact is specified</td>
<td>Structural refinement: can be modeled using realization relationship, implicit; Behavioral refinement: implicit.</td>
</tr>
<tr>
<td>SysML</td>
<td>9 diagram types</td>
<td>Hierarchical for some (not all) diagrams</td>
<td>Explicit requirements traceability; relations between blocks</td>
<td>Structural, behavioral refinement: using block decomposition</td>
</tr>
<tr>
<td>BPMN</td>
<td>1 diagram type</td>
<td>Hierarchical: pools/lanes; process/ sub-process</td>
<td>Explicit for tasks and activities using sequence and message flows;</td>
<td>Behavioral refinement: defined by sub-process modeling; Structural refinement: can be modeled using pools – lanes combination.</td>
</tr>
<tr>
<td>DEMO</td>
<td>5 diagram types</td>
<td>Hierarchical</td>
<td>Explicit, using cross-model tables</td>
<td>Behavioral and structural refinements: using functional and constructional (de)composition</td>
</tr>
<tr>
<td>OPM</td>
<td>1 diagram type</td>
<td>Hierarchical</td>
<td>Explicit for processes using a control flow.</td>
<td>Behavioral and structural refinements: in the form of in-zooming, unfolding, and expressing</td>
</tr>
<tr>
<td>ADORA</td>
<td>Base view + aspect views</td>
<td>Hierarchical</td>
<td>Explicit, using view transitions</td>
<td>Behavioral and structural refinements: using hierarchical decomposition;</td>
</tr>
</tbody>
</table>

Our analysis shows that most of the methods consider behavioral and structural refinement for their models, however semantics of refinement (criteria of refinement validity) and refinement rules are often left for an implementation of the method.
2.3 Visual Modeling Tools and their Support of Model Refinement and Refinement Verification

Modeling methods are largely based on theoretical paradigms; they may exist in a form of the guidelines, and may have no tool support. Modeling tools, compared to methods, are concrete applications. Some of the tools are grounded on modeling methods (e.g. UML, BPMN), whereas the others may have no underlying theory but a set of best practices. Modeling tools usually provide an additional functionality to the methods, such as simulation and verification.

Model simulation and verification require details about dynamic and static constraints of a modeled system that are often omitted in the visual model. Therefore, semantics of the visual modeling language needs to be extended. For these purposes, visual models are often annotated with expressions written in other languages, e.g. OCL annotations for UML diagrams.

In this section we consider visual modeling tools which implement some of the modeling methods listed above.

2.3.1 Classification Framework for Modeling Tools

To answer the question, “How different modeling tools support model analysis and refinement verification?”, we define the following classification framework:

1. A Source Language
   We classify modeling tools by modeling languages that they support or modeling methods they implement. We call these languages or methods source languages, as the model expressed in this language is used as a source for further processing and analysis.

2. A Constraint Specification Language
   Apart from the source language, we distinguish two other types of languages that (if defined) characterize the modeling tool: a constraint specification language and a target language. The constraint specification language is a language for annotating visual models in order to extend their semantics and increase their precision.

3. Migration to another Language
   Some modeling tools use their own means to simulate or verify their models; other tools provide a translation of their models to other (target) languages and profit from the simulation and verification tools, developed for those languages.

4. A Target Language
   The target language is an executable or verifiable specification language. Visual specifications, written in a source language and annotated with expressions written in a constraint specification language are mapped to the target language for further simulation and/or verification.

5. Simulation is a capability of a modeling tool to simulate or execute the model.

6. Well-Formedness and Consistency Checking is a capability of a modeling tool to check if the model is well-formed (a correct instance of its meta-model) and consistent (semantically non-contradictory).
7. Refinement Support is a capability of a modeling tool to provide an assistance in at least one of the following refinement–related activities:

- the support of incremental model development, when different parts of a model can be iteratively refined;
- the control of refinement consistency, when specific rules are implemented to prevent the model from incorrect refinement;
- the refinement synchronization, when the rest of the model is synchronized (adjusted) with respect to the refined model part;
- the refinement verification, when the refined model is proven a correct refinement of the initial model with respect to the formal definition of refinement correctness.

2.3.2 Modeling Tools Overview

Four commercial tools and seven tools developed in academia (or originated from it) have been selected for our analysis. We find the analyzing of both groups of tools important, because the former group reflects the current needs of practitioners, whereas the latter illustrates the research innovations in the area.

For our analysis we have selected the tools that facilitate model simulation, analysis and refinement support.

Commercial tools:
No Magic - MagicDraw (UML2.0, SysML, BPMN, DoDAF) - www.magicdraw.com/
Telelogic - SystemArchitect (BPMN, DoDAF) - www.telelogic.com/products/systemarchitect/index.cfm
Intalio - Designer (BPMN) - www.intalio.com/products/designer/

Research prototypes and research based tools:
ArgoUML (UML)
RoclET (UML, OCL)
UML2Alloy (UML, OCL)
BPMN2PNML (BPMN)
OPCAT (OPM)
ADOR (ADOR)
DEMS (ER)

MagicDraw is a business modeling tool, developed by No Magic Inc.[67]. MagicDraw UML 15.0 is the latest version of the product by the time of this work. This tool supports UML 2, BPMN notations, and provides a plugin for SysML.

MagicDraw supports OCL constraints for its model elements. OCL syntax is validated automatically. The tool supports model decomposition and provides the automated check of model completeness and correctness. Model versioning can serve for refinement support: one can see the changes made between two different versions of a model. To the best of our knowledge, MagicDraw does not provide means to keep track and to validate these changes with respect of the initial model (what we call refinement verification).

Telelogic System Architect is a tool for business and enterprise architecture modeling [104]. This tool supports BPMN and provides facilities for planning, modeling, and execution of business process specifications. System Architect has its own simulator for process
specifications, called System Architect Simulator II. System Architect complements another Telelogic tool called TAU G2 supporting UML2.0 visual modeling.

Metastorm ProVision [86] is a tool for business process modeling and analysis that supports (among the others) BPMN notation for the processes. The tool includes both Monte Carlo and discrete event simulators to define scenarios and perform process simulation. Scenario-based simulation shows how the process will behave under specific conditions.

Intalio Designer [56] is an Eclipse-based integrated development environment for BPMN business processes. It is a part of Intalio BPMS 4.0. Intalio designer supports the static process validation and automatic process code generation. Refining processes into sub-processes in Intalio Designer is performed using the in-line sub-process drill-down approach.

ArgoUML [4] is an open source UML modeling tool. ArgoUML provides OCL constraint modeling for its diagrams. ArgoUML supports syntax and type checking of OCL constraints using the Dresden OCL toolkit [37]. ArgoUML implements design critics feature to supervise the modeling process and to correct the modeler’s activity. The tool does not mention explicitly its refinement capabilities; however we consider design critics potentially beneficial for the refinement support.

RoclET [94] is an open source tool for analysis of UML/OCL specifications. The current version of RoclET supports UML 1.5 class and objects diagrams and provides a parser/typechecker for annotated OCL 2.0 constraints. RoclET supports the refactoring of UML class diagrams and automatic synchronization of attached OCL constraints. Baar and Marcovi [5] introduce a proof technique for the semantic preservation of refactoring rules for UML class diagrams and OCL constraints. Evaluation of invariants, pre-, and postconditions for object diagrams is also provided by the tool.

UML2Alloy [13] is a tool for the analysis of discrete event systems modeled in UML. This tool provides an interactive interface to translate UML diagrams annotated with OCL constraints into Alloy specifications. UML2Alloy tool accepts XMI serializations of UML models developed in some UML modeling tool (e.g. Magic Draw 9.5, ArgoUML). The tool generates text files with Alloy specifications that can be analyzed in Alloy Analyzer 4.0 [3].

The BPMN to Petri net transformer (BPMN2PNML)[17] is a tool that generates Petri Net Markup Language (PNML) [43][83] specifications from BPMN models for further static analysis. The tool accepts XMI serializations of BPMN models generated by existing BPMN modeling tools (e.g. ILOG BPMN Modeler tool). The semantic analysis of BPMN models can be conducted by importing generated PNML specification into the Petri net-based verification tool ProM [33][84]. This tool allows for the verification of the two following properties of BPMN models: the absence of dead tasks, and the absence of improper process completion, which means that any process instance eventually reaches proper completion. Further details can be found in [30].

The Object-Process CASE Tool (OPCAT) [35][80] is a tool for the development and simulation of OPM system specifications. OPCAT provides an abstraction/refinement mechanism in the form of in-zooming/out-zooming, unfolding/folding and expression/suppression of the states. OPCAT's simulation capability enables an animated running of a system model, a testing of its functionality against the requirement specifications, and a debugging of them at the model level [36].
DEMOS [26] is a modeling tool for the EP modeling language [60]. This tool is developed within the project of Declarative Approaches to Software Complexity [25]. The EP-model is a declarative executable model for engineering object-based systems. EP-models model both static and dynamic aspects of a system in a single diagram. The executable part of EP-model is specified in the form of Java code snippets that annotate model elements. DEMOS tool is implemented as an Eclipse plug-in and provides:

- graphical editing of applications using the EP model,
- background code generation, and
- immediate feedback on syntactical validity of models and user-supplied code.

A recent work of the authors defines the abstract syntax, static semantics, and dynamic semantics of the EP modeling language in Alloy [59].

The ADORA tool [2] implements the modeling method ADORA. This tool was successfully applied for the creation, validation and evolution of behavioral requirements models [46]. ADORA defines a stepwise incremental process of behavior specification, where a behavioral model is refined in each step by specifying partial behaviors. The tool simulates partial system behaviors documented in message sequence charts. The modeler can then generalize these partial behaviors and revalidate the resulting behavior by simulating it against previously recorded behavior. Model revalidation at each step stands for the refinement consistency control.

The ADORA tool simulates models regardless of their degree of formality and completeness. If the information needed for the simulation is missing, the tool interrupts the simulation and the modeler provides the required information interactively.

2.3.3 A Comparison of Modeling Tools
Table 2-3 presents a summary of our comparative analysis. One of the difficulties we met conducting this analysis was related to the fact that commercial tools rarely disclose their technical details or underlying heuristics. Thus, it is often difficult to position them within our classification framework. Whereas tools developed in academia are usually based on scientific publications, which clearly explain the theoretical foundations, and potential benefits for the user. However, some of these tools exist only as research prototypes.

This is reflected in the summary table, which is incomplete. We use a question mark ‘?’ if we are unable to make a judgment about the tool based on the information available.
<table>
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<tbody>
<tr>
<td>Magic Draw</td>
<td>UML, BPMN, SysML</td>
<td>OCL</td>
<td>No</td>
<td>-</td>
<td>No</td>
<td>Yes</td>
<td>Model decomposition/model differencing; No verification</td>
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<td>?</td>
<td>?</td>
<td>Language supported by native Simulator II tool</td>
<td>Yes</td>
<td>Yes</td>
<td>?</td>
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<tr>
<td>ProVision</td>
<td>BPMN, UML, etc</td>
<td>?</td>
<td>?</td>
<td>Languages supported by native Monte-Carlo / discrete event simulator tools</td>
<td>Yes</td>
<td>Yes</td>
<td>?</td>
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<td>Intalio Designer</td>
<td>BPMN</td>
<td>?</td>
<td>Yes</td>
<td>BPEL</td>
<td>Yes</td>
<td>Yes</td>
<td>In-line drill-down modeling of activities</td>
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<td>UML</td>
<td>OCL</td>
<td>No</td>
<td>No</td>
<td>No</td>
<td>Yes</td>
<td>Design critics</td>
</tr>
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<td>RocLET</td>
<td>UML</td>
<td>OCL</td>
<td>No</td>
<td>-</td>
<td>No</td>
<td>Yes</td>
<td>Refactoring; verification of semantic preservation</td>
</tr>
<tr>
<td>UML2 Alloy</td>
<td>UML</td>
<td>OCL</td>
<td>Yes</td>
<td>Alloy</td>
<td>No</td>
<td>Yes</td>
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<td>BPMN</td>
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<td>Yes</td>
<td>Yes</td>
<td>?</td>
<td>?</td>
</tr>
<tr>
<td>OPCAT</td>
<td>OPM</td>
<td>OPL</td>
<td>No</td>
<td>-</td>
<td>Yes</td>
<td>Yes</td>
<td>In-zooming, unfolding, state expression.</td>
</tr>
<tr>
<td>DEMOS</td>
<td>EP</td>
<td>Java</td>
<td>Yes</td>
<td>Java</td>
<td>Yes</td>
<td>Yes</td>
<td>Functional decomposition</td>
</tr>
<tr>
<td>ADORA</td>
<td>ADORA</td>
<td>No</td>
<td>No</td>
<td>-</td>
<td>Yes</td>
<td>Yes</td>
<td>Stepwise refinement; refinement consistency control by revalidation/regression simulation</td>
</tr>
</tbody>
</table>
The SEAM Method

Our work defines the formal semantics and the theory for refinement and refinement verification for the SEAM method [108]. The SEAM method was designed to model enterprises and can be used to model software systems. SEAM defines one diagram type for its specifications. The SEAM ontology is based on the second part of the RM-ODP [92] specification. Based on this standard, the main modeling concepts of SEAM such as property, state, and action are defined [108].

SEAM defines a model of a system as a set of system specifications structures within two hierarchies: a hierarchy of organizational levels, and a hierarchy of functional levels. The first hierarchy incrementally reveals a system’s construction, whereas the second hierarchy addresses an incremental specification of system’s functionality.

SEAM explicitly models the traceability between model elements across functional and organizational levels using traceability relations.

The transition of model from one hierarchical level to another is formalized in SEAM as a refinement (contribution of this work). Two main classes of refinement are defined in SEAM: an organizational refinement, which addresses the incremental specification of a system structure, and a functional refinement, which addresses the incremental specification of behavior of the system.

Several prototypes of SEAM-based applications have been recently developed. The SeamCAD tool [66] is a framework for SEAM graphical modeling. SEAM to Java is a prototype of SEAM model transformation application that translates visual SEAM specifications to Java programs. This application is based on ATL - Atlas Model Transformation language [55] and is developed as a plug-in under Eclipse [39]. SEAM to Java accepts as input a SEAM model in XML format and generates another XML that corresponds to the target Java model. Using XSLT [105] script, the executable Java code is obtained. SEAM to AsmL is a prototype tool that translates SEAM applications to AsmL - the Abstract State Machine Language [15][11] for further simulation and verification with AsmL verification tool [95].

As a part of this Ph.D thesis, a prototype of SEAM to Alloy translator was developed. This translator is based on the XSLT script and allows for the generation of Alloy models from SEAM specifications, documented in XML. The XML file with a SEAM specification is obtained from the EMF (Eclipse Modeling Framework)-based SEAM Editor. The mapping rules from SEAM to Alloy are explained in Chapter 6.

As future work, we plan an implementation of the Seam to Jahob translator that will provide us with the possibility of verifying specification refinement using the Jahob verification system [63].

In Tables 2-4, 2-5, we evaluate the SEAM method based on the frameworks we applied for the other modeling methods and tools:
### Table 2-4

<table>
<thead>
<tr>
<th></th>
<th></th>
<th></th>
<th></th>
<th></th>
</tr>
</thead>
<tbody>
<tr>
<td>SEAM</td>
<td>1</td>
<td>Hierarchical (functional + organizational hierarchies)</td>
<td>Explicit, via whole/composite relationships</td>
<td>Structural refinement: explicit; results in a transition to the next org. level; Behavioral refinement: explicit; results in a transition to the next functional level.</td>
</tr>
</tbody>
</table>

### Table 2-5

<table>
<thead>
<tr>
<th></th>
<th></th>
<th></th>
<th></th>
<th></th>
<th></th>
<th></th>
<th></th>
</tr>
</thead>
<tbody>
<tr>
<td>Seam to Java</td>
<td>SEAM</td>
<td>Java</td>
<td>Yes</td>
<td>Java</td>
<td>Yes</td>
<td>No</td>
<td>No</td>
</tr>
<tr>
<td>Seam to AsmL</td>
<td>SEAM</td>
<td>ASM</td>
<td>yes</td>
<td>AsmL</td>
<td>Yes</td>
<td>Yes</td>
<td>No</td>
</tr>
<tr>
<td>SEAM to Alloy</td>
<td>SEAM</td>
<td>FOL/Alloy</td>
<td>Yes</td>
<td>Alloy</td>
<td>No</td>
<td>Yes</td>
<td>Refinement verification</td>
</tr>
<tr>
<td>SEAM to Jahob (future work)</td>
<td>SEAM</td>
<td>FOL/Alloy + Java</td>
<td>yes</td>
<td>Jahob</td>
<td>Yes</td>
<td>Yes</td>
<td>Refinement verification</td>
</tr>
</tbody>
</table>
Chapter 3

The SEAM Method

In this chapter, we introduce the SEAM method for Enterprise Architecture modeling and the SEAM visual modeling language. SEAM considers marketing segments, organizations, IT systems and IT applications as systems, structured in organizational levels of an enterprise model. The SEAM ontology is based on the second part of the RM-ODP [92] specification. Based on this standard, the main modeling concepts of SEAM such as property, state, and action have been defined [108]. This work contributes in a definition of the additional concepts necessary for the formal verification of SEAM visual specifications: preconditions, postconditions, invariants, and updates.

SEAM specifies various model elements and different ways to combine them in a diagram. A modeler may choose her own strategy in order to enhance the traceability of concepts across levels and to improve the model transparency.

To specify a system structure, SEAM defines a working object and two views of it:
- a working object as a whole;
- a working object as a composite.
To specify a system behavior, SEAM defines properties and three action types:
- a localized action;
- a joint action;
- a distributed action;
two views of a property:
- a property as a whole;
- a property as a composite;
two views of each action:
- an action as a whole;
- an action as a composite; and
two ways of action specification:
- declarative action specification;
- imperative action specification.

Sections 3.1-3.2 of this chapter describe SEAM model elements, their views and specification styles. Section 3.3 presents a metamodel of SEAM, which specifies its abstract syntax. As a contribution of this work, the SEAM metamodel is extended with new model elements. Section 3.4 presents the the semantics of SEAM model elements and specifies their graphical notation.

3.1 The SEAM Specification of a System

In a SEAM specification, a system is represented by a working object. The working object can be seen as a whole where its construction is hidden or as a composite that reveals its components. The views as a whole and as a composite belong to two adjacent organizational levels.
Example 3-1. Figure 3-1 illustrates a SEAM specification of a system, modeled as a working object $W$. $W$ is shown as a whole (denoted $W[w]$) in Fig. 3-1(a), and as a composite (denoted $W[c]$) in Fig. 3-1(b,c).

A working object as a composite specifies system components (also modeled as working objects) and a joint action (JA) or a distributed action (DA) between these components.

Figure 3-1: a) a SEAM working object $W$ as a whole; b) $W$ as a composite with component working objects $S_1$ and $S_2$ and a joint action JA seen as a whole; c) $W$ as a composite with components $S_1$ and $S_2$ and a distributed action DA seen as a whole.

A working object as a whole has properties and may specify localized actions (LA). Properties represent the data that the working object stores or operates with. A collection of all properties of the working object determines a state of this working object. A localized action changes the state of the working object by updating its properties.

Each action and property in SEAM can be seen as a whole where its construction is hidden or as a composite, where the components (component actions and component properties respectively) are shown.

The term ‘joint action’ in SEAM was taken from [38]. A joint action describes a collaboration of the components of a working object. This action changes states of these components by updating their properties (Fig. 3-1(b)).

Diagrams in Fig. 3-1(a,b) illustrate the following: To perform the localized action LA at $W$ (as a whole), the collaboration JA[w] of component working objects $S_1$ and $S_2$ is required. JA[w] modifies a property $P$ at $S_1$ and a property $P_1$ at $S_2$.

Working object decomposition (a transition from a whole to a composite) requires that the properties of the parent working object are distributed between component working objects. Localized actions for the component working objects can be omitted.

A working object as a composite specifies a distributed action between components of the working object (Fig. 3-1(b)). The keyword Distributed stands for a distribution of

---

3 We use indexes $w$ (w or [w]) or $c$ (c or [c]) to specify SEAM elements as a whole or as a composite respectively.
responsibilities between components, answering the question, “Who does what?” The responsibilities are modeled as localized actions.

In contrast to localized and joint actions, distributed action does not update the properties of a working object directly. This action changes the states of the working object by invoking localized actions of its components (Fig. 3-1(c)).

Diagrams in Fig. 3-1(a,c) illustrate the following: To perform the localized action LA at W, the collaboration DA[w] of component working objects S1 and S2 is required. S1 participates in DA[w] by performing a localized action LA1[w]. LA1 changes a property P; similarly, S2 performs a localized action LA2[w], which changes a property P1.

Action specifications ‘as a whole’ and ‘as a composite’ correspond to the terms ‘action’ and ‘activity’ of RM-ODP [92].

To specify the communication between component working objects or component actions of one working object, SEAM uses shared properties and input/output parameters.

A shared property is a property that does not belong to a specific component working object; shared properties represent the common knowledge maintained by the system. Input and output parameters are properties that specify the information flow from one working object (or action) to another.

In contrast to shared properties that can be perceived as global variables of a system, SEAM also defines local variables for its actions. A local variable is a property that belongs to a concrete working object and is defined by an action of this working object. The lifecycle of a local variable is related to an action (for other properties, it is related to a working object): the local variable exists only during the action execution.

We distinguish primitive and compound properties in SEAM. A primitive property can be considered as an alias for an operational (primitive) data type (e.g. int, string, boolean, etc.). The compound property is defined by a set of component properties and references to properties using property associations and property compositions.
Table 3-1 illustrates the relationships between concepts in SEAM. The 10 columns specify main SEAM elements and one of their views - as a whole or as a composite. The rows specify the same elements plus shared properties, parameters, and local variables.

<table>
<thead>
<tr>
<th></th>
<th>WO</th>
<th>Property</th>
<th>LA</th>
<th>JA</th>
<th>DA</th>
</tr>
</thead>
<tbody>
<tr>
<td>Whole</td>
<td>whole</td>
<td>x</td>
<td>composite</td>
<td>x</td>
<td>whole</td>
</tr>
<tr>
<td>composite</td>
<td>x</td>
<td>whole</td>
<td>x</td>
<td>composite</td>
<td>x</td>
</tr>
<tr>
<td>Property</td>
<td>whole</td>
<td>x</td>
<td>whole</td>
<td>x</td>
<td>composite</td>
</tr>
<tr>
<td>LA</td>
<td>whole</td>
<td>x</td>
<td>composite</td>
<td>x</td>
<td>whole</td>
</tr>
<tr>
<td>JA</td>
<td>whole</td>
<td>x</td>
<td>composite</td>
<td>x</td>
<td></td>
</tr>
<tr>
<td>DA</td>
<td>whole</td>
<td>x</td>
<td>composite</td>
<td>x</td>
<td></td>
</tr>
<tr>
<td>Parameters</td>
<td>In/Out</td>
<td>x</td>
<td>x</td>
<td>x</td>
<td>x</td>
</tr>
<tr>
<td>Shared properties</td>
<td>x</td>
<td>x</td>
<td>x</td>
<td>x</td>
<td>x</td>
</tr>
<tr>
<td>Local variables</td>
<td>x</td>
<td>x</td>
<td>x</td>
<td>x</td>
<td>x</td>
</tr>
</tbody>
</table>

An ‘x’ in a row-column intersection means that the ‘column’ element can specify (or own) the ‘row’ element. (Graphically, this is equivalent to having a relation with a black-diamond between elements).

An ‘r’ in row-column intersection means that the ‘column’ element can be related to the ‘row’ element. (Graphically, this is equivalent to having a simple relation between elements).

For example, a working object seen as a whole (column 1) can specify properties, localized actions, and input/output parameters; LA (localized action) seen as a composite (column 6) can specify component localized actions seen as a whole or as a composite, input/output parameters, shared properties, and local variables; it can be also related to other localized actions and properties. A property as a whole (column 3) cannot specify any other elements; it can be related to other properties.
3.2 Declarative vs. Imperative Action Specifications in SEAM

Actions in SEAM can be modeled declaratively or imperatively.

Declarative specifications describe the state of the working object prior to the action execution – pre-state - and the state of this working object upon the action termination – post-state. The pair (pre-state, post-state) describes the overall effect of the action and characterizes the external behavior of the working object.

Declarative specifications define an action contract - a triple (precondition, invariant, postcondition) - and leave the detail of implementation of this contract unspecified. Imperative specifications, in contrast, encourage the modeler to commit to an explicit scenario of an action execution.

Imperative specifications make explicit the intermediate effects of the action by defining the sequence of states the working object goes through during the action execution. This sequence of states is also called the internal behavior of the working object.

A declarative specification is beneficial when a modeler has a limited knowledge about the system and develops an abstract system specification. Once the action contract is extended with the concrete scenario of its realisation (a sequence of intermediate states), the specification becomes imperative.

For declarative specifications there exists a frame problem [14]. This problem appears when more than one implementation of the specification corresponds to its contract. To avoid erroneous implementations, the specification should explicitly indicate the properties that must remain unchanged after the action termination. This is done using frame conditions.

In contrast to declarative specification, imperative specification does not allow unspecified updates and stipulates that “what was not explicitly updated is unchanged”.

SEAM action A, seen as a whole, specifies a state change as a single transition from pre-state to post-state. Therefore the view as a whole corresponds to a declarative action specification.

SEAM action A, seen as a composite, specifies actions A1..At that should be executed to accomplish A. Action A here is called a parent action and A1..At are called component actions. A declarative specification of an action seen as a composite is useful when the modeler wants to ignore the order of component actions.

An imperative action specification introduces the ordered set of the intermediate states for this action.

Table 3-2 presents the elements of action specifications (rows) and shows the visibility of these elements in different action specifications (columns). A specification, in which less elements are visible is called more abstract, when compared to a specification where more elements are visible. For example, the most abstract specification is a declarative specification of a localized action seen as a whole.
3.3 The SEAM Metamodel (Abstract Syntax)

SEAM modeling language defines one diagram type for system specifications. The SEAM diagram is a graphical specification of a system. Figure 3-2 presents a SEAM metamodel specified as a UML [77] class diagram.

The recursive definition of the SEAM abstract syntax is presented below.

As a contribution of this work, the following elements have been added to the SEAM modeling language:
- A distributed action;
- Input/output parameters, shared properties, and local variables for actions;
- Action-to-property relations and their specializations;
- Action-to-action relations and their specializations;
- Distributed-to-localized action relations.

(These elements are denoted in **bold** in the syntax definition below.)

```
working_object = wo_whole | wo_composite
wo_whole = property {property} {localized_action}
property = primitive_property | compound_property
compound_property = {property, p_composition} {property, p_association}
localized_action = la_whole | la_composite
la_whole = {AP-relation} {input_par}{output_par}{local_var}
la_composite = localized_action {localized_action} {AA-relation}{input_par}{output_par}{shared} {local_var}
wo_composite = working_object, wo_composition {working_object, wo_composition}
```
The well-formedness rules are out of the scope of this work.

Figure 3-2: SEAM metamodel
The extension of the SEAM metamodel is resulted in a possibility to specify formal semantics for the other model elements in SEAM, including:
- A working object as a whole and as a composite;
- An action (localized, joint, distributed) as a whole or as a composite;
- A property and property-to-property relations;
- A working object-to-property relation.

Formal semantics of SEAM will be discussed in the next chapter.

### 3.4 The SEAM Semantics and Graphical Notation (Concrete Syntax)

The metamodel in Fig. 3-2 illustrates the SEAM model elements and relations between them - the abstract syntax of SEAM specifications. In this section, we specify a concrete syntax of SEAM specifications. The concrete syntax describes how model elements can be depicted and put together in SEAM diagrams.

The SEAM modeling language defines the following graphical elements:
- A working object (WO);
- A WO-composition;
- A property;
- A property composition;
- A property-to-property (PP-) relation;
- A working object-to-property (WOP-relation);
- An action;
- An action-to-action (AA-) relation;
- An action-to-property (AP-) relation;
- A distributed-to-localized action (DALA-) relation.

The following sections address these graphical elements as well as their semantics in detail.

#### 3.4.1 Working Object

The boundary of a SEAM diagram is always specified by a working object (WO) that represents the system of interest; other model elements (component working objects, properties, actions, etc) are depicted inside this working object – ‘box in the box’.

SEAM uses a ‘porter arrow’ pictogram to specify a working object (Fig. 3-3(a)). When it is necessary to emphasize the nature of the working object – other pictograms are used (Fig. 3-3(b)).

![Figure 3-3: SEAM working object: a) general representation b) specific pictograms.](image)
A working object can be modeled as a whole or as a composite. A working object as a composite (indicated by ‘_c’ or [c] in the pictogram) specifies component working objects of the same or a different kind. These component working objects are depicted inside the parent working object and are connected to it using a composition relation (Fig. 3-4). The source of the working object composition (marked with a black diamond) is called ‘parent’, the destination is called ‘component’.

Figure 3-4: Working object composition: a) composition relation with multiplicity and instance expressions; b) Example: a car as a composite specifies 4 Wheels: w1..w4.

3.4.2 Property
Working object as a whole (indicated by ‘_w’ or [w] in the pictogram) specifies properties. Properties are depicted with rectangles (Fig. 3-5(a)). For primitive properties their primitive type (e.g. ‘string’, ‘int’, ‘boolean’, etc.) is indicated under the property name.

The properties hosted by a working object are placed inside the pictogram, representing this working object and are connected to it using a working object to property (WOP) – relation (or host relation) as illustrated in Fig. 3-5(b).

A property (if compound) can be associated with another property (or group of properties), which is hosted by the same working object. This is depicted using a property association (Fig. 3-5(c)).

A property (if compound) can have component properties. The component properties are connected to their parent property using a composition relation. The source of this relation (marked with a black diamond) is called ‘parent’; the destination(s) is called ‘component’. Two versions of graphical representation are presented in Fig. 3-5(d).

Properties hosted by different working objects can be connected using a trace (Fig. 3-5(e)). In the example, the trace specifies that properties ProductID and DesiredProductID are the same.
Figure 3-5: SEAM property: a) graphical notation; b) host relation c) property association; d) composition; e) trace.

3.4.3 Action
To specify a behavior of a working object, SEAM defines localized, joint, and distributed actions (Fig. 3-6). These actions are depicted by rounded rectangles with indicated action name, type, and view.

The action type can be one of the following: LA for a Localized Action, JA for a Joint Action, or DA for a Distributed Action. The action view specifies the action modeled as a whole or as a composite (indicated by ‘_w’ or [w] and ‘_c’ or [c] respectively).

For an action seen as a composite, component actions are placed inside the pictogram representing this action. The border of the parent action is depicted using a dashed line. Fig. 3-6(b) illustrates a joint action as a composite with two component joint actions.

Figure 3-6: SEAM action specification.

3.4.4 Action-to-Action (AA-) Relations
A control flow between component actions of an action seen as a composite is specified in SEAM using action-to-action (AA-) relations. The notation is based on BPMN (Business
Process Modeling Notation) [78]. Fig. 3-7 shows the control flow of a localized action AAA seen as a composite.

SEAM specifies the following AA-relations:
- Start – to define an entry point of an action as a composite;
- End – to define an exit point of an action as a composite;
- Transition – to define a sequential composition between component actions;
- Conditional transition – to define a transition that happens if a certain condition holds;
- Fork (AND, OR, XOR) – to specify a branching of process (parallel or alternative execution of component actions);
- Merge (AND, OR, XOR) – to specify a synchronization (AND) or concurrency (OR, XOR).

Figure 3-7: Localized action AAA seen as a composite with component localized actions BB and CC. The control flow is specified using the following AA-relations (in their order of appearance from the left to the right): Start, AND-Fork, AND-Merge, End. Intermediate system states are not shown.

Figure 3-8 illustrates the SEAM graphical notation for AA-relations and the corresponding BPMN notation.

Figure 3-8: SEAM action-action (AA-) relations vs. BPMN elements (events and gateways). Taken from www.bpmn.org
Table 3-3 presents AA-relations and their semantics in more detail. Textual notation on the left specifies the action ordering. Diagrams on the right stand for imperative action specifications.

<table>
<thead>
<tr>
<th>AA-relation name and description</th>
<th>SEAM Graphical notation</th>
<th>AA-relation name and description</th>
<th>SEAM Graphical notation</th>
</tr>
</thead>
<tbody>
<tr>
<td>Start(A1) – A1 is an action start;</td>
<td><img src="image" alt="Start(A1)" /></td>
<td>AndFork(A1, {A2, A3}) – A1 is followed by A2 and A3, executing in parallel;</td>
<td><img src="image" alt="AndFork(A1, {A2, A3})" /></td>
</tr>
<tr>
<td>End(A1) – A1 is an action end;</td>
<td><img src="image" alt="End(A1)" /></td>
<td>AndMerge([A1, A2], A3) – A3 starts after both A1 and A2 terminate (synchronization);</td>
<td><img src="image" alt="AndMerge([A1, A2], A3)" /></td>
</tr>
<tr>
<td>Transition(A1, A2) – a sequential composition of A1 and A2 (A2 follows A1);</td>
<td><img src="image" alt="Transition(A1, A2)" /></td>
<td>OrFork(A1, {A2, A3}) – A1 is followed by A2, or by A3, or by both of them executing in parallel (inclusive);</td>
<td><img src="image" alt="OrFork(A1, {A2, A3})" /></td>
</tr>
<tr>
<td>ConditionalTransition (A1, A2, C) – A2 follows A1 if C holds;</td>
<td><img src="image" alt="ConditionalTransition (A1, A2, C)" /></td>
<td>OrMerge([A1, A2], A3) – A3 starts after either one of A1, A2 or both terminate (concurrency);</td>
<td><img src="image" alt="OrMerge([A1, A2], A3)" /></td>
</tr>
<tr>
<td>ConditionalTransition (A1, [A2, A3], C) – A1 is followed by A2 if C holds and by A3 otherwise;</td>
<td><img src="image" alt="ConditionalTransition (A1, [A2, A3], C)" /></td>
<td>xOrFork (A1, [A2, A3]) – A1 is followed by A2, or by A3, but not by both of them (exclusive);</td>
<td><img src="image" alt="xOrFork (A1, [A2, A3])" /></td>
</tr>
<tr>
<td>xOrMerge([A1, A2], A3) – A3 starts after either one of A1, A2, but not both terminate (concurrency);</td>
<td><img src="image" alt="xOrMerge([A1, A2], A3)" /></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

Similarly to Inclusive/Exclusive Merge and a Parallel Join gateways in BPMN (Fig. 3-8), Or- and xOr- Merge relations in SEAM specify a concurrent action execution; whereas AndMerge specifies a synchronisation. In this work, we do not consider concurrency in SEAM specification. This is a topic for future work.

Current graphical notation provides no information about the intermediate states. Fig. 3-9 illustrates the (prospective) notation, in which intermediate states of the imperative specification are shown.

![Figure 3-9](image)

Figure 3-9: Proposed graphical notation for AA-relations where intermediate states are shown; a) an imperative specification of a parallel fork; b) an imperative specification of a transition.
3.4.5 Action-to-Property (AP-) Relations

![Diagram](image)

The following action-to-property (AP-) relations are defined in SEAM (Fig. 3-10 (a)):

- ‘Pre:’ – for precondition;
- ‘Post:’ – for postcondition;
- ‘Inv:’ – for invariant;
- ‘U:’ – for update statement.

AP-relations are depicted by arrows, annotated with corresponding precondition, postcondition, invariant, or update expressions.

A precondition is a condition (or state) of the working object where the action can be triggered; a postcondition specifies the states of the working object after the action termination; an invariant is a logical expression that must hold before, after, and during the action execution.

We distinguish between action invariants, which are modeled using action to property relations and hold for a particular action, and system invariants, which hold for all the actions of this working object.

Figure 3-10(b) illustrates a local invariant Inv of action BB and a global invariant S.Inv that must hold for any action of S.

A triple (preconditions, postconditions, invariants) is also called the action contract; an update statement explicitly defines how this contract is fulfilled.

Precondition, postcondition and invariant expressions are logical expressions. In SEAM diagrams, these expressions annotate corresponding AP-relations. We write these expressions in a subset of the Alloy specification language [59].

Update statements typically stand for a change of a value of a given property and are written using assignment expressions: ‘property_old := property_new’.

Definition of AP-relations in SEAM is one of the contributions of this work. Syntax and semantics of AP-relation expressions is explained in more detail in Section 4.3.5 of the next chapter.
3.4.6 Localized vs. Joint vs. Distributed actions

SEAM defines three types of actions (localized, joint and distributed action). These actions are distinguished by the way they change a state of a working object.

- A localized action (Fig. 3-11(a)) changes the state of a working object seen as a whole by modifying its properties.
- A Joint action (Fig. 3-11(b)) changes the state of a working object seen as a composite by modifying properties of its component working objects.
- A distributed action (Fig. 3-11(c)) changes the state of a working object seen as a composite by invoking localized actions of its component working objects.

![Figure 3-11: Localized vs. Joint vs. Distributed Action.](image)

3.4.7 Shared Properties, Input and Output Parameters, Local Variables

SEAM uses action shared properties, input and output parameters, and local variables to specify a flow of data in its specifications.

Shared properties are shown in SEAM diagrams as properties with a stereotype <shared>. A shared property represents a common knowledge that is maintained by a working object as a composite (Fig. 3-12(a)); it can also specify a flow of data between component actions (Fig. 3-12(b)).

![Figure 3-12: Shared property](image)

By definition, if a property is ‘shared’ – it is visible to several working objects and can be modified by actions of these working objects. It can be considered as a global variable. Alternatively, a SEAM action may specify local variables. A local variable p:P of an action AA (Fig. 3-13) is an instance of a property P, which is created by AA and exists only during the execution of AA. A local variable is modeled using a directed relation with multiplicity and a black diamond on the action’s side.

**Note** that the instance p:P in Fig. 3-13 is defined in the context of action AA and is disjoint from the instances p1, p2,... defined in the context of working object S.
Shared and local variables are useful for modeling **persistence** of business objects.

Input and output parameters are shown in SEAM diagrams as properties with a stereotype `<IN>` or `<OUT>` (Fig. 3-14). These parameters are used to specify the data coming into the system or leaving the system while performing the action; they can be also a subject of action precondition and postcondition.

Typically, input parameters are associated with the action precondition (i.e. an **input** is something that should be received by the system to trigger the action). However, input parameters can be also received by the system in an intermediate action state. Thus, inputs are NOT always a part of the observable external behavior (i.e. a part of the precondition).

Similarly, output parameters are often identified with action postconditions (i.e. an **output** is something that is produced by the system upon the action termination). However, output parameters can be also produced by the system in an intermediate action state (as a part of internal behavior). In this case, the output parameter is not a part of the action postcondition.

### 3.4.8 Relations with Multiplicities

A working object composition, a property association, a property composition, and an action-to-local variable relation (ALocalVar) are **relations with multiplicities** in SEAM. They contain multiplicity and instance expressions in the form:

\[ M \upharpoonright I_M \]

A multiplicity expression shows how many instances of a property of a given type are considered by this relation; an instance expressions provide a list of names of these instances.

\( M \) is a multiplicity expression; it has the following format:

\[ M = # | #..#|#..*|* \]

- # - a nonnegative integer constant 0,1,2...;
- #..# - an interval with constant lower and upper bounds;
- #..*- an interval with an undefined upper bound;
- * - an interval 0..*.
IM is an instance expression; it has the following format:

\[ IM = \langle \text{inst.name}\rangle[, \langle \text{inst.name}\rangle] \]

IM defines a set \( p_1..p_M \) of allocated instance names. The size of this set is defined by the multiplicity expression \( M \) and is equal to the difference between the lower and the upper bound of an interval specified by \( M \). If the upper bound is undefined – indexed list of names can be used. For example, let multiplicity expression \( M \) be “0..*” then we define an instance expression \( I_M \) as an indexed list of names \( \{\text{name}_i\}, \) where \( i=0..* \).
Chapter 4

Formal Semantics for SEAM Specifications

To rigorously reason about visual specifications, we define a formal semantics for SEAM. This semantics is based on the set theory and first-order logic (FOL). It enables the mapping of a SEAM specification to other specification languages, i.e. Alloy [59], Jahob [63] for further validation.

In Chapter 3, the SEAM method was introduced. This work extends the SEAM modeling language with concepts of action-to-property relations, action-to-action relations, and distributed actions. In this chapter we define the formal semantics for the following concepts of SEAM modeling language:

1. SEAM working object as a whole with its
   - Properties
   - Localized action (as a whole or as a composite) [optional]
2. SEAM working object as a composite with its
   - Component working objects
   - Joint action (as a whole or as a composite) or
   - Distributed action (as a whole or as a composite)
3. Action-to-property (AP-) relations for joint and localized actions seen as a whole and its specializations:
   - Precondition
   - Postcondition
   - Invariant
   - Update statement
4. Distributed-to-localized action (DALA-) relations for distributed actions seen as a whole
5. Action-to-action (AA-) relations for localized, joint, and distributed actions seen as a composite;
6. Imperative and declarative action specifications;

As a consequence of formalization, new modeling concepts are explicitly specified in SEAM:

- State of a working object as a whole
- State of a working object as a composite
- Primitive property
- Compound property
- State of a primitive and a compound property
Based on formal semantics, we are able to define refinement relations between SEAM specifications, for example, we say that:

- A SEAM working object modeled as a composite is a refinement of a corresponding SEAM working object modeled as a whole;
- A joint or a distributed action specified for the SEAM working object as a composite is a refinement of a localized action, specified for the corresponding working object as a whole;
- A SEAM (localized, joint, distributed) action modeled as a composite is a refinement of a corresponding SEAM (localized, joint, distributed) action modeled as a whole;
- A SEAM action modeled imperatively is a refinement of a corresponding action modeled declaratively.

These refinement relations and the notion of their correctness are presented in Chapter 5.

The outline of this chapter is the following: Section 4.1 is a short introduction of first-order logic (FOL); we present a syntax, semantics, and introduce the notion of satisfiability and validity of FOL formulas – concepts fundamental for verification. In Sections 4.2 and 4.3 we present the formalization of SEAM modeling concepts in set theory and FOL. In Section 4.4 we discuss imperative and declarative modeling of behavior in SEAM; In Section 4.5 we present how creation and deletion of an object can be modeled with SEAM.

### 4.1 First-Order Logic

First-order logic (FOL) is a system of formal reasoning also known as first-order predicate calculus [18]. In this section we present a short introduction to FOL. For more details, see [18].

#### The FOL Syntax

The basic terms of FOL are **constants** a, b, c, .. and **variables** x, y, v,... Complex terms are constructed using **functions** of a different arity. Functions are denoted by symbols f, g, h,.. in FOL. An n-ary function f takes n terms as arguments: for example a function f(x, y) is a binary function applied to variables x and y. A function with arity 0 is a constant. Predicates in FOL are denoted by symbols p, q, r,... An n-ary predicate p takes n terms as arguments. A predicate can be seen as a function with a codomain \{true, false\}. An n-ary predicate applied to n terms is called an **atom** in FOL. An atom or its negation (¬) is a **literal**. FOL also defines logical **connectives** (¬,→,↔,∧) and **quantifiers** (∀,∃) that can be applied to literals to produce a FOL **formula**. FOL formulas evaluate as 'true' or 'false'.

The recursive definition of the FOL syntax is presented as follows:

- term = function(term{, term}) | constant | variable
- predicate = predicate(term{,term})
- atom = true | false | predicate
- literal = atom | ¬ atom
- formula = literal | quantifier variable . formula | formula connective formula | connective formula

- connective = ¬ | → | ↔ | ∨ | ∧
- quantifier = ∀ | ∃
variable = x | y | z |.. 
constant = a | b | c |.. 
function = f | g | h |.. 

Symbol ‘.’ is an application of a quantifier. In this work, we often use the Alloy notation [59] to specify FOL expressions for SEAM. The Alloy specification language uses the symbol ‘|’ instead of ‘.’ to denote an application of a quantifier.

Example 4-1: \( \exists x, y, z. x \cdot x + y \cdot y = z \cdot z \) is a formula where \(+,=\) are binary functions on integers. In Alloy, we write this formula as follows: \text{some } x, y, z \mid x*x + y*y = z*z

The FOL Semantics

In [18], FOL semantics is defined in terms of interpretations. An interpretation \( I : (D_I, \alpha_I) \) in FOL is a pair, where \( D_I \) is the interpretation domain, and \( \alpha_I \) is the assignment. The interpretation domain \( D_I \) is a finite or infinite set of objects (e.g. integers, SEAM properties, SEAM working objects, etc). The assignment \( \alpha_I \) maps FOL constant s and variables to elements of \( D_I \), and FOL functions and predicates to functions and predicates over elements of \( D_I \).

Based on these semantics, satisfiability and validity properties can be introduced:

A formula \( F \) is \text{satisfiable} if and only if there exists an interpretation \( I : (D_I, \alpha_I) \) such that \( F \) evaluates to ‘true’ on \( I \). A formula \( F \) is \text{valid} if and only if it is satisfiable for all interpretations \( I \).

One approach to prove that a formula \( F \) is satisfiable is to construct an interpretation \( I \), i.e. to find a configuration of values from \( D_I \) that evaluates \( F \) to ‘true’. This approach is implemented by the Alloy Analyser [3]. Validity of a formula in the Alloy Analyzer is checked by contradiction: from the definition of validity, \( F \) is valid if and only if the negation of \( F \) (\( \neg F \)) is unsatisfiable.

Another approach to prove a satisfiability or validity of a formula is based on logical inference. This approach is implemented by theorem provers, including the Jahob verification system [115][63].

In this work, we reduce the problem of refinement verification for visual SEAM specifications to the proof of validity of a corresponding FOL formula. We explain how to write such a formula for SEAM specifications in Chapter 5. In Chapter 6, we illustrate the technique of refinement verification using the Alloy Analyzer and the Jahob verification system.

4.2 Intuition for Set-Theoretical Interpretation of SEAM Modeling Concepts

We represent SEAM model elements as sets and relations between them. Table 4-1 illustrates a set-theoretical interpretation of SEAM model elements.

The elements of sets are static, whereas the relations between them can be seen as a matter of change. The change of property value can be specified by relations between sets.
Table 4-1.

<table>
<thead>
<tr>
<th>SEAM element</th>
<th>Graphical notation</th>
<th>Set–theoretical interpretation</th>
</tr>
</thead>
<tbody>
<tr>
<td>Working object</td>
<td><img src="image" alt="W" /></td>
<td>Set W</td>
</tr>
<tr>
<td>Property</td>
<td><img src="image" alt="P" /></td>
<td>Set P</td>
</tr>
<tr>
<td>WO composition</td>
<td><img src="image" alt="W" /> × <img src="image" alt="W1" /></td>
<td>Relation between two sets:&lt;br&gt;(r_{WO\text{comp}} \subseteq W \times W1);</td>
</tr>
<tr>
<td>Property composition and property to property (PP-) relation</td>
<td><img src="image" alt="Person" /> × <img src="image" alt="Age" /> × <img src="image" alt="Company" /></td>
<td>Relation between two sets:&lt;br&gt;(r_{\text{comp}} \subseteq \text{Person} \times \text{Age}) (is equivalent to &lt;br&gt;(r_{\text{comp}} \subseteq \text{Person} \times \text{Int}));&lt;br&gt;(r_{\text{assoc}} \subseteq \text{Person} \times \text{Company})</td>
</tr>
<tr>
<td>Working object to property relation (host relation)</td>
<td><img src="image" alt="Car" /> × <img src="image" alt="Year" /></td>
<td>Relation between two sets:&lt;br&gt;(r_{\text{host}} \subseteq \text{Car} \times \text{Year}) (is equivalent to &lt;br&gt;(r_{\text{host}} \subseteq \text{Car} \times \text{Int});</td>
</tr>
<tr>
<td>Multiplicity expressions and instance expressions of SEAM relations:</td>
<td><img src="image" alt="P" /> → <img src="image" alt="Q" /></td>
<td>For relation r, multiplicity expression is a cardinality of r:&lt;br&gt;(r \subseteq P \times Q;)&lt;br&gt;(\forall p \in P) 0 ≤ ({q \in Q</td>
</tr>
</tbody>
</table>

Example 4-2: Figure 4-1 illustrates a compound property, Account, which has a component property, Balance. A property composition relation between Account and Balance can be formulated as follows: \(r_{\text{comp}} \subseteq \text{Account} \times \text{Balance}\) (is equivalent to \(r_{\text{comp}} \subseteq \text{Account} \times \text{Int}\).<br><br>A multiplicity expression ‘1’ of this relation denotes that every account has exactly one value of balance (balanceValue) which is an integer (Fig.4-1(a)); We can also say that every element of Account set is related to exactly one element of Balance set (called balanceValue) which is an Integer (Fig.4-1(b)): <br>\(\forall a \in \text{Account} | \{(\text{balanceValue} \in \text{Balance} | (a, \text{balanceValue}) \in r_{\text{comp}}\} = 1\)<br>An instance expression ‘b’ of relation r specifies that for some account \(a_1\) the value of its balance is calculated as \(a_1.b\) and it is equal 1500 (Fig. 4-1(b)):<br>\(a_1.b = 1500\);<br>To change the balanceValue means to ‘redirect’ relation b from one element at Balance set to another, as shown in Fig. 4-1 (b).
Figure 4-1: a) SEAM notation; b) Set – relations notation; ‘a value change’ is modeled as a redirection of a corresponding relation.

Fig. 4-2 and 4-3 present the SEAM notation and its set-theoretical interpretation respectively.

Fig. 4-3(a) illustrates a SEAM working object W seen as a whole, properties Px, Py, Pz, and relations x, y, z, r between these elements; Fig. 4-3(b) illustrates a set-theoretical interpretation of SEAM working object W seen as a composite, its component working objects W1, W2, properties Px, Py, Pz, and relations c, t, x, y, z, r between these elements. In Fig. 4-2(b) and 4-3(b) the property Py refers to the same set of objects (interpretation domain) in reality.

Figure 4-2: a) working object W seen as a whole; b) working object W seen as a composite.

Figure 4-3: a) working object W seen as a whole (see also Fig. 4-2-a); b) working object W seen as a composite (see also Fig. 4-2-b);
4.3 Formalization of SEAM Model Elements in FOL

4.3.1 Working Object

A working object seen as a whole (denoted \( W_w \)) describes a system by a number of properties \( P_1, \ldots, P_m \) and a localized action \( LA \).

\[
W_w = (P_1, \ldots, P_m, LA)
\]  

(4.1)

Localised action \( LA \) describes the functionality of the working object. This localized action can be modeled as a whole (denoted \( LA_w \)) or as a composite (denoted \( LA_c \)). For the localized action seen as a whole no component actions are shown; the localized action as a composite, in contrast, reveals component actions and possibly their order.

A working object seen as a composite (denoted \( W_c \)) describes a system’s construction by a number of component working objects \( W_1, W_2, \ldots \) seen as a whole and a joint action \( JA \) or a distributed action \( DA \). We formalize it as follows:

\[
W_c = (W_1, \ldots, JA);
\]

\[
W_c = (W_1, \ldots, DA)
\]  

(4.2)

\( JA \) and \( DA \) can be modeled as a whole (denoted \( JA_w, DA_w \)) or as a composite (denoted \( JA_c, DA_c \)).

A working object in SEAM is represented by a set in a set-theoretical interpretation (Table 4-1). However, this working object is so precisely defined that often it explicitly refers to only one instance in the reality – the company, the IT system, the IT application, etc. Therefore, we are able to reason on the instance level using the notion of sets. In the text, we often use the term ‘working object’ and omit the word ‘instance’ to refer to the system of interest.

Working objects, representing components (components of components and so on) of this working object may have an arbitrary number of instances (elements of the same set). A number of instances for each of component working objects is specified by a multiplicity constraint of a working object composition relation.

4.3.2 Property and State

SEAM property \( P_i \) is specified in FOL as a set whose elements are instances of this property.

A state \( \overline{X} \) of a working object seen as a whole is defined by a tuple of state variables:

\[
V = (p_1, \ldots, p_{n_p})
\]  

(4.3)

The state is computed by assigning state variables to values in the domain \( D_I \). Components \( p_1, \ldots, p_{n_p} : P_1, \ldots, p_{n_p}, \ldots, p_{n_m} : P_m \) are instances of properties this working object hosts; \( D_I \) is an interpretation domain of a working object. \( D_I \) is a non-empty set of values of property instances \( p_1, \ldots, p_{n_p} \). \(| D_I | \) denotes the cardinality of \( D_I \).

To compute the state \( \overline{X} \in \Sigma \) of the working object \( W \) means to interpret \( V \) on \( D_I \), i.e. to map \( p_{11}, \ldots, p_{nm} \) to their values in \( D_I \);

The assignment \( \alpha_t \) maps variables \( p_{11}, \ldots, p_{nm} \) to elements of \( D_I \):

\[
\alpha_t : \{ p_{i_j} \mapsto 11, \ldots, p_{i_j} \mapsto \text{'Smith'}, \ldots, p_{mn} \mapsto \text{true} \}
\]  

(4.4)

Using the assignment, we denote the state \( \overline{X} \) as follows:
\[
\overline{X} = state(p_{i1},...,p_{in}) = (\alpha_1[p_{i1}],...\alpha_i[p_{in}])
\] (4.5)

To model an interaction of working objects with the environment, we specify input parameters \(I_1,...,I_k\) and output parameters \(O_1,...,O_l\). Property instances \(p_{i1},...,p_{in}\), inputs \(i_1,..,i_n\), and outputs \(o_1,..,o_n\) are state variables of a working object:

\[
V = (p_{i1},...,p_{in},i_1,...,i_n,o_1,...,o_n)
\] (4.6)

A state space of a working object defines all possible interpretations of \(V\) in \(D_I\).

A state \(\overline{X}\) of a working object seen as a composite is a tuple \(\overline{X} = (\overline{X}_1,..,\overline{X}_k)\) whose components are states of (instances of) component working objects.

We distinguish *primitive* and *compound* properties in SEAM (Fig. 4-4). Each instance of a primitive property has a value, which is a single element of its interpretation domain. This value is a *state* of this instance:

In Fig. 4-4(a), a property Age is a primitive property (a subset of integers \(\{0..200\}\)). Here \(a:Age\) specifies an instance of the property Age and has a value in the range \(0..200\). We can write: \(state(a) \in \{0..200\}\). \(\{0..200\}\) is the interpretation domain of the property Age.

![Figure 4-4: a) a primitive property; b) a compound property with two references on primitive properties.](image)

Interpretation domain \(D_I\) of a compound property is defined by a Cartesian product of interpretation domains of its component properties and properties it refers to:

A compound property Address in Fig. 4-4(b) references two primitive properties: \(s: Street\) and \(n:Number\). A pair \((s,n)\) defines a state of \(addr:Address\). We write: \(state(addr) = state(addr.s,addr.n) \in Street \times Number\), which is equivalent to: \(state(addr) \in String[30] \times \{1..200\}\)

Host relations, property associations and property compositions are defined in SEAM as *SEAM relations with multiplicities* based on relation-partition algebra [41] and a theory of multi-relations [40]. To specify the cardinality of a host relation, property association, or property composition relation, a multiplicity expression is used.

### 4.3.3 Host Relations, Property Associations, and Property Compositions

The Relation Partition Algebra (RPA) by Feijs and van Ommering [41] defines *part-of* and *use* relations as special types of binary relations. The theory of multi-relations by Feijs and Krikhaar [40] defines formalism, suitable for reasoning about relation multiplicities.
We combine these theories and formalize: (1) SEAM host relations and property compositions as *part-of relations* with multiplicities; (2) SEAM property associations as *use relations* with multiplicities.

Multi-relation \( m(x,y) = n \) (Fig. 4-5(a)), defined in [40], specifies \( n \) occurrences of the binary relation \((x, y)\), where \( x \in X \) and \( y \in Y \).

SEAM multi-relations *part-of* and *use* (Fig. 4-5(b,c)) between properties \( P \) and \( Q \), and \( P \) and \( T \), specify 'relations with multiplicities' between elements \( x:P \), \( y:Q \), \( z:T \) of corresponding properties.

\[
m(x,y) = n
\]

**Figure 4-5:** SEAM relations with multiplicities. a) binary multi-relation; b) SEAM property composition represented as a 'part-of' relation: '\( P \) is a part of \( Q \)'. This is also valid for SEAM host relations; c) SEAM property association as a 'use' relation: '\( P \) uses \( T \)'.

SEAM multi-relations *part-of* and *use* are defined by a pair of functions:

\[
\begin{align*}
\text{part}_{\inf}(P,Q) &= n_1 \\
\text{part}_{\sup}(P,Q) &= n_2 \\
\text{use}_{\inf}(P,T) &= r_1 \\
\text{use}_{\sup}(P,T) &= r_2
\end{align*}
\]

Figure 4-6: SEAM relations annotated with multiplicity and instance expressions. a) A host relation and a property composition modeled as part-of relations; b) A property association modeled as use relation; c) Well-formedness of host and property composition relations. \( T,W,Q \) are free floating properties.
Figure 4-6-a illustrates a **property composition** between P and Q modeled as a part-of relation:

\[
\text{part}_{\text{inf}}(P, Q) = 0, \quad \text{part}_{\text{sup}}(P, Q) = M_1
\]  

Eq. (4.9) can be read as follows: *There exist at most \(M_1\) instances of P for each instance of Q.*

\(x_1,..,x_{M_1}\) specifies a list of component property names in SEAM. In a set-theoretical interpretation, \(x_1,..,x_{M_1}\) specifies a list of names of relations between elements of P and Q.

Property composition relations in SEAM are *functional* and *cycle-free*. Functionality means that the property P can be a part of, at most, one compound property:

\[
\forall P, Q, R \in \tilde{P} \mid \text{part}_{\text{sup}}(P, Q) > 0 \land \text{part}_{\text{sup}}(P, R) > 0 \iff Q = R
\]  

\(\text{part}^+(P, P)\) is a set of all properties of a working object.

A property composition relation is cycle-free, i.e. property P cannot be a direct (or indirect) parent of itself (i.e. there is no path of one or more legs that starts at P and leads back to P) as defined in [41]:

\[
\forall P \in \tilde{P} \mid \text{part}^+(P, P) = \emptyset
\]  

\(\text{part}^+(P, P)\) is a transitive closure.

We define a transitive closure \(\text{part}^+(P_1, P_2)\) on \(\tilde{P}\) as a sequence of elements \(Q_i \in \tilde{P}, i = 1..n\) such that \(P_1 = Q_1\) and \(\text{part}(Q_1, Q_2) \circ \ldots \circ \text{part}(Q_{n-1}, Q_n) = \text{part}^+(P_1, P_2)\). Symbol ‘\(\circ\)’ denotes a relation composition; \(\text{part}^+(P_1, P_2)\) is an n-step path from P1 to P2.

Figure 4-6(a) illustrates a SEAM **host relation** between a working object \(\text{Spec1}\) and a property Q: \(\text{part}_{\text{sup}}(Q) = M; \text{part}_{\text{inf}}(Q) = 1\) - there exist at most M instances of Q in \(\text{Spec1}\).

Similarly to a property composition, a host relation in SEAM is *functional*, i.e. property Q can be a part of at most one working object.

A maximum and minimum number of instances of property P (denoted \(\text{Inst}_{\text{max}}(P)\), \(\text{Inst}_{\text{min}}(P)\)) in a working object can be calculated as follows:

\[
\text{Inst}_{\text{max}}(P) = \text{part}_{\text{sup}}(P) + \sum_{Q \in P} \text{part}^+(P, Q) \cdot \text{part}_{\text{sup}}(Q), \quad \text{part}^+(P, Q) = \sum_{n=1}^{\infty} \text{part}^n_{\text{sup}},
\]

\[
\text{Inst}_{\text{min}}(P) = \text{part}_{\text{inf}}(P) + \sum_{Q \in P} \text{part}^+(P, Q) \cdot \text{part}_{\text{inf}}(Q), \quad \text{part}^+(P, Q) = \sum_{n=1}^{\infty} \text{part}^n_{\text{inf}}
\]  

(4.12)

An **association** between properties P and T specifies the fact that the property P references (uses) property T. Figure 4-6-b illustrates an association between properties P and T modeled as a use relation: \(\text{part}_{\text{sup}}(P, T) = M_2; \text{part}_{\text{inf}}(P, T) = 0\) - there exist at most \(M_2\) references on T for each instance of P.

A property association relation is non-functional, i.e property T can be referenced by multiple compound properties:

\[
\exists T, P, P' \in \tilde{P} \mid P \neq P' \land \text{use}_{\text{sup}}(P, T) > 0 \land \text{use}_{\text{sup}}(P', T) > 0
\]  

(4.13)

A property association relation can be cyclic, i.e property T can be referenced by itself:

\[
\exists T \in \tilde{P} \mid \text{use}^+(T, T) \neq \emptyset
\]  

(4.14)
A maximum number of references to $T$ in the working object (denoted $\text{Ref}_{\text{max}}(P)$):
\[
\text{Ref}_{\text{max}}(T) = \max_{P} \left( \text{Inst}_{\text{max}}(P) \cdot \text{use}_{\text{sup}}(P, T) \right)
\] (4.15)

$P_i$ is a property that references $T$.

**Specification Consistency**

**Example 4.2:** Specification illustrated in Fig. 4-6 (b) defines a working object with properties $P$ and $T$ where each instance of $P$ refers some instances of $T$. We can calculate how many instances of $T$ can be demanded by a system as $\text{Ref}_{\text{max}}(T) = M \times M$. The maximum number of instances of $T$ is $\text{Inst}_{\text{max}}(T)=M_1$

If $M_1 < M \times M$ we have an insufficient declaration of $T$ that cannot cover its demand. Typically, this problem is a subject of dynamic testing; however, based on the proposed formalism, insufficient instance declaration can be detected during the static analysis, prior to code generation and execution.

We formulate the following criterion of specification consistency.

**Definition 4.1.**

A specification of a working object as a whole is consistent if:

- all host relations and property compositions are functional and cycle-free;
- instance declaration of all properties is sufficient (covers its potential demand):

\[
\exists P \in P \mid \text{Ref}_{\text{max}}(P) \leq \text{Inst}_{\text{max}}(P)
\]

Specification consistency is a part of the static semantic of the model; it can be also included into the well-formedness rules for the SEAM models\(^4\).

4.3.4 **Action**

A behavior of a working object is represented in a SEAM diagram by an action $A$ that can be modeled as a whole (denoted $A_w$) or as a composite (denoted $A_c$). In this section we provide a general formalism for actions in SEAM. Specific action types (localized, joint, and distributed actions) are discussed in the following sections.

**Action as a Whole**

Action $A$ seen as a whole ($A_w$) is a tuple $(A_{\text{in}}, A_{\text{pre}}, A_{\text{post}}, I, O)$. $I$ and $O$ denote input and output parameters of action $A$. These parameters specify the information entering and leaving the working object during the action execution. $I$ and $O$ belong to the set of state variables $V$ of the working object. **Postcondition** $A_{\text{post}}$ is a condition that a working object meets after the action termination. **Precondition** $A_{\text{pre}}$ specifies a condition that must hold prior to the action execution: *If $A$ is started in a state satisfying $A_{\text{pre}}$, it is guaranteed to terminate in a state satisfying $A_{\text{post}}$*

Precondition and postcondition are modeled as predicates over state space $\Sigma$:

\[
A_{\text{pre}} : \Sigma \rightarrow \{\text{true, false}\},
A_{\text{post}} : \Sigma \times \Sigma \rightarrow \{\text{true, false}\}
\] (4.16)

\(^4\) Static semantics of SEAM, including a definition of well-formedness rules for SEAM models is addressed in the Ph.D thesis of Lam-Son Le [tbd].
A precondition of the action A specifies a set of states of a working object, where A can be triggered. A postcondition of the action A defines a relation between the states of a working object before and after this action respectively.

**Invariant** $A_{inv}$ is a condition that holds before, after, and during the action execution. It constraints action pre-states, post-states, and intermediate states. Fig. 4-7 illustrates how action precondition, postcondition and invariant constraints the state space of a working object. The region labeled $A_{pre}$ is the set of states that satisfy the action precondition; the region labeled $A_{post}$ is the set of states of the action A, where the postcondition holds; the region labeled $A_{inv}$ is the set of states, which includes pre-states, post-states, and possible intermediate states of A.

![Figure 4-7: Representation of an action precondition, postcondition, and invariant as constraints over the state space.](image)

Any state of a working object must satisfy its **global invariants** $S_{inv}$. Invariants are formalized as predicates over state space $\Sigma$:

$$S_{inv}, A_{inv} : \Sigma \rightarrow \{true, false\} \quad (4.17)$$

Action $A$ defines a transition of the working object from state $\overline{X}$ to state $\overline{X}'$ (pre-state and post-state respectively). Action semantics is provided by an FOL-formula $A : \Sigma \times \Sigma \rightarrow \{true, false\}$. We specify the SEAM action using logical implication between precondition and postcondition:

$$A(\overline{X}, \overline{X}') \overset{def}{=} A_{pre}(\overline{X}) \rightarrow A_{post}(\overline{X}, \overline{X}') \quad (4.18)$$

If at a given state $\overline{X}$ the precondition $A_{pre}$ of the action $A$ holds, then the working object will be transferred to a state $\overline{X}'$, for which the postcondition of $A - A_{post}$ holds.

For actions with invariants we write:

$$A(\overline{X}, \overline{X}') \overset{def}{=} S_{inv}(\overline{X}) \land A_{inv}(\overline{X}) \land A_{pre}(\overline{X}) \rightarrow A_{post}(\overline{X}, \overline{X}') \land A_{inv}(\overline{X}') \land S_{inv}(\overline{X}') \quad (4.19)$$

If at a given state $\overline{X}$ the precondition $A_{pre}$ of the action $A$, and the invariants $S_{inv}, A_{inv}$ hold, then the working object will be transferred to a state $\overline{X}'$, for which the postcondition $A_{post}$ and invariants $S_{inv}, A_{inv}$ hold.

Action specifications often contain **frame conditions**. These conditions are originated from the frame problem of declarative specifications [14]: This problem appears when more than one implementation of the specification corresponds to its contract. Frame conditions constrain the number of such possible implementations by specifying the variables that are supposed to remain 'unchanged' during the action execution. We consider frame conditions in SEAM as a special case of action postconditions, as they must hold upon the action termination. We conjoin a frame condition $A_{frame}(\overline{X}, \overline{X}')$ with a postcondition to obtain the following action specification:
If the action is specified by input parameters \( I \) and output parameters \( O \), then we specify the action as follows:

\[
A(X, X', I, O) \triangleq A_{\text{pre}}(X, I) \rightarrow A_{\text{post}}(X, I, X', O)
\] (4.21)

Here action postcondition relates pre-state, post-state, input, and output parameters of the action.

If at a given state \( X \) the working object receives an input \( I \) such as the precondition \( A_{\text{pre}} \) of the action \( A \) holds, then the working object will be transferred to a state \( X' \) and generate an output \( O \), for which the postcondition of \( A - A_{\text{post}} \) holds.

Action input and output parameters can be considered as state variables.

Note that if the precondition does not hold – the post state \( X' \) is arbitrary.

In Eq. (4.21) we consider input \( I \) and output \( O \) as parts of the observable external behavior (i.e. the input is received in the pre-state and is necessary to trigger the action; the output is produced in the post-state). Note that this is not always a case: inputs and outputs can make a part of the internal (not necessarily observable) action behavior, i.e. they may appear in the intermediate action states.

**Successful Action**

Action specifications in Eq. (4.18) - (4.21) are defined as predicates that evaluate as 'false' only when the state transition is incorrect, i.e. when \( X \) satisfies \( A_{\text{pre}} \) but \( X' \) does not satisfies \( A_{\text{post}} \). Therefore, such predicate evaluates to 'true' not only when the action makes a correct state transition, but also when \( A_{\text{pre}} \) is not satisfied (i.e. no action is executed).

Now we specify a predicate that evaluates to 'true' if the action executes and makes a correct transition and as 'false' otherwise. We call this predicate a successful action specification. An action is successful if its precondition holds and its postcondition realizes. We write the expression for successful action from Eq.(4.17) as follows:

\[
A_{\text{success}}(X, X') \triangleq A_{\text{pre}}(X) \land A(X, X')
\] (4.22)

Eq. (4.22) is equivalent to \( A_{\text{pre}}(X) \land A_{\text{post}}(X, X') \)

**Update Statement**

In Eq.(4.18)-(4.21) partial action specifications are defined: these specifications do not show how the transition from a pre-state to a post-state is carried out. This transition can be explicitly specified using an update statement (or statements).

**Example 4.3:** An action contract defined by a triple (precondition, invariant, postcondition) can be implemented in many ways. Let us consider a working object \( W \) having a property \( x: \text{Int} \) (Fig. 4-8). We define an action \( A: \text{Int} \times \text{Int} \rightarrow \{\text{true}, \text{false}\} \) with the following contract:

\[
(A_{\text{pre}} : x < 0; \text{ true}; A_{\text{post}} : x' > x).
\]

Here and later in the text we denote by \( x, y, z, \ldots \) values of variables before the action execution and, respectively, by \( x', y', z', \ldots \) values of the same variables after execution of an action.
An action contract specifies that starting at a pre-state, where \( x<0 \), the action \( A \) switches the state of the system such that in a post-state \( x'>x \).

We write the action specification where the transition from the pre-state \( \overline{X} = \text{state}(x) = x \) to the post-state \( \overline{X}'=\text{state}(x) = x' \) is explicit: \( A_{\text{pre}}(x) \rightarrow (x' = A_u(x)) \wedge A_{\text{post}}(x, x') \)

\( A_u \) is an update statement. All the update statements below can correctly specify a transition from \( \overline{X} \) to \( \overline{X}' \):

- \( x' := -x \)
- \( x' := -x + 1 \)
- \( x' := -x + 2 \)
- \( \ldots \)

We define an update statement as a function that explicitly specifies how the state of a working object is switched during the action: \( A_u : \Sigma \rightarrow \Sigma \)

We distinguish two types of update statements: assignments and assumptions. An assignment update binds a variable to a (new) value: \( v := s \); An assumption update specifies a condition that, if holds, guarantees that some formula \( F \) is satisfied: \( \text{if } c \text{ then } F \).

An action specification with an update statement is written as follows:

\[
A(\overline{X}, \overline{X}') = \forall \overline{X} \left| A_{\text{pre}}(\overline{X}) \rightarrow (\exists \overline{X}' | (\overline{X}' = A_u(\overline{X})) \wedge A_{\text{post}}(\overline{X}, \overline{X}')) \right.
\]

(4.23)

For functional updates we can also write:

\[
A(\overline{X}, \overline{X}') = \forall \overline{X} \left| A_{\text{pre}}(\overline{X}) \rightarrow A_{\text{post}}(\overline{X}, A_u(\overline{X})) \right.
\]

(4.24)

Eq. (4.23)-(4.24) specifies that If at a given state \( \overline{X} \) the precondition \( A_{\text{pre}} \) of the action \( A \) holds, then the working object will be transferred to a state \( \overline{X}' = A_u(\overline{X}) \), for which the postcondition of \( A - A_{\text{post}} \) holds.

**Weakest Precondition and Hoare Triple**

We can specify Dijkstra’s Weakest Precondition [18] for the action \( A \). The weakest precondition of an action \( A \) (denoted \( wp(A_{\text{post}}, A_u) \)) defines a set of states, such that when the action \( A \) is started on a state \( \overline{X} \) satisfying \( wp(A_{\text{post}}, A_u) \), and the update statement \( A_u \) is executed on \( \overline{X} \) to produce the state \( \overline{X}' \), then \( \overline{X}' \) meets the action postcondition \( A_{\text{post}} \) [18].

This is illustrated in Fig. 4-9: The region labelled \( A_{\text{post}} \) is the set of states that satisfy action postcondition; the region labelled \( wp(A_{\text{post}}, A_u) \) is the set of states of the working object that satisfy the weakest precondition. Every state \( \overline{X} \) on which the execution of the update statement \( A_u \) leads to a state \( \overline{X}' \) in the \( A_{\text{post}} \) region must be in the \( wp(A_{\text{post}}, A_u) \) region. This is the reason the precondition \( wp(A_{\text{post}}, A_u) \) is called weakest. By definition, any other
precondition can only reduce the set of states \( \bar{X} \) on which the execution of the update statement \( A_u \) leads to \( A_{post} \) being satisfied.

**Figure 4-9: Weakest precondition**

For a sequence of update statements \( A_{u_1}; \ldots; A_{u_n} \) (operator ';' denotes the sequential composition) we denote the weakest precondition as \( \text{wp}(A_{post}, A_{u_1}; \ldots; A_{u_n}) \). For the action \( A_{post} \) to hold after executing the sequence of update statements \( A_{u_1}; \ldots; A_{u_n} \), the weakest precondition must hold on an initial state of \( A \). This weakest precondition defines the set of states \( \Sigma_{A_{pre}} \) as follows:

\[
\text{wp}(A_{post}, A_{u_1}; \ldots; A_{u_n}) = \text{wp}(\text{wp}(A_{post}, A_{u_n}), A_{u_{n-1}}; \ldots; A_{u_1})
\]

(4.25)

The postcondition \( A_{post} \) holds if it holds after the last update statement. The weakest precondition \( \text{wp}(A_{post}, A_{u_n}) = A_{post}^{n-1} \) can be considered as a postcondition of a sequence \( A_{u_1}; \ldots; A_{u_{n-1}} \) of update statements.

The verification condition for the sequence of update statements is:

\[
A_{pre} \rightarrow \text{wp}(A_{post}, A_{u_1}; \ldots; A_{u_n})
\]

(4.26)

The validity of this condition implies that when the precondition \( A_{pre} \) holds, then after the execution of the sequence of updates of \( A \), the postcondition \( A_{post} \) holds.

This verification condition is denoted by the Hoare Triple [18]:

\[
\{ A_{pre} \} A_{u_1}; \ldots; A_{u_n} \{ A_{post} \}
\]

(4.27)

**Example 4.4:** Consider Example 4.3 with the contract: \( A_{pre} = x < 0; \ A_{post} = x' > x \) and the update statement \( A_u: x' := -x \).

We write the verification condition from (4.27):

\[
\{ x < 0 \} x' := -x \{ x' > x \}
\]

\( x < 0 \rightarrow \text{wp}(x' > x, x' := -x) \);

We compute this as follows:

\[
\text{wp}(x' > x, x' := -x) \\
\leftrightarrow -x > x \text{ by substituting } x' \text{ with its assignment } x' := -x \; \\
\leftrightarrow x < -x
\]

We obtain: \( x < 0 \rightarrow x < -x \), which is valid.

A specification that defines a contract (precondition, invariant, postcondition) and omits update statements is called **partial**. A specification that defines several update statements and the order of their execution is called **imperative**. Update statements (and their order) can be considered as an **implementation** of an action contract.
Preconditions, postconditions, update statements, and invariants relate actions and properties of a working object. In SEAM graphical specifications, preconditions, postconditions, and update statements are modeled using action-property relations with annotations.

**Action as a Composite**

The action $A$ seen as a composite (denoted $A_c$) is a tuple $(A_{inv}, A_{pre}, A_1, A_2, \ldots, A_t, A_{post})$. This action specification is a detailed specification of a corresponding action seen as a whole - $A_w$. $A_1, A_2, \ldots, A_t$ are component actions of $A_c$. These actions make the action structure explicit. (Recall that in $A_w$ only the external behavior, specified by the action contract, is visible.) In the next chapter we consider the action, modeled as a composite, as a refinement of the same action, modeled as a whole.

$A_c$ can be specified declaratively, or imperatively. A declarative specification shows the effect of the action application – a transition from a pre-state to a post-state. It conceals the intermediate states and omits the specification of a control flow - the order of component actions occurrence. An imperative specification reveals the intermediate states resulted from ordered execution of component actions. An action control flow is modeled in SEAM using action-action relations.

$A_c$ is a $t$-ary predicate $\rho$ applied to the set of component actions $A_1\ldots A_t$:

$$A_c(X, X') = \rho(A_1, \ldots, A_t)$$  \hspace{1cm} (4.28)

We call $\rho$ the **ordering function**. If an action as a composite is modeled declaratively, then the ordering function $\rho$ is not specified, i.e. all combinations of component actions are possible. We express such an action as follows:

$$A_c(X, X') = \bigcup_O A_i O A_i$$  \hspace{1cm} (4.29)

Here $O$ stands for some ordering between two component actions. The specification in Eq. (4.29) is difficult to formulate for many component actions and different ordering types.

If component actions in Eq. (4.29) operate on disjoint states (i.e. do not affect each other), these actions are called **independent**.

Actions $A_1\ldots A_t$ are independent if and only if for each state variable $p_{ij}$ of a working object there is at most one component action $A_k, 1 \leq k \leq t$ that modifies this state variable during the execution of $A_c$.

Independent component actions $A_1\ldots A_t$ can be executed in parallel. In this case, the action seen as a composite will be expressed as a conjunction of its component actions:

$$A_c(X, X') = A_1 \land \ldots \land A_t$$  \hspace{1cm} (4.30)

Here all the component actions make a transition from the same pre-state $X$ to the same post-state $X'$:

$$A_c(X, X') = A_i(X, X') \land \ldots \land A_j(X, X')$$  \hspace{1cm} (4.31)

For an action, modeled imperatively, we specify the intermediate states $X_1, \ldots, X_{t-1}$ and obtain the following formula:
In Eq.(4.32) specification of intermediate states defines the order in which the component actions will be executed. This means that the execution of some action $A_i(\overline{X}_j, \overline{X}_k)$ switches the state of a working object and enables other action(s) $A_i$, for which a precondition at $\overline{X}_k$ holds: $\forall A_i | A_{i_{po}}(\overline{X}_k)$.

4.3.5 Action-to-Property (AP-) relations

Action to property (AP-) relations in SEAM diagrams are used for the explicit modeling of action contracts and update statements. AP-relations in SEAM diagrams are annotated with the corresponding expressions (the graphical notation for AP-relations was defined in section 3.4.5.).

The expressions for preconditions, invariants, and postconditions are logical expressions (predicates). We use the Alloy syntax [59] for these expressions in SEAM diagrams. For further validation and refinement verification, we define the mapping rules for the translating SEAM specifications to Alloy specifications (these rules are presented in Chapter 6). Thus, using the Alloy specification language in graphical specifications facilitates these mapping rules.

Table 4-1 lists the Alloy constructs used for annotating SEAM AP-relations.

<table>
<thead>
<tr>
<th>Alloy expression</th>
<th>SEAM</th>
</tr>
</thead>
<tbody>
<tr>
<td>all a:X</td>
<td>F</td>
</tr>
<tr>
<td>no a:X</td>
<td>F</td>
</tr>
<tr>
<td>some a:X</td>
<td>F</td>
</tr>
<tr>
<td>lone a:X</td>
<td>F</td>
</tr>
<tr>
<td>one a:X</td>
<td>F</td>
</tr>
<tr>
<td>F1</td>
<td></td>
</tr>
<tr>
<td>F1 or F2</td>
<td></td>
</tr>
<tr>
<td>F =&gt; ..</td>
<td>Logical implication. Is used for guarder update specification: ‘if F then …’, or ‘If F then .. else ..’</td>
</tr>
<tr>
<td>F &gt;= ..else ..</td>
<td></td>
</tr>
<tr>
<td>F1 &amp; &amp; F2</td>
<td>Logical conjunction. Specifies that both F1 and F2 are satisfied;</td>
</tr>
<tr>
<td>F1 and F2</td>
<td></td>
</tr>
<tr>
<td>!F</td>
<td>Negation. Specifies that F must not hold.</td>
</tr>
<tr>
<td>A in X</td>
<td>Subset. Specifies that a property instance (or group of instances) A belongs to (or does not belong to) a set defined by a property X.</td>
</tr>
<tr>
<td>A .in X</td>
<td></td>
</tr>
<tr>
<td>= &lt; &gt;</td>
<td>Operations of comparison: ‘equal to’, ‘less than’, ‘greater than’, ‘less or equal’, ‘greater or equal’, ‘not equal’</td>
</tr>
<tr>
<td>&lt;= &gt;= !=</td>
<td></td>
</tr>
<tr>
<td>+ -</td>
<td>Algebraic operations</td>
</tr>
</tbody>
</table>

For update statements, we use expressions written in Java language.

Example 4.5: Consider the action SellProduct specified as illustrated in Fig. 4-10. The expression: [one p:Product | p.id = requested_ID] is a selection of a property instance that will be updated by the action. Here, it is a selection of a product with a given id from the set of products.
An update statement expressed as an assignment `p.quantity := p.quantity - 1` defines how the selected instance will be modified by the action. Here, the quantity of a selected product will be reduced by 1.

![Diagram showing the update statement and its implementation](Image)

Figure 4-10: Update statement expressed as a selection condition followed by the assignment expression.

### 4.3.6 Action-to-Action (AA-) relations

Action-to-action (AA-) relations in SEAM connect component actions and define their order of execution. SEAM specifies AA- relations using a subset of graphical elements defined in Business Process Modeling Notation (BPMN) [78]. AA- relations defined in SEAM are:

- Start
- End
- Transition
- Conditional transition
- Fork (AND, OR, XOR)
- Merge (AND, OR, XOR)

Forking and merging of a control flow are defined using BPMN data-based or event-based gateways.

The semantics of SEAM action-action relations can be expressed using combinations of logical connectives:

- `'¬A'` - a negation 'not A';
- `'A1 ∨ A2'` - a disjunction ‘A1 or A2’;
- `'A1 ∧ A2'` - a conjunction ‘A1 and A2’;
- `'A1 → A2'` - an implication ‘A1 implies A2’.

The graphical notation of SEAM AA-relations is presented in Table 3-3 of the previous chapter; FOL semantics for these relations is presented in Table 4-2.

An AA-relation is specified by a pair `(src, dst)`, where src is a source action(s) of this relation and dst is its destination action(s).

A `Start` relation defines an entry point for an activity (a sequence of component actions, specified for some actions seen as a composite, Fig. 4-11); it has no `src` action. A destination action of a Start relation is the action, which will be executed first. This action is related to a parent action as follows: `A_{src} (X) → A_{dst} (X)`;
An End relation specifies a terminating point for a sequence of actions; it has no dst. A source action $A_n$ of the End relation illustrated in Fig. 4-10 is related to a parent action as follows: $A_{n_{pre}}(\overline{X}_n, \overline{X}') \rightarrow A_{n_{post}}(\overline{X}, \overline{X}')$

### Table 4-2: FOL-Semantics of AA-relations in SEAM

<table>
<thead>
<tr>
<th>SEAM</th>
<th>FOL:</th>
</tr>
</thead>
<tbody>
<tr>
<td>Start(A1)</td>
<td>$A_1(\overline{X}, \overline{X}_1)$</td>
</tr>
<tr>
<td>End(A1)</td>
<td>$...A_1(\overline{X}_1, \overline{X}')$</td>
</tr>
<tr>
<td>Transition(A1,A2)</td>
<td>$\exists \overline{X}_2 \mid A_1(\overline{X}_1, \overline{X}_2) \land A_2(\overline{X}_2, \overline{X}_3)$</td>
</tr>
<tr>
<td>ConditionalTransition(A1,A2,C)</td>
<td>$\exists \overline{X}_2 \mid A_1(\overline{X}_1, \overline{X}_2) \land C(\overline{X}_2) \rightarrow A_2(\overline{X}_2, \overline{X}_3)$</td>
</tr>
<tr>
<td>ConditionalTransition(A1,A2,A3,C)</td>
<td>$\exists \overline{X}_2 \mid A_1(\overline{X}_1, \overline{X}_2) \land \left( (C(\overline{X}_2) \rightarrow A_2(\overline{X}_2, \overline{X}_3)) \lor (\neg C(\overline{X}_2) \rightarrow A_1(\overline{X}_2, \overline{X}_4)) \right)$</td>
</tr>
<tr>
<td>AndFork(A1,A2,A3)</td>
<td>$\exists \overline{X}_2 \mid A_1(\overline{X}_1, \overline{X}_2) \land \left( A_2(\overline{X}_2, \overline{X}_3) \land A_3(\overline{X}_2, \overline{X}_4) \right)$</td>
</tr>
<tr>
<td>AndMerge(A1,A2,A3)</td>
<td>$\exists \overline{X}_3 \mid \left( A_1(\overline{X}_1, \overline{X}_3) \land A_2(\overline{X}_2, \overline{X}_3) \right) \land A_3(\overline{X}_3, \overline{X}_4)$</td>
</tr>
<tr>
<td>OrFork(A1,A2,A3)</td>
<td>$\exists \overline{X}_2, \overline{X}_3, \overline{X}_6 \mid \left( A_1(\overline{X}_1, \overline{X}_2) \land A_2(\overline{X}_2, \overline{X}_3) \right) \lor \left( A_1(\overline{X}_1, \overline{X}_3) \land A_3(\overline{X}_3, \overline{X}_4) \right) \lor \left( A_2(\overline{X}_2, \overline{X}_3) \land A_3(\overline{X}_3, \overline{X}_4) \right) \lor \left( A_1(\overline{X}_1, \overline{X}_6) \land A_2(\overline{X}_6, \overline{X}_7) \land A_3(\overline{X}_6, \overline{X}_8) \right)$</td>
</tr>
<tr>
<td>OrMerge(A1,A2,A3)</td>
<td>$\exists \overline{X}_2, \overline{X}_4, \overline{X}_7 \mid \left( A_1(\overline{X}_1, \overline{X}_2) \land A_2(\overline{X}_2, \overline{X}_3) \right) \lor \left( A_2(\overline{X}_2, \overline{X}_4) \land A_3(\overline{X}_4, \overline{X}_6) \right) \lor \left( A_1(\overline{X}_1, \overline{X}_7) \land A_2(\overline{X}_7, \overline{X}_8) \land A_3(\overline{X}_7, \overline{X}_8) \right)$</td>
</tr>
<tr>
<td>XORFork(A1,A2,A3)</td>
<td>$\exists \overline{X}_2 \mid \left( A_1(\overline{X}_1, \overline{X}_2) \land \neg A_2(\overline{X}_2, \overline{X}_4) \land A_3(\overline{X}_2, \overline{X}_4) \right) \lor \left( A_1(\overline{X}_1, \overline{X}_2) \land \neg A_1(\overline{X}_2, \overline{X}_5) \land A_2(\overline{X}_2, \overline{X}_5) \right)$</td>
</tr>
<tr>
<td>XORMerge(A1,A2,A3)</td>
<td>$\exists \overline{X}_2, \overline{X}_4 \mid \left( A_1(\overline{X}_1, \overline{X}_2) \land A_2(\overline{X}_2, \overline{X}_3) \land \neg A_1(\overline{X}_4, \overline{X}_4) \right) \lor \left( A_2(\overline{X}_3, \overline{X}_4) \land A_3(\overline{X}_4, \overline{X}_6) \land \neg A_3(\overline{X}_2) \right)$</td>
</tr>
</tbody>
</table>

SEAM transition relation specifies a sequential composition of actions, when after the termination of one action, another action is triggered. We formalize a transition from action $A_1$ to action $A_2$ as a conjunction of predicates specifying actions:

$$\exists \overline{X}_2 \mid A_1(\overline{X}_1, \overline{X}_2) \land A_2(\overline{X}_2, \overline{X}_3) \quad (4.33)$$

Here $\overline{X}_2$ is an intermediate state between $A_1$ and $A_2$; it is a post-state of $A_1$ and a pre-state of $A_2$.

Using Eq. (4.18), we rewrite Eq. (4.33) as follows:
If update statements $A_{1u}, A_{2u}$ are specified – we write the following expression for action transition:

$$
\exists X_2 \left[ \left(A_{1\text{pre}}(X_1) \rightarrow A_{1\text{post}}(X_1, X_2) \right) \land \left( A_{2\text{pre}}(X_2) \rightarrow A_{2\text{post}}(X_2, X_3) \right) \right]
$$

(4.34)

Recall the discussion about successful action specification: the expression for action transition in Eq. (4.34)-(4.35) will be evaluated to ‘true’ even if one of its actions is not successful (i.e. when $A_{1\text{pre}}(X_1) = \text{false}$ or $A_{2\text{pre}}(X_2) = \text{false}$). We call a transition successful when the preconditions of both $A_1$ and $A_2$ are satisfied:

$$
\exists X_2 \left[ A_{1\text{pre}}(X_1) \land A_{1}(X_1, X_2) \land A_{2\text{pre}}(X_2) \land A_{2}(X_2, X_3) \right]
$$

(4.35)

(4.36)

**SEAM conditional transition** relation specifies a sequential composition of actions $A_1$ and $A_2$, assuming that a condition $C$ holds:

$$
\exists X_2 \left[ A_1(X_1, X_2) \land C(X_2) \rightarrow A_2(X_2, X_3) \right]
$$

(4.37)

Note that if $C$ does not hold, then the transition results in an arbitrary state.

By analogy with the successful transition in Eq.(4.36), we write the successful conditional transition:

$$
\exists X_2 \left[ A_{1\text{pre}}(X_1) \land A_1(X_1, X_2) \land C(X_2) \land A_{2\text{pre}}(X_2) \land A_2(X_2, X_3) \right]
$$

(4.38)

A conditional transition can be specified as an ‘exclusive OR’ - XOR fork. This means that if $C$ holds, then action $A_2$ is triggered, else action $A_1$ is triggered:

$$
\exists X_2 \left[ A_1(X_1, X_2) \land \left( C(X_2) \rightarrow A_2(X_2, X_3) \right) \lor \left( \neg C(X_2) \rightarrow A_1(X_2, X_4) \right) \right]
$$

(4.39)

A **fork** relation in SEAM specifies a split of the control flow, when after a termination of an action, several actions can be triggered. A fork relation has one source action ($src$) and a set of destination actions ($dst$).

A **merge** relation in SEAM is the opposite of the fork relation. It specifies a join of different branches in the control flow, when several actions should terminate before another action is triggered. A merge relation can be used for modeling synchronization or concurrency. This relation is specified with a set of source actions ($src$) and one destination action ($dst$).

We distinguish **AND** (parallel), **OR** (inclusive OR), and **XOR** (exclusive OR) fork and merge relations in SEAM.

**AND fork** defines a parallel execution of a set of actions, specified in a $dst$ parameter.

**AND merge** stands for synchronization: all the actions specified in a $src$ parameter of AND merge relation must terminate at the same post-state;

**OR fork** specifies a nondeterministic performance: any combination of actions from the $dst$ set can be triggered. As a result, several different traces of intermediate states can be produced;

**OR merge** specifies a concurrency.

**XOR fork** and **XOR merge** are exclusive choices, when only one action from the $dst$ set (the $src$ set for merge) executes.
We use logical connectives and their combinations to connect component actions within a parent action seen as a composite. This is shown in Table 4-2. This table complements Table 3-3 where the visual SEAM syntax of AA-relations is presented.

4.3.7 Distributed Action and Distributed to Localized Action (DALA-) Relations

In contrast to SEAM localized and joint actions, a distributed action does not affect the properties of a working object directly. It specifies an interaction between component working objects and an invocation of the localized actions of these component working objects:

\[
DA(\bar{X}, \bar{X}') = \rho_d(LA_1, ..., LA_k) \tag{4.40}
\]

Distributed action does not specify its own precondition, postcondition, and invariants.

If a distributed action is modeled declaratively, then the ordering function \( \rho_d \) is not specified, i.e. localized actions can be triggered in any order:

\[
DA(\bar{X}, \bar{X'}) = \bigcup_\varnothing LA_1.O..OLA_k \tag{4.41}
\]

Here \( O \) stands for some ordering between two localized actions. Eq. (4.41) specifies all possible combinations of action invocations.

If localized actions in Eq. (4.41) operate on disjoint states (i.e. do not affect each other), these actions are independent and can be executed in parallel. We represent a declarative specification of a distributed action by a conjunction of these localized actions:

\[
DA(\bar{X}, \bar{X}') = LA_1(\bar{X}, \bar{X'}) \land .. \land LA_k(\bar{X}, \bar{X'}) \tag{4.42}
\]

Here all localized actions make a transition from the same pre-state \( \bar{X} \) to the same post-state \( \bar{X}' \).

For a distributed action, modeled imperatively, we specify the intermediate states \( \bar{X}_1, ..., \bar{X}_{k-1} \) and obtain the following formula:

\[
DA(\bar{X}, \bar{X'}) = \exists \bar{X}_1, ... , \bar{X}_{k-1} \mid LA_1(\bar{X}, \bar{X}_1) \land .. \land LA_k(\bar{X}_{k-1}, \bar{X'}) \tag{4.43}
\]

We use distributed-to-localized action relations (DALA-relations) in SEAM diagrams to specify the localized actions, bound by a given distributed action, and their order of invocation.

In the next chapter, we consider a distributed action of a working object seen as a composite as a refinement of a localized action of the same working object seen as a whole.

4.4 Imperative vs. Declarative Specifications

A declarative action specification defines a single transition of a working object from a pre-state to a post-state and does not show the intermediate states.

An imperative specification of an action introduces the ordered set of the intermediate states for this action. Each intermediate state may correspond to:
- a post-state of some component action (for an action as a composite);
- a post-state of a localized action executed as a part of a distributed action;
- an update of a single property (for a localized or a joint actions as a whole).
4.5 Instance Creation and Deletion: Local Variables

The creation and deletion of an instance of a component working object, a property, or a reference to a property can be seen as a part of a dynamic behavior of a system. To create a new instance means to specify a binding between an instance name and a value in its interpretation domain. A new instance name is a name, defined by the instance expression and not yet allocated to any other instance. Instance deletion respectively releases this binding.

![Diagram](image.png)

Figure 4-12: a) Creation of a new element in a list using a local variable; b) Creation of an element modifies an instance counter $M_{current}$

In SEAM specifications, creation or deletion operations also modify a current number $M_{current}$ of instances of a given object. This number is usually restricted by a multiplicity expression (Fig. 4-12 (b)). $M_{current}$ can be seen as an instance counter. Its minimum and
maximum values are defined by a multiplicity constraint. For the model in Fig. 4-12 it is: \(0 \leq M_{current} \leq \infty\). The fact that the instance \(newP\) becomes an \((M_{current}+1)\)th element in the \(listP\) – i.e. increases the instance counter value by 1 - is not explicit in Fig. 4-12 (a).

The deletion of an instance can be specified in a similar way (Fig. 4-13). To delete an instance that corresponds to a certain condition \(c\):

1. We specify a local variable \(oldP\): \(\text{one oldP} \mid c(oldP)\)
2. We state that such a variable exists in \(listP\) but does not exist in \(listP'\).

Here \(listP\) and \(listP'\) define the state of a system before and after the action \(\text{DeleteP}\) respectively.

Instance deletion decreases the instance counter value by 1.

![Diagram](image)

Figure 4-13: a) Deletion of an ‘old’ element from the list; b) Deletion of an element modifies an instance counter \(M_{current}\)
Chapter 5

Transformations of Refinement in SEAM and Refinement Verification

To reason about alignment between SEAM visual specifications, we identify the relationships between these specifications with a transformation of refinement as defined in Model-Driven Engineering (MDE). As MDE does not provide a formal notion of correctness for these transformations, it is challenging to specify a verification procedure for them.

Refinement and refactoring are also defined in software engineering; they specify the transformations of programs. Compared to MDE, refinement correctness in software engineering is formally defined and can be validated using formal methods.

Formal semantics for visual specification increases the precision of these specifications. Based on this, we can specify the criteria of refinement correctness for visual specifications by an analogy with refinement correctness, defined for programs.

In software engineering, formal methods allow us to formulate a refinement correctness of a program as a first-order logic formula and to validate this formula. Along these lines, we represent SEAM visual specifications and relationships between them as first-order logic formulas and reduce the problem of refinement verification to a problem of validation of the first-order logic formula.

In Section 5.1 we discuss the transformations of refinement and refactoring. In Section 5.2 we make an overview of simulation techniques for refinement verification. We present in more details data refinement [51], forward simulation as a method to prove its correctness, and ASM refinement method [16] based on generalized forward simulation.

Modification, creation, or deletion of model elements in a diagram leads to a specification refinement. In sections 5.3 – 5.7 we specify different forms of refinement in SEAM. We formulate the criteria of correctness for each form of refinement in terms of forward simulation (as defined in [51][27][112]) or in terms of generalized forward simulation (as defined in [16]).

5.1 Refinement vs. Refactoring

In software engineering, a technique for transforming an existing code (its internal structure) without changing its external behavior is known as refactoring [42][69].

We specify the external behaviour of a system, executing an action $A$, as a pair of system states $\overline{X}, \overline{X'}$ before and after the execution of $A$. Refactoring preserves this pair for each execution of the action $A$ and its refactoring $A_{\text{refact}}$ such that whenever the action $A_{\text{refact}}$ starts at $\overline{X}$ and terminates at $\overline{X'}$, there exists a corresponding run of the action $A$, which also starts at $\overline{X}$ and terminates at $\overline{X'}$. We formulate this as follows:
\[ \forall X, X' \in \Sigma \mid A_{\text{refact}}(X, X') \Rightarrow A(X, X') \]  

(5.1)

Eq. (5.1) is a criterion of refactoring correctness. Various refactoring types are specified in www.refactoring.org and in the literature. Automated refactoring is supported by a number of tools and environments for automated software development, such as IDEA by IntelliJ, Eclipse, NetBeans, Visual Studio, etc.

Refinement [111] is a general technique that specifies a stepwise development of the program by adding details or eliminating nondeterminism. As opposed to refactoring, refinement can change an observable behavior of a model (including its external behavior), thus it specifies a wider class of transformations than refactoring does (www.refactoring.org). Adding or removing a field or a method of a class are examples of refinement, but they are not refactoring.

Refinement can be seen as a transformation which preserves the corresponding external behavior:

\[ \forall X', X' \in \Sigma, X \in \Sigma \mid A_{\text{refine}}(X, X') \land R(X, X') \Rightarrow \exists X', X' \in \Sigma \mid A(X, X') \land R(X, X') \]  

(5.2)

Formula (5.2) denotes that whenever the refined action \( A_{\text{refine}} \) starts at \( X \) and terminates at \( X' \), there exists a corresponding run of the action \( A \), which starts at the corresponding state \( X \), related to \( X \) by \( R \), and terminates at a state \( X' \), which is also related to \( X \) by \( R \).

The initial action specification is also called abstract; respectively, the refined action specification is called concrete. Therefore, we use indexes ‘a’ and ‘c’ to specify states of the abstract and concrete specification in Eq. (5.2).

\( R \) is a refinement relation. It defines a relation between observable system states of the concrete and abstract specifications: \( R : \Sigma \times \Sigma \rightarrow \{\text{true, false}\} \). A refinement relation can be specified as a function \( R : \Sigma \rightarrow \Sigma \) that maps each state of the concrete specification to exactly one state of the abstract specification.

Refactoring can be considered as a special case of refinement: If a state space of the concrete (refined) specification is the same as a state space of the abstract (initial) specification, i.e. \( \Sigma_a = \Sigma_c \), and \( R \) is defined as an identity function: \( R : \forall X \in \Sigma \mid R(X) = X \), then the definition of refinement correctness from (5.2) transforms to the definition of refactoring correctness from (5.1).

In this work, we use program refinement as semantics for all transformations defined for SEAM specifications. A model development process in SEAM can be also considered as a stepwise refinement of graphical specifications [96].

5.2 Simulation Techniques: the State of the Art

The verification of concurrent systems is largely based on the use of simulation techniques [65]. By simulation we understand a correspondence between the states of two systems, abstract and concrete; here the concrete system is considered an implementation and the abstract system is its specification. The simulation proof is based on the establishing of this correspondence. The fact that a simulation exists between two systems shows that any behavior of one system can be exhibited (simulated) by the other system.

Along these lines, we consider two visual system specifications, where one is refining the other. The refinement correctness can thus be verified. The proof of refinement correctness is based on the establishing of a refinement relation between the abstract and concrete system specifications, and on the demonstration that this relation is a simulation.
A large number of different types of simulations is presented in the research literature; we consider only several of them: forward simulations, backward simulations, hybrid simulations (i.e. forward-backward and backward-forward simulations) [65][112][50], refinement mappings [1], and the proof method called generalized forward simulation [16][98].

Here we illustrate how different simulations can be used to verify data refinement. In software engineering, data refinement is a special case of refinement where one data type in program is refined by the other. Later we show that many forms of refinement in SEAM can be also considered as data refinements. Thus, the simulation techniques for the verification of data refinement (e.g. forward simulation) can be used to verify certain forms of refinement in SEAM.

**Data refinement.** A data type X can be defined by a state space $\Sigma$ and an indexed collection of operations $o_i : \Sigma \rightarrow \Sigma, i : I$. Where I is an indexing set.

A program $P(X)$ on data type X can be seen as a sequence of operations from the indexed set performed on X. In data refinement, we replace an abstract data type by a more concrete data type in a program while preserving its algorithmic structure. Abstract operations are similarly replaced by corresponding concrete operations [72].

**Simulation proof of data refinement** correctness is based on forward or backward simulation (often specified as functional relation). This relation is established for each pair of corresponding operations. We say that data refinement has a (1-1)-refinement proof schema. To verify that data type A is a correct refinement of data type B, values produced at each step of a program's execution are considered.

**Forward simulation for verification of data refinement:**
If data types A and B share the same indexing set I, a forward simulation from A to B is a relation $R : \Sigma_A \rightarrow \Sigma_B$ over states of A and B, which satisfies:
- If $s_0 \in \text{start}(A)$, then $R(s_0) \cap \text{start}(B) \neq \emptyset$, where $\text{start}(A) \subseteq \Sigma_A, \text{start}(B) \subseteq \Sigma_B$ are sets of initial states of A and B respectively; here $R(s_0)$ defines an image of $s_0$ – a start state of A – on the state space $\Sigma_B$. The expression $R(s_0) \cap \text{start}(B) \neq \emptyset$ means that some states in this image are start states of B.
- For all $i : I$, if an operation $o_{IA}$ performed on A such that $s \rightarrow_{o_{IA}} s'$ and $u \in R(s)$, then there exists a state $u' \in R(s')$ such that it is a resulting state of the corresponding operation $o_{IB}$ performed on B: $u \rightarrow_{o_{IB}} u'$. Expression $s \rightarrow_{o_{IA}} s'$ denotes a transition from s to $s'$ in A as a result of the operation $o_{IA}$; respectively, $u \rightarrow_{o_{IB}} u'$ is a corresponding transition in B.

The first condition relates respective initial states; the second condition matches the effect of each step in A with a corresponding forward step in B.

**Backward simulation for verification of data refinement:**
If data types A and B share the same indexing set I, a backward simulation from A to B is a total relation $R^* : \Sigma_A \rightarrow \Sigma_B$ over states of A and B that satisfies:
- If $s_0 \in \text{start}(A)$, then $R^*(s_0) \subseteq \text{start}(B)$. Compared to forward simulation, backward simulation requires that all states in the image of $s_0$ in $\Sigma_B$ are start states of B;
- For all $i:I$, if an operation $o_{iA}$ performed on $A$ such that $s \xrightarrow{o_{iA}} s'$ and $u \in R^-(s')$, then there exists a state $u \in R^-(s)$ such that it is an initial state of the corresponding operation $o_{iB}$ performed on $B$: $u \xrightarrow{o_{iB}} u'$

The first condition relates respective initial states; the second condition matches the effect of each step at $A$ with a corresponding backward step in $B$.

There are also cases where a combination of backward and forward simulations is required (a complete proof method): $A$ is behaviorally equivalent to $B$ if there is some $C$ such that there exists a forward simulation $R$ from $A$ to $C$ and the backward simulation $R^-$ from $C$ to $B$ [65].

Forward-backward and backward-forward simulations combine in a single relation both a forward and a backward simulation. For more details, read [65].

The refinement mappings introduced in [1] are another proof method for refinement verification. Refinement mapping from a lower level specification $S_1$ to a higher level specification $S_2$ is defined as a mapping from a state space of $S_1$ to a state space of $S_2$. If $S_1$ implements $S_2$, then by adding auxiliary – history and prophecy - variables to $S_1$ the existence of a refinement mapping (and subsequently, refinement correctness) can be guaranteed. The connection between history variables and forward simulations and also between prophecy variables and backward simulation is shown in [65].

Generalized forward simulation:
The ASM-refinement method [15][16] defines the method of refinement verification based on forward simulation. The simulation proof specified in [98] is called a generalized forward simulation: it generalizes forward simulations from [65][112] by allowing arbitrary diagrams, i.e. providing a (m-n)-refinement proof schema.

ASM-refinements are verified using an informal notion of commuting diagrams. Instead of matching the results of execution of corresponding operations $o_{iA}$, $o_{iB}$ - considered in forward and backward simulation methods for data refinement - ASM splits the programs of an abstract and a concrete specifications into (finitely or infinitely) many 'subcomputations'(of finite length) and matches the results of these subcomputations. The idea is to verify that each pair of subcomputations preserves a so-called coupling invariant. The coupling invariant may be equal to the refinement relation $R$ between specification state spaces.

5.2.1 Data Refinement with Forward Simulation: (1, 1) - refinement schema

We adopt the notion of data refinement from [51][72][50][101][102] and consider forward simulation, presented in [50][112] as a technique to validate refinement correctness.

Definition of refinement correctness
Let us consider a working object $W_a$, specified on the state space $\Sigma_a$ with an action $A_a$, and a working object $W_c$, specified on the state space $\Sigma_c$ with an action $A_c$.

Definition 5.1.
Given a refinement relation between state spaces, $W_c$ is called a correct refinement of $W_a$ if and only if for each run of the $R: \Sigma_a \times \Sigma_c \rightarrow \{true, false\}$ concrete action $A_c$ of $W_c$, which
starts at $\overline{X}_c \in \Sigma_c$ and terminates at $\overline{X}_c' \in \Sigma_c$, there exists a run $A_a$ of $W_a$, which starts at $\overline{X}_a \in \Sigma_a$ such that $R(\overline{X}_a, \overline{X}_c')$ holds and terminates at $\overline{X}_a'$, such that $R(\overline{X}_a', \overline{X}_c')$ holds.

This definition can be expressed with the following formula:

$$ R : \Sigma_a \times \Sigma_c \rightarrow \{true, false\}; $$

$$ \forall \overline{X}_c, \overline{X}_c' \in \Sigma_c \mid \forall \overline{X}_a \in \Sigma_a \mid (R(\overline{X}_a, \overline{X}_c) \land A_c(\overline{X}_c, \overline{X}_c')) \Rightarrow \exists \overline{X}_a' \in \Sigma_a \mid A_a(\overline{X}_a, \overline{X}_a') \land R(\overline{X}_a', \overline{X}_c') \quad (5.3) $$

if refinement relation is a function $R : \Sigma_c \rightarrow \Sigma_a$, we rewrite (5.3):

$$ R : \Sigma_c \rightarrow \Sigma_a; $$

$$ \forall \overline{X}_c, \overline{X}_c' \in \Sigma_c \mid \forall \overline{X}_a \in \Sigma_a \mid (R(\overline{X}_c) = \overline{X}_a) \land A_c(\overline{X}_c, \overline{X}_c') \Rightarrow (\exists \overline{X}_a' \in \Sigma_a \mid A_a(\overline{X}_a, \overline{X}_a') \land (R(\overline{X}_c') = \overline{X}_a')) \quad (5.4) $$

This is equivalent to:

$$ A_c(\overline{X}_c, \overline{X}_c') \Rightarrow A_a(R(\overline{X}_c), R(\overline{X}_c')) \quad (5.5) $$

Data refinement verification by forward simulation is reduced to a proof of validity of (5.3) - (5.5).

The data refinement schema for SEAM specifications is illustrated in Fig. 5-1, where $W_c$ is a concrete specification and $W_a$ is the abstract specification. $A_c$ and $A_a$ are concrete and abstract actions respectively. “$W_c$ correctly refines $W_a$” means that whenever $A_c$ makes a transition from $\overline{X}_c$ to $\overline{X}_c'$, $A_a$ is also making a transition from $\overline{X}_a$ to $\overline{X}_a'$ and these states are related by $R$ as defined in (5.3)-(5.5).

![Figure 5-1: The (1,1)-refinement for SEAM specifications](image)

The proposed formal semantics allow for a validation of SEAM specifications as well as a validation of their refinements (i.e. a transition from one specification to another).

### 5.2.2 ASM Refinement: $(m,n)$ – Refinement Schema

Forward simulation for data refinement preserves the corresponding pre- and post- states, the external behaviour of a working object. We use the definition 5.1 to express the refinement correctness between two SEAM actions modeled declaratively, where only corresponding pre- and post- states of these actions are observable. When the analysis of intermediate action states is required, we use the generalized $(m,n)$-refinement schema, specified by ASM-refinement method.

**The ASM Refinement Method**

In [16][98], the Abstract State Machine (ASM) refinement method is presented. The ASM refinement method generalises the notion of refinement for an arbitrary number of transitions (called run segments) between an initial (pre-) and a final (post-) states of a transition system.
We call a refinement schema, defined by this method, an \((m,n)\)-refinement schema. The number of run segments for an abstract and a concrete system in the \((m,n)\)-refinement schema can be different. This generalized notion of refinement takes into consideration the intermediate system states. We use the \((m,n)\)-refinement schema defined by the ASM refinement method as semantics for refinement between SEAM specifications modeled imperatively.

The ASM refinement method specifies a run as a sequence of states that starts from the initial state. Runs can be finite and infinite. A finite run terminates at a final state after a number of transitions (run segments) have been performed. Each run segment transits the system to an intermediate state (respectively, the last segment transits the system to its final state). A state is final if it has no successor state.

In SEAM, by a run we understand an execution of an action (or a set of actions) by a working object. It starts at a pre-state, terminates at a post-state, and may include intermediate states. For a SEAM (localized, joint, or distributed) action seen as a composite and modeled imperatively, intermediate states are post- and pre-states of component actions; for a SEAM distributed action modeled imperatively, intermediate states are post- and pre-states of the localized actions bound by this declarative action.

The ASM refinement method specifies a relation \(R^*\) between \textit{states of interest} of an abstract and a concrete transition systems. States of interest are specification states that we want to preserve after refinement. They include an initial state, a final state, and a number (not necessarily all) of intermediate states: these states represent a particular interest in a specification analysis. We formulate \(R^*\) for SEAM specifications as a relation between the \textit{states of interest} of the abstract and the concrete working objects respectively:

\[
R^*: \Sigma_c^* \times \Sigma_c^* \rightarrow \{\text{true, false}\}, \text{ where } \Sigma_c^* \subseteq \Sigma_c, \Sigma_a^* \subseteq \Sigma_a
\]  

(5.6)

The ASM method gives definitions of partial and total refinement correctness. A partial correctness is defined for the terminating abstract and refined runs. It stipulates that the refinement is partially correct if the terminating refined run produces the same result (with respect to the relation \(R^*\)) as the terminating abstract run. It is a weak definition of correctness because it accepts the possibility of simulating a terminating abstract run by a non-terminating concrete run. In other terms, if the concrete run is non-terminating, we cannot reason about the refinement correctness.

A total correctness stipulates that a refinement is [totally] correct with respect to the relation \(R^*\) when it is partially correct and for each non-terminating (infinite) refined run there exists an infinite abstract run. The generalized forward simulation, presented in [98], is a technique for validating a correctness of ASM-refinement.

In this work we assume that all actions specified in SEAM are terminating actions. Therefore, we provide only a definition of partial refinement correctness for SEAM specifications. We address in our future work the refinement correctness for possibly infinite action runs.

**Definition of Refinement Correctness**

The \((m,n)\)-refinement schema can be considered as a generalized \((1,1)\)-refinement schema from the previous section. First, we provide a definition of the correct \((m,n)\)-refinement for SEAM specifications. It preserves the external behavior of a working object, i.e. its pre- and post-states. Then we proceed with a refinement correctness for \((m,n)\)-refinement that takes into account the intermediate states (the internal behavior of a working object).
Let us consider a working object \( W_a \), specified on the state space \( \Sigma_a \) with an action \( A_a \), and a working object \( W_c \), specified on the state space \( \Sigma_c \) with an action \( A_c \). \( \Sigma_c \subseteq \Sigma \) and \( \Sigma_a^* \subseteq \Sigma_a \) are sets of states of interest of corresponding working objects.

**Definition 5.2** [preservation of the external behavior]
Given a refinement relation between state spaces \( R^*: \Sigma_a^* \times \Sigma_c^* \rightarrow \{ \text{true}, \text{false} \} \), \( W_c \) is called a **correct refinement** of \( W_a \) if and only if for each run of the concrete action \( A_c \) of \( W_c \), which starts at \( \overline{X}_c \in \Sigma_c^* \) and terminates in \( n \) steps at \( \overline{X}_c' \in \Sigma_c^* \), there exists a run \( A_a \) of \( W_a \), which starts at \( \overline{X}_a \in \Sigma_a^* \) such that \( R^*(\overline{X}_a, \overline{X}_c) \) holds and **after a number of steps** \( m \), \( A_a \) terminates at \( \overline{X}_a' \) where \( R^*(\overline{X}_a', \overline{X}_c') \) holds.

If the intermediate states are not shown, Definition 5.2 corresponds to the Definition 5.1 and can be expressed by the following formula:

\[
R^*: \Sigma_a^* \times \Sigma_c^* \rightarrow \{ \text{true}, \text{false} \};
\]

\[
\forall \overline{X}_c, \overline{X}_c' \in \Sigma_c^* \mid \forall \overline{X}_a \in \Sigma_a^* \mid (R^*(\overline{X}_a, \overline{X}_c) \land A_c(\overline{X}_c, \overline{X}_c')) \Rightarrow \exists \overline{X}_a' \in \Sigma_a^* \mid A_a(\overline{X}_a, \overline{X}_a') \land R^*(\overline{X}_a', \overline{X}_c') \tag{5.7}
\]

Fig. 5-2 illustrates the \((m,n)\)-refinement schema that preserves the external behavior, adopted for SEAM specifications. \( W_c \) is a concrete specification and \( W_a \) is the abstract specification of a working object. \( A_c \) and \( A_a \) are concrete and abstract actions respectively. The concrete specification makes \( n \) steps from its initial state \( \overline{X}_c \) to the final state \( \overline{X}_c' \), whereas an abstract specification makes \( m \) steps from \( \overline{X}_a \) to \( \overline{X}_a' \). Initial and final specifications states are related with \( R^* \).

**Figure 5-2:** The \((m,n)\)-refinement for SEAM specifications: preservation of the external behavior

When a refinement is carried out, the preservation of both external and internal behavior of the system might be required. By the internal behavior we understand a sequence of intermediate states of the working object. The following definition specifies the correctness of the \((m,n)\)-refinement the preserves the sequences of intermediate states.

**Definition 5.3** [preservation of the external and the internal behavior]
Given a refinement relation between state spaces \( R^*: \Sigma_a^* \times \Sigma_c^* \rightarrow \{ \text{true}, \text{false} \} \), \( W_c \) is called a **correct refinement** of \( W_a \) if and only if for each run of the concrete action \( A_c \) of \( W_c \) defined
by the ordered sequence of states, including the initial and the terminating states: $X_{i_0}c, X_{i_1}c, ..., X_{i_n}c, X_{i_n+1}c, X_{i_{n+2}}c \in \Sigma^*_c | (X_{i_0}c = X_c) \land (X_{i_n+1}c = X'_c)$, such that $i_0 \rightarrow i_1 \rightarrow \ldots \rightarrow i_n$ is a monotone sequence of natural numbers; there is a run $A_a$ of the abstract action of $W_a$, also defined by the ordered sequence of states: $X_{j_0}a, X_{j_1}a, ..., X_{j_m}a, X_{j_{m+1}}a, X_{j_{m+2}}a \in \Sigma^*_a | (X_{j_0}a = X_a) \land (X_{j_{m+1}}a = X'_a)$, such that $j_0 \rightarrow j_1 \rightarrow \ldots \rightarrow j_m$ is a monotone sequence of natural numbers; and for every $k$ the states of the abstract and concrete specifications $X_{k_e}c, X_{k_t}c \in \Sigma^*_c$ the refinement relation $R^*(X_{k_t}c, X_{k_e}c)$ holds.

We write the following formula to express the definition above:

$$R^*: \Sigma_c \times \Sigma_a \rightarrow \{true, false\};$$

$$\forall X_c, X'_c, X_a \in \Sigma_c, X_a \in \Sigma_a,$$

$$((R^*(X_c, X_a)) \land A_c(X_c, X'_c)) \Rightarrow \exists X'_a \in \Sigma^*_a | A_a(X_a, X'_a) \land (R^*(X'_c, X'_a)) \land$$

$$\exists X_{k_e}c, X_{k_t}c, X_{k_{t+1}}c, ..., X_{k_{t+n}}c, X_{k_{t+n+1}}c \in \Sigma^*_c, X_{j_0}a, X_{j_1}a, ..., X_{j_{m+1}}a, X_{j_{m+2}}a \in \Sigma^*_a |$$

$$((X_{k_e}c = X_c) \land (X_{k_t}c = X'_c) \land (X_{j_0}a = X_a) \land (X_{j_{m+1}}a = X'_a)) \land$$

$$i_0 \leq i_1 \leq \ldots \leq i_n \land j_0 \leq j_1 \leq \ldots \leq j_n \land$$

$$\forall k, X_{k_e}c \in \Sigma^*_c, X_{k_t}c \in \Sigma^*_c \land R^*(X_{k_t}c, X_{k_e}c))$$

(5.8)

The first part of the expression at Eq.(5.8) defines a refinement correctness that preserves the external behavior as in the definition 5.2. The second part of this expression specifies the correspondence between the intermediate states of the abstract and the concrete specification.

Refinement verification by generalized forward simulation is reduced to a proof of validity of (5.8) for the (m-n)-refinement.

Fig. 5-3 illustrates the (m,n)-refinement schema that preserves the external and the internal behavior. $W_c$ is a concrete specification and $W_a$ is the abstract specification of a working object. $A_c$ and $A_a$ are concrete and abstract actions respectively. The concrete specification makes $n$ steps of interest from its initial state $X_{0c} = X_c$ to the final state $X_{nc} = X'_c$, whereas an abstract specification makes $m$ steps of interest from $X_{0a} = X_a$ to $X_{ma} = X'_a$. States of interest are related with $R^*$.

![Figure 5-3: The (m,n)-refinement for SEAM specifications: preservation of the external and the internal behavior](image-url)
In SEAM, by a refinement we understand a set of modifications applied to a SEAM visual specification. The result of a refinement is a transition of the specification to the next functional or organizational level.

Refinement verification aims at checking that a refined specification (obtained as a result of a refinement) preserves the external (or the external and the internal) behavior of an initial specification. This can be done by forward (or generalized forward) simulation, using the refinement schemas defined above.

A refinement verification procedure can be applied under the assumption that both the initial and the refined specifications are well-formed and consistent. A specification is well-formed if it conforms to the syntax of a modeling language. This is typically controlled by a modeling tool. A specification consistency is related to its semantics.

### 5.3 Specification Consistency

Formal semantics provided for visual specifications allow for the validation of the specification consistency: this analysis can detect overconstrained specifications. A specification is overconstrained if it contains contradictory preconditions, invariants, or postconditions. For example, a specification with a postcondition \( A_{\text{post}}(\bar{X}, \bar{X}') = (x' > a) \land (x' < a) \) is inconsistent. This postcondition cannot be satisfied, i.e. the action \( A \) cannot be successfully executed.

In Chapter 4 we define a successful action as an action, whose precondition holds and, postcondition is satisfied. We denote this action as the first order formula:

\[
A_{\text{success}}(\bar{X}, \bar{X}') \overset{\text{def}}{=} A_{\text{pre}}(\bar{X}) \land A(\bar{X}, \bar{X}')
\]

Eq. (5.9) is equivalent to:

\[
A_{\text{success}}(\bar{X}, \bar{X}') \overset{\text{def}}{=} A_{\text{pre}}(\bar{X}) \land A_{\text{post}}(\bar{X}, \bar{X}')
\]

If there exists a pair of states \((\bar{X}, \bar{X}')\), such that Eq.(5.9) evaluates to ‘true’, then this formula is satisfiable. Satisfiability indicates that the specification is not overconstrained.

Underconstrained specifications represent another class of semantically incorrect specifications. These specifications can be also called ‘incomplete’, as they do not restrict the unwilling (or meaningless) state transitions. In contrast to overconstrained specifications, underconstrained specifications cannot be detected automatically. It is a designer who should guarantee that the specification is adequate and complete.

### 5.4 Functional and Organizational Refinement in SEAM

Refinement in SEAM specifies a transition of a working object from one hierarchical level (n) where this working object is called ‘abstract’, to another hierarchical level (n+1) where more details about the working object construction and/or functionality is provided. This working object is called ‘concrete’. We say that the concrete specification refines the abstract specification. A relation between state spaces of the concrete and the abstract working objects is called a refinement relation.
The design process in SEAM is carried along two axes: the organizational level hierarchy and the functional level hierarchy. Therefore, we define two classes of refinement for SEAM specifications: a functional refinement and an organizational refinement (Fig. 5-4(a)).

**The functional refinement** in SEAM defines a set of modifications that results in more precise specification of a *behavior* of a working object. The term ‘functional’ refers to a transition of this working object from one functional level, where some property and/or some action is presented as a whole, to another functional level, where this property and/or action is presented as a composite. Functional refinement can be made by either modifying, or creating, or eliminating any actions, properties, and relations between them. It is illustrated in Fig. 5-5 – 5.7.

**The organizational refinement** in SEAM defines a set of modifications that results in a more precise specification of a *construction* of a working object. The term ‘organizational’ refers to a transition from one organizational level, where the working object is presented as a whole, to another organizational level, where this working object is presented as a composite. Organizational refinement is made by the specifications of component working objects and collaborations between them. It is illustrated in Fig. 5-8.

The refinement of both the construction and behavior of a working object in one refinement step is called **functional + organizational refinement**. This is often seen in practice. However, in SEAM, we are interested in modeling *traceable* concepts, whose origins are explicit. This means that every ‘diagonal’ step in SEAM model hierarchy, which stands for functional + organizational refinement, must be equivalent to one ‘horizontal’ step (functional refinement) followed by one ‘vertical’ step (organizational refinement) or to one ‘vertical’ step followed by one ‘horizontal’ step (Fig. 5-4 (a)). Semantically, each functional refinement step stands for a definition of concepts (action or property or both) and each organizational refinement step defines the construction, suitable to hosting these concepts and operating with them.

Fig. 5-4 (b) illustrates a SEAM model represented by a set of specifications at different functional and organizational levels:

- Specification b is a functional refinement of a;
- Specification c is an organizational refinement of a;
- Specification d is a functional refinement of c, (it must be also a correct refinement of a and b);
- Specification f is obtained as a functional refinement of e, which refines c;
- Specification f must be also a correct refinement of a, b, c, and d.
Plain arrows stand for functional or organizational refinement steps; dashed arrows stand for functional + organizational refinement.

NOTE: when we say that one specification is a refinement of the other, this does not necessarily mean that the former is obtained from the latter by adding details: both specifications can be created independently and, in general, can be specified in different modeling languages. The expression ‘is a refinement of’ states that there is a refinement relation between these specifications. The refinement correctness between specifications can be verified using definitions from the previous chapter.

Functional and organizational refinements result from manipulations with individual model elements or groups of elements in a SEAM diagram. They may take different forms depending on the elements modified. In the following sections, we focus on functional and organizational refinements and their types.

5.4.1 Functional Refinement in SEAM
A functional refinement specifies a transition to the next functional level and may take the form of property refinement, behavioral refinement, or a combination of property and behavioral refinements.

A property refinement is illustrated in Fig. 5-5, it comprises:
- A property decomposition (representation of a property by a set of component properties) - Fig. 5-5(a);
- A definition of a new property - Fig. 5-5(b);
- An elimination of a property from the working object;
- A definition of a new property association, composition, or a working object to property relation (a host relation) - Fig. 5-5(c);
- An elimination of a property association, composition, or a working object to property relation (a host relation);
- A modification of a multiplicity expression - Fig. 5-5(d).
Figure 5-5: Property refinement of a working object as a whole: a) a property decomposition; b) a definition of a new property; c) a definition of a property to property (PP-) relation; d) a modification of a multiplicity expression.

Property refinement extends or reduces the state space of the working object seen as a whole.

A behavioral refinement is illustrated in Fig. 5-6 and Fig. 5-7. This refinement is defined for three types of actions in SEAM and may comprise:
- An action decomposition (a specification of a set of component actions with implicit or explicit ordering) – Fig. 5-6(a);
- A modification of an action preconditions, postconditions, invariants, and updates (action to property (AP-) relations) - Fig. 5-6(b);
- A modification of an action input/output parameters – Fig. 5-6(c);
- A definition of a new action - Fig. 5-7(a);
- An elimination of an action;
- A modification of the ordering between actions (action to action (AA-) relations) - Fig. 5-7(b).
5.4.2 Organizational Refinement in SEAM

An organizational refinement specifies a transition to a next organizational level and takes the following forms:

- A working object decomposition and specification of a joint action between components – Fig. 5-8(a), which includes:
  - A definition of component working objects;
  - A distribution of properties of the working object between the components;
  - A definition of a joint action and its AP-relations with the properties of its components;

- A working object decomposition and a definition of a distributed action between components – Fig. 5-8(b), which includes:
  - A definition of component working objects;
  - A distribution of properties of the working object between the components;
  - A distribution of responsibilities of the working object between the components (where responsibility of each component is specified by a localized action);
  - A definition of a distributed action and its DALA-relations.
In the following sections we specify the refinement correctness for each form of organizational and functional refinements.

5.5 Correctness of Functional Refinement

5.5.1 Property Refinement

Property Decomposition

Refinement by property decomposition is a relation between two working objects \( W_a \) and \( W_c \), where \( W_a \) specifies a property \( P_k \) as a primitive property, and \( W_c \) specifies this property as a compound property by defining component properties for it. We can also say that in \( W_a \), the property \( P_k \) is seen as a whole, whereas in \( W_c \), it is seen as a composite - Fig.5-5(a).

Let us consider a working object \( W_a \) seen as a whole, specified on the state space \( \Sigma_a \) with a localized action \( L_{A_a} \), and properties \( P_1, \ldots, P_m \), and a working object \( W_c \) seen as a whole, specified on the state space \( \Sigma_c \) with a localized action \( L_{A_c} \), and properties \( P_{k_1}, \ldots, P_{k_m} \). If \( W_a \) defines a property \( P_k \) as a whole and \( W_c \) defines the corresponding property as a composite, (i.e. it specifies for \( P_k \) component properties \( P_{k_1}, \ldots, P_{k_m} \)) then we say that \( W_c \) refines \( W_a \) by property decomposition.

We write the expression for the abstract and the concrete state spaces as follows:

\[
\Sigma_a = P_1 \times \cdots \times P_k \times \cdots \times P_m \\
\Sigma_c = P_1 \times \cdots \times P_{k_1} \times \cdots \times P_{k_m} \times \cdots \times P_m
\]

(5.10)

In Section 4.3, we define a state \( \overline{X} \) of a working object by a tuple of state variables of this working object \( V \) and interpretation domain \( D_I \). By state variables we understand instances of properties: \( p_1, \ldots, p_m : P_1, \ldots, p_{k_1}, \ldots, p_{k_m} : P_{k_m} \).

For simplicity, let us consider that working objects \( W_a \) and \( W_c \) host one instance of each property. Then the state \( \overline{X}_a \) of \( W_a \) is defined by a tuple \( (p_1, \ldots, p_{k_1}, \ldots, p_m) \); and the state \( \overline{X}_c \) of \( W_c \) is defined by a tuple \( (p_1, \ldots, p_{k_1}, \ldots, p_m) \).
To compute a state of a working object means to interpret \( V \) on \( D \): we write for \( W \) a and \( W_c \):

\[
\text{state}(W_a) = \overline{X}_a = \text{state}(p_1, \ldots, p_k, \ldots, p_m);
\]

\[
\text{state}(W_c) = \overline{X}_c = \text{state}(p_1, \ldots, p_k, p_{k+1}, \ldots, p_m).
\]

Considering that \( p_1, \ldots, p_{k+1}, \ldots, p_m \) are the same for \( W_a \) and \( W_c \), we define a refinement relation \( R \) between state spaces of \( W_a \) and \( W_c \) as a relation values of the property \( p_k \): \( P_k \) in the abstract specification and values of the tuple \( (p_{k+1}, p_{k+2}, \ldots, p_k) \) in the concrete specification:

\[
R(\overline{X}_a, \overline{X}_c) = R((p_k, p_{k+1}, \ldots, p_k)) \in \{\text{true}, \text{false}\}\]

Similarly, this relation can be defined for an arbitrary number of instances of \( P_k \). We specify the correctness of property refinement using the definition of correctness for data refinement by forward simulation (definition 5.1):

**Definition 5.4.**

Given a refinement relation \( R \) as specified in (5.12), \( W_c \) is a correct refinement of \( W_a \) by property decomposition if and only if for each run of the concrete action \( LA_c \) of \( W_c \), which starts at \( X_c \in \Sigma_c \) and terminates at \( X_c' \in \Sigma_c \), there exists a run of the abstract action \( LA_a \) of \( W_a \), which starts at \( X_a \in \Sigma_a \) such that \( R(X_a, X_c) \) holds and terminates at \( X_a' \), where \( R(X_a', X_c') \) holds.

Using the expression at Eq. (5.3) that expresses correctness for data refinement by forward simulation the expression for correct refinement by property decomposition is written as follows:

\[
\forall X_c, X_c' \in \Sigma_c \mid \forall X_a \in \Sigma_a \mid \left( R(X_a, X_c) \land LA_a(X_a, X_c') \right) \Rightarrow \exists X_a' \in \Sigma_a \mid LA_a(X_a, X_a') \land R(X_a', X_c')
\]

**Definition of a New Property or Property Elimination**

Let us consider a working object \( W_a \) seen as a whole, specified on the state space \( \Sigma_a \) with a localized action \( LA_a \), and properties \( P_1, \ldots, P_m \), and a working object \( W_c \) seen as a whole, specified on the state space \( \Sigma_c \) with a localized action \( LA_c \) and properties \( P_1, \ldots, P_n \), where \( n \neq m \).

- If \( n > m \), then \( W_c \) specifies a functional refinement of \( W_a \) by property definition - Fig.5-5(b);
- If \( n < m \), then \( W_c \) specifies a functional refinement of \( W_a \) by property elimination.

Considering that working objects \( W_a \) and \( W_c \) host one instance of each property, we write the following expressions for their states:

\[
\text{state}(W_a) = \overline{X}_a = \text{state}(p_1, \ldots, p_m);
\]

\[
\text{state}(W_c) = \overline{X}_c = \text{state}(p_1, \ldots, p_n).
\]

A refinement relation \( R \) between state spaces of \( W_a \) and \( W_c \) is a relation between the corresponding tuples from (5.14):

\[
R(\overline{X}_a, \overline{X}_c) = R((p_1, \ldots, p_m), (p_1, \ldots, p_n)) \in \{\text{true}, \text{false}\}\]
Correctness of property refinement we specify as a correctness of data refinement by forward simulation:

**Definition 5.5.**
Given a refinement relation $R$ as specified in (5.15), $W_c$ is a correct refinement of $W_a$ by property definition or property elimination if and only if for each run of the concrete action $LA_c$ of $W_c$, which starts at $X_c \in \Sigma_c$ and terminates at $X_c' \in \Sigma_c$, there exists a run $LA_a$ of $W_a$, which starts at $X_a \in \Sigma_a$ such that $R(X_a, X_c)$ holds and terminates at $X_a'$, where $R(X_a', X_c')$.

**NOTE 1.**
1. The elimination of a property from a working object implies the elimination of all incoming and outgoing relations of this property in this working object (the opposite is not true);
2. The definition of a new property $P$ in a working object $W_a$ with a multiplicity $m$ implies a definition of a host relation between $W_a$ and $P$ with the corresponding multiplicity expression $m$;
3. The decomposition of a property $P$ into properties $P_1, P_2$ with corresponding multiplicities $m_1, m_2$ implies a definition of a property composition relations between $P$ and $P_1$, and between $P$ and $P_2$ with corresponding multiplicity expressions $m_1$ and $m_2$.

**Definition and Elimination of Property Associations, Property Compositions, and Host Relations between a Working Object and a Property; and the Modification of a Multiplicity Expression.**
In Section 4.3.3, semantics of property associations, property compositions, and host relations between a working object and a property was specified as semantics of relations with multiplicities. Definition and elimination of these relations as well as modification of their multiplicity expressions affects specification consistency introduced in Chapter 4.

**NOTE 2.**
The following dependencies between different forms of refinement exist:
1. The definition or elimination of a host relation between a working object and a property is semantically equivalent to a property definition or elimination;
2. The definition of a property association or a property composition relation is semantically equivalent to a property decomposition; elimination of these relation is a reversed process;
3. The modification of a multiplicity expression stands for modification of the number of instances of a property. This is semantically equivalent to a definition or elimination of a property in the specification (Fig. 5-9).

![Figure 5-9: Property refinement: modification of a multiplicity expression seen as a property definition.](image)
Assuming that manipulations with host- and PP-relations do not violate the specification consistency, the correctness of these refinement forms is reduced to the correctness of data refinement by forward simulation.

Let us consider a working object $W_a$ seen as a whole (specified on the state space $\Sigma_a$ with a localized action $L_{A_a}$, and properties $P_1, ..., P_m$), and a working object $W_c$ seen as a whole (specified on the state space $\Sigma_c$ with a localized action $L_{A_c}$ and the same set of properties $P_1, ..., P_m$). $W_c$ refines $W_a$ by defining, eliminating, or modifying some of property associations, property compositions, or host relations specified in $W_a$.

**Definition 5.6.** $W_c$ specifies a correct property refinement of $W_a$ if:

1. The refined specification $W_c$ is consistent by Definition 4.1,
2. $W_c$ is a correct functional refinement of $W_a$ by definitions 5.4-5.5.

### 5.5.2 Behavioural Refinement

**Modification of Action Parameters**

Let us consider a working object $W_a$ specified with an action $A_a(X, X', I_a, O_a)$, and a working object $W_c$, specified with an action $A_c(X, X', I_c, O_c)$. Abstract and concrete actions are specified with different sets of input and output parameters: $I_a \neq I_c, O_a \neq O_c$. We say that $W_c$ is a behavioural refinement of $W_a$, where the action $A_c$ refines the action $A_a$ by modifying input and output parameters.

As inputs and outputs make a part of the object state space (Section 4.3), then the refinement by modification of action parameters is reduced to a data refinement. In other terms, to prove refinement correctness, a refinement relation $R$ between state spaces $\Sigma_a$ and $\Sigma_c$ is needed:

$$ R : \Sigma_a \times \Sigma_c \rightarrow \{true, false\}.$$ 

Assuming that only input parameters (or only output parameters) have been refined, we can specify $R_{\text{In}}$ or $R_{\text{Out}}$, where $R_{\text{In}}$ is a refinement relation between input parameters of abstract and concrete specifications; $R_{\text{Out}}$ is a refinement relation between output parameters of abstract and concrete specifications. We give the following definition for these refinement relations:

**Definition 5.7.**

Given refinement relations $R_{\text{In}}$ and $R_{\text{Out}}$ between abstract and concrete input and output parameters, $W_c$ specifies a correct refinement of $W_a$ by modifying action input and output parameters if and only if for each run of the concrete action $A_c$ of $W_c$ - which starts at some pre-state $X$ and terminates at some post-state $X'$ and has an inputs $I_c$ and an output $O_c$ - there exists a run $A_a$ of $W_a$ - which starts at $X$, terminates at $X'$ - and has an input $I_a$, such that $R_{\text{In}}(I_a, I_c)$ holds and an output $O_a$, such that $R_{\text{Out}}(O_a, O_c)$ holds.

If the input is needed to trigger the action (it is a part of the precondition) and the output is obtained upon the action termination (a part of the action postcondition), then we can write the following expression for refinement correctness:

$$ \forall X, X', I_c, O_c, I_a \mid R_{\text{In}}(I_a, I_c) \land A_c(X, X', I_c, O_c) \Rightarrow \exists O_a \mid A_a(X, X', I_a, O_a) \land R_{\text{Out}}(O_a, O_c) $$

(5.16)
Modification of an Action Contract and Action Update Statements

Let us consider a working object $W_a$, specified on the state space $\Sigma$ with an action $A_a$ defined as follows:

$$A_a(\overline{X}, \overline{X}') = A_{a_{\text{inv}}} (\overline{X}) \land A_{a_{\text{pre}}} (\overline{X}) \rightarrow A_{a_{\text{post}}} (\overline{X}, \overline{X}') \land A_{a_{\text{inv}}} (\overline{X}');$$

for $A_a$ modeled as a whole we may specify an update statement: $\overline{X}' = A_{a_{\text{inv}}} (\overline{X})$;

and a working object $W_c$, specified on the same state space $\Sigma$ with an action $A_c$ defined as follows:

$$A_c(\overline{X}, \overline{X}') = A_{c_{\text{inv}}} (\overline{X}) \land A_{c_{\text{pre}}} (\overline{X}) \rightarrow A_{c_{\text{post}}} (\overline{X}, \overline{X}') \land A_{c_{\text{inv}}} (\overline{X}');$$

for $A_c$ modeled as a whole we may specify an update statement: $\overline{X}' = A_{c_{\text{inv}}} (\overline{X})$

If $A_{c_{\text{inv}}} \neq A_{a_{\text{inv}}}$ or $A_{c_{\text{pre}}} \neq A_{a_{\text{pre}}}$ or $A_{c_{\text{post}}} \neq A_{a_{\text{post}}}$ or $A_{c_{\text{inv}}} \neq A_{a_{\text{inv}}}$, $W_c$ is a behavioural refinement of $W_a$ with the action $A_c$ refining the action $A_a$ by modifying its contract or update statement.

We specify this form of behavioural refinement using the $(m,n)$-refinement schema:

- For actions modeled as a whole: $m=n=1$;
- For actions modeled declaratively we use the definition of correct $(m,n)$-refinement preserving the external behavior;
- For actions modeled imperatively we define the states of interests $\Sigma_c^* \subseteq \Sigma, \Sigma_a^* \subseteq \Sigma$ and specify a refinement relation $R^* : \Sigma_c^* \times \Sigma_c^* \rightarrow \{\text{true}, \text{false}\}$ between them. Then we use the definition of correct $(m,n)$-refinement preserving the internal and the external behavior.

**Definition 5.8.**

Given a refinement relation $R$, $W_c$ specifies a **correct refinement of $W_a$ by modifying its action contract and update statement** if and only if it can be represented as a correct $(m,n)$-refinement from Definition 5.2 or 5.3.

If abstract and concrete actions specify update statements $A_{a_{\text{inv}}}, A_{a_{\text{pre}}}$, then for refinement correctness we require that for the post-states $\overline{X}_a', \overline{X}_c'$ of the abstract and concrete actions the following holds:

$$R^* (\overline{X}_a', \overline{X}_c') = R^* (A_{a_{\text{inv}}} (\overline{X}_a'), A_{a_{\text{pre}}} (\overline{X}_a')) (5.17)$$

**Behavioral Refinement Using Transformers**

Another way to define the refinement correctness is to leverage the logic of our reasoning by introducing relations of higher order. We can specify the relations between ‘new’ (refined) and ‘old’ (initial) invariants, preconditions, postconditions, and update statements as predicates of higher order - **predicate transformers**.

$$T_{\text{pre}} : T_{\text{post}} : T_{\text{inv}} : \Phi \Sigma_c \mapsto \Phi \Sigma_a;$$

$$T_a : \Phi \Sigma_c \mapsto \Phi \Sigma_a$$

Here $\Phi \Sigma$ defines a set of predicates on $\Sigma$ and $\Phi \Sigma_c$ defines a set of update functions on $\Sigma$.

For example, using transformers, we write:
\[ T_{\text{inv}}(A_{\text{inv}}) = A_{\text{inv}} \]

Where \( T_{\text{inv}} \) transforms a predicate \( A_{\text{inv}} \) that specifies the invariant of the concrete action to a predicate \( A_{\text{inv}} \) that specifies a corresponding invariant of the abstract action.

**Definition 5.9.**

Given a refinement relation between action preconditions, postconditions, invariants and update statements as predicate transformers \( T_{\text{pre}}, T_{\text{post}}, T_{\text{inv}}, T_a \), \( W_c \) specifies a **correct refinement of \( W_a \) by modifying its action contract and update statement** if and only if the following holds:

\[ \forall \overline{X}_c, \overline{X}_c' \in \Sigma, \forall \overline{X}_a \in \Sigma_a \mid \left( A_{\text{inv}}(\overline{X}_c) \land A_{\text{pre}}(\overline{X}_c) \rightarrow A_{\text{post}}(\overline{X}_c, \overline{X}_c') \land A_{\text{inv}}(\overline{X}_c') \right) \Rightarrow \]

\[ \exists \overline{X}_a \in \Sigma_a \mid \left( T_{\text{pre}}(A_{\text{inv}})(\overline{X}_a) \land T_{\text{inv}}(A_{\text{inv}})(\overline{X}_a) \rightarrow T_{\text{post}}(A_{\text{inv}})(\overline{X}_a, \overline{X}_a') \land T_{\text{inv}}(A_{\text{inv}})(\overline{X}_a') \right) \]

(5.18)

For update statements we write:

\[ A_{\text{inv}}(\overline{X}_a) = T_{\text{pre}}(A_{\text{inv}})(\overline{X}_a) = \overline{X}_a' \]

(5.19)

Substituting \( \overline{X}_c' \) and \( \overline{X}_a' \) in Eq.(5.18) with their expressions from (5.19), we write:

\[ \forall \overline{X}_c \in \Sigma, \forall \overline{X}_a \in \Sigma_a \mid \left( A_{\text{inv}}(\overline{X}_c) \land A_{\text{pre}}(\overline{X}_c) \rightarrow A_{\text{post}}(\overline{X}_c, A_{\text{pre}}(\overline{X}_c)) \land A_{\text{inv}}(A_{\text{pre}}(\overline{X}_c)) \right) \Rightarrow \]

\[ \left( T_{\text{pre}}(A_{\text{inv}})(\overline{X}_a) \land T_{\text{inv}}(A_{\text{inv}})(\overline{X}_a) \rightarrow T_{\text{post}}(A_{\text{inv}})(\overline{X}_c, T_{\text{pre}}(A_{\text{inv}})(\overline{X}_a), T_{\text{inv}}(A_{\text{inv}})(\overline{X}_a)) \right) \]

(5.20)

**Action Decomposition**

Action decomposition typically takes place when the abstract action \( A_a \) is specified as a whole and its run makes one transition from a pre-state to a post-state, whereas the refined action \( A_c \) executes multiple component actions and makes \( n>1 \) transitions from its pre-state to its post-state.

Let us consider a working object \( W_a \), specified on the state space \( \Sigma \) with an action \( A_a \) (Fig. 5-10(a)). This action is defined as follows:

\[ A_a(\overline{X}, \overline{X'}) = A_{\text{inv}}(\overline{X}) \land \overline{X}_{\text{pre}}(\overline{X}) \rightarrow A_{\text{post}}(\overline{X}, \overline{X'}) \land A_{\text{inv}}(\overline{X'}) \]

We can also specify an update statement as follows: \( \overline{X'} = A_{\text{inv}}(\overline{X}) \)

A working object \( W_c \) is specified on the same state space \( \Sigma \) with an action \( A_c(\overline{X}, \overline{X'}) = \rho(A_1, ..., A_n) \), which is a decomposition of \( A_a \) with the ordering function \( \rho \) (Fig. 5-10(b,c)).
If the action is specified imperatively:

\[ A_c(X, X') = \exists X_1, \ldots, X_{i-1} \mid A_i(X, X'_1) \land \ldots \land A_i(X, X') \; ; \]

To prove that \( W_c \) is a correct behavioural refinement of \( W_a \) with the action \( A_i \) refining the action \( A_a \) by decomposition, we use the \( (m,n) \)-refinement schema as follows:

- For actions modeled declaratively, we use the definition of correct \( (m,n) \)-refinement preserving the external behavior;
- If the concrete action \( A_c \) is modeled imperatively, we define the states of interests \( \Sigma^*_c \subseteq \Sigma, \Sigma^*_a \subseteq \Sigma \) and specify a refinement relation \( R^*: \Sigma^*_a \times \Sigma^*_c \to \{true, false\} \) between them. Then we use the definition of correct \( (m,n) \)-refinement preserving the internal and the external behavior.

The idea is to define the refinement relation \( R^* \) in a way that intermediate steps of the concrete action specification reflect the move from a pre-state to a post-state of the abstract specification. We use the definition of correct \( (m,n) \)-refinement preserving the internal and the external behavior.

- If the abstract action \( A_a \) is modeled as a whole, the states of interest \( \Sigma^*_a \) include only the initial and the final states of \( A_a \):
  \[ \overline{X}_{h_a}, X_{h_a} \in \Sigma^*_a, \overline{X}_{h_a} = X_a; \overline{X}_{h_a} = X'_c \]

\[ W_a \] \[ \ldots \] \[ A_a \] \[ (a) \]

\[ W_c \] \[ \ldots \] \[ A_1 \ldots A_i \ldots A_t \]
\[ (b) \]

\[ W_c \] \[ \ldots \] \[ A_1 \ldots A_i \ldots A_t \]
\[ (c) \]

**Figure 5-10: Behavioral refinement: action decomposition**

**Definition 5.10.**

Given a refinement relation \( R^* \) between the states of interests of abstract and concrete specifications, \( W_c \) specifies a correct refinement of \( W_a \) by action decomposition if and only if it can be represented as a correct \( (m,n) \)-refinement from Definition 5.2 or 5.3.
Definition of a New Action or Action Elimination

Let us consider a working object \( W_a \), specified on the state space \( \Sigma \) with an action \( A_a(X, X') = \rho_1(A_1, \ldots, A_t) \), and a working object \( W_c \), specified on the same state space \( \Sigma \) with an action \( A_c(X, X') = \rho_2(A_1, \ldots, A_s) \), where \( t \neq s \).

If \( t > s \), then \( W_c \) is a behavioural refinement of \( W_a \) with the action \( A_t \) refining the action \( A_a \) by action elimination;

If \( t < s \), then \( W_c \) is a behavioural refinement of \( W_a \) with the action \( A_t \) refining the action \( A_a \) by new action definition.

For actions \( A_t \) and \( A_s \) modeled declaratively (i.e. intermediate states are not shown), we use the definition of correct \((m,n)\)-refinement preserving the external behavior;

For actions \( A_t \) and \( A_s \) modeled imperatively (with explicitly modeled intermediate states and their order), we define the states of interests \( \Sigma_{a} \subseteq \Sigma, \Sigma_{a} \subseteq \Sigma \), and specify the relation \( R^* : \Sigma_{a} \times \Sigma_{a} \rightarrow \{true, false\} \) between them.

Then we use the definition of correct \((m,n)\)-refinement preserving the internal and the external behavior.

**Definition 5.11.**

Given a refinement relation \( R^* \) between the states of interests of abstract and concrete specifications, \( W_c \) specifies a correct refinement of \( W_a \) by action elimination or by new action definition if and only if it can be represented as a correct \((m,n)\)-refinement from Definition 5.2 or 5.3.

Modification of a component Actions’ Ordering

Let us consider a working object \( W_a \), specified on the state space \( \Sigma \) with an action \( A_a(X, X') = \rho_1(A_1, \ldots, A_t) \), and a working object \( W_c \), specified on the same state space \( \Sigma \) with an action \( A_c(X, X') = \rho_2(A_1, \ldots, A_s) \). \( \rho_1 \) and \( \rho_2 \) define the order of component action invocation in abstract and concrete actions. If \( \rho_1 \neq \rho_2 \), then we say that \( W_c \) is a behavioural refinement of \( W_a \) with the action \( A_t \) refining the action \( A_a \) by modification of a component actions’ ordering.

If \( \rho_1 \) and/or \( \rho_2 \) specify a formula, we can convert this formula to an equivalent formula in conjunctive normal form (CNF) and obtain the equivalent expression in the transformed state space:

\[
A_a(X, X') = \rho_1(A_1, \ldots, A_t) = \exists Y_1, \ldots, Y_{t-1} : \bigwedge B_1(Y, Y_1) \land \ldots \land B_t(Y_{t-1}, Y')
\]

\[
A_c(X, X') = \rho_2(A_1, \ldots, A_s) = \exists Z_1, \ldots, Z_{s-1} : \bigwedge C_1(Z, Z_1) \land \ldots \land C_s(Z_{s-1}, Z')
\]

For action specifications from Eq. (5.21) we identify the states of interest: \( \Sigma_{a} \subseteq \Sigma, \Sigma_{a} \subseteq \Sigma \), and specify the relation \( R^* : \Sigma_{a} \times \Sigma_{a} \rightarrow \{true, false\} \) between these states of interest. Then we use the definition of correct \((m,n)\)-refinement preserving the internal and the external behavior.
Definition 5.12.
Given a refinement relation between transformed state spaces \(R^*: \Sigma^* \times \Sigma^* \rightarrow \{\text{true}, \text{false}\}\), \(W_c\) specifies a correct refinement of \(W_a\) by modification of a component actions’ ordering if and only if it can be represented as a correct \((m,n)\)-refinement from Definition 5.3.

5.6 Correctness of Organizational Refinement

Organizational refinement defines a relation between the working object seen as a whole and the same working object seen as a composite. The specification of a working object as a composite shows how the component working objects collaborate to implement the behavior, specified for the parent working object as a whole. We identify the following modeling activities that result in organizational refinement:

- Definition of component working objects (working object decomposition)
- Distribution of properties of the parent working object between its component working objects;
- Definition of a joint action as a collaboration between components and its relations to properties of these components (AP-relations); or
- Definition of a distributed action as collaboration between components and its relations to localized actions of these components (DALA-relations).

In this section we formalize correctness for each type of organizational refinement.

5.6.1 Working Object Decomposition and Property Distribution

Example 5.1. Figure 5-11 illustrates the organizational refinement, where a working object \(W_a\) (abstract) is refined by a working object \(W_c\) (concrete). \(W_c\) represents a decomposition of \(W_a\) into working objects \(S_1\) and \(S_2\). Properties \(P_1\) and \(P_2\) are distributed between component working objects.

A property can be fully delegated to one of the component working objects (the property \(P_2\) in Fig. 5-11) or shared by several working objects (the property \(P_1\) in Fig. 5-11).

- \(x, y\) define multiplicities of properties \(P_1\) and \(P_2\) in the working object \(W_a\);
- \(c_1, c_2\) define multiplicities of component working objects \(S_1\) and \(S_2\) in \(W_c\);
- \(x_1, x_2, y_1\) are multiplicities of properties \(P_1\) at \(S_1\), \(P_1\) at \(S_2\) and \(P_2\) at \(S_2\).

The state of the abstract working object \(W_a\) is defined by a tuple of state variables: \(V^{(W_a)} = (p_1, ..., p_1, p_2, ..., p_2)\) and can be calculated as follows:

\[
\overline{X}_a = \text{state}(p_1, ..., p_1, p_2, ..., p_2).
\]

Here \(p_1\) and \(p_2\) are instances of the corresponding properties;
The state of the concrete working object \(W_c\) is defined by a tuple of state variables:

![Figure 5-11: Organizational refinement: property distribution.](image)
\[ V^{(W_j)} = \left( p_1^{(S_1)}, \ldots, p_1^{(S_1)}, p_1^{(S_2)}, \ldots, p_1^{(S_2)}, \ldots, p_2^{(S_2)} \right) \]

and can be also seen as a tuple of states of component working objects:

\[ \overline{X}_c^{(W_j)} = state(p_1^{(S_1)}, \ldots, p_1^{(S_1)}, p_1^{(S_2)}, \ldots, p_1^{(S_2)}, p_2^{(S_2)}, \ldots, p_2^{(S_2)}) = (\overline{X}_1^{(S_1)}, \ldots, \overline{X}_1^{(S_1)}, \overline{X}_2^{(S_1)}, \ldots, \overline{X}_2^{(S_1)}) \]

Considering \( c_1 = c_2 = 1 \), we write an expression for \( \overline{X}_c^{(W_j)} \) as follows:

\[ \overline{X}_c^{(W_j)} = \overline{X}_c^{(S_1)} \times \overline{X}_c^{(S_2)} \]

where \( p_1^{(S_1)}, p_1^{(S_2)}, p_2^{(S_2)} \) are property instances in the component working objects, and \( i = 1..x_1, j = 1..x_2, k = 1..y_1 \).

The organizational refinement illustrated in Fig. 5-11 distributes properties correctly if
- all instances of the property \( P_2 \) are delegated to the working object \( S_2 \) such as \( c_1 \cdot y_1 = y \);
- instances of the property \( P_1 \) are shared between component working objects \( S_1 \) and \( S_2 \) (possibly with duplications) such as \( c_1 \cdot x_1 + c_2 \cdot x_2 \geq x \).

Let us consider a working object \( W_a \) seen as a whole, specified on the state space \( \Sigma_a \), and a working object \( W_c \) seen as a composite with component working objects \( (W_1, \ldots, W_j) \). We define the multiplicities of each component working object by \( ml \cdot ms \).

\( W_c \) refines \( W_a \) by decomposition and property distribution.

Given \( x_i \) - a number of instances of the property \( P_i \) specified in \( W_a \); and \( x_{ij} \) - a number of instances of the property \( P_i \) specified in the component working object \( W_j \), we calculate the maximum number of instances of property \( P_i \) in \( W_c \) as

\[ Inst^{(W_j)}_{\text{max}}(P_i) = \sum_j m_j x_{ij}, \]

where \( m_j \) is a number of instances of \( W_j \) in \( W_c \).

The state space \( \Sigma_c \) of \( W_c \) can be seen as a Cartesian product of state spaces of the component working objects:

\[ \Sigma_c = \Sigma_{w_1} \times \ldots \times \Sigma_{w_l} \]

**Definition 5.13.**

\( W_c \) specifies a correct refinement of \( W_a \) by decomposition and property distribution if and only if:

1. Each property \( P_i \) of \( W_a \) is delegated to at least one component working object \( W_j \) of \( W_c \);
2. The maximum number of instances of property \( P_i \) in \( W_c \) is greater or equal to the number of its instances in \( W_a \):

\[ \forall P_i \mid Inst^{(W_c)}_{\text{max}}(P_i) \geq x_i \]

A refinement relation \( R \), between the states of working objects \( W_a \) and \( W_c \), reflects a permutation (and/or duplication) of state variables in \( V^{(W_c)} \) compared to \( V^{(W_a)} \).

**NOTE:** The decomposition of a working object \( W \) into component working objects \( W_1, W_2 \) with multiplicities \( ml \) and \( m2 \) expresses a definition of a working object composition relation between \( W \) and \( W_1 \) and between \( W \) and \( W_2 \) with multiplicity expressions \( ml \) and \( m2 \) respectively;
5.6.2 Refinement of a Localized action with a Joint action

Example 5.2. Figure 5-12-a illustrates a specification of a working object $W_a$ as a whole with a localized action $LA(\overline{X}(W_a), \overline{X}'(W_a))$. $\overline{X}(W_a), \overline{X}'(W_a) \in \Sigma_a$ are states of $W_a$ before and after the action. Working object $W_c$ refines $W_a$ by decomposing it into working objects $S1$ and $S2$ (Fig. 5-12-b). $c_1, c_2$ define multiplicities of component working objects $S1$ and $S2$ in $W_c$. Properties $P1$ and $P2$ are distributed between component working objects $S1$ and $S2$; the configuration of properties is the same as in Example 5.1.

Working object $W_c$ is specified with a joint action $JA(\overline{X}(W_c), \overline{X}'(W_c))$. $\overline{X}(W_c), \overline{X}'(W_c) \in \Sigma_c$ are states of $W_c$ before and after the joint action. These states can be expressed as following tuples:

$\overline{X}(W_c) = (X_{i}^{(S1)}, \ldots, X_{c_1}^{(S1)}, \overline{X}_{1}^{(S2)}, \ldots, X_{c_2}^{(S2)})$;

$\overline{X}'(W_c) = (\overline{X}_{i}^{(S1)}, \ldots, X_{c_1}^{(S1)}, \overline{X}_{1}^{(S2)}, \ldots, X_{c_2}^{(S2)})$

where $X_i^{(S1)}$ - is a state of the $i$-th instance of component working object $S1$, $i=1..c_1$; $\overline{X}_j^{(S2)}$ - is a state of the $j$-th instance of component working object $S2$, $j=1..c_2$.

Joint action $JA$ modifies the properties of component working objects $S1$ and $S2$ to change the state of parent working object $W_c$. In other terms, $JA$ implements the localized action $LA$ defined for the working object $W_a$ seen as a whole in Fig. 5-12(a).

$W_c$ correctly refines $W_a$ with the joint action $JA$ as a whole refining the localized action $LA$ as a whole if $JA$ preserves the external behavior of the localized action $LA$.

If localized and joint actions are modeled as composites, then we may be interested in a preservation of the correspondent internal behavior.

We proceed with the following definition of correct organizational refinement:

Let us consider a working object $W_a$ seen as a whole, specified on the state space $\Sigma_a$ with its properties $P_1..P_n$ and a localized action $LA$, and a working object $W_c$ seen as a composite with component working objects $W_1, \ldots, W_s$. Multiplicity of a component working object $W_i$ in $W_c$ is $m_i$, where $i=1..s$. $W_c$ is specified on the state space $\Sigma_c$ with a joint action $JA$. $\Sigma_c$ is a Cartesian product of state spaces of the component working objects: $\Sigma_c = \Sigma_{w_1} \times \ldots \times \Sigma_{w_s}$.

We denote localized action $LA$ as follows:

$$LA(\overline{X}(W_i), \overline{X}'(W_i)) \overset{def}{=} LA_{inv}(\overline{X}(W_i)) \land LA_{pre}(\overline{X}'(W_i)) \land LA_{post}(\overline{X}(W_i), \overline{X}'(W_i)) \land LA_{inv}(\overline{X}'(W_i)) \ (5.23)$$
Here \( \overline{X}^{(W_a)}, \overline{X}^{(W_a)} \in \Sigma_a \) are pre- and post- states of the working object \( W_a \) carrying out \( LA \). These states can be calculated by assigning values to the tuples of state variables of \( W_a \) as follows:

\[
\overline{X}^{(W_a)} = \text{state}(p_1, ..., p_{n_m})
\]

\[
\overline{X}^{(W_a)} = \text{state}(p'_1, ..., p'_{n_m})
\]

Where \( p_1, ..., p_{n_m}, p'_1, ..., p'_{n_m} \).

We denote joint action \( JA \) of the refined working object \( W_c \) as follows:

\[
JA(\overline{X}^{(W_c)}, \overline{X}^{(W_c)}) \overset{\text{def}}{=} JA_{\text{post}}(\overline{X}) \land JA_{\text{pre}}(\overline{X}) \rightarrow JA_{\text{post}}(\overline{X}^{(W_a)}), \overline{X}^{(W_a)}) \land JA_{\text{pre}}(\overline{X}^{(W_a)})
\]

Here \( \overline{X}^{(W_c)}, \overline{X}^{(W_c)} \in \Sigma_c \) pre- and post- states of the refined working object \( W_c \) carrying out \( JA \). These states are expressed as tuples:

\[
\overline{X}^{(W_c)} = (X_1^{(W_1)}, X_{m_1}^{(W_1)}, ..., X_1^{(W_s)}, X_{m_s})
\]

\[
\overline{X}^{(W_c)} = (X'_1^{(W_1)}, X'_{m_1}^{(W_1)}, ..., X'_1^{(W_s)}, X'_{m_s})
\]

\( \overline{X}_{j}^{(W)} \) - is a state of \( j \)-th instance of component working object \( W_i, i=1..s, j=1..m_i \).

\( W_c \) refines \( W_a \) by decomposition, with the joint action \( JA \) refining the localized action \( LA \).

We identify the states of interest: \( \Sigma^*_a \subseteq \Sigma_a, \Sigma^*_c \subseteq \Sigma_c \), which include initial states \( \overline{X}^{(W)}, \overline{X}^{(W)} \) and terminating states \( \overline{X}^{(W)}, \overline{X}^{(W)} \) of both actions. Then we specify the relation \( R^*: \Sigma^*_a \times \Sigma^*_c \rightarrow \{\text{true, false}\} \) between these states of interest and use the definition of correct \((m,n)\)-refinement. First we define refinement the correctness that preserves the external behavior: This formalization is applicable when both joint action and localized actions are modeled declaratively. We continue defining the refinement correctness that preserves the external and internal behavior.

**Definition 5.14. [preservation of the external behavior]**

\( W_c \) specifies a **correct refinement of \( W_a \) by decomposition, with joint action \( JA \) refining localized action \( LA \)** if and only if

1. \( W_c \) is a correct refinement of \( W_a \) by decomposition and property distribution (Definition 5.13)

2. given a refinement relation \( R^*: \Sigma^*_a \times \Sigma^*_c \rightarrow \{\text{true, false}\} \) between states of abstract and concrete specifications, for every run of the joint action \( JA \) of \( W_c \), which starts at \( \overline{X}^{(W_c)} \in \Sigma^*_c \) and terminates at \( \overline{X}^{(W)} \in \Sigma^*_c \), there exists a run \( LA \) of \( W_a \), which starts at \( \overline{X}^{(W_a)} \in \Sigma^*_a \) such that:

\[
R^*(\overline{X}^{(W_a)}, \overline{X}^{(W_a)}) = R^*(\overline{X}^{(W_a)}, (X_1^{(W_1)}, X_{m_1}, ..., X_1^{(W_s)}, X_{m_s}))
\]

holds, and terminates at \( \overline{X}^{(W_a)} \in \Sigma^*_a \), for which

\[
R^*(\overline{X}^{(W_a)}, \overline{X}^{(W_a)}) = R^*(\overline{X}^{(W_a)}, (X_1^{(W_1)}, X_{m_1}, ..., X_1^{(W_s)}, X_{m_s}))
\]

holds.

We rewrite the expression for correctness of data refinement by forward simulation from Eq. (5.3) by using the refinement relation \( R^* \) defined above and we obtain the expression for correct organizational refinement as follows:

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\[
\forall \overline{X}^{(w_a)} \in \Sigma_c, \overline{X}^{(w_c)} \in \Sigma_a \mid R^* (\overline{X}^{(w_a)}, \overline{X}^{(w_c)}) \land JA (\overline{X}^{(w_a)}, \overline{X}^{(w_c)}) \Rightarrow \\
\exists \overline{X}^{(w_c)} \in \Sigma_a \mid LA (\overline{X}^{(w_a)}, \overline{X}^{(w_c)}) \land R^* (\overline{X}^{(w_a)}, \overline{X}^{(w_c)})
\] (5.27)

When both localized and joint actions are specified imperatively, preservation of sequences of intermediate states (an internal behavior) might be required.

**Definition 5.15.** [preservation of the external and the internal behavior]

\(W_c\) specifies a *correct refinement of \(W_a\) by decomposition, with joint action \(JA\) refining localized action \(LA\) if and only if

1. \(W_c\) is a correct refinement of \(W_a\) by decomposition and property distribution (Definition 5.13)
2. given a refinement relation \(R^* : \Sigma^*_a \times \Sigma^*_c \rightarrow \{true, false\}\) between the states of abstract and concrete specifications, for every run of the joint action \(JA\) defined by the ordered sequence of states, including initial and the terminating states:

\[
\overline{X}_0, \overline{X}_i, \ldots, \overline{X}_{i_n}, \overline{X}^{(w_c)} \in \Sigma^*_c \mid (\overline{X}_0 = \overline{X}^{(w_a)}), (\overline{X}_i = \overline{X}^{(w_c)})
\]

such that \(i_0, i_1, \ldots, i_n\) is a monotone sequence of natural numbers; there is a run \(LA\) of the abstract action, also defined by the ordered sequence of states:

\[
\overline{X}_0, \overline{X}_j, \ldots, \overline{X}_{j_m}, \overline{X}^{(w_a)} \in \Sigma^*_a \mid (\overline{X}_0 = \overline{X}^{(w_a)}), (\overline{X}_j = \overline{X}^{(w_a)})
\]

such that \(j_0, j_1, \ldots, j_m\) is a monotone sequence of natural numbers;

and for every \(k\) and \(\overline{X}_i, \overline{X}_j \in \Sigma^*_c \mid R^* (\overline{X}_i, \overline{X}_j)\) holds.

\[
R^* (\overline{X}_i, \overline{X}_j) = R^* (\overline{X}_{i_1}, \overline{X}_{j_1}, \ldots, \overline{X}_{i_m}, \overline{X}_{j_m})
\] (5.28)

### 5.6.3 Refinement of a Localized Action with a Distributed Action

**Example 5.3.**

Figure 5-13(a) illustrates a specification of a working object \(W_a\) as a whole with a localized action \(LA(\overline{X}^{(w_a)}, \overline{X}^{(w_a)})\);

Working object \(W_c\) refines \(W_a\) by decomposing it into working objects S1 and S2 as specified in the previous example. Properties P1 and P2 are distributed between component working objects S1 and S2; localized actions \(LA_1\) and \(LA_2\) are specified for component working objects.

Working object \(W_c\) is specified with a distributed action \(DA(\overline{X}^{(w_c)}, \overline{X}^{(w_c)})\). We denote the distributed action as follows:

\[
DA(\overline{X}^{(w_c)}, \overline{X}^{(w_c)}) = \rho_d (LA_1, \ldots, LA_1, LA_2, \ldots, LA_2) = \\
\rho_d (LA_1(\overline{X}_i), \overline{X}_i^{(w_1)}, \ldots, LA_1(\overline{X}_i), \overline{X}_i^{(w_1)}), LA_2(\overline{X}_i^{(w_2)}, \overline{X}_i^{(w_2)}), \ldots, LA_2(\overline{X}_i^{(w_2)}, \overline{X}_i^{(w_2)})
\]
Figure 5-13: Organizational refinement by definition of a distributed action

Distributed action $DA$ binds localized actions $LA_1$ and $LA_2$ of all instances of component working objects $S_1$ and $S_2$ in $W_c$; here $LA_i(X_{i}^{(S_i)}, X_i^{(S_i)})$ - is a localized action $LA_i$ specified for the $i$-th instance of component working object $S_1$, $i = 1..c_1$.

$\overline{X}^{(W)}_i, \overline{X}^{(W)}(i) \in \Sigma_c$ are the initial and final states of the refined working object $W_c$ that performs $DA$. These states are expressed via the states of component working objects as explained in the previous example.

$LA_1$ and $LA_2$ modify the properties of corresponding component working objects $S_1$ and $S_2$ and change their states. The state of the parent working object $W_c$ is expressed as a tuple of states of its component working objects:

$\overline{X}^{(W)}_i = (\overline{X}_1^{(S_1)}, ..., \overline{X}_i^{(S_1)}, \overline{X}_1^{(S_2)}, ..., \overline{X}_j^{(S_2)})$;

where $\overline{X}_i^{(S_1)}$ - is a state of the $i$-th instance of component working object $S_1$, $i = 1..c_1$; $\overline{X}_j^{(S_2)}$ - is a state of the $j$-th instance of component working object $S_2$, $j = 1..c_2$.

In our example, $W_a$ with $LA$ can be considered a specification of a certain behaviour; and $W_c$ with $DA$ can be considered as an implementation of this behaviour. Here component working objects participate in the distributed action to accomplish the behavior specified by the localized action $LA$. $W_c$ correctly implements $W_a$ if its distributed action $DA$ preserves the external behavior of $LA$ (for $LA$ modeled declaratively) or its external and internal behavior (for $LA$ modeled imperatively).

We proceed with the following definition of correct organizational refinement:

Let us consider a working object $W_a$ seen as a whole, specified on the state space $\Sigma_a$ with a localized action $LA$, and a working object $W_c$ seen as a composite with component working objects $W_1, .., W_s$. Multiplicity of component working object $W_i$ in $W_c$ is $m_i$, where $i = 1..s$. $W_c$ is specified on the state space $\Sigma_c$ with a joint action $JA$. $\Sigma_c$ is a Cartesian product of state spaces of the component working objects: $\Sigma_c = \Sigma_{a1} \times \times \Sigma_{as}$.

We specify the localized action $LA$ as follows:

$LA(\overline{X}_i^{(W_1)}, \overline{X}_i^{(W_s)}) = LA_{inv}(\overline{X}_i^{(W_1)}), LA_{pre}(\overline{X}_i^{(W_s)}) \rightarrow LA_{post}(\overline{X}_i^{(W_1)}, \overline{X}_i^{(W_s)}) \land LA_{inv}(\overline{X}_i^{(W_s)})$ (5.29)

We specify distributed action $DA$ of the refined working object $W_c$ that binds the localized actions of component working objects:
\[
DA(\overline{X}^{(W)}, \overline{X}^{(W)}) = \\
\rho_d (LA_1(\overline{X}_1^{(W)}, \overline{X}_1^{(W)}), \ldots, LA_s(\overline{X}_m^{(W)}, \overline{X}_m^{(W)}))
\]

Here \( \overline{X}^{(W)}, \overline{X}^{(W)} \in \Sigma_c \) are states of the refined working object \( W_c \). These states are expressed as tuples:

\[
\overline{X}^{(W)} = (\overline{X}_1^{(W)}, \ldots, \overline{X}_m^{(W)})
\]

\[
\overline{X}^{(W)} = (\overline{X}_1^{(W)}, \ldots, \overline{X}_m^{(W)})
\]

\( \overline{X}_j \) - is a state of \( j \)-th instance of component working object \( W_i \);

\( LA_j(\overline{X}_j^{(W)}, \overline{X}_j^{(W)}) \) - is a localized action specified for the \( j \)-th instance of component working object \( W_i \), \( i=1..s, j=1..m_i \).

\( W_c \) refines \( W_a \) by decomposition, with the distributed action \( DA \) refining the localized action \( LA \).

We identify the states of interests: \( \Sigma^*_a \subseteq \Sigma_a, \Sigma^*_c \subseteq \Sigma_c \), which include initial states \( \overline{X}^{(W)} \), \( \overline{X}^{(W)} \) and terminating states \( \overline{X}^{(W)}, \overline{X}^{(W)} \) of both actions. Then we specify the relation \( R^*: \Sigma^*_a \times \Sigma^*_c \to \{ \text{true, false} \} \) between these states of interest and use the definition of correct \( (m,n) \)-refinement. First we define the refinement correctness that preserves the external behavior: This formalization is applicable when the localized action is modeled declaratively. Second, we define the refinement correctness that preserves the external and internal behavior.

**Definition 5.16.** [preservation of the external behavior]

\( W_c \) specifies a **correct refinement of \( W_a \) by decomposition, with distributed action \( DA \) refining localized action \( LA \)** if and only if

1. \( W_c \) is a correct refinement of \( W_a \) by decomposition and property distribution (Definition 5.13)
2. given a refinement relation \( R^*: \Sigma^*_a \times \Sigma^*_c \to \{ \text{true, false} \} \) between states of abstract and concrete specifications, for every run of the distributed action \( DA \) of \( W_c \), which starts at \( \overline{X}^{(W)} \in \Sigma^*_c \) and terminates at \( \overline{X}^{(W)} \in \Sigma^*_c \), there exists a run \( LA \) of \( W_a \), which starts at \( \overline{X}^{(W)} \in \Sigma^*_a \) such that:

\[
R^*(\overline{X}^{(W)}, \overline{X}^{(W)}) = R^*(\overline{X}^{(W)}, (\overline{X}_1^{(W)}, \ldots, \overline{X}_m^{(W)}))
\]

holds, and terminates at \( \overline{X}^{(W)} \in \Sigma^*_a \), for which

\[
R^*(\overline{X}^{(W)}, \overline{X}^{(W)}) = R^*(\overline{X}^{(W)}, (\overline{X}_1^{(W)}, \ldots, \overline{X}_m^{(W)}))
\]

holds.

We rewrite the expression for correctness of data refinement by forward simulation from Eq. (5.3) by using the refinement relation \( R^* \) defined above. We obtain the expression for correct organizational refinement as follows:

\[
\forall \overline{X}^{(W)}, \overline{X}^{(W)} \in \Sigma_a, \overline{X}^{(W)} \in \Sigma_c \mid R^*(\overline{X}^{(W)}, \overline{X}^{(W)}) \land DA(\overline{X}^{(W)}, \overline{X}^{(W)}) \Rightarrow \exists \overline{X}^{(W)} \in \Sigma_a \mid LA(\overline{X}^{(W)}, \overline{X}^{(W)}) \land R^*(\overline{X}^{(W)}, \overline{X}^{(W)})
\]
For localized and distributed actions, the modeler might require the imperative preservation of sequences of intermediate states (an internal behavior).

**Definition 5.17.** [preservation of the external and the internal behavior]

$W_c$ specifies a correct refinement of $W_a$ by decomposition, with distributed action $DA$ refining localized action $LA$ if and only if

1. $W_c$ is a correct refinement of $W_a$ by decomposition and property distribution (Definition 5.13)
2. given a refinement relation $R^*: \Sigma^*_a \times \Sigma^*_c \rightarrow \{true, false\}$ between states of abstract and concrete specifications, for every run of the distributed action $DA$ defined by the ordered sequence of states, including initial and the terminating states:
   \[
   X_{i_0}^{(W_c)}, X_{i_1}^{(W_c)}, \ldots, X_{i_n}^{(W_c)} \in \Sigma^*_c \ | \ (X_{i_0}^{(W_c)} = X_0^{(W_c)}) \land (X_{i_n}^{(W_c)} = X_n^{(W_c)}) ,
   \]
   such that
   \[i_0 \ i_1 \ldots \ i_n\]
   is a monotone sequence of natural numbers; there is a run $LA$ of the abstract action, also defined by the ordered sequence of states:
   \[
   X_{j_0}^{(W_a)}, X_{j_1}^{(W_a)}, \ldots, X_{j_m}^{(W_a)} ,
   \]
   such that
   \[j_0 \ j_1 \ldots \ j_m\]
   is a monotone sequence of natural numbers;
   and for every $k$ and $X_{k_0}^{(W_a)} \in \Sigma^*_c$, $X_{k_i}^{(W_a)} \in \Sigma^*_a$, $R^*(X_{j_k}^{(W_a)}, X_{k_i}^{(W_a)})$ holds.

\[
R^*(X_{j_k}^{(W_a)}, X_{k_i}^{(W_a)}) = R^*(X_{j_k}^{(W_a)},(X_{k_i_1}^{(W_a)}, X_{k_i_2}^{(W_a)}, \ldots, X_{k_i_{m_k}}^{(W_a)})) \quad (5.32)
\]
Chapter 6

Analysis of SEAM Specifications using Formal Specification Languages

In Chapter 4 we specify the FOL-based semantics for SEAM. In Chapter 5 we formulate correctness for different refinement types in SEAM as FOL formulas. The refinement verification is reduced to a proof of validity of these formulas.

The algorithm for refinement verification involves the following steps:

1. Representation of the abstract specification as an FOL-formula;
2. Representation of the concrete specification as an FOL-formula;
3. Definition of a refinement relation between states of the concrete and the abstract specifications as an FOL-formula;
4. Checking that abstract and concrete specifications, as well as the refinement relation, are not overconstrained (i.e. there exists an interpretation of their state variables that evaluates the corresponding FOL-formula to ‘true’);
5. Application of (1,1)- or (m,n)-schema for refinement correctness as explained in Chapter 5: This means a specification of forward or generalized forward simulation between the abstract and the concrete specifications. Refinement correctness is also a FOL-formula, which is a combination of formulas from 1-3.
6. Validation of refinement correctness.

The validation of an FOL formula can be automated using model checkers and theorem provers.

In this chapter, we define the technique for an automated validation of refinement correctness, which is based on two model verification tools: the Alloy Analyzer [3]; and the Jahob verification system [63][115]. We apply this technique for refinement verification of SEAM specifications.

The idea behind the automated verification is to translate a SEAM specification to a (target) specification language, supported by a verification tool.

Technically, we automate the steps 1 and 2 from the algorithm above by defining and implementing the mapping rules for SEAM specifications to a formal specification language;

Using the verification tool for the target formal specification language, we automate the steps 4 and 6 of the algorithm above. These two steps are reduced to satisfiability and validity problems for the corresponding FOL-formulas. These problems can be solved by the tool.

The identification of a refinement type, specification of a refinement relation, and the formalisation of the refinement correctness as an FOL-formula (steps 3 and 5 of the algorithm above) should be done manually, by a designer.
In Section 6.1 of this chapter we provide an overview of the approaches to formal verification based on model checking and formal theorem proving. We examine in detail the Alloy modeling language and its analyzer, which is an example of a model checker; and the Jahob verification system, which is an example of a formal theorem prover. In Section 6.2 we present a simple example of SEAM specification. This specification is verified with Alloy and Jahob in the following sections: In Section 6.3 we specify a mapping of SEAM to the Alloy specification language and illustrate the refinement verification in the Alloy Analyzer tool. In Section 6.4 we present a prototype tool for automated mapping of SEAM specifications to Alloy. In Section 6.5 we formalize the refinement correctness for SEAM specifications as a Jahob formula and illustrate the refinement verification in the Jahob verification system.

6.1 Approaches to Formal Verification

There are two main approaches to formal verification: model checking [20] and a theorem proving based on logical inference [47] [64]. When a designer specifies refinement correctness, for example, based on simulations from Chapter 5, these approaches verify this correctness. Not only refinement correctness, but any other property of a specification can be verified.

Model checking is an approach for verifying requirements and design for a vast class of systems, including real-time embedded and safety-critical systems. Model checkers analyze system models written in some specification language. The fact that the model satisfies a certain property is expressed as a logical formula. Model checkers often use counterexample-based algorithms to validate the formula. If a counterexample (a set of values of system state variables that evaluates the formula to 'false') is found - this formula is invalid. The major drawback of the model checking is a state explosion problem, which originates from the fact that for real systems the size of the state space grows exponentially with the number of processes [21]. To avoid this problem, model checkers validate the formula for the limited test spaces. Therefore, the validation result is not universal, and related only to this test space of a model checker. The absence of a counterexample does not imply the formula validity in model checkers. Some examples of model checkers are: Alloy Analyzer [3], BLAST [52], SPIN [54].

The second approach is an automated theorem proving based on logical inference. As in the previous approach, to be processed by a theorem prover, system models are written in some specification languages; the fact that the model satisfies a certain property is expressed as a logical formula. The task is to prove the validity of this formula, deducing it from a set of axioms that exist for the underlying logic (e.g. first-, second-, higher-order logic etc), and hypotheses made about the system. If the theorem prover manages to construct a proof, then the formula is valid. The absence of a proof, dually to model checkers, does not necessarily mean that the formula is invalid - due to the complexity of a proving procedure.

Despite the fact that the automated theorem proving is complex and requires much human involvement, compared to the model checking, its application is promising: this approach is not limited by the state explosion problem and can handle the infinite number of states. The examples of theorem provers for the first-order logic are: [100][99]. The examples of theorem provers for the higher-order logic are: [48][74][82].

To prove desired properties of specifications, or to verify the correctness of their refinement, a visual modeling language can benefit from model checkers and automated theorem provers. In Chapter 4, we introduce our formal semantics for SEAM visual
specifications. Based on these semantics, we specify a mapping of SEAM models to (1) the Alloy specification language for the refinement verification with the Alloy Analyzer tool [3], (2) the Jahob formulas, written in subset of the Isabelle specification language, or Jahob programs for proving the refinement correctness in Jahob verification system. Both the Alloy Analyzer and Jahob verification system support the automated specification analysis.

6.1.1 The Alloy Specification Language and the Alloy Analyzer

The Alloy Analyzer is a tool for the automated analysis of models written in the Alloy specification language [59]. This tool is an example of a model checker.

Alloy is a declarative specification language developed by the Software Design Group at MIT. Alloy is a language for expressing complex structural constraints and behaviour based on first-order logic. The syntax of Alloy is similar to the syntax of OCL – the Object Constraint Language for UML[76]. However, Alloy is a fully declarative, whereas OCL combines both declarative and imperative (operational) elements.

Unlike a programming language, a declarative Alloy model describes the effect of behaviour and does not reveal its mechanism. This modeling technique allows for the creating and analysis of partial models and is beneficial when a modeler, for example, has a limited knowledge about the system or develops an abstract system specification.

Given a logical formula and a data structure that defines the value domain for this formula, the Alloy Analyzer decides whether this formula is satisfiable. Mechanically, the Alloy Analyzer attempts to find a model instance - a binding of the variables to values - that makes the formula true. A logical formula may correspond to some property of the modeled system or its behavior. The current version of Alloy Analyzer is based on the new SAT-based model finder Kodkod [106].

Analysis with Alloy

We model the actions performed by a system as Alloy formulas. The parameters of these formulas are values of system state variables before and after the action.

With the Alloy Analyzer, we can (1) validate that the action specification does not contain contradictory constraints (i.e. it is not overconstrained); (2) validate a refinement between two specifications: to do so, we specify abstract and concrete action specifications ($A_a$ and $A_c$) and a refinement relation $R$ between their states as Alloy predicates. The fact that $A_c$ correctly refines $A_a$, given a refinement relation $R$, is expressed in the Alloy specification language as an assertion.

Assertions are proven in Alloy by a counterexample, as follows: An assertion is valid if and only if it is satisfiable by every model instance (see Chapter 3 for semantics of FOL). If there is at least one model instance that falsifies this assertion, then the assertion is invalid. Such an instance is called a counterexample. If the analyzer finds no counterexample, then the assertion may be valid. The assertion validity is limited by the test space of model instances, considered by the analyzer.

To prove refinement correctness (i.e. to validate it for all possible model instances), the same assertion can be examined by theorem provers. If the proof of validity is constructed than the assertion is valid without a limitation. We use the Jahob verification system [63] to make a formal proof of refinement correctness.

6.1.2 The Jahob Verification System

Jahob is a data structure verification system [63][115]. Jahob combines the techniques from static analysis, decision procedures, and theorem proving. The Jahob system analyzes
programs written in a subset of Java and annotated with specification constructs. The main idea is to verify that the program is consistent with its specification.

The input language for Jahob is a subset of Java, extended with annotations. These annotations contain formulas written in a subset of higher-order logic (HOL) of the Isabelle theorem prover [74][82] and represent a program specification.

Based on this architecture, a Jahob program can be compiled, tested, and executed using existing Java tools; and it can be statically verified to satisfy important data structure consistency properties. Jahob reduces the verification problem to deciding on the validity of HOL formulas; these formulas are used as an input for the Jahob form decider, which carries out the proof of validity (Fig. 6-1).

Specification constructs in Jahob are written in special comments: /*: this is a special comment */. These constructs mainly contain formulas denoting a predicate on a program state or a relationship between the current and a previous program state.

Similarly to a state of a working object in SEAM, the program state in Jahob is specified by the values of the program’s variables. Jahob distinguishes two types of program variables: Standard Java variables called concrete variables, and variables defined as a part of Jahob specification called specification variables. Specification variables do not affect program execution and exist for verification purposes.

To specify a program behavior, Jahob uses procedure contracts [71] that contain:

- A precondition, stating the state of the procedure upon its invocation;
- A frame condition, listing the components of state that may be modified by the procedure, meaning that the other state components remain unchanged;
- A postcondition, describing the state of the procedure at the end of its invocation.

To constrain the data structure of a program, apart from procedure contracts, Jahob can specify program invariants.

Given the invariants and procedure contracts, the Jahob system statically analyzes the program implementation to ensure that (1) it preserves data structure consistency properties, and (2) each procedure conforms to its specification.

When analyzing a procedure p, Jahob assumes that the precondition of p holds and checks that p satisfies its postcondition and the frame condition. Dually, when analyzing a call to procedure p, Jahob checks that the precondition of p is satisfied, assuming that the frame condition and the postcondition of p hold.

From Jahob programs, the Jahob verification system first generates logical constraints (proof obligations) in higher-order logic and then proves their validity using a form decider. Jahob attempts to prove these proof obligations using various specialized reasoning procedures. Although some procedures may fail in deciding formula validity, the others may succeed.

Fig. 6-1 illustrates an architecture of the Jahob verification system. This system may accept for verification both Jahob specifications (Java programs annotated with Jahob expressions) and Jahob formulas (expressions, written in a subset of Isabelle specification language). Jahob specifications are first pre-processed and transformed into Jahob formulas. Then the formulas are validated by using various decision procedures (e.g. Isabelle, SPASS, E, etc). Jahob formulas can be entered for validation directly by using the Jahob formDecider tool.
Figure 6-2: Jahob Verification system: (a) a Jahob specification is an input for the Jahob verification system. It is a program, written in a subset of Java and annotated with Jahob expressions. This specification is transformed later into Jahob formula; (b) a Jahob formula is a ‘ready to prove’ expression that is an input for the formDecider.

Analysis with Jahob

1. The possibility of using directly the Jahob form decider (formDecider) allows us to verify a refinement of SEAM specifications without writing Jahob programs, but specifying Jahob formulas.

FormDecider is a command-line tool for proving formulas (Fig. 6.1(b)). We map an FOL formula that expresses the refinement correctness for SEAM specifications to a Jahob formula and pass the latter to the Jahob formDecider. FormDecider attempts to decide formula validity. The result is supposed to approve or refute the result obtained earlier with the Alloy Analyzer.

Technically, we specify Jahob formulas from corresponding formulas in Alloy. The mapping between Alloy and Jahob formulas is introduced later in this section.

2. SEAM specifications with explicit update statements can be translated to Jahob specifications - Java programs annotated with Jahob expressions – for further verification with Jahob verification system (Fig. 6-1(a)). The mapping of SEAM action contracts to Jahob specification constructs, and the mapping of SEAM update statements to Java statements are two main parts of this approach. The representation of a SEAM specification as a Jahob program permits us to formally prove that the action implementation (the update statements) is consistent with its specification (the action contract). We expect to develop this approach in the future.

6.2 The 'XYZ' Example

In this section we introduce a simple example and use this example in the following sections to specify the mapping rules of SEAM to Alloy and then to Jahob for further verification.
Fig. 6-2 illustrates the SEAM specification of a working object $M$ seen as a whole ($M_w$) with three primitive properties $X, Y, Z$. A localized action $doMath$ of the working object specifies the operation on the instances of these properties (integer values). One instance of each property is specified in the model: $x:X, y:Y, z:Z$. This is done using host relations with multiplicity and instance expressions. We define the state of the working object $M$ by a tuple of state variables: $V = (x, y, z)$; The state is calculated as a binding of these state variables and their values: $\overline{X} = state(x, y, z)$.

The localized action $doMath$ (denoted as $LAdoMath$ in Fig. 6-2) is specified with the following contract:

$LAdoMath_{pre} : true$;

$LAdoMath_{frame} : x' = x$; \hspace{1cm} (6.1)

$LAdoMath_{post} : (y' = x + y) \land (z' = z + x + y)$

The action specifies a transition from a pre-state $\overline{X}$ to a post-state $\overline{X}'$. The pre-state and the post-state are defined by values of state variables $x, y, z$ before the action execution and after the action termination respectively. We denote this as follows:

$\overline{X} = state(x, y, z) = (x, y, z)$ \hspace{1cm} pre \hspace{1cm} state

$\overline{X}' = state(x, y, z) = (x', y', z')$ \hspace{1cm} post \hspace{1cm} state

The precondition of this action ‘true’ means that the action is available (i.e. can be triggered) at any state of the system.

The postcondition defines relations between values of $x, y$ and $z$ before and after the action. The fact that the value of $x$ is not changed by the action is expressed by a frame condition.

We write the action specification as a formula:

$LAdoMath (\overline{X}, \overline{X}') \overset{def}{=} LAdoMath (x, y, z, x', y', z') = true \rightarrow (y' = x + y) \land (z' = z + x + y) \land (x' = x)$ \hspace{1cm} (6.3)

This is equivalent to: $LAdoMath (\overline{X}, \overline{X}') = (y' = x + y) \land (z' = z + x + y) \land (x' = x)$.
Preconditions, postconditions, frame conditions, and invariants (if any) are specified as annotations for action-property relations in SEAM specifications. These annotations are expressed in a subset of the Alloy language.

6.3 Mapping to Alloy

6.3.1 Model Elements

A SEAM working object seen as a whole \((W_w)\) and the properties of this working object \(P_i\) are represented in Alloy as sets and denoted by signatures.

We specify the working object \(M_w\) from our example (Fig. 6-2) in Alloy as:

\[
\text{sig } M_w{...}\]

An Alloy signature can be considered as a class in the object-oriented paradigm.

Property instances \(p_1, ..., p_n\) are relations of a type \(W_w \rightarrow P_i\), having \(W_w\) as its domain and the set \(P_i\) as its range. The expression \(W_w \cdot p\) returns a value from its range \(P_i\). Alloy relations can be seen as analogy of fields in the object-oriented paradigm.

SEAM uses relations with multiplicities to specify host relations, composition relations and property to property (PP-) relations (Section 3.4). These relations are annotated with expressions of the form \(M \mid M\), \(I_M\) where \(M = # | #..# | #..* | *;\) and \(I_M = \langle\text{inst.name}\rangle[,, <\text{inst.name}>]\).

\(M\) is a multiplicity expression; \(I_M\) – an instance expression. Instance names \(p_1, ..., p_n\), define the names of relations in Alloy. \(M\) specifies a number of such relations. Table 6-1 illustrates the most useful expressions of the form \(M \mid M\) in SEAM and their mapping to Alloy [59]:

<table>
<thead>
<tr>
<th>(Mk)</th>
<th>Alloy:</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>a</td>
</tr>
<tr>
<td>0..1</td>
<td>a</td>
</tr>
<tr>
<td>1..3</td>
<td>a,b,c</td>
</tr>
<tr>
<td>*</td>
<td>b</td>
</tr>
</tbody>
</table>

Table 6-1

SEAM relations with multiplicities are shown in Fig. 6-3:

Fig. 6-3(a) illustrates a single instance. We denote it in Alloy as: \(a: \text{one } A\)

Fig. 6-3(b) illustrates an unbounded set of undistinguishable instances: \(b: \text{set } B\)

Fig. 6-3(c) illustrates a finite (bounded) set of distinguishable instances: \(c_1, c_2, c_3: \text{one } C\)

Figure 6-3: SEAM multiplicities
Properties A, B, C in Fig. 6-3 are primitive properties; they specify sets of integers: for example, each instance of A has a value that is a relation of type $A \rightarrow \text{Int}$. In Alloy, we specify these properties as follows:

```alloy
sig A {value : one Int}
sig B {value : one Int}
sig C {value : one Int}
```

we simplify the notation for primitive properties:

```alloy
a : one Int
b : set Int
c1, c2, c3 : one Int
```

We provide a specification for the working object $M_w$ from our example as follows:

```alloy
sig $M_w$
{x, y, z: one Int}
```

![Figure 6-4: SEAM compound property](image)

### Example 6.1.
Considering a data structure illustrated in Fig. 6-4, we specify **compound properties** Client and Address by the following Alloy signatures:

```alloy
sig Client {
  id : one ID,
  n: one Name,
  a1, a2: one Address}
sig Address {
  s : one Street,
  npa : one NPA}
```

**SEAM actions** are mapped to Alloy predicates. **Action parameters** are mapped to the parameters of these predicates.

**Preconditions, postconditions and invariants** of a SEAM action are specified as annotated action to property (AP-) relations in SEAM diagrams.

*In our example (Fig. 6-2), we obtain the action specification by combining corresponding annotation expressions as follows:

$$L\text{AdoMath}(X, X') \overset{\text{def}}{=} L\text{AdoMath}_{\text{post}}(X) \rightarrow L\text{AdoMath}_{\text{post}}(X, X') \land L\text{AdoMath}_{\text{frame}}(X, X') \quad (6.4)$$

If an action precondition, postcondition, or invariant is specified by several annotated AP-relations in the diagram, then the corresponding action condition is represented in Alloy as a conjunction of
**annotation expressions.** If an action precondition is not specified - we consider that this action is available at each state of the working object. This can be denoted as: \( A_{pre} = true \).

In Fig. 6-2, two AP-relations are stereotyped with a keyword **Post.** Thus, the action postcondition is a conjunction of the annotating expressions: \( LAdoMath_{post} = (y' = y + x) \land (z' = z + (y + x)) \).

The Alloy specification language is based on first-order logic, which allows us to map the action specification from Eq.(6.4) to an Alloy predicate as follows:

```alloy
pred LAdoMath[x,y,z:one Int, x',y',z':one Int] { - LAdoMath(x, x')
  //true =>
  y' = y + x &&
  z' = z + (y + x) &&
  x = x'}
```

Logical conjunction ‘\( \land \)’ is expressed by the operator ‘and’ or ‘&&’ in Alloy. Table 6-2 illustrates the logical connectives and quantifiers of FOL and correspondent Alloy symbols, used in this work.

<table>
<thead>
<tr>
<th>FOL</th>
<th>Alloy:</th>
</tr>
</thead>
<tbody>
<tr>
<td>( \forall a:X</td>
<td>F )</td>
</tr>
<tr>
<td>( \exists a:X</td>
<td>F )</td>
</tr>
<tr>
<td>( \exists! a:X</td>
<td>F )</td>
</tr>
<tr>
<td>( \top )</td>
<td>true</td>
</tr>
<tr>
<td>( \bot )</td>
<td>false</td>
</tr>
<tr>
<td>( \neg )</td>
<td>not</td>
</tr>
<tr>
<td>( \land )</td>
<td>&amp;&amp;</td>
</tr>
<tr>
<td>( \lor )</td>
<td></td>
</tr>
<tr>
<td>( \Rightarrow )</td>
<td>=&gt;</td>
</tr>
<tr>
<td>( \Rightarrow )</td>
<td>=&gt;</td>
</tr>
<tr>
<td>( \iff )</td>
<td>==</td>
</tr>
<tr>
<td>( \in )</td>
<td>in</td>
</tr>
<tr>
<td>( \not\in )</td>
<td>!in</td>
</tr>
<tr>
<td>( = )</td>
<td>==</td>
</tr>
<tr>
<td>( &lt; )</td>
<td>&lt;</td>
</tr>
</tbody>
</table>

### Successful Action

With the Alloy Analyzer we can verify the consistency of a SEAM action by checking if this action specification is not overconstrained (see Section 5.3). This is done by checking the satisfiability of the formula that expresses the successful action in Eq. (5.9).

For the successful action \( LAdoMath \) in Fig. 6-2 we write:

\[
LAdoMath_{pre}(\overline{X}) \land LAdoMath_{post}(\overline{X}, \overline{x'}) \land LAdoMath_{frame}(\overline{X}, \overline{x'})
\]  

(6.5)

The satisfiability of this formula means that there exists at least one binding of the properties to values such that the action precondition holds and its postcondition is satisfied. To verify satisfiability of Eq.(6.5), we translate this formula to the Alloy predicate and run this predicate in the Alloy Analyzer:

**Action precondition of LAdoMath in the example is ‘true’ (i.e. it always holds). Thus, technically, specification of LAdoMathc and specification of the successful action LAdoMath_suc are the same.**

We run the predicate in the Alloy Analyzer using the command **run** with the predicate name and other (optional) parameters:

5 See the Alloy Analyzer documentation on http://alloy.mit.edu/ for the details.
6.3.2 Functional Refinement: from an Action as a Whole to an Action as a Composite

We continue working on the example, presented in Section 6.2 and illustrate the mapping of the refined SEAM specification illustrated in Fig. 6-5 to Alloy.

SEAM diagram in Fig. 6-5 specifies the working object \( M \) seen as a whole with the localized action \( doMath \) seen as a composite (\( LAdoMath_c \)). This specification is a functional refinement of the specification presented in Fig. 6-2: The computation presented by action \( LAdoMath \) in Fig. 6-2 is decomposed into two subcomputations, one modifying the property \( y \), and another one modifying the property \( z \). These subcomputations are component localized actions \( LAaddToY1 \) and \( LAaddToZ1 \).

![Figure 6-5: Specification of a working object M as a whole, with a localized action doMath seen as a composite. LAdoMath_c is modeled declaratively.](image)

First, we consider a declarative specification of \( LAdoMath_c \): we do not specify the order of component actions and do not show the intermediate states of action execution.

Component actions \( LAaddToY1 \) and \( LAaddToZ1 \) are independent. Therefore, we write the following expression for the localized action \( doMath \) seen as a composite from Eq.(4.30):

\[
LAdoMath_c \_\_decl ar(\bar{X}, \bar{X}') = LAdoMath_c \_\_decl ar(x, y, z, x', y', z') = \text{true} \rightarrow LAaddToY_1(x, y, z, x', y', z') \land LAaddToZ_1(x, y, z, x', y', z')
\]

Component localized actions are specified with the following formulas:

\[
LAaddToY_1(x, y, z, x', y', z') = \text{true} \rightarrow (x' = x) \land (y' = y + x)
\]

This is equivalent to: \( LAaddToY_1(x, y, z, x', y', z') = (x' = x) \land (y' = y + x) \)

\[
LAaddToZ_1(x, y, z, x', y', z') = \text{true} \rightarrow (x' = x) \land (z' = z + x + y)
\]

This is equivalent to: \( LAaddToZ_1(x, y, z, x', y', z') = (x' = x) \land (z' = z + x + y) \)

Preconditions for both component actions of \( LAdoMath_c \) are ‘true’.
Similarly to \textit{LAdoMath} seen as a whole, we map \textit{LAdoMath}\textsubscript{c} and its component actions to Alloy predicates:

\begin{verbatim}
pred LAdoMath_c_declar[x, y, z, x', y', z': one Int ]{
    //true =>
    LAaddToY1[x, y, z, x', y', z'] &&
    LAaddToZ1[x, y, z, x', y', z']
}
pred LAaddToY1[x, y, z, x', y', z': one Int ]{
    x' = x &&
    y' = y + x
}
pred LAaddToZ1[x, y, z, x', y', z': one Int ]{
    x' = x &&
    z' = z + x + y
}
\end{verbatim}

\textbf{NOTE:} Despite the fact that the action \textit{LAaddToY1} does not change the value of \textit{z}, and the action \textit{LAaddToZ1} does not change the value of \textit{y} - we do not specify this as a frame condition. The declarative specification Eq.(6.6) specifies two actions \textit{LAaddToY1} and \textit{LAaddToZ1} executed within one state transition, where both \textit{z} and \textit{y} are changed. Therefore, a frame condition would lead here to the action inconsistency.

The imperative specification of \textit{LAdoMath}\textsubscript{c} is illustrated in Fig. 6-6. The SEAM diagram specifies the order of component actions - the control flow- using SEAM \textit{action-action} (AA) \textbf{relations}. In our example actions are composed \textit{sequentially}, using SEAM transition (see Section 4.3).

\begin{figure}[h]
\centering
\includegraphics[width=\textwidth]{example_diagram.png}
\caption{Specification of a working object \textit{M} as a whole, with a localized action \textit{doMath} seen as a composite. \textit{LAdoMath}\textsubscript{c} is modeled imperatively, with an intermediate state $\overline{X}_t = state(x_t, z_t, z_t)$. Local variables $x_t, z_t, z_t$ specify the intermediate state of the action as a composite. a) Local variables are emphasized; b) action contract is emphasized.}
\end{figure}

SEAM defines several types of \textbf{AA-relations}: Start, End, Transition, Conditional transition, Fork (AND, OR, XOR), Merge (AND, OR, XOR). In Section 4.3.6 we have introduced the FOL semantics of these relations. In Table 6-3 we present the semantics of these relations in Alloy.
### Table 6-3

<table>
<thead>
<tr>
<th>SEAM</th>
<th>Alloy:</th>
</tr>
</thead>
<tbody>
<tr>
<td>Start(A1)</td>
<td>( A_1(x, x_1) )</td>
</tr>
<tr>
<td>End(A1)</td>
<td>( A_1(x_1, x') )</td>
</tr>
<tr>
<td>Transition(A1,A2)</td>
<td>( A_1(x_1, x_2) \land A_2(x_2, x_3) )</td>
</tr>
<tr>
<td>ConditionalTransition (A1,A2,C)</td>
<td>( A_1(x_1, x_2) \land C \Rightarrow A_2(x_2, x_3) )</td>
</tr>
<tr>
<td>ConditionalTransition (A1,A2,A3,C)</td>
<td>( A_1(x_1, x_2) \land C \Rightarrow A_2(x_2, x_3) \text{ else } A_3(x_2, x_4) )</td>
</tr>
<tr>
<td>AndFork(A1,[A2,A3])</td>
<td>( A_1(x_1, x_2) \land (A_2(x_2, x_3) \land A_3(x_2, x_4)) )</td>
</tr>
<tr>
<td>AndMerge([A1,A2,A3])</td>
<td>( (A_1(x_1, x_3) \land A_2(x_2, x_3)) \land A_3(x_3, x_4) )</td>
</tr>
<tr>
<td>OrFork(A1,[A2,A3])</td>
<td>( (A_1(x_1, x_2) \land A_2(x_2, x_4)) \lor (A_1(x_2, x_4) \land A_3(x_2, x_4)) \lor (A_1(x_1, x_6) \land A_2(x_6, x_7) \land A_3(x_6, x_8)) )</td>
</tr>
<tr>
<td>OrMerge([A1,A2,A3])</td>
<td>( (A_1(x_1, x_3) \land A_2(x_2, x_3) \land A_3(x_2, x_4)) \lor (A_1(x_1, x_7) \land A_2(x_2, x_7) \land A_3(x_7, x_8)) )</td>
</tr>
<tr>
<td>XorFork (A1,[A2,A3])</td>
<td>( (A_1(x_1, x_2) \land \neg A_3(x_2) \land A_2(x_2, x_4)) \lor (A_1(x_1, x_2) \land \neg A_2(x_2) \land A_3(x_2, x_4)) )</td>
</tr>
<tr>
<td>XorMerge([A1,A2],A3)</td>
<td>( (A_1(x_1, x_2) \land A_3(x_2, x_5) \land \neg A_3(x_2)) \lor (A_2(x_3, x_4) \land A_3(x_4, x_6) \land \neg A_3(x_2)) )</td>
</tr>
</tbody>
</table>

The action \( LAaddToY_2 \) seen as a whole specifies a transition of a working object \( M \) from a pre-state \( \overline{X} \) to an intermediate state \( \overline{X} ' \). We write:

\[ \overline{X} = \text{state}(x, y, z) = (x_i, y_i, z_i) \rightarrow \text{intermediate state} \]

Here \( (x_i, y_i, z_i) \) is a tuple of values of state variables \( x, y, z \) ‘in the middle of’ the action execution (Fig. 6-6).

The action \( LAaddToZ_2 \) seen as a whole specifies a transition of a working object \( M \) from \( \overline{X} ' \) to a post-state \( \overline{X} '' \). We write the following expression for the action \( LAaddToMathc \):

\[ LAaddToMathc \_imper(x, y, z, x', y', z') = \]

\[ \text{true} \rightarrow \exists x_i : X, y_i : Y, z_i : Z \]  \hspace{1cm} (6.10)

Component localized actions are specified with the following formulas:

\[ LAaddToY_2(x, y, z, x', y', z') = \]

\[ \text{true} \rightarrow (x' = x) \land (y' = y + x) \land (z' = z) \]  \hspace{1cm} (6.11)

\[ LAaddToZ_2(x, y, z, x', y', z') = \]

\[ \text{true} \rightarrow (x' = x) \land (y' = y) \land (z' = z + y + x) \]  \hspace{1cm} (6.12)

**NOTE:** The specifications of component localized actions in Eq. (6.10), (6.11) are different from those in Eq. (6.7), (6.8): In Eq. (6.11), (6.12) we specify the *frame conditions* on the variables \( z \) and \( y \).

We map \( LAaddToMathc \) and its component actions to Alloy:
The imperative and declarative specifications of localized action `doMath`, seen as a composite, are related. The imperative specification `refines` the declarative specification as it reduces nondeterminism. We can check the refinement between these specifications. We call the declarative specification `abstract` and the imperative specification `concrete` and specify the refinement relation between abstract and concrete states. We express the refinement correctness as the following Alloy assertion:

```alloy
assert Declar_Imper{
all xc, yc, zc, x'c, y'c, z'c, xa, ya, za: one Int |
(LAdoMath_c_imper[xc, yc, zc, x'c, y'c, z'c ] &&
(xa = xc) && (ya = yc) && (za = zc))=>
//R(Xc,Xa)
(some x'a, y'a, z'a: Int |
LAdoMath_c_declar[xa, ya, za, x'a, y'a, z'a ] &&
(x'a = x'c) && (y'a = y'c) && (z'a = z'c) )
//R(X'c, X'a)
}
```

The Alloy Analyzer validates this assertion using a counterexample-based algorithm; it explores a limited test state space and looks for an example that invalidates the assertion. Not discovering such a counterexample, it concludes that the assertion may be valid.

**Refinement Verification**

We formalize the refinement correctness for the working object M performing action `LAdoMathc` (the `concrete` specification) refining the working object M performing action `LAdoMath` seen as a whole (the `abstract` specification). `LAdoMathc` is a functional refinement by action decomposition of the action `LAdoMath`. The correctness of this refinement is formulated in Definition 5.10. As we do not introduce new properties, the state spaces of the abstract and the concrete specifications are the same, and the refinement relation between these state spaces is an identity function. We specify the refinement relation with the following Alloy predicate:

```alloy
pred R_LAC_to_LAW[xc, yc, zc, xa, ya, za: one Int ]{
  ( xc = xa) &&
  ( zc = za) &&
  ( yc = ya)
}
```

Here the tuple `(xc,yc,zc)` specifies a state of the concrete specification, and a tuple `(xa,ya,za)` specifies a state of the abstract specification.

We specify the criterion of refinement correctness from Definition 5.10 with the following assertion in Alloy:
The localized action seen as a whole does not specify the intermediate states, therefore we verify only the correspondence of external behavior of \(LAdoMath\) and \(LAdoMath_c\).

We check the validity of this assertion in the Alloy Analyzer using the command `check` with the assertion name and other (optional) parameters\(^6\):

```
check LAW_LAC
```

### 6.3.3 Organizational Refinement: from a Working Object as a Whole to a Working Object as a Composite

Fig 6-7 illustrates the working object \(M\) seen as a composite (\(M_c\)). For \(M_c\) we specify component working objects A and B and a joint action `doMath` (denoted: \(JAdoMath\)) that represents collaboration between these component working objects.

The properties of \(M\) are distributed between A and B such that \(X\) and \(Y\) are presented in both A and B (duplicated), and \(Z\) is ‘fully delegated’ to A.

The specifications of component working objects A, B, and their parent working object \(M_c\) are mapped to Alloy as follows:

---

\(^6\) See the Alloy Analyzer documentation on http://alloy.mit.edu/ for the details
1. Component working objects are mapped to Alloy signatures. Host relations of component working objects specify relations between working objects and properties. These relations are annotated with multiplicity-instance expressions of a form $M'|I_M$. We map these relations to the fields of an Alloy signature as specified in Table 6-1:

$$\text{sig } A\{ \\
Ax, Ay, Az: \text{one Int} \\
\}$$

$$\text{sig } B\{ \\
Bx, By: \text{one Int} \\
\}$$

2. Parent working object $M_c$ is mapped to Alloy signature $M_c$. WO composition relations of $M_c$ specify relations between this working object and its component working objects. These relations are annotated with multiplicity-instance expressions of a form $M'|I_M$. We map these relations to the fields of an Alloy signature as specified in Table 6-1:

$$\text{sig } M_c\{ \\
a: \text{one } A, \\
b: \text{one } B \\
\}$$

$M_c$ is the organizational refinement of $M_w$, with $JAdoMath$ refining $LAdoMath$.

We can show that $M_c$ correctly refines $M_w$ by decomposition and property distribution by Definition 5.13:

All properties of $M_c$ are delegated to component working objects. Based on Eq. (5.22) we write:

$$\text{Inst}^{(M_c)}_{\text{max}}(X) = 2 > \text{Inst}^{(M)}_{\text{max}}(X);$$

$$\text{Inst}^{(M_c)}_{\text{max}}(Y) = 2 > \text{Inst}^{(M)}_{\text{max}}(Y);$$

$$\text{Inst}^{(M_c)}_{\text{max}}(Z) = \text{Inst}^{(M)}_{\text{max}}(Z) = 1;$$

Figure 6-7 presents a declarative specification of $JAdoMath$: We do not specify in which order the properties of component working objects are modified and do not show the intermediate states of action execution. We define shared properties $\text{shared}_x:X$, $\text{shared}_y:Y$ for the working object to maintain the common knowledge of $M_c$.

The state of the working object $M_c$ is represented by a tuple of states of its component working objects: $\overline{X}^{(M_c)} = (\overline{X}^{(A)}, \overline{X}^{(B)})$, where each component working object is characterised by its state variables, and

$$\overline{X}^{(A)} = \text{state}(x, y, z);$$

$$\overline{X}^{(B)} = \text{state}(x, y)$$

State variables of A and B are disjoint. To distinguish them, we use prefixes as follows:

$$\overline{X}^{(A)} = \text{state}(Ax, Ay, Az);$$

$$\overline{X}^{(B)} = \text{state}(Bx, By);$$

We write the following expression for the joint action $\text{doMath}$:

$$\sum_{\text{doMath}}$$
We map this formula to the Alloy predicate as follows:

\[
\text{JAdoMath\_w\_declar}([Ax, Ay, Az, Bx, By], [Ax', Ay', Az', Bx', By']) = \text{true} \Rightarrow \\
\exists \text{shared\_x} : \text{X}, \text{shared\_y} : \text{Y} | \\
(Ax' = Ax) \land (Bx' = Bx) \land (By' = By + Bx) \land (Az' = Az + Ax + Ay) \land \\
(\text{shared\_x} = Ax) \land (\text{shared\_x} = Bx) \land (\text{shared\_y} = Ay') \land (\text{shared\_y} = By')
\]

(6.15)

Refinement Verification

We formalize the refinement correctness for the working object \(M_c\) with the action \(\text{JAdoMath}\) (the concrete specification) refining the working object \(M_a\) with the action \(\text{LAdoMath}\) (the abstract specification). By Definition 5.14, this is an organizational refinement by decomposition, with a joint action refining a localized action. We specify the refinement relation between state spaces with the following Alloy predicate:

\[
\text{pred } \text{R\_JA\_to\_LA}\left([Ax_t, Ay_t, Az_t, Bx_t, By_t] : \text{one Int}, [xa_t, ya_t, za_t] : \text{one Int} \right) \land (Ax_t = xa_t) \land (Az_t = za_t) \land (Ay_t = ya_t)
\]

We specify the formula for correct refinement with the Alloy assertion and check this assertion in the Alloy Analyzer.

\[
\text{assert } \text{LA\_JA}\{ \\
(\text{all Ax, Ay, Az, Ax', Ay', Az', Bx, By, Bx', By': Int, xa, ya, za: Int | (JAdoMath\_w\_declar[Ax, Ay, Az, Ax', Ay', Az', Bx, By, Bx', By'] \land R\_JA\_to\_LA[Ax, Ay, Az, Bx, By, xa, ya, za] ) \Rightarrow \\
(some xa', ya', za': Int | R\_JA\_to\_LA[Ax', Ay', Az', Bx', By', xa', ya', za'] \land \text{LAdoMath\_w}[xa, ya, za, xa', ya', za'] } \\
\}
\]

check \text{LA\_JA}

The joint action seen as a whole does not specify the intermediate states, therefore we verify only the correspondence of external behavior of \(JAdoMath\) and \(LAdoMath\). In Appendix A, we provide a listing of Alloy specifications for the ‘XYZ’ example. This listing contains other simple refinement verification exercises and comments on them.
6.4 Automated SEAM to Alloy Translation

We explore the possibility of automating the translation of SEAM specifications to Alloy and we build a technique based on XSLT\[105\] transformation. This technique is illustrated in Fig. 6-8.

![Figure 6-8: Automated SEAM to Alloy transformation.](image)

Based on the SEAM metamodel from Chapter 3, we create the Simple Seam Editor - a EMF-based Eclipse application [39] that simulates a back-end of a tool for SEAM graphical modeling\(^7\). This application allows for creating SEAM hierarchical models using textual interface, and stores them in XML format.

Figure 6-9 illustrates the interface of the Simple Seam Editor. On the left pane, a SEAM model is created using a hierarchical tree-structure.

![Figure 6-9: A screenshot of the Simple Seam Editor application](image)

\(^7\) Currently, an official tool for SEAM visual modeling - SeamCAD tool [66] - is under development. The metamodel, presented in this work, and some important elements, required for the model analysis, are not yet adopted by this tool. Due to this limitation, the application, simulating a tool back-end, was created.
The root object is a model that contains one working object that represents a system. Using a contextual menu, new sibling and/or child elements can be added to a current element. This is defined by a SEAM metamodel. On the bottom of the screen, element properties are listed in the property pane. These properties (e.g. name, parent element, condition expression, etc.) are also specified for each element based on the SEAM metamodel. Values of these properties are defined by a designer.

Figure 6-10 shows the model pane in detail and illustrates how the model of the XYZ example from Section 6.2 corresponds to the SEAM graphical specification of this example.

The second part of the automated translation is an XSLT script that transforms XML files, created in the Simple Seam Editor into Alloy specifications.

The XSLT transformation of the SEAM model stored as an XML file, results in a formatted textual file that can be stored as *.als (native file type for Alloy) and opened in the Alloy Analyzer. This file contains a data structure and a specification of SEAM actions, extracted from SEAM working object specification and mapped to Alloy as it is specified in the Section 6.3.
Refinement relations and assertions for refinement verification should be provided manually: the specification of a refinement relation between models is a designer's choice. To simplify this task, we consider an implementation of automated alignment assistant – a supplementary function of the SEAM modeling tool SeamCAD [66] - as a part of our future work. This assistant will identify a refinement type based on designer's activities and will help the modeler to define the refinement relations and refinement verification procedures.

By providing an automated mapping of a SEAM specification to Alloy, we facilitate the analysis process; though, understanding of the Alloy model by a designer remains indispensable for interpreting results of this analysis. Verification in Alloy, if successful, approves the correctness of the design process; however, when it fails - the designer has no further support from the tool to find out the reason of the failure. The lack of interpretation of the verification result is one of the main drawbacks of this method.
Figure 6-11 illustrates an XML file, representing a SEAM model before the processing, the XSL script for processing, and a resulting Alloy file. The Alloy plug-in under Eclipse allows us to make all the steps - a model creation, its transformation, and analysis - in the common Eclipse environment.

6.5 Mapping to Jahob

We specify two approaches to a formal verification of SEAM specifications by using the Jahob verification system: The first approach uses the Jahob formDecider to validate formulas for refinement correctness; the second approach aims at verification of consistency of SEAM specifications.

In the first approach, a Jahob formula that expresses the refinement correctness is written based on SEAM action specifications. This formula can also be generated from the Alloy code. We validate the obtained Jahob formula with the Jahob form decider (Fig. 6-1(b)).

The second approach is based on the mapping of SEAM specifications to Jahob programs. Jahob programs are further converted to Jahob formulas to be used with the formDecider (Fig. 6-1(a)).

6.5.1 From an Alloy Specification to a Jahob Formula

Jahob formulas use Isabelle notation as a semantic and syntactic basis. In this section we explain how a Jahob formula can be generated from the Alloy code and illustrate this with XYZ example.

Jahob Formula as a Lambda-expression

A Jahob formula consists of two parts: the first part contains the definitions of SEAM abstract and concrete actions $A_{\text{a}}$, $A_{\text{c}}$, and a refinement relation $R$; the second part states the refinement correctness, expressed using the definitions from the first part. Jahob formula is a lambda expression of lambda calculus [9]. A recursive definition of a lambda expression is the following:
expression = name | lambda-function | function application
name = function name | variable name
lambda-function = \(\lambda\) name . expression
function application = expression expression

In a Jahob formula, SEAM actions and a refinement relation are formulated as \textit{lambda functions}. For example, for a SEAM action \(A\), expressed as a FOL formula \(A(x, x') = A_{pre}(x) \rightarrow A_{post}(x, x')\), where \(x\) and \(x'\) are values of state variables before and after the action, we can write the following lambda function:
\[
A = \lambda \: xy. A_{pre}(x) \rightarrow A_{post}(x, x')
\] (6.16)
Here \(A_{pre}\) and \(A_{post}\) can also be lambda functions.

To formulate the refinement correctness, we define (1) the abstract action specification \(A_a\), (2) the concrete action specification \(A_c\), and (3) the refinement relation \(R\) between the abstract and the concrete specifications as \textit{lambda-functions}. We connect these functions as follows:
\[
(A_a = \lambda \ldots) \land (A_c = \lambda \ldots) \land (R = \lambda \ldots) \rightarrow \text{[refinement correctness]}
\] (6.17)

The refinement correctness follows from the conjunction of lambda-functions. Refinement correctness can be written using the expressions defined in sections 5.5 and 5.6. Some modifications of syntax, compared to definitions in Chapter 5, are required:
- symbol ‘\(|\)’ is replaced by ‘\(\cdot\);’
- an application of a FOL formula or predicate is written: \(A(x_1, x_2, \ldots, x_n)\); application of a corresponding lambda functions is written: \(A(x_1) (x_2) \ldots (x_n)\) or \(A_{x_1} x_2 \ldots x_n\).

We write a lambda expression for a SEAM specification \(W'\) with concrete action \(A_c\) correctly refines the specification \(W\) with abstract action \(A_a\) given a refinement relation \(R\), as follows:
\[
A_a \overset{\text{def}}{=} A_a \land R \overset{\text{def}}{=} \left( \forall x \: \forall x'. \: \forall x'' \: A_a(x) (x') (x'') \land R(x)(x') (x'') \rightarrow \exists x'' . \left( A_a(x) (x') \land R(x')(x'') \right) \right)
\] (6.18)

In Eq.(6.16) \(A_a\), \(A_c\), \(R\) are definitions of corresponding lambda-functions.

Using the syntax of Jahob formulas, we write:
\[
A_a \land A_c \land R \rightarrow (\forall x \: \forall x'. \: A_a(x) (x') \land R(x)(x') \land R(x)(x')) 
\]

Note that the syntax of Jahob does not accept “’” symbol in a variable name. We replace it by “p” (which stands for ‘post’).

**From an Alloy specification to a Jahob formula**
Table 6-4 illustrates the correspondence between the Alloy syntax and the syntax of Jahob formulas.
In Alloy, we separately specify the predicates for abstract and concrete action specifications, plus the predicate that expresses a refinement relation between them. Then we express the refinement correctness as an assertion:

`pred Aa [x, x’: one Int ]{..}
pred Ac [y, y’: one Int ]{..}
pred R [x, y: one Int ]{..}
assert A2_refines_A1{all x,y,y’ | R(x,y)&& A2(y,y’) => A1(x,x’)&& R(x’,y’)}

An analogous Jahob formula starts with a conjunction of lambda function definitions, which specify SEAM actions and a refinement relation. These definitions are followed by an expression of a correct refinement:

`Aa = (% x xp.  .... )) &   //function definition (abstract action)
Ac = (% y yp.  .... )) &   //function definition (concrete action)
(R = (% x y. .... )) -->  //function definition (refinement relation)
ALL x y yp. Ac(y)(yp) & R (x)(y) -->
EX xp. Aa(x)(xp) & R (xp) (yp)) //function application (correctness)

**The XYZ Example in Jahob**

We map the Alloy code for XYZ example to Jahob formulas by using the rules for specification of lambda expressions and the syntax correspondence from Table 6-4. Then validate these formulas with the Jahob form decider. The code below illustrates the mapping of the Alloy predicate for the localized action `doMath` seen as a whole to the lambda function:

**Alloy Predicate LAdoMath:**

```alloy
pred LAdoMath[x,y,z:one Int, x',y',z':one Int] { y' = y + x &
  z' = z + ( y + x) &
  x = x'
}
```

**Lambda function LAdoMath:**

```alloy
(LAdoMath = (% x y z xp yp zp.
  yp = x + y &
  zp = z + (y + x) &
  xp = x))
```

In Section 6.3.2 the functional refinement for XYZ example is specified in Alloy. We consider the localized action `doMath` (Fig. 6-2) an abstract action, and the localized action `doMath` modeled imperatively (Fig.6-6) – a concrete action.

The listing below specifies the Jahob formula that expresses refinement correctness between the abstract and the concrete actions:
File: final_law_laci.form

(* action LAdoMath_w *)
(ActionAbstract = (% x y z xp yp zp.
  yp = x + y &
  zp = z + (y + x) &
  xp = x)) &

(* component actions *)
(LAaddToY2 = (% x y z xp yp zp.
  xp = x &
  zp = z &
  yp = y + x )) &

(LAaddToZ2 = (% x y z xp yp zp.
  xp = x &
  yp = y &
  zp = z + x + y )))&

(* LAdoMath_composite - imperative *)
(ActionConcrete = (% x y z xp yp zp.
  EX x_t, y_t, z_t.
  LAaddToY2 x y z x_t y_t z_t &
  LAaddToZ2 x_t y_t z_t xp yp zp ))&

(*Refinement verification*)
(* refinement relation *)
(RefinementRelation = (% xc_t yc_t zc_t xa_t ya_t za_t.
  xc_t = xa_t &
  zc_t = za_t &
  yc_t = ya_t )) -->

(*assert LAW_LAC *)
((ALL xa ya za xc yc zc xcp ycp zcp.
  ActionConcrete xc yc zc xcp ycp zcp &
  RefinementRelation xc yc zc xa ya za) -->
  (EX xap yap zap.
  ActionAbstract xa ya xap yap xap zap &
  RefinementRelation xcp ycp xcp xap yap zap))

The values of xa, ya, za and xap, yap, zap define the pre-state and the post-state of the abstract action; The values of xc, yc, zc and xcp, ycp, zcp define the pre-state and the post-state of the concrete action.

This formula is used for a verification of functional refinement with the Jahob form decider. Jahob formulas are stored in a textual file *.form. To verify the formula, the Jahob form decider is called:

~/Alloy-Jahob$ ../jahob/bin/formDecider.opt final_law_laci.form -usedp e isa z3

The command –usedp followed by a list of parameters specifies the decision procedures that will be used to prove the formula.

Executing the command above with specified decision procedures we obtain the formula validity proven by E:

=================================================================
E proved 1 out of 1 sequents. Total time : 0.1 s
=================================================================
In Appendix B, we provide listings of several Jahob formulas that are used to verify refinement in the XYZ example. These formulas are obtained from the corresponding Alloy code in Appendix A. All the results obtained with Alloy Analyzer, are confirmed by Jahob.

6.5.2 From a SEAM Specification to a Jahob Program

We specify SEAM actions as untyped lambda functions. The verification of complex data types is possible with the Jahob verification system by specifying a Jahob program.

An approach, where SEAM specifications with explicit update statements are translated to Java programs annotated with Jahob specification constructs and verified using Jahob verification system, is a part of our future work. There are two main tasks to anticipate:

- A mapping of SEAM action contracts (FOL formulas) to Jahob specification constructs;
- A mapping of SEAM update statements to Java statements.

At the time of this writing, a student project on the translation of SEAM specifications with explicitly modeled update statements into a subset of Java has been completed [tbd]. This project is resulted in a prototype tool for the automated SEAM to Java translation. This tool is developed on the platform of ATL (Atlas Model Transformation) tool [55].

A representation of a SEAM specification as a Java program permits us to simulate this specification on the Java platform. A representation of SEAM specification as a Jahob program will enable us to formally prove that the action implementation (the update statements) is consistent with its specification (the action contract).

For the moment, we do not have a theory to interpret the verification results and to provide the recommendations on specification improvement for designers. We address this topic in our future work.
Chapter 7

Practical Impact: Application of the Developed Theory in Practice

In this chapter we focus on the practical contribution of this thesis. We illustrate our technique of refinement verification presented in the previous chapter with two examples:

The On-Line Book Store example shows different customizations and designs of the book store sale process. The verification of developed business process specifications against each other, or against a higher level specification, guarantees that all specifications are behaviorally compatible and correspond to the same strategic goal of the company. This example is presented in Section 7.1;

The Gas Incident Service case study shows a service specification at one level and its planned implementation by a group of IT applications on the other. A formal verification of a service specification against its planned implementation serves as a proof that the service is implemented correctly. This example is presented in Section 7.2;

In both cases the problem is reduced to a verification of refinement between two specifications and solved using the algorithm defined in Chapter 6: We provide the SEAM diagrams, the Alloy specifications obtained from these diagrams, and we illustrate the refinement verification with the Alloy Analyzer.

In Section 7.3 we present results of the inquiry conducted among practitioners. We discussed the research results of this dissertation with experts who meet the problem of Business/IT alignment in practice. This inquiry provided us with valuable feedback and helped us to prioritize the directions of our research in future.

7.1 High-Level Design and Analysis of Business Processes: The On-Line Book Store Example

Problem description:

Aligning business processes with business strategy is an important preoccupation in modern organizations. This alignment is made simpler if an adequate level of abstraction for business process representation is used. A business process can be defined as “a set of partially ordered activities aimed at reaching a well-defined goal.” [61]. The keyword partial alludes to the problem of defining, ahead of time, the exact order in which the activities will be executed. Indeed a business process may be subjected to many conditions in which this order cannot be identified at design time. The exact sequence of activities is therefore quite impossible to predict [61]. Even a simple sale process has been shown to incorporate optional execution orders depending on, among other aspects, cultural and legal considerations [90]. The example given in [90] describes an on-line book store that needs to adapt its sale process to local customs in different countries. The sequence of execution between payment and order fulfilment needs to be adapted to different local preferences. In the United States for example, payment by credit card is most often required before goods are shipped. In some
European countries, e.g. Switzerland, customers are used to paying for goods after they have been received.

Organizations have a marked tendency to limit their interpretations of their environment [109]. These interpretations constrain their business processes at the early phases of their design [73]. Modeling techniques, such as BPMN [78] and use cases [58], also encourage modeling details at an early stage. As a result, in many cases, an organization will commit to one of the execution paths (e.g. paying before sending the goods) and later, handle the second one (sending the goods before receiving the payment) as an exception. The number of exceptions, however, often results in tangled processes containing many exceptions. This has two related consequences. First of all, the alignment between the strategy of the organization (i.e. selling on-line) and its detailed business processes is not apparent. Second, the flexibility of the processes themselves [91] is limited because they become difficult to manage and change.

We propose a technique that complements imperative business process specifications with declarative specifications. This declarative specification enables designers to describe the actions that a business process needs to contain, but not their sequence. It omits the specification of the control flow between the actions thus keeping the process design independent from constraints imposed by an environment in which this process will be implemented. The control flow, often specific to a given environment, is later modeled in an imperative specification. Our technique includes checking the conformance of the imperative and the declarative specifications.

Our technique can improve the alignment of the business process with the business strategy of an organization by giving a synthesis of a set of business processes (abstracting the control flow) and maintain a rigorous relationship with the detailed process. Flexibility may also be enhanced because alternative paths are modeled as separate business processes conforming to an overall process, thereby helping organizations to tailor them to different environments without losing the overall view.

We illustrate our technique with the example of an On-Line Book Store: The company wants to design a global view on its sale process in order to maintain the alignment between the different customizations of this process for different countries and to simplify the design of these customizations. We illustrate a business process redesign task using the same example and show how declarative specifications help designers to understand the relation between the redesigned process and the initial one.

We formalize the concepts of the SEAM modeling language using first-order logic with the Alloy specification language [59]. This enables us to check our models using the Alloy Analyzer [3].

7.1.1 A Business Process Specification in SEAM
A SEAM working object, as a composite, specifies a distributed action (DA) between components of the working object (Chapter 3). The distributed action can be considered as a declarative specification of a business process within a working object. It defines the actions to be performed by component working objects, but does not prescribe the order in which these actions will be performed. Many execution paths are valid for a given distributed action. The selection of one of them is the business process designer’s choice. When a designer commits to a concrete control flow, the specification is no longer declarative; it is transformed into a traditional imperative business process model. We call it a customization.
7.1.2 Example: A Sale Process for the On-Line Book Store

In this section we illustrate the declarative business process specifications with the example of a sale process for an On-Line Book Store. We also clarify the relationships between these declarative specifications and traditional imperative business process models.

The On-Line Book Store Description

The On-Line Book Store (BS) is a company that collaborates with a publisher (P), and a bank (B) to sell books to customers. BS manages requests from customers via the Internet. A sale begins when a customer logs into www.BS.com using an id (customerID) and requests a book using a book id (bookID). If the requested book is available in the publisher’s inventory and if the customer’s rating in the data base of the bank is good then the sale is successful. The successful sale terminates when the book is delivered by the publisher to the customer and the payment for the book is received by the bank from the customer.

If the ordered book is not available or the customer’s rating is not good, we assume that no action is executed (the cash and the inventory remain unchanged).

The Successful Sale: Process Design

The company wants to design different customizations of its sale process for different countries by maintaining a global view of this process.

For the sake of simplicity, we limit our discussion to the specification of the successful sale. We do not specify the case where the payment is not received or the book is not delivered.

Localized Action sellOk

In Fig. 7.1 the On-Line Book Store value network is modeled as a working object seen as a whole - SVN_w. The successful sale process is modeled as a localized action LAsellOk of this working object. LAsellOk specifies the strategic goal of the value network: To perform a sale by guarantying that if a book is available and if a customer has a good rating then this book will be delivered and paid by the customer.

Action-property relations are used on the diagram in Fig.7-1 to specify pre- and post-conditions of LAsellOk. In a legend for Fig.7-1 we present a formal specification of pre- and post-conditions for LAsellOk written in the Alloy specification language.

Figure 7-1: Localized Action SellOk.
**Distributed Action DAsellOk**

To relate the strategic goal of the value network with the specification of a business process that supports this goal, we represent the On-Line Book Store value network as a collaboration between the bank, the publisher and the book store – the participants in the value network. In Fig. 7-2 the On-Line Book Store value network is modeled as a working object seen as a composite - SVN_c. The SEAM distributed action DAsellOk in Fig.5 specifies how the responsibilities in a successful sale are distributed between the value network participants. The bank, the publisher and the book store are modeled as working objects seen as wholes. The responsibilities are modeled as localized actions of the corresponding working objects: for example, the fact that the bank checks the customer’s rating is modeled by localized action checkRating within the B working object.

To specify the communication between the book store, the bank and the publisher, we define additional actions preocessRequest and getID, and properties cID, bID in Fig. 7-2. These actions and properties serve for information exchange between working objects and are not specific to the successful sale process; we show them without shading and place the relations between them and another actions and properties as dashed lines.

![Figure 7-2: Distributed Action DAsellOk.](image)

In our example, sharedBook and sharedCustomer are shared properties. They represent the information used by the bank, the publisher, and the book store to manage their tasks within the successful sale process of the value network.

**The Process Customization**

The distributed action DAsellOk is a declarative business process specification that defines the conditions and the results of the process but does not impose any constraints on how this process will be conducted in a particular environment.

Considering that the On-Line Book Store wants to pursue international markets, namely US and European markets (including Switzerland), different process customizations have to be designed [90].

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In the US, most on-line orders are paid by a credit card and shipped only after the payment is received. A customization of the sale process for the US market is illustrated in Fig. 7-3 (a). This customization is modeled as a BPMN business process diagram (BPD).

In countries such as Switzerland most mail order companies and on-line stores have traditionally trusted customers enough to deliver ordered goods without an obligation to pay in advance. A payment form is shipped with the purchase and customers can then use it to pay for their purchases in a post office or through their bank [90]. For the Suisse market, the sell process should be customized allowing for the delivery prior to (or simultaneously with) the payment procedure as illustrated in Fig. 7-3 (b).

The distributed action DAsellOk relates business process customizations illustrated in Fig. 7-3 with the strategic goal of the On-Line Book Store value network, specified as a localized action in Fig. 7-1.

**The Successful Sale: Process Redesign**

The second business process modeling task that can benefit from an additional declarative specification layer is a business process redesign. A decision of the company to redesign its business process (or processes) can be based on different internal or external factors, e.g. the emergence of new technologies or new products, the change of a political situation, the competitive landscape etc. Considering our example, let’s imagine that the On-Line Book Store discovered that its shipment service suffers from chronic delays and is found unsatisfactory by the customers. The On-Line Book Store decides to maintain its own inventory and to provide the shipment service by itself, instead of outsourcing this service to the publisher.

Although the strategic goal of the value network remains the same, the value network itself is reorganized and, as a consequence, a business process redesign is required. The redesign of a successful sale can be rigorously modeled using a declarative specification that
reflects a new distribution of responsibilities between participants of the reorganized value network. We specify a new (redesigned) distributed action for sellOK in Fig. 7-4. In this specification, the book inventory modeled as a set of books, and the localized actions checkAvailability and deliverBook become a part of the BS working object specification. Working object P that represents the publisher in our specification is removed.

The distributed action DAsellOK in Fig.7-4 is consistent with the localized action LAsellOk in Fig.4 because the latter specifies only the work to be done - but not the distribution of this work. This illustrates an integration of two declarative specifications of the sale process: the initial one and the redesigned one.

Based on the redesigned distributed action, new process customizations for the US and Switzerland are modeled in Fig. 7-5. The redesigned distributed action DAsellOK relates the business process customizations illustrated in Fig. 7-5 with the strategic goal of the On-Line Book Store value network, specified as a localized action in Fig. 7-1.
7.1.3 Validation of Declarative Business Process Specifications in Alloy

A transition from the localized action specified for the working object seen as a whole to the distributed action specified for the same working object seen as a composite is a form of organizational refinement, defined in Section 5.7.3.

Specification of Localized and Distributed Actions SellOk Using Alloy

We model SEAM actions as Alloy predicates. In SEAM, an action defines a transition of a working object from one state (pre-state) to another (post-state). The SEAM action specification uses a pre-state and a post-state as parameters. We use indexes _pre, _post, and _prepost to model parameters of the Alloy predicate:

- all parameters indexed with _pre correspond to the properties of the working object before the action and define a pre-state of this working object \( X \);
- all parameters indexed with post- correspond to the properties of the working object after the action happens and define the post-state \( X' \) of this working object;
- index _prepost specifies parameters that are not modified by the action. These parameters correspond to the properties that make a part of both \( X \) and \( X' \).

We write the following Alloy specifications of pre- and post-states for localized action LAsellOk in Fig.7-1:

```plaintext
bInventory_pre: one Inventory,
customerDB_prepost: one CustomerDB,
customerID_prepost: one Int,
bookID_prepost: one Int,
cash_pre: one Int \( \Rightarrow X \)

bInventory_post: one Inventory,
customerDB_prepost: one CustomerDB,
customerID_prepost: one Int,
bookID_prepost: one Int,
cash_post: one Int \( \Rightarrow X' \)
```
The Alloy code below specifies the LAsellOk localized action as a corresponding Alloy predicate. Lines 1-7 in this code correspond to the action’s precondition; lines 8-14 – to its postcondition. The predicate LAsellOk holds when its precondition implies its postcondition.

```
pred LAsellOk [bInventory_pre, bInventory_post: one Inventory, 
customerDB_prepost: one CustomerDB, 
customerID_prepost, bookID_prepost, cash_pre, cash_post: one Int] {
  1. (all requested_book: Book, buyer: CustomerInfo| 
  2. (requested_book.id = bookID_prepost) and 
  3. (requested_book in bInventory_pre.content) and 
  4. (requested_book.quantity>0) and 
  5. (buyer.id = customerID_prepost) and 
  6. (buyer in customerDB_prepost.content) and 
  7. (buyer.rating > 0) ) =>
  8. ((one b_post: Book | 
  9. (b_post.id = requested_book.id) and 
 10. (b_post.quantity= requested_book.quantity- 1) and 
 11. (bInventory_post.content = bInventory_pre.content - requested_book + b_post) and 
12. //(customerToDeliver.id = bookDeliveredToID) 
13. (cash_post = cash_pre + 1 ) ) 
14. //(buyer.id = paymentFromID) 
})
```

The specification of the localized action LAsellOk in Alloy can be read as follows:
For all buyers and requested books (line 1): the precondition of LAsellOk holds if the values of their id fields are equal to the values of bookID and customerID respectively (lines 2,5), and the requested book exists in the inventory (line 3), and is available (line 4), and a buyer exists in the customer DB (line 6), and has a good rating (line 7). The postcondition expresses that there exists a book_post (line 8) that corresponds to the requested book (line 9) and its quantity is equal to the quantity of the requested book decreased by one (line 10), and the book inventory after the action (bInventory_post) is equivalent to the inventory before this action (bInventory_pre) with the requested book substituted by the book_post (line 11), and the cash value after the action is augmented by one unit (line 13). We also need to specify that the requested book is delivered to the proper buyer, and that the payment is received from the proper customer (lines 12, 14). For the sake of simplicity we do not model it in this example.

The working object SVN_c from the SEAM specification in Fig.7-1 is specified with its three component working objects: the bank (B), the publisher (P) and the book store (BS). The localized actions of component working objects are modeled as the following Alloy predicates:

```
pred p_checkAvailability[..]{..} – the publisher checks if the requested book is available;

pred b_checkRating[..]{..} - the bank checks if a rating of the customer is good;

pred p_deliverBook[..]{..} – the publisher delivers the book to the customer;

pred b_getPayment[..]{..} - the bank receives payment from the customer.
```

The following predicates specify communication between the book store, the bank, and the publisher, as do so the corresponding localized actions in Fig. 7-2:
pred bs_processRequest[. . ]{. . } - the book store gets request and externalizes the requested book id and the customer id for the rest of the network.
pred p_getID[. . ]{. . } - the publisher gets the requested book id;
pred b_getID[. . ]{. . } - the bank gets the customer id.

The distributed action DAsellOk binds the localized actions of the component working objects. The Alloy code below specifies the DAsellOk distributed action as an Alloy predicate. Lines 1-7 in this code correspond to the precondition of a localized action LAsellOk from the listing above; lines 8-9 – to its postcondition.

pred DAsellOk[p_bInventory_pre, p_bInventory_post: one Inventory, p_requestedID_prepost: one Int, b_customerDB_prepost: one CustomerDB, b_requestedID_prepost: one Int, b_cash_pre, b_cash_post: one Int, bs_customerID_prepost, bs_bookID_prepost: one Int]{
  1. ( one cID,bID: Int | 
     2. bs_processRequest[bs_bookID_prepost, bs_customerID_prepost, bID,cID] and 
     3. p_getID[bID, p_requestedID_prepost] and 
     4. b_getID[cID, b_requestedID_prepost]) and  
     5. all sharedBook:one Book, sharedCustomer: one CustomerInfo| 
     6. (p_checkAvailability[p_bInventory_pre, p_requestedID_prepost, sharedBook] and 
     7. b_checkRating[b_customerDB_prepost, b_requestedID_prepost, sharedCustomer]) => 
     8. (p_deliverBook[p_bInventory_pre, p_bInventory_post,p_requestedID_prepost,sharedBook, sharedCustomer] and 
     9. b_getPayment[b_cash_pre,b_cash_post, sharedCustomer])
}

Prefixes p_, b_, bs_ in the names of predicates specifying localized actions and in the names of predicate parameters specifying properties refer to the component working objects these localized actions or properties belong to (e.g. p_bInventory specifies the book inventory, which is the property of the publisher).

7.1.4 Validation of Refinement from LA to DA Using Alloy Analyzer 4.0

To relate the designed business process of successful sale to the strategic goal of the On-Line Book Store, we have to guarantee:

1) The correct refinement from the localized action LAsellOk to the distributed action DAsellOk;

2) The correct mapping between the declarative specification DAsellOk and the imperative business process specifications (i.e. BPMN diagrams) that specify process customizations.

To check if the distributed action DAsellOk correctly refines the localized action LAsellOk in our example, we use the definition of refinement correctness from Definition 5.16. We write an Alloy assertion that specifies the correct refinement from abstract to concrete specification:

assert DA_LA{
  all \( \overline{X}_c,\overline{X}_c',\overline{X}_a \)
  (R_LA_to_DA (\( \overline{X}_c,\overline{X}_a \))and DAsellOk(\( \overline{X}_c,\overline{X}_c' \)) => 
  some \( \overline{X}_a' \) LAsellOk(\( \overline{X}_a,\overline{X}_a' \))and R_LA_to_DA(\( \overline{X}_c',\overline{X}_a' \))}
Here $\overline{X}_c$, $\overline{X}_a$, $\overline{X}_a'$ stand for pre- and post-states at concrete and abstract specifications respectively. $R_{LA\_to\_DA}$ is a refinement function that relates state spaces of the SVN_w and SVN_c. We provide the complete specification of this refinement function:

$$\text{pred } R_{LA\_to\_DA}(p_{b\_Inventory\_t}: \text{one } \text{Inventory}, p_{requestedID\_t}: \text{one } \text{Int}, b_{customerDB\_t}: \text{one } \text{CustomerDB}, b_{requestedID\_t}: \text{one } \text{Int}, b_{cash\_t}: \text{one } \text{Int}, b_{customerID\_t}, b_{bookID\_t}: \text{one } \text{Int}, // \text{concrete}$$

$$b_{Inventory\_t}: \text{one } \text{Inventory},$$

$$customerDB\_t: \text{one } \text{CustomerDB}, customerID\_t, bookID\_t, cash\_t: \text{one } \text{Int} // \text{abstract}$$

$$
\begin{align*}
& p_{b\_Inventory\_t} = b_{Inventory\_t} \\
& p_{requestedID\_t} = bookID\_t \\
& b_{customerDB\_t} = customerDB\_t \\
& b_{requestedID\_t} = customerID\_t \\
& b_{cash\_t} = cash\_t \\
& b_{customerID\_t} = customerID\_t \\
& b_{bookID\_t} = bookID\_t
\end{align*}
$$

$\Leftrightarrow R(\overline{X}_a', \overline{X}_c')$

From Declarative to Imperative Business Process Specification

The mapping between SEAM distributed actions, modeled declaratively, and imperative business process diagrams modeled in BPMN can be done in two steps:

First, we define a control flow for the SEAM distributed actions modeled declaratively. This is equivalent to the specification of intermediate states, caused by the execution of individual localized action, and the order of their occurrence.

The second step is a mapping of the obtained imperative specifications to BPMN. This mapping and its automation is a part of our future work.

The conformance of the imperative specification with the declarative specification in SEAM can be formally verified in Alloy by using the same approach as for refinement verification and by assuming that the imperative action specification is nothing but a correct refinement of this action, specified declaratively.

7.2 Specification and Alignment Verification of Services in ITIL: The Gas Incident Service Case Study

Problem description:

The Information Technology Infrastructure Library (ITIL) [57] is a collection of good practices for the management of IT services. The perceived value of ITIL is the improvement of the relationship between the business and its IT service providers. The relationship between a business and its internal IT department is defined with the use of Service Level Agreements (SLA). Similar agreements define the relationships between sub-departments of the IT department (Operational Level Agreements, OLA) and between the IT departments and their external providers (Underpinning Contract, UC). For the IT department to be able to live up to its obligations defined in the SLA, it has to make sure that the SLA is implementable with the existing and envisioned infrastructure and with its OLAs and UCs. In
In this paper, we propose a formal method for specifying the alignment between an SLA and a set of OLAs. We illustrate our method with a concrete ITIL project currently in progress. This project is done for the public utility of Geneva: SIG (http://www.sig-ge.ch/). SIG provides, among other services, water, gas, and electricity to Geneva residents. One of the important services is the management of gas incidents, i.e., leaks from gas machinery or pipes. The IT department of SIG provides support for this service. The expectation of the gas department and the possibilities afforded by the IT department are captured in an SLA. In this project, the utility company, the consulting company Itecor and the EPFL University have partnered to apply the SEAM method for the definition of the SLA.

Though we are inspired by the real example, we have substantially simplified the actual processes. In particular, all process definitions and quantities, e.g., intervention time, are illustrative only. To account for the fact that the example is an academic illustration only, we use the name City Industrial Service to refer to the utility company.

7.2.1 Case Study: Gas Incident Service

In this section, we model a case study that specifies a security service for gas leaks (‘gas incident service’), provided by the City Industrial Service (CIS) and supported by the IT system GasIncident. We consider the service description as follows: [The gas incident service has] to neutralize a gas leak reported by a witness, guaranteeing that if the incident site is not secured within 45 minutes from the time of the registration of the witness’ call by a CIS operator, then an emergency call is made to the local Fire Brigade.

Service Specification

In Fig. 7-6, we specify the Service Level Agreement (SLA), which represents the service specification.

The IT system IT_GasIncident_w is a service provider in our example (the postfix ‘w’ means that the system is represented as a whole). The process of securing an incident is modeled as an action LA_GasIncidentService of this IT system. This action specifies the service, provided by CIS.

To support the incident processing, we define an incidentList property for the IT system. The incidentList represents a set of records of incident cases. The fields of an Incident record are set during the incident processing.

Action-property relations in Fig. 7-6 explicitly specify the action contract (precondition, postcondition, invariant). For example, the condition ‘if the incident is not secured after 45 minutes from the time of the registration of the call, then the emergency signal (out_emergency) is generated’ is expressed as a following postcondition expression:

\((\text{newInc.t3} - \text{newInc.t1} \leq 45) \land (\text{out\_emergency}=0)\) or
\((\text{newInc.t4} = \text{newInc.t1} + 45) \land (\text{out\_emergency}=1)\)
Service specification, illustrated in Fig. 7-6 is declarative. This specification defines the action contract but does not show how this contract will be implemented.

Service Construction

In Fig. 7-7, we specify the Operational Levels Agreements (OLA)s. The service is implemented by several applications; each application provides its ‘part of the service’. Concretely, IT_GasIncident_c (the postfix c means that the system is represented as a composite), which describes the planned construction of the IT_GasIncident_w has three component applications: (1) SAP_App, the SAP application, which processes the data from the help desk and provides the CIS operator with the GPS coordinates of the site; (2) the ECS_App application (Emergency Call Service), which provides an automated call service to the local fire brigade; and (3) GasIncident_App application that coordinates the incident processing, triggers the call to the fire brigade afterwards and maintains the incident record in the incident list. Specifications of the services offered by these applications correspond to Operational Levels Agreements (OLAs). Note that Underpinning Contracts (UCs) would be specified in a similar manner. Underpinning contracts specificity services offered by third parties.

The action DA_GasIncidentService1 specifies how the responsibilities in the incident securing are distributed between the applications. It is, therefore, called a distributed action. The distributed action DA_GasIncidentService1 is a declarative process specification that defines the conditions and the results of the process, but it does not impose any constraints on how this process has to be conducted in a particular environment.
Figure 7-7: Service implementation modeled as SEAM distributed action

The GasIncidentProcess action specifies the responsibility of the GasIncident_App application and is also modeled declaratively: the set of tasks this action performs is listed, but no control flow is defined.

The SEAM specification of LA_GasIncidentService in Fig. 7-6 corresponds to the SLA; the SEAM specification of DA_GasIncidentService1 (as a distributed action) in Fig. 7-7 shows the planned construction of this SLA by a collaboration of three applications: SAP_App, ECS_App, and GasIncident_App. An OLA is defined for each application. The transition from the specification of the SLA (Fig. 7-6) to the specification of the multiple OLAs (Fig. 7-7) is a result of the organizational refinement (Section 6.3.3).

7.2.2 Validation of a Service and its Construction in Alloy

Specification of SLA using Alloy

To proceed with the specification analysis and alignment verification, we map the SEAM visual specifications to Alloy. Figure 5 illustrates the result of the translation of the LA_GasIncidentProcess (Fig. 1) to Alloy specification language.

In mapping the SEAM specification to the Alloy specification language, the annotations made to the diagrams are used to specify the action in Alloy.

Similarly to the previous example, we use indexes pre, post, and prepost to model parameters of the Alloy predicate. We also use prefixes in_ and out_ to specify input and output parameters of the action.

incidentList_pre: set Incident,
locationList_prepost: set GEOInfo \( \times X \)
in_call: one WitnessCall,
in_securedTime: one Int \( \times I \)
out_emergency: one Int,
out_incident: one Incident \( \times O \)
incidentList_post: set Incident,
locationList_prevpost: set GEOInfo,
in_call: one WitnessCall ⊳ X'

In the listing below, lines 1-2 defines the Alloy signature that specifies the action, line 3 specifies the action precondition, and lines 4-13 specify the action postcondition. No invariant is defined.

1. pred LA_GasIncidentService [incidentList_pre, incidentList_post: set Incident, locationList_prepost: set GEOInfo, in_call: one WitnessCall, in_securedTime: one Int, 2.out_emergency: one Int, out_incident: one Incident] {
   3. ((in_call.t >0 ) and (in_securedTime >0)) =>
   4. (one newInc: Incident | //local var. newInc
   5. (![newInc in incidentList_pre]) and //Added to the list:
   6. (incidentList_post = incidentList_pre + newInc) and
   //Initial values from the witness call:
   7. (newInc.t1 = in_call.t) and (newInc.info = in_call.d) and
   //GPS data is obtained from the Address
   8. (one loc: GEOInfo | (loc in locationList_prepost) and
   9. (loc.a = in_call.a) and (newInc.siteInfo = loc)) and
   //secured time as an income call from the technician
   10. ((newInc.t3 = in_securedTime)) and
   //either the site is secured within 45 min or emergency sent
   11. (((newInc.t3 - newInc.t1 <= 45) and (out_emergency=0)) or
   12. ((newInc.t4 = newInc.t1 + 45) and (out_emergency=1))) and
   13. (out_incident = newInc))

newInc is a local variable introduces in the action LA_GasIncidentService to create a new instance of the incident and to add it later on to the list. (See Section 4.5 about instance creation in SEAM).

The Alloy specification of a GasIncidentService localized action, modeled as a predicate LA_GasIncidentService can be read as follows:

Given a system, with its state specified by the incidentList and a locationList, and input parameters in_call, in_securedTime, and output parameters out_incident, and out_emergency (line 1,2): the precondition of LA_GasIncidentService holds if the witness call in_call with non-negative time is registered, and a non-negative securization time in_securedTime was obtained (line 3). The postcondition expresses that upon the action termination there will be created a record of incident newInc such that this record is not in the list incidentList_prev (line 4-6), and the fields of this record are received from the witness call in_call and the technician call in_securedTime (line 7-10) and if the incident is not secured after 45 minutes from the time of the registration of the witness call then the emergency signal (out_emergency) is generated (line 11), and the created incident record is an output parameter of the system – out_incident (line 13).

The working object IT_GasIncident_c from the SEAM specification in Fig.7-7 is specified with its three component working objects: SAP_App, ESC_App, and GasIncident_App. The localized actions of component working objects, defining OLAs, are modeled as the following Alloy predicates:

pred LocalizeAddress[locationList_prepost: set GEOInfo, in_address: one Int, out_location: one GEOInfo]{
   //post
   one loc: GEOInfo |
   (loc in locationList_prepost) and (loc.a = in_address) and (out_location = loc)
Getting an address as an input, the SAP_App retrieves a site location from the GEOInfo database;

```alloy
pred CallFB[mList_pre, mList_post: set EmergencyMsg, in_inc: one Incident, in_emergency: one Int, out_m: one EmergencyMsg] {
//pre
(in_emergency = 1) =>
//post: create an outgoing emergency call and add it to the list
(one out_m: EmergencyMsg | (out_m.inc = in_inc) and
(mList_post = mList_pre+out_m)) else (mList_post = mList_pre)
}
```

Getting an emergency signal as an input, the ESC_App generates a phone call to a fire brigade;

```alloy
pred GasIncidentProcess [incidentList_pre, incidentList_post: set Incident, in_call: one Int, in_siteInfo: one GEOInfo, in_onSite, in_secured: one Int, in_info: one Int, out_emergency: one Int, out_incident :one Incident] {
one shared_incident: Incident |
(OpenIncident[incidentList_pre, incidentList_post, in_call, in_siteInfo, in_info, shared_incident] and
GetTechOnSite[in_onSite,shared_incident] and
GetSiteSecured[in_secured, shared_incident] and
InciCallFB[out_emergency, shared_incident] and
CloseIncident[shared_incident] and
(out_incident = shared_incident))
}
```

The GasIncident_App manages the process, having a witness call and information from operator as input parameters.

The `GasIncidentProcess` localized action is specified as a composite with component actions `OpenIncident`, `GetTechOnSite`, `GetSiteSecured`, `InciCallFB`, and `CloseIncident`, they define responsibility of the IncidentGas application within the service in detail.

The distributed action `DA_GasIncidentService` specifies how localized actions of SAP, ECS, and GasIncident applications are bound together to provide the implementation of the GasIncidentService. The Alloy code below specifies the `DA_GasIncidentService` distributed action as an Alloy predicate.

```alloy

some shared_siteInfo: GEOInfo, shared_inc: Incident, shared_emergency: Int |
LA_GasIncidentProcess_w[incidentList_pre, incidentList_post, in_call.t, in_call.d, shared_siteInfo, in_securedTime, shared_emergency, shared_inc] and
LocalizeAddress[locationList_prepost,in_call.a, shared_siteInfo] and
CallFB[mList_pre, mList_post, shared_inc, shared_emergency, out_emergencyCall]
}
```

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7.2.3 Validation of Refinement from SLA (Modeled as SEAM Localized Action) to OLAs (Modeled as SEAM Distributed Action) Using Alloy Analyzer 4.0

Based on the Alloy semantics for SEAM specifications, defined in Chapter 6, we transform the visual SEAM specifications of the SLA or the OLA/UC (SLA and OLAs+UCs in Fig. 7-8) to the corresponding programs written in Alloy formal specification language (P1 and P2 in Fig. 7-8). We can verify the refinement correctness between the Alloy models using the Alloy Analyzer tool (http://alloy.mit.edu/).

To relate the service specification modeled as a localized action – that corresponds to the SLA - with its implementation modeled as a distributed action – that combines the OLAs -, we have to guarantee the correct refinement from the localized action LA_GasIncidentService to the distributed action DA_GasIncidentService. Similarly to the previous example, we use the definition of refinement correctness from Definition 5.16. We write an Alloy assertion that expresses the correct refinement from abstract to concrete specification

```
assert DA_LA{
    all \(X_c, X'_c, X_a, \overline{I}_c, \overline{I}_a, \overline{O}_c, \overline{O}_a\) |
    (R_Input(\(\overline{I}_c, \overline{I}_a\))\&\& R_LA_to_DA (\(X_c, X_a\))\&\& DA_OK(\(X_c, X'_c\))) =>
    some \(X'_a, \overline{O}_a\) | LA_OK(\(X_a, X'_a\))\&\& R_LA_to_DA(\(X'_a, X'_c\))\&\& R_Output(\(\overline{O}_c, \overline{O}_a\))}
```

Here \(X_c, X'_c, X_a, X'_a\) stand for pre- and post- states at concrete and abstract specifications respectively; \(\overline{I}_c, \overline{I}_a, \overline{O}_c, \overline{O}_a\) stand for input and output parameters of concrete and abstract specifications. \(R_LA_to_DA\) is a refinement relation that relates state spaces of the IT_GasIncident_w and IT_GasIncident_c. \(R\) Input and \(R\) Output are relations between input and output parameters respectively. We provide the complete specification of this relations:

```
    (incidentList_t= incidentList1_t) and
    (locationList_t= locationList1_t)}
pred R_Input[in_call: one WitnessCall, in_call1: one WitnessCall, in_securedTime, in_securedTime1: one Int ]{
    in_call = in_call1 and
    in_securedTime = in_securedTime1}
```
pred R_Output[out_emergencyCall: EmergencyMsg, out_Incident: one Incident, out_emergency: one Int]| 
(out_emergency = 1) && 
(out_emergencyCall.inc = out_Incident )

assert DA_LA{
all incidentList_pre: IDB, mList_pre: MSG, in_call: WitnessCall, 
in_securedTime: Int, incidentList1_pre: IDB, in_call1: WitnessCall, 
in_securedTime1: Int, incidentList_post: IDB, mList_post: MSG, 
locationList_prepost: GEO, locationList1_prepost: GEO |
⇔ all \(\overline{X_c}, \overline{X'_c}, \overline{X_a}, \overline{I_c}, \overline{I_a}, \overline{O_c}\) |

(DA_GasIncidentService[incidentList_pre.v, incidentList_post.v, 
locationList_prepost.v, mList_pre.v, mList_post.v, in_call, 
out_emergencyCall, in_securedTime] && 
⇔ DAsellOk(\(\overline{X_c}, \overline{X'_c}\))

R_LA_to_DA[incidentList_pre.v, locationList_prepost.v, mList_pre.v, 
incidentList1_pre.v, locationList1_prepost.v] && 
⇔ R_LA_to_DA(\(\overline{X_c}, \overline{X_a}\))

R_Input[in_call, in_call1, in_securedTime, in_securedTime1])=⇒
⇔ R_Input(\(\overline{I_c}, \overline{I_a}\))

(some incidentList1_post: IDB, out_emergencyCall: EmergencyMsg, 
out_Incident: Incident, out_emergency: Int) |
⇔ some \(\overline{X'_a}, \overline{O_a}\) |

LA_GasIncidentService_w[incidentList1_pre.v, incidentList1_post.v, 
locationList1_prepost.v, in_call1, in_securedTime1, out_emergency, 
out_Incident] && 
⇔ LAsellOk(\(\overline{X_a}, \overline{X'_a}\))

R_LA_to_DA[incidentList_post.v, locationList_prepost.v, mList_post.v, 
incidentList1_post.v, locationList1_prepost.v] && 
⇔ R_LA_to_DA(\(\overline{X'_c}, \overline{X'_a}\))

R_Output[out_emergencyCall, out_Incident, out_emergency])}
⇔ R_Output(\(\overline{O_c}, \overline{O_a}\))

7.3 Practical Feedback

To reason about a practical value of our research, we have conducted an inquiry among experts in the domain who meet the problem of business/IT alignment in practice. During this inquiry, we propose that the experts read one of our recent research papers that illustrate the practical examples above. To state their opinion about our technique, we propose that the experts answer the following questions:

1. Whether the problem discussed in the paper is encountered in practice?
2. What do you think about the usefulness of the method presented in the paper for a practitioner? Please, explain your answer.
3. How do you think the validation / verification technique presented in the paper can help you (your company)? Please, describe the advantages and disadvantages that you can expect.

The list of experts:
1. Ian F. Alexander
2. Ilia Bider
3. Alexander Samarin
4. Thomas Langenberg
5. Donald C. Gause

Below, we summarise the results of our inquiry.

Summary
1. Experts:
   - All the experts participating in our inquiry have years of experience in consulting. The areas of their expertise range from SAP consulting in IT to solutions in enterprise architecture and requirements engineering;
   - Four of the experts are active in the research community;
   - Three of the experts have their own consulting companies;
   - One expert is a full academic professor.

2. Modeling methods and tools used in practice:
   - All the experts use visual modeling techniques to develop their solutions, and to communicate them with the customers. The following tools were named by the experts: Intalio BPM suite, IBM WebSphere Integration Developer, Enterprise Architect for UML, i*, and Microsoft Power Point.
   - Most of the experts also admitted that they use their own methods and tools, created for specific problems.

3. Problem soundness:
   All the experts confirmed that the alignment of business processes with business strategy (as described in Section 7.1) and the alignment between a service level agreement (SLA) and the operational level agreements (OLAs) (as described in Section 7.2) are important problems for their organizations.

4. The usefulness of the presented method:
   (below we provide the excerpts from the answers)
   - The proposed method is useful as a methodological base for discussing problems and finding solutions. It could help to create accurate service specifications for clients;
   - The method sounds useful because it considers the complimentary of declarative and imperative techniques. The synergy of these two techniques (complimented by some guidance how to combine them) will certainly create more flexible business process models.
   - The evaluation of each alternative solution and the validation that this solution does not violate the requirements is a typical problem. Though, having a technique with which one can evaluate proposed solutions could save project resources and would be a useful instrument for a consultant;
   - It is hard to imagine a computer design problem that would not benefit from a refinement tool that is capable of recognizing and correcting inconsistencies between
high-level business and systems requirements and implementation instructions (functional specifications).

5. Advantages:
   - By expressing the relationships between actions and data graphically, it is highly expressive, making it clear what is needed when.
   - The proposed technique may serve for a consultant to verify solutions against requirements and also to evaluate and to compare these solutions.
   - Any formal verification is very useful in daily practical work because such verification can bring highly demanded, objective, and scientifically proven reasoning into a modern enterprise environment with all its political tensions and power games (where it is almost impossible to have something willingly accepted and followed by everyone).

6. Disadvantages/Concerns
   - The scalability of the method is questionable: the technique was nicely illustrated with the “toy” example, however a big concern is about how such a notation may scale up for large problems; the number of relationships may increase rapidly with the number of both actions and pieces of data, which could make the diagrams hard to read. It could also make a formal proof of correctness long; but as this is supported by the Alloy Analyzer tool, this should not be a problem.
   - The complex graphical notation plus the use of formal methods prevents this technique from being used for communication with a client.
   - The industrialisation of the approach would involve training for requirements practitioners, tooling, and reasonable assurance to both the company and the client that the approach is workable in practice (on a real problem, and by practitioners).
   - The utilization of this technique will introduce a new step in the project development process, which is promising but time and money consuming. It could be difficult to communicate a profitability of this technique to the customer.
   - It is difficult to imagine the use of formal methods of verification/validation in any foreseeable future.

7. Suggested improvements:
   - A popular version and texts in methodological style should be written, e.g. manuals, etc.
   - Making full use of the methodology will require an introduction of it in a tool that helps to design processes/support systems;
   - The visual notation needs some enhancements before meeting non-experts;
   - Several realistic projects in the field have to be accomplished using this technique to demonstrate its scalability and potential profitability for a customer;
   - There might be some possibilities for promoting formal verification/ validation, provided they are incorporated in some tool, e.g.:
     - As a sales argument for the tool
     - To provide guarantees in cases of extremely importance for the customers (e.g. SOX compliance).

The results of the conducted inquiry are valuable feedback for this work and help us to prioritize the directions of this research for the future.
Chapter 8

Conclusion

In this dissertation we have defined the formal semantics for SEAM language that permit us to validate the alignment between models, specified in SEAM.

We have achieved four main advantages for visual SEAM specifications:

1. The SEAM extension with AP-relations and AA-relations and their semantics. This extension allows for the explicit modeling of a system behavior as a change of a system state;
2. The formalization of relations between SEAM Visual Specifications as Refinements. This formalization allows for the utilization of theories that already exist in software engineering and are dedicated to rigorous program development;
3. The formalization of SEAM concepts in first-order logic (FOL). This formalization allows us to be able to reduce the problem of refinement verification in visual models to a problem of validity of an FOL-formula;
4. The definition of a language migration and refinement verification using formal specification languages. This migration allows for the utilization of tools (i.e. the Alloy Analyzer, the Jahob verification system) for automated verification of refinement.

We have illustrated our technique of refinement verification with two examples: In the first example, we consider the problem of alignment verification in the context of business process modeling; the problem presented in the second example discusses the alignment in context of service specification and design.

Using formal semantics for SEAM specifications, we have defined declarative and imperative process specifications. We use combinations of these specifications:

- to integrate different customizations and redesigns of a business process; and
- to specify services at different levels of abstraction;

We have shown how a refinement theory can be applied to validate the alignment between the processes (e.g. business processes, services), specified at different abstraction levels.

We have illustrated how Alloy, a light weight specification language, can be used to verify the alignment. We have also explored the alternative method of alignment verification, based on the Jahob verification system.

Our contribution establishes a bridge between the formal methods of Software Engineering and practical problems in the area of Business/IT alignment (i.e. the verification of alignment between process specifications and their implementations).
8.1 Future Work

The problem the alignment of Business and IT is gaining an importance. Various methods and tools have been developed in this domain in order to support the modeler in creating the models and making these models transparent, traceable, and aligned. In conducting this research, we have pursued the goal of bringing the visual specifications to such a level of precision that they become self-contained means for system validation. To do so, we have extended the visual notation with formal concepts and textual annotations. By defining the formal semantics for visual SEAM specifications, we were able to create a technique for mapping these specifications to the verifiable code. The main directions of our future work are:

(1) To decrease the visible complexity of the method by providing documentation, guidelines and by implementing the front-end of the technique in the form of an application. This should hide the complexity from the user (see for example [13]).
(2) Further exploration of opportunities given by formal semantics in SEAM;
(3) Further exploration of opportunities given by refinement formalization for SEAM visual specifications.

8.1.1 Complexity Reduction, Usability

Documentation. At the time of this writing, this PhD dissertation is the most complete documentation of the technique created. To enhance the usability of the method, documentation, focused on the practical application of the technique (e.g. a tutorial) would be very useful.

The SEAM graphical notation.
The development of a simpler notation that can be used both in an education process with an academic audience (i.e. students, research community), and in practice with a business audience (as a technique for business workshops) is the major goal in the future.

The automated alignment assistant.
We consider an implementation of the automated alignment assistant – a supplementary function of the SEAM modeling tool SeamCAD [66]. This assistant will identify a refinement type based on the modeler’s activities; depending on the refinement type, the assistant may propose that the modeler specify the states of interest and define a refinement relations between them.

8.1.2 Formal Semantics

Deterministic vs. nondeterministic.
Formal semantics for SEAM and, in particular, a possibility of specifying a system declaratively, opens an interesting discussion about nondeterministic specifications and the way to specify and validate them. By a nondeterministic specification, we understand a specification whose behavior is not explicit. For example, different actions can be triggered by a ‘random choice’ or action parameters can be randomly chosen from some range of allowed values. Formal semantics provides a mechanism to specify nondeterminism for SEAM models.

Formal semantics allows us to design and implement various applications for the simulation and animation of SEAM visual specifications.

From a visual specification to an executable code.
During this work, we have developed several tool prototypes for generating executable and verifiable specifications from SEAM visual models. The improvement of these prototypes, their testing, and documentation is one of the tasks in the future.
SEAM to Jahob is an application that we plan to develop based on the theory created in this dissertation. This tool will help the modeler to animate her specifications by simulating them in Java; providing the Jahob specification constructs will give us an opportunity to formally prove that the implementation corresponds to its specification.

**Scalability.** The technique we created was tested on realistic, but small problems. Considering the integral complexity of the SEAM extended notation, plus the complexity of the verification procedure, the scalability of our technique on a real-size problem is questionable for the moment. By improving both the notation and the transformation procedure, we expect to make our technique scalable.

### 8.1.3 Refinement

**From an executable code to a visual specification.** For the moment, the lack of interpretation of (negative) verification results is a serious drawback of this technique: when the refinement is incorrect, the only recommendation that can be given to the modeler is: ‘*Change the specification and repeat the verification!*’. Several sources of the verification failure can be listed: the refined specification is incorrect; the refinement relation is incorrect; the assertion about refinement is incorrect; the proof technique failed to construct a proof; the validation technique failed; etc. To identify the reasons for failure based on the verification results (error messages, traces, etc. received from verification tools) and to provide recommendations on how to solve the problem is an important task that makes a topic for the future research. Heuristics

**Refinement propagation**

Significant efforts in future might be invested in the further exploration and development of the *refinement propagation technique* [96] based on refinement theory for SEAM specifications:

In contrast to techniques where a refinement is first proposed and then proved to be correct, some techniques allow for the *calculation* of a refinement step based on the refinement laws. The refinement calculus is an underlying theory. This calculation assures refinement correctness ‘by construction’, and enables the reduction of proof obligations.

We believe that refinement by calculation [72] can be beneficial for the practical application in the context of visual modeling. By exploring the refinement types, specified in Chapter 5, we found relations between them in the form “*refinementX implies refinement*”. This implication we call a *propagation of refinement*. With refinement correctness criteria defined, a sufficient part of the calculations can be done without a modeler’s involvement.
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Appendix A

Alloy Specification of the XYZ Example

//=======================================
//=========== Model Abstract ==============
// WO as a whole

lone sig M_w{
  x, y, z : one Int
}

//=======================================
//==== LAdoMath_whole

pred LAdoMath_w_d[x, y, z, x', y', z': one Int] {
  ( y' =  y + x) &&
  ( z' =  z + ( y +  x)) && (x = x')
}

//run LAdoMath_w_d for 5

//successful action doMath
pred LAdoMath_s[x, y, z, x', y', z': one Int] {
  ( y' =  y + x) &&
  ( z' =  z + ( y +  x)) && (x = x')
}

//=======================================
//== Activity components

pred LAaddToY2[x, y, z, x', y', z': one Int ]{
  x' =  x &&
  z'=  z &&
  y'=  y + x
}
pred LAaddToZ2[x, y, z, x', y', z': one Int ]{
  (x'=x) && (y'= y) &&(z'=z +x+y)
}
pred LAaddToY1[x, y, z, x', y', z': one Int ]{
  x'=  x&&
  y' =  y + x
}
pred LAaddToZ1[x, y, z, x', y', z': one Int ]{
  x'=x  &&
  z'= z +x+y
}

//=======================================
//==== LAdoMath_composite - declarative
pred LAdoMath_c_d[x, y, z, x', y', z': one Int ]{
  // true =>
  LAaddToY1[x, y, z, x', y', z'] &&
  LAaddToZ1[x, y, z', x', y', z']
}
//run LAdoMath_c_d

//====================================
//===== LAdoMath_composite - imperative
//====================================
pred LAdoMath_c_i[x, y, z, x', y', z': one Int ]{
  //t - local time stamp
  // true  =>$ (some x_t, y_t, z_t : Int |
  LAaddToY2[x, y, z, x_t, y_t, z_t] &&
  LAaddToZ2[x_t, y_t, z_t, x', y', z'])
}
//run LAdoMath_c_i

assert Declar_Imper{
  all xc, yc, zc, x'c, y'c, z'c, xa, ya, za: one Int |
  (LAdoMath_c_i[xc, yc, zc, x'c, y'c, z'c] && (xa = xc) && (ya = yc) && (za = zc))=>
  (some x'a, y'a, z'a: Int | LAdoMath_c_d[xa, ya, za, x'a, y'a, z'a] && (x'a = x'c) && (y'a = y'c) && (z'a = z'c))
}
//check Declar_Imper

//==================================================
//=======Refinement check
//==================================================
//Given 2 specifications - abstract Ma and concrete Mc; Mc obtained from Ma by a refinement;
//Actions Ac and Aa are defined for both specifications as relations between states at pre and post:
//  Ac = Ac(Mc, Mc') && Aa = Aa(Ma, Ma').
//Formal refinement verification states the following:
//  given a refinement relation R which
//  makes a correspondence between Mc and Ma, such as : Ma_t = R(Mc_t) then the refinement is correct
//  under the following
//  condition: For All Mc, Mc' | Ac(Mc, Mc') => Aa(R(Mc), R(Mc'))
//Must be read: if a step happens in a concrete specification, there will be also a step in the abstract
//specification.

//In particular case, we specify refinement function R as a predicate that is R(Mc -> Ma) -> boolean
//And refinement correctness condition is reformulated as follows:
//  For All Xa,Xa',Xc,Xc' | (Ac(Xc,Xc') && R(Xc ->Xa) && R(Xc'->Xa')) => Aa(Xa, Xa'))

//============================================================= ==============
// REFINEMENT: Localized action as a whole is refined to a composite
//==    R - refinement relation ;
//==    xa - stands for model abstract; xc - for refined model ,
//== or model concrete (both models represent the system as a whole)
//============================================================= ===============
pred R_LAC_to_LAW[xc_t, yc_t, zc_t, xa_t, ya_t, za_t: one Int ]{
  (xc_t= xa_t) &&
  (zc_t= za_t) &&
  (yc_t= ya_t)
}
assert LAW_LAC{
  all xa, ya, za, xc, yc, zc, xc', yc', zc': Int |
  (LAdoMath_c_d[xc, yc, zc, xc', yc', zc'] &&
R_LAC_to_LAW[xc, yc, zc, xa, ya, za] =>
(some xa', ya', za': Int |
LAdoMath_w_d[xa, ya, za, xa', ya', za']&&
R_LAC_to_LAW[xc', yc', zc', xa', ya', za'])
}
//check LAW_LAC

//==================================
//========= WO as a composite
//==================================
// == M_C with 2 components: A and B
// A with 3 attributes: X, Y, Z
// B with 2 attributes: X, Y
// y = y + x; z = z + y
// Two actions:
// - JAdoMath_w
// - DAdoMath_w
//==================================
//===== Components
//==================================
lone sig A{
Ax, Ay, Az: one Int
}
lone sig B{
Bx, By: one Int
}
lone sig M_c{
a: one A,
b: one B
}

//====================================
//===== JointAction - declarative
//====================================
pred JAdoMath_w_d[Ax, Ay, Az, Ax', Ay', Az', Bx, By, Bx', By': one Int] {
true =>
Ax'= Ax &&
Bx'= Bx &&
By'= By + Bx &&
Az'= Az + Ax + Ay &&
some shared_x, shared_y: Int |
(shared_x = Ax &&
Bx = shared_x &&
shared_y = Ay' &&
shared_y= By')
}
//run JAdoMath_w_d for 5

//====================================
//===== JointAction - imperative
//====================================
pred JAdoMath_w_i[Ax, Ay, Az, Ax', Ay', Az', Bx, By, Bx', By': one Int] {
some shared_x, shared_y: Int |
(Ax = shared_x &&
Bx = shared_x &&
Ay' = shared_y &&
By' = shared_y) &&
some Ax lt, Ay lt, Az lt, Bx lt, By lt: Int |
(( Ax lt= Ax) && ( Bx lt= Bx) &&
(Ax'= Ax lt) && ( Bx'= Bx lt) &&

assert JImper_Jdeclar{
    all Axc, Ayc, Azc, Axc', Ayc', Azc', Bxc, Byc, Bxc', Byc', Ax, Ay, Az, Bx, By: Int |
    (JAdoMath_w_i[Axc, Ayc, Azc, Axc', Ayc', Azc', Bxc, Byc, Bxc', Byc'] &&
    Axc = Ax &&
    Ayc = Ay &&
    Azc = Az ) =>
    (some Ax', Ay', Az', Bx', By': Int |
    JAdoMath_w_d[Ax, Ay, Az, Ax', Ay', Az', Bx, By, Bx', By'] &&
    Ax' = Ax' &&
    Ay' = Ay' &&
    Az' = Az' )
}

check JImper_Jdeclar

//============================================================= ==============
// REFINEMENT: System is refined from w to c; Localized action is refined to a Joint Action
//============================================================= ==============
pred R_JA_to_LA[Ax_t, Ay_t, Az_t: one Int, // model concrete
    xa_t, ya_t, za_t: one Int ] // model abstract
    {  ( Ax_t= xa_t)  &&
    ( Az_t= za_t)  &&
    ( Ay_t= ya_t) }

assert LAw_JAd{
    all Ax, Ay, Az, Ax', Ay', Az', Bx, By, Bx', By', xa, ya, za: Int |
    (JAdoMath_w_i[Ax, Ay, Az, Ax', Ay', Az', Bx, By, Bx', By'] &&
    R_JA_to_LA[Ax, Ay, Az, xa, ya, za] ) =>
    (some xa', ya', za': Int |
    R_JA_to_LA[Ax', Ay', Az', xa', ya', za'] )
}

//check LAw_JAd

assert LAc_JAd{
    all Ax, Ay, Az, Ax', Ay', Az', Bx, By, Bx', By': Int , xa, ya, za: Int |
    (JAdoMath_w_d[Ax, Ay, Az, Ax', Ay', Az', Bx, By, Bx', By'] &&
    R_JA_to_LA[Ax, Ay, Az, xa, ya, za] ) =>
    (some xa', ya', za': Int |
    R_JA_to_LA[Ax', Ay', Az', xa', ya', za'] )
}

//check LAc_JAd

assert LAc_JAi{
    all Ax, Ay, Az, Ax', Ay', Az', Bx, By, Bx', By': Int , xa, ya, za: Int |
    (JAdoMath_w_i[Ax, Ay, Az, Ax', Ay', Az', Bx, By, Bx', By'] &&
    R_JA_to_LA[Ax, Ay, Az, xa, ya, za] ) =>
    (some xa', ya', za': Int |
    R_JA_to_LA[Ax', Ay', Az', xa', ya', za'] )
}

//check LAc_JAi  - to check
Figure A-1: Specification of a component working objects A and B with their localized actions aLAdoMath and bLAdoMath.

//=================================
//===== Actions for A (Fig. A-1-a)
//=================================
pred aLAdoMath_w[Ax, Ay, Az, Ax', Ay', Az': one Int] {
  //true =>
  (Ax' = Ax &&
   Az' = Az + Ax + Ay)
}

//=================================
//===== Actions for B (Fig. A-1-b)
//=================================
pred bLAdoMath_w[Bx, By, Bx', By': one Int] {
  //true =>
  (Bx' = Bx &&
   By' = By + Bx)
}

//========================================= //===== Distributed Action - declarative (Fig. A-2) //========================================= pred DA_w_d[Ax, Ay, Az, Ax', Ay', Az', Bx, By, Bx', By': one Int] {
  blAdoMath_w[Bx, By, Bx', By'] &&
  aLAdoMath_w[Ax, Ay, Az, Ax', Ay', Az'] &&
  some sharedX, sharedY one Int |
  Bx' = sharedX && Ax' = sharedX &&
  Ay' = sharedY && By' = sharedY
}

//run DA_w_d for 10
Figure A-2: Specification of a distributed action DAdoMath.

//===========================================================================
// REFINEMENT: Joint action is refined to a Distributed Action
//===========================================================================

pred R_DA_to_JA[Axc_t, Ayc_t, Azc_t, Bxc_t, Byc_t, //model concrete
Axa_t, Aya_t, Aza_t, Bxa_t, Bya_t: one Int  ]{ //model abstract
  ( Axc_t =  Axa_t)  &&
  ( Ayc_t =  Aya_t)  &&
  ( Azc_t =  Aza_t)
}
assert JA_DAD{
  all  Axc, Ayc, Azc, Axc', Ayc', Azc', Bxc, Byc, Bxc', Byc',
  Axa, Aya, Aza, Bxa, Bya : Int  |
  ( DA_to_JA[Axc, Ayc, Azc, Axc', Ayc', Azc', Bxc, Byc, Bxc', Byc']  &&
  R_DA_to_JA[Axc, Ayc, Azc, Axc', Ayc', Azc', Bxc, Byc, Bxc', Byc'] ) =>
  some Axa', Aya', Aza', Bxa', Bya': Int  |
  Axa', Aya', Aza', Bxa', Bya'] )
}
check JA_DAD

//===========================================================================
// REFINEMENT: System is refined from w to c; Localized action is refined to a Distributed Action
//===========================================================================

pred R_DA_to_LA[Ax, Ay, Az, Bx, By, xa, ya, za: one Int ]{
  Ax=  xa  &&
  Az=  za  &&
  Ay=  ya
}
assert JA_DAD{
  all  Ax, Ay, Az, Bx, By, Xa, Ya, Za, Xa', Ya', Za', Bx', By',
  Xa, Ya, Za, Bxa, Bya : Int  |
  ( DA_to_LA[Ax, Ay, Az, Bx, By, Xa, Ya, Za, Xa', Ya', Za', Bx', By']  &&
  R_DA_to_LA[Ax, Ay, Az, Bx, By, Xa, Ya, Za, Xa', Ya', Za', Bx', By', Bxa', Bya'] ) =>
  some Xa', Ya', Za', Bxa', Bya': Int  |
  ( R_DA_to_LA[Ax, Ay, Az, Bx, By, Xa', Ya', Za', Bx', By', //model concrete
  Xa', Ya', Za', Bxa', Bya'] )
}
check JA_DAD

//valid for DAdoMath_w_d, JAdoMath_w_d, JAdoMath_w_i

//valid for DAdoMath_w_d, LAdoMath_w_j, LAdoMath_w_d, LAdoMath_c_i, LAdoMath_c_d

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assert LA_DAD{
    all Ax, Ay, Az, Ax', Ay', Az', Bx, By, Bx', By', xa, ya, za: Int |
    ( DA_w_d[Ax, Ay, Az, Ax', Ay', Az', Bx, By, Bx', By'] &&
    R_DA_to_LA[Ax, Ay, Az, Bx, By, xa, ya, za] ) =>
    (some xa', ya', za': Int |
    R_DA_to_LA[Ax', Ay', Az', Bx', By', xa', ya', za'] &&
    LAdoMath_c_i[xa, ya, za, xa', ya', za'] )
}
//check LA_DAD to check
Appendix B

Jahob Formulas for the XYZ Example

1. File: final_law_lacd.form

This formula validates the fact that the localized action as a composite modeled declaratively correctly refines the localized action as a whole:

(* action LAdoMath_w *)
(ActionAbstract = (% x y z xp yp zp.
yp = x + y &
zp = z + (y + x) &
xp = x)) &

(* component actions *)
(LAaddToY1 = (% x y z xp yp zp.
xp = x &
yp = y + x )) &

(LAaddToZ1 = (% x y z xp yp zp.
xp = x &
zp = z + x + y ))&

(* LAdoMath_composite - declarative *)
(ActionConcrete = ( % x y z xp yp zp.
LAaddToY1 x y z x_t y_t z_t &
LAaddToZ1 x_t y_t z_t xp yp zp )))&

(*Refinement verification*)
(* refinement relation *)
(RefinementRelation = (% xc_t yc_t zc_t xa_t ya_t za_t.
xc_t =  xa_t &
zc_t =  za_t &
yc_t =  ya_t )) -->

(*assert LAW_LAC *)
(ALL xa ya za xc yc zc xc xcp ycp zcp.
ActionConcrete xc yc zc xc xcp ycp zcp &
RefinementRelation xc yc zc xa ya za) -->
(EX xap yap zap.
ActionAbstract xa ya za xap yap zap &
RefinementRelation xcp ycp zcp xap yap zap))

2. File: final_law_laci.form

This formula validates the fact that the localized action as a composite modeled imperatively correctly refines the localized action as a whole modeled declaratively:

(* action LAdoMath_w *)
(ActionAbstract = (% x y z xp yp zp.
yp = x + y &
zp = z + (y + x) &
xp = x)) &
(* component actions *)
(LAaddToY2 = (% x y z xp yp zp.
xp = x &
zp = z &
yp = y + x )) &

(LAaddToZ2 = (% x y z xp yp zp.
xp = x &
yp = y &
zp = z + x + y )) &

(* LAdoMath_composite - imperative *)
(ActionConcrete = ( % x y z xp yp zp.
EX x_t, y_t, z_t.
LAaddToY2 x y z x_t y_t z_t &
LAaddToZ2 x_t y_t z_t xp yp zp )) &

(* Refinement verification *)
(* refinement relation *)
(RefinementRelation = (% xc_t yc_t zc_t xa_t ya_t za_t.
xc_t = xa_t &
zc_t = za_t &
yc_t = ya_t ) -->
(* assert LAW_LAC *)
((ALL xa ya za xc yc zc xcp ycp zcp.
(ActionConcrete xc yc zc xcp ycp zcp &
RefinementRelation xc yc zc xa ya za) -->
(EX xap yap zap.
ActionAbstract xa ya za xap yap zap &
RefinementRelation xcp ycp zcp xap yap zap))

3. File: final_laci_lacd.form

This formula validates the fact that the localized action as a composite modeled imperatively correctly refines the same action modeled declaratively:

(* component actions *)
(LAaddToY1 = (% x y z xp yp zp.
xp = x &
yp = y + x )) &

(LAaddToZ1 = (% x y z xp yp zp.
xp = x &
zp = z + x + y )) &

(* LAdoMath_composite - declarative *)
(ActionAbstract = ( % x y z xp yp zp.
LAaddToY1 x y z x_t y_t z_t &
LAaddToZ1 x_t y_t z_t xp yp zp )) &

(* component actions *)
(LAaddToY2 = (% x y z xp yp zp.
xp = x &
zp = z &
yp = y + x )) &
This formula validates the fact that the distributed action as a whole modeled declaratively correctly refines the localized action as a composite modeled declaratively / imperatively:

4. File: final_dad_laci.form

(* component actions *)
(LAAddToY2 = (% x y z xp yp zp.
xp = x &
yp = y &
zp = z + x + y )) &

(LAAddToZ2 = (% x y z xp yp zp.
xp = x &
yp = y &
zp = z + x + y )) &

(* LAdoMath_composite - imperative *)
(ActionConcrete = ( % x y z xp yp zp.
EX x_t, y_t, z_t.
LAAddToY2 x y z x_t y_t z_t &
LAAddToZ2 x_t y_t z_t xp yp zp )) &

(* refinement relation *)
(RefinementRelation = (% xc_t yc_t zc_t xa_t ya_t za_t.
xc_t = xa_t &
zc_t = za_t &
yc_t = ya_t )) -->

(*assert declar_imper *)
(ALL xa ya za xc yc zc xcp ycp zcp.
(ActionConcrete xc yc zc xcp ycp zcp &
RefinementRelation xc yc zc xa ya za) -->
(EX xap yap zap.
ActionAbstract xa ya za xap yap zap &
RefinementRelation xcp ycp zcp xap yap zap))
To validate the refinement of the localized action as a composite modeled declaratively and the distributed action, the abstract action definition should be replaced with one from the previous examples. The rest of the formula will not change.

5. File: final_jad_dad.form

This formula validates the fact that the distributed action as a whole modeled declaratively correctly refines the joint action modeled declaratively:

(* Joint action JAdoMath_w - declarative *)
(ActionAbstract = ( % Ax Ay Az Axp Ayp Azp.
Axp = Ax & Bxp = Bx &
Byp = By + Bx &
Azp = Az + Ax + Ay &
EX shared_x shared_y.
(shared_x = Ax & Bx = shared_x &
shared_y = Ayp & shared_y= Byp )))

(* WO as a composite = A + B (see Fig. A-1) *)
(* Actions for A:)
(aLAdoMath_w = (% Ax Ay Az Axp Ayp Azp.
Axp = Ax &
Azp = Az + Ax + Ay )) &

(* Actions for B:)
(bLAdoMath_w = (% Bx By Bxp Byp.
Bxp = Bx &
Byp = By + Bx ))&

(* Distributed action - declarative *)
(ActionConcrete = ( % Ax Ay Az Axp Ayp Azp Bx By Bxp Byp.
alAdoMath_w Ax Ay Az Axp Ayp Azp &
bLAdoMath_w Bx By Bxp Byp &
EX x_shared, y_shared.
Bxp = x_shared & Axp = x_shared &
Ayp = y_shared & Byp = y_shared )))

(* refinement relation *)
(RefinementRelation = (% x_t y_t z_t Ax_t Ay_t Az_t.
Axc_t = x_t &
Az_t = z_t &
Ay_t = y_t )) -->

(* assert LA_DAD *)
((ALL Ax Ay Az Axp Ayp Azp Bx By Bxp Byp x y z.
(ActionConcrete Ax Ay Az Axp Ayp Azp Bx By Bxp Byp &
RefinementRelation Ax Ay Az x y z) -->
(EX xp yp zp.
ActionAbstract x y z xp yp zp &
RefinementRelation xp yp zp Axp Ayp Azp))

To validate the refinement of the localized action as a composite modeled declaratively and the distributed action, the abstract action definition should be replaced with one from the previous examples. The rest of the formula will not change.

5. File: final_jad_dad.form

This formula validates the fact that the distributed action as a whole modeled declaratively correctly refines the joint action modeled declaratively:
\[ \text{Azc}_t = \text{Aza}_t \land \text{Ayc}_t = \text{Aya}_t \] -->

(*assert JA_DAD *)

((\forall \text{Axc} \ \text{Ayc} \ \text{Azc} \ \text{Axcp} \ \text{Aycp} \ \text{Azcp} \ \text{Bxc} \ \text{Byc} \ \text{Bxcp} \ \text{Bycp} \ \text{Axa} \ \text{Aya} \ \text{Aza} \ \text{Bxa} \ \text{Bya}. )

(\text{ActionConcrete} \ \text{Axc} \ \text{Ayc} \ \text{Azc} \ \text{Axcp} \ \text{Aycp} \ \text{Azcp} \ \text{Bxc} \ \text{Byc} \ \text{Bxcp} \ \text{Bycp} \ \land \ \text{RefinementRelation} \ \text{Axc} \ \text{Ayc} \ \text{Azc} \ \text{Axa} \ \text{Aya} \ \text{Aza}) -->

(\exists \text{Axap} \ \text{Ayap} \ \text{Azap} \ \text{Bxap} \ \text{Byap}.

\text{ActionAbstract} \ \text{Axa} \ \text{Aya} \ \text{Aza} \ \text{Axap} \ \text{Ayap} \ \text{Azap} \ \text{Bxa} \ \text{Bya} \ \text{Bxap} \ \text{Byap} \ \land \ \text{RefinementRelation} \ \text{Axcp} \ \text{Aycp} \ \text{Azcp} \ \text{Axap} \ \text{Ayap} \ \text{Azap})))

NOTE: Axa – stands for the value of variable x of the component working object A of the abstract specification; Axc – stands for the value of variable x of the component working object A of the concrete specification; Correspondingly, Axap and Axcp are values of these variables after the action termination.
Appendix C

Practical Feedback

Ian F Alexander
Company: Scenario Plus (UK)
Director (consultant, trainer, author)

- What is your expertise in business/IT alignment? (based on your past projects)


- Do you use any modeling techniques for your projects? (i.e. UML, BPMN, other.)

I use a wide range of modelling techniques including goal modelling, scenario analysis, context modelling, and rationale modelling. I have personally developed stakeholder analysis techniques and extended the use of negative scenario analysis with “misuse cases”. I have not found most kinds of UML diagram especially helpful, but make use of them (e.g. class diagrams, activity diagrams) from time to time.

- Do you use any software for automated modeling / documentation / analysis in your projects?

Scenario Plus for Use Cases was originally conceived as a tool which would animate (step through) a scenario AND/OR tree to generate specific scenarios which could be used directly as test cases. Now I use a range of Scenario Plus tools to edit diagrammatic models (goal models, rationale models, etc), as well as Enterprise Architect for UML models, and DOORS to automate traceability in requirements documentation.

2. Validation:

- Whether the problem discussed in the paper is encountered in practice?

Yes. There is no doubt that many SLAs are poorly written and result in poor service to the business.

-Here I would refer not only to the fact that the SLA can be poorly written: What I really wanted to address in my work, is the fact that even from the initially well written SLA one can get the poorly constructed service, which will violate this SLA. Do you think this is a sound problem?

Yes, certainly. Traceability is a major problem in industry – it is horribly tedious to apply, and always error-prone.
- What do you think about the usefulness of the method presented in the paper for a practitioner? Please, explain your answer.

Firstly the specification is remarkably clear and easy to read, despite being in an unfamiliar notation.

Secondly, by expressing the relationships between actions and data graphically, it is highly expressive, making it clear what is needed when.

These properties of the approach make it an attractive new possibility for practical use. It appears far more likely to be practical than the majority of formal methods from research projects.

A possible concern is about how such a notation may scale up for large problems; the number of relationships may increase rapidly with the number of both actions and pieces of data, which could make the diagrams hard to read. It could also make formal proof of correctness long, though as this is supported by the Alloy Analyzer tool that should not be a problem.

- How do you think the validation / verification technique presented in the paper can help you (your company)? Please, describe the advantages and disadvantages that you can expect.

In principle the techniques could help to create accurate service specifications for clients. The industrialisation of the approach would involve training for requirements practitioners, tooling, and reasonable assurance to both the company and the client that the approach is workable in practice (on a real problem, and by practitioners).

Ilia Bider
Company: IbisSoft (Sweden)
Director R&D

- What is your expertise in business/IT alignment? (based on your past projects)

Organizational change through introduction of business process support systems

- Do you use any modeling techniques for your projects? (i.e. UML, BPMN, other.)

Yes (others)

- Do you use any software for automated modeling / documentation / analysis in your projects?

We use (and develop) tools for getting IT support system from (or at the same time as) process specification.

2. Validation:

- Whether the problem discussed in the paper is encountered in practice?

Personally, I have not encountered them in my practice. Nevertheless, I can easily imagine who have this kind of problems, one example being vendors of software systems with business processes built-in in them, for example CRM vendors, WEB-shopping systems
vendors, etc. They need to be able to adjust their systems to each customer needs.

- What do you think about the usefulness of the method presented in the paper for a practitioner? Please, explain your answer.

It could be quite useful as a methodological base for discussing problems and finding solutions. To achieve this, a popular version and texts in methodological style should be written, e.g. manuals, etc. Making full use of the methodology will require introduction of it in a tool that helps to design processes/support systems.

- How do you think the validation/verification technique presented in the paper can help you (your company)? Please, describe the advantages and disadvantages that you can expect.

I cannot see direct use of them in our current practice. I can imagine using them as a methodological framework, if we come across an appropriate task in the future.

As far as formal methods are concerned, I do not think we will use formal methods of verification/validation in any foreseeable future. As an explanation of my response, I would like to draw a parallel with formal verification/validation of computer programs. The domain is quite old, but I have never seen it being used in the development of business applications, at a maximum people use formal testing methods. As I understand, these are used for very critical applications, like in a space ship sent by NASA to Mars, or in high volume low margin cases, like hardware built-in programs. In the latter case the vendors cannot afford serious faults in a program, and high volume of production can justify investment in formal methods and tools. In addition, their programs, normally, have well-defined formal specifications.

I cannot see any signs of the two situations above in the market of BPM/process support tools. What is more, tools vendors might not be much interested in formal staff. Considerable share of their income is coming from tuning/adjustment of their tools to the customers needs. In this area, customers are charged on the consulting basis, i.e. per hour, and the vendors are quite happy with that. I cannot se why they suddenly would like to invest in formal validation/verification.

Nevertheless, there might be some possibilities to promote formal verification/validation, provided they are incorporated in some tool, e.g.:

- As a sales argument for the tool
- To provide guarantees in cases of extremely importance for the customers (e.g. SOX compliance).

In general, I believe that there is only one way to answer the question of practical applicability of a method of this kind – to implement it as an own toolkit for process design, or as an ad on to somebody’s else toolkit. Thus the authors need to develop and market their own stuff, or sell the idea to an existing toolkit vendor. Another option is to wait until somebody will pick it up, but it may take a long time.

Alexander Samarin
Company: Teamlog S.A. (Suisse)
Enterprise solutions architect
- What is your expertise in business/IT alignment? (based on your past projects)

Many years of active participation in architecting and implementing flexible enterprise solutions.

- Do you use any modeling techniques for your projects? (i.e. UML, BPMN, other.)

BPMN and some proprietary methods

- Do you use any software for automated modeling / documentation / analysis in your projects?

IBM WebSphere Integration Developer, Oracle SOA suite, Intalio BPM suite

2. Validation:

- Whether the problem discussed in the paper is encountered in practice?

Use of declarative specifications for complex dynamic systems is very attractive [1] and very challenging at the same time. Higher flexibility and higher potentials for optimisation are coming together with higher difficulty, especially, for non-experts for creating such specifications.

Experience shows that always we have to find a balance between different techniques for coordination of business activities – some aspects/fragments of a business process are better to express with an imperative technique and others are better to express with a declarative technique.

A practical example of the problem of customisation has been encountered at a client from the international standardisation. The core business process at this client is a well-defined sequence of step-by-step enrichments (commenting, balloting, technical editing, translating, etc.) of a complex document. We found that it would be better if each document would have its own sequence. So, we wanted to customize a template for each instance. We didn’t find an easy way to implement this with modern tools.

- What do you think about the usefulness of the method presented in the paper for a practitioner? Please, explain your answer.

From a practitioner point of view, the method sounds useful and promising because it considers complimentary of declarative and imperative techniques. Synergy of these two techniques (complimented by some guidance how to combine them) will certainly create better more flexible business process models.

- How do you think the validation / verification technique presented in the paper can help you (your company)? Please, describe the advantages and disadvantages that you can expect.

Any formal verification is very useful in daily practical work because such a verification can bring highly demanded objective and scientifically proven reasoning into modern enterprise environment with all its political tensions and power games (where it is almost impossible to have something willingly accepted and followed by everyone).

So far, I think that the visual notation needs some enhancements before meeting non-experts. For example, some traditional modelling artefacts (e.g. events and roles) are expected by the
users. Also some diagramming style should be recommended to improve explicitness of diagrams and their structuring for better “executability”.


Thomas Langenberg
Company: Accenture (Germany)
2 years of experience, SAP Consultant, Project manager

- What is your expertise in business/IT alignment? (Based on your past projects)

Implementation of SAP BW for large corporations (I was working with Siemens, Deutsche Telecom, Otto Versand). I was customizing the predefined SAP solutions for controlling and performance monitoring units of financial departments within the client organization.

- Do you use any modeling techniques for your projects? (i.e. UML, BPMN, other.)

Standard document formats accepted in financial departments are typically Microsoft Word, Excel, and PowerPoint. Therefore, all as-is and to-be modeling of the work flow and processes during my projects was done in MS Power Point. Based on my experience, presentations are very efficient for the client (who is typically not used to any modeling standard). I was using the ad-hoc graphical notation, similar to BPMN.

- Do you use any software for automated modeling / documentation / analysis in your projects?

Power Point presentations for discussing and documenting projects; no further analysis.

2. Validation:

- Whether the problem discussed in the paper is encountered in practice?

The projects I was involved in aimed at substituting an existing system for financial monitoring by a more efficient and productive system, such as SAP. These projects usually contain two parts:
1. Initial configuration of a system, using a standard SAP solution. The goal of this part is to make a quick solution for the customer that will work as a substitute of the old system;
2. When the initial configuration is built, we switch to the system optimization. This typically involves customization and reorganization of components within the standard solution and aims at improving, for example, the speed and responsiveness of the system. Customization includes re-programming of some components, and their interconnection.

In context of such projects, the problem of verification that the customized system performs as well the standard solution or provides at least the same functionality as an old system is important.

- What do you think about the usefulness of the method presented in the paper for a practitioner? Please, explain your answer.
Based on my experience, standard development process (typically presented as Requirements specification, Development, Testing, and Deployment) is never linear. Many iterations are usually required during a development phase. There are several reasons to it: the requirements keep changing; many different stakeholders are involved proposing their own solutions; many political interests must be taken into account. Each iteration of the development process is costly and time consuming. Evaluation of each alternative solution and validation that this solution does not violate the requirements is a typical problem. Though, having a technique with which one can evaluate proposed solutions could save project resources and would be a useful instrument for a consultant.

- How do you think the validation / verification technique presented in the paper can help you (your company)? Please, describe the advantages and disadvantages that you can expect.

As I see it, the proposed technique may serve for a consultant to verify solutions against requirements and also to evaluate and to compare these solutions. This is definitely an attractive instrument. However I consider several main challenges in adopting such technique:

1. The complex graphical notation plus the use of formal methods prevents this technique from being used for communication with a client. (Based on my experience, only a small part of the organization, mainly from the IT department, uses and understands UML or other modeling techniques). Therefore, the proposed technique can be used only by a trained consultant, in the project back-office.
2. The utilization of this technique will introduce a new step in the project development process, which is promising but time and money consuming. As time is essential during the project, it can be difficult to communicate a profitability of this step to the customer. Several successful projects in a field, accomplished using this technique and illustrating its profitability can help. Therefore, some statistics might be needed prior to a commercial use.

Donald C. Gause  
Company: Savile Row LLC (USA) - Principal and Consultant  
Thomas J. Watson School of Engineering, Binghamton University, State University of New York – Research Professor

- What is your expertise in business/IT alignment? (based on your past projects)

The preponderance of my work deals with the application of generic requirements processes developed as a result of observing common problems and lost opportunities in practice.

Recent professional and consulting activities include:

- Requirements, design, and process consultant to global banking community on projects involving:
  - Gap analysis and cross-functional system development for the replacement of divisional legacy systems; Formal design reviews of requirements and specifications for systems under development; Post-release user reviews of systems and design processes of recently released systems; Advising management teams in the enhancement of information flow and productive innovation within and across banking functions; etc.
  - Advised a number of commercial and government organizations in concept, function and requirements development for:
Traumatic brain injury treatment management system; Traumatic brain injury full-care delivery information system; FDA drug approval protocol system; etc.
Directed a corporate task force in the development of advanced computer concepts and strategic plans for next generation cars and trucks.
Advised directors in the integrated development of the business plan, business requirements, feature and function development and design risk analysis for a new Internet start-up company.

- **Do you use any modeling techniques for your projects? (i.e. UML, BPMN, other.)**

My work focuses on the non-functional requirements short of functional specification and implementation but does include use scenarios and test cases.

I have worked with systems in which Parnas’s structured decision tables, Jackson’s problem frames, Yu’s i*, Petri nets and UML have been used for algorithm specification. I have had graduate professional student projects in which APL was used as a meta-language to describe the final system with the advantage that the executable meta-language was used to test and refine the algorithm before final implementation was achieved in assembler language. I have also designed evolutionary programs capable of improving their performance with experience thus demonstrating their ability to define their own required modification and structure based on ill-defined goals as well as explicit goals. These approaches are based on genetic and neural network models.

- **Do you use any software for automated modeling / documentation / analysis in your projects?**

I have used software of my own design to document the requirements elicitation process described above and to test for consistency and completeness based on binary context matrices defining pair-wise relationships between users, attributes, and constraints.

2. **Validation research:**

- **Whether the problem discussed in the paper is encountered in practice?**

The problem discussed in this paper is a fundamental problem in design and implementation of software systems. It is, in fact, a fundamental problem in the design of computer solutions, in general (hardware and software), as it has grown more advantageous to delay decisions determining the allocation of required functionality to software, firmware, or hardware until the full functionality has been defined. This is particularly true in the design of imbedded process control systems (manufacturing, vehicular stabilizing, traffic, robotic control) as well as with the implementation of distributed computing systems designed to take advantage of highly parallel algorithms (genetic and evolutionary programs, neural networks, reconstructability and cluster analysis).

- **What do you think about the usefulness of the method presented in the paper for a practitioner? Please, explain your answer.**

It is hard to imagine a computer design problem that would not benefit from a refinement tool that is capable of recognizing and correcting inconsistency between high-level business and systems requirements and implementation instructions (functional specifications). Many factors contribute to our increasing needs to apply effective specification refinement, a few of
which are: 1) we are building larger, more complex systems to be used by more diverse user populations, 2) these systems must integrate into even larger systems, 3) systems usability has become a stronger differentiating factor in increasingly competitive markets, 4) because of these three factors, many critical contextual factors cannot be recognized until the product has been released and unintended consequences are discovered giving rise to continual change activity.

The main concern I have with the EPFL white paper\textsuperscript{8} is that I have not seen enough evidence that the proposed method has been properly validated.

- How do you think the validation, verification technique presented in the paper can help you (your company)? Please, describe the advantages and disadvantages that you can expect.

Advantages:
- Assuming that your claims are correct in all process assumptions you have based your study on, the technique will certainly be beneficial to designers, clients, and end users alike. The one aspect assures this is the fact that this substantially enhances design visibility to each of the targeted constituents enabling the users to say, “No, that’s not what I mean.” Rather than, “No, that’s not what I meant.” This is what we are all striving for.

Potential problems:
- Your technique was nicely illustrated with the “toy” example because of admitted difficulty in describing a more complex (realistic) case in SEAM. And yet, SEAM is described as being a visual tool.
- I have the advantage of being relatively ignorant of the SEAM visual representation schema and, as such, wonder if there might not be a serious difficulty in scaling up to more typically complex design problems. I have no doubt that people working with SEAM on a daily basis find the notation to be elegant in its simplicity but doubt that the end-users (and many other critical but computer notationally disadvantaged users) will find SEAM to be the visually accessible tool that provides enhanced visibility to all.
- How critical is ITIL to the success of this approach? I raise this point from a commercial perspective because, as I understand it, members of the potential ITIL market have criticized the product because of the need to purchase expensive system books and the zeal with which the ITIL backers express themselves with respect to their product. One member of the potential customer community felt that his ITIL contact was more full of zeal than the pragmatics of his problem.
- As a last point, what can this SEAM-based model system do that UML, i*, Petri nets or other current meta-languages not do? What does it do better than any of these meta-languages?

\textsuperscript{8} Donald C. Gause is mentioning the paper, which shortly illustrates the research result of this dissertation using the SIG example from Section 7.2.
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Figure 6-1: Jahob Verification system: (a) a Jahob specification is an input for the Jahob verification system. It is a program, written in a subset of Java and annotated with Jahob expressions. This specification is transformed later into Jahob formula; (b) a Jahob formula is a ‘ready to prove’ expression that is an input for the formDecider

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List of Abbreviations

<table>
<thead>
<tr>
<th>Abbreviation</th>
<th>Description</th>
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</thead>
<tbody>
<tr>
<td>c, _c, [c]</td>
<td>- view as a composite</td>
</tr>
<tr>
<td>DA</td>
<td>- distributed action</td>
</tr>
<tr>
<td>EA</td>
<td>- Enterprise Architecture</td>
</tr>
<tr>
<td>FOL</td>
<td>- First-Order Logic</td>
</tr>
<tr>
<td>HOL</td>
<td>- Higher-Order Logic</td>
</tr>
<tr>
<td>In</td>
<td>- input parameter</td>
</tr>
<tr>
<td>Inv</td>
<td>- invariant</td>
</tr>
<tr>
<td>JA</td>
<td>- joint action</td>
</tr>
<tr>
<td>LA</td>
<td>- localized action</td>
</tr>
<tr>
<td>Out</td>
<td>- output parameter</td>
</tr>
<tr>
<td>Post</td>
<td>- postcondition</td>
</tr>
<tr>
<td>Pre</td>
<td>- precondition</td>
</tr>
<tr>
<td>RM-ODP</td>
<td>- Reference Model for Open Distributed Processing</td>
</tr>
<tr>
<td>RPA</td>
<td>- Relation Partition Algebra</td>
</tr>
<tr>
<td>SE</td>
<td>- Software Engineering</td>
</tr>
<tr>
<td>SEAM</td>
<td>- Systemic Enterprise Architecture Methodology</td>
</tr>
<tr>
<td>w, _w, [w]</td>
<td>- view as a whole</td>
</tr>
<tr>
<td>WO</td>
<td>- working object</td>
</tr>
</tbody>
</table>
List of Publications


8. **Teaching Enterprise and Service-Oriented Architecture in Practice.** Wegmann, Alain; Regev, Gil; de la Cruz, José Diego; Lê, Lam-Son; Rychkova, Irina. Accepted in: *Journal of Enterprise Architecture*, vol. 4, num. 3, 2007, p. 15 – 24.

9. **An Example of a Hierarchical System Model Using SEAM and its Formalization in Alloy.** Wegmann, Alain ; Lê, Lam-Son ; de la Cruz, José Diego ; Rychkova, Irina et al. Presented at: *4th International Workshop on ODP for Enterprise Computing (WODPEC 2007)*, Annapolis, Maryland, October 15.


Curriculum Vitae

Irina RYCHKOVA

School of Computer and Communication Sciences
Ecole Polytechnique Fédérale de Lausanne (EPFL)
EPFL - I&C – LAMS, CH - 1015 Lausanne, Switzerland

+41 76 385.2240 (tel.)
Irina.rychkova@gmail.com

PROFESSIONAL INTERESTS

- Business/IT Alignment
- Business Process Modeling and Analysis
- IT Service specification
- Visual Modeling (UML-inspired languages), Simulation, and Analysis

DEGREES & EDUCATION


2000 – 2002 M.Sc. (with Honors). Department of Physical and Quantum Electronics. Moscow Institute of Physics and Technology (MIPT), Russia

1995 – 2000 Engineer diploma (with Honors), School of Information Sciences. Samara State Aerospace University (SSAU), Russia.

RESEARCH EXPERIENCE

2003 – .. EPFL - I&C – LAMS, research assistant
Project: Semantics and Verification of SEAM visual models.
SEAM is a modeling method for Enterprise Architecture. I develop semantics that allow for verification of SEAM Visual models on the formal basis. My approach is applied in the context of Business/IT alignment, where a system implementation needs to be verified against its specification. Results are used in the joint project with Itecor company, performed for Service Industrielle de Genève.

Teaching assistantship, exam expertise, project supervision:
- ESOA (Enterprise and Service-Oriented Architecture) course for Master students (2007 - 2008);
- Programmation I-II (in French) course for Bachelor students (2006);
- Various Master (diploma) and semester projects.
07.2008 – 12.2008 adidas group, GlobalIT (Herzogenaurach, Germany). 6 months internship in IT Architecture. Complexity reduction and IT consolidation is one of the main initiatives in GlobalIT. I’m working on validation of Business/IT alignment between the Go-to-market core process of the company and the IT- landscape, supporting this process across the different deviations of the company. My task is to develop a framework for evaluating the impact of late changes in product specification. Based on the change impact, IT solution for change management has to be specified.

2000-2002 Center of Open Systems and High Technologies (Moscow, Russia), project member
Project: Information system for aviation and engineering services of an airline company.
In collaboration with engineering department of Aeroflot – Russian Air lines, I was designing and developing integrated services for different company departments. My objectives was to analyze and to optimize the process based on data mining.

LANGUAGES

French – good communication skills; English (spoken and written) – fluent; Russian - native; Italian – basic; German - basics.

INTERESTS

Triathlon (Team.Triody.com), cross-country skiing, alpinism, landscape photography and art.